TECHNICAL NOTES AND SHORT PAPERS

The Approximate Solution of an Integral Equation Using High-Order Gaussian Quadrature Formulas

By Stephen M. Robinson and A. H. Stroud

The purpose of this note is to illustrate the usefulness of the high-order Gaussian quadrature formulas given in [1], [2], [3] in a problem of approximating the value of

$$I = \int_a^b g(x)\varphi(x) \ dx$$

where $\varphi(x)$ is the solution of a Fredholm integral equation

(2)
$$\varphi(x) - \int_a^b K(x, y)\varphi(y) \, dy = f(x).$$

Here K(x, y), f(x) and g(x) are known functions and K(x, y) has a discontinuity at y = x.

The approximate solution of (2) was found by a method described in [4], p. 101. It consists of replacing (2) by

$$\varphi(x)\left[1-\int_a^b K(x,y)\,dy\right]-\int_a^b K(x,y)[\varphi(y)-\varphi(x)]\,dy=f(x).$$

Now, since K(x, y) is a known function, $\int_a^b K(x, y) dy$ can be determined as a function of x, say $\chi(x)$. It is reasonable to suppose that the integral

(3)
$$\int_{a}^{b} K(x,y) [\varphi(y) - \varphi(x)] dy$$

can be better approximated by a quadrature formula than the original integral in (2). If we use a quadrature formula with weights A_k and points x_k , $k = 1, 2, \dots, n$, to evaluate (3), then approximate values of the function $\varphi(x_k)$ may be determined by solving the linear system

$$\varphi(x_i)[1-\chi(x_i)] - \sum_{k=1}^n A_k K(x_i, x_k)[\varphi(x_k) - \varphi(x_i)] = f(x_i) \quad i = 1, 2, \dots, n.$$

The same quadrature formula may then be applied to approximate the integral (1).

To illustrate the accuracy of Gaussian quadrature formulas in this problem we give the results of some calculations concerning flow of a gas through a conical opening which were carried out for Prof. R. P. Iczkowski of the University of Wisconsin Extension Chemistry Department. The kernel K(x, y) was defined for two

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TABLE 1	
Values of	I

n	$\begin{array}{c} \alpha = 0 \\ L = 2 \end{array}$	$\begin{array}{c} \alpha = 10 \\ L = 2 \end{array}$	$\begin{array}{c} \alpha = 10 \\ L = 10 \end{array}$
12 16 24 36 48	0.5142287 0.5142294 0.5142305 0.5142306 0.5142306	 0.6705783 0.6706079 0.6706184	0.4768471 0.4775303 0.4777735

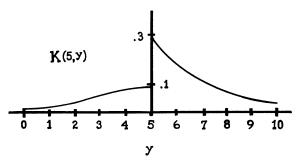


Fig. 1.—Cross-Section of the Kernel K (x, y).

parameters, α and L. The table gives values of I for three cases; in each case I was evaluated using the indicated n-point Gaussian quadrature formulas. The calculations were carried out using single-precision, floating point arithmetic.

The nature of the kernel is illustrated in the figure which gives a typical cross-section of K(x, y).

The calculations for $\alpha=0$, L=2 are a good illustration of the accuracy achieved over most of the range investigated: $\alpha=0$ to 89, L=0.1 to 10.0. In this case the 24-point formula seems to give 6-decimal accuracy. The other cases of the table are some of the least accurate. For $\alpha=10$, L=10 the 24-point formula seems to give 3-decimal accuracy and the 48-point formula about 4-decimal accuracy. In all of these calculations it appears that, roughly, doubling the number of points produces another decimal place of accuracy. No analytical estimates of the error were carried out. These calculations illustrate, however, that by using 8 significant figures in such calculations it is possible to achieve 6- or 7-figure accuracy in the result if a sufficiently accurate formula is used.

The calculations for n = 12, 16 were carried out on the IBM 650 at the Numerical Analysis Laboratory and for n = 24, 36, 48 on the IBM 704 at the Midwestern Universities Research Association. The programs were written by Mr. Robinson. Funds for the computations were provided by the University of Wisconsin Chemistry Department.

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Bi-Variate, Rectangular, Optimum-Interval Interpolation

By Ferdinand Freudenstein

1. Definition of "Optimum-Interval" Interpolation. Let the real function f(x, y), defined in the interval $-h \le x \le h$, $-k \le y \le k$, h > 0, k > 0, and assumed to have continuous partial derivatives of order up to (m + n + 2) in the rectangle, be approximated by the polynomial

(1)
$$P_{mn}(x, y) = \sum_{r=0}^{m} \sum_{s=0}^{n} a_{rs} x^{r} y^{s}$$

so that at the (m + 1)(n + 1) precision points, (x_u, y_v) , $u = 0, 1, 2, \dots m$; $v = 0, 1, 2, \cdots n,$

(2)
$$P_{mn}(x_u, y_v) = f(x_u, y_v).$$

In that case,

(3)
$$f(x, y) = P_{mn}(x, y) + R_{mn}$$

where the remainder, R_{mn} , is given by the expression (see [1])

(4)
$$R_{mn} = \frac{1}{(m+1)!} \prod_{u=0}^{m} (x - x_u) \frac{\partial^{m+1} f(\xi, y)}{\partial \xi^{m+1}} + \frac{1}{(n+1)!} \prod_{v=0}^{n} (y - y_v) \frac{\partial^{n+1} f(x, \eta)}{\partial \eta^{n+1}} - \frac{1}{(m+1)!(n+1)!} \prod_{u=0}^{m} (x - x_u) \prod_{v=0}^{n} (y - y_v) \frac{\partial^{(m+1)+(n+1)} f(\xi' \eta')}{\partial \xi'^{m+1} \partial \eta'^{n+1}}$$

where ξ , $\xi'(\eta, \eta')$ lie between the greatest and least of the numbers x, $x_u(y, y_v)$.

Consider the set, S, of all precision points (x_u, y_v) within the rectangle (-h, h)(-k, k)—called (h, k) from now on. S will be called the spacing. Let $h = k\delta$, where δ is a positive number defining the proportions of the rectangle. Furthermore, we restrict ourselves to functions for which the partial derivatives $\frac{\partial^{m+1} f(x,y)}{\partial x^{m+1}}, \frac{\partial^{n+1} f(x,y)}{\partial y^{n+1}},$ $\frac{\partial^{(m+1)+(n+1)}f(x,y)}{\partial x^{m+1}\partial y^{n+1}}$ are not equal to zero within (h,k). Let R be the largest lower

limit on the maximum absolute value of R_{mn} regardless of spacing. It is assumed