Bounds for Eigenvalues of Some Differential Operators by the Rayleigh-Ritz Method

By Burton Wendroff

1. Introduction. In 1943 R. Courant [1] suggested a variation of the Rayleigh-Ritz method for eigenvalue problems. In the classical Rayleigh-Ritz method one finds the stationary values of the Rayleigh quotient J(u) as u varies over a finite-dimensional subspace of the space of admissible functions. The subspace usually consists of analytic functions, for example, polynomials. Courant's idea, in essence, is to use nonanalytic functions. For example, if the problem is

$$(1) y'' + \lambda y = 0,$$

$$(2) y(0) = y(1) = 0,$$

we divide the interval [0, 1] into n equal intervals of length h = 1/n, the subintervals being $[x_i, x_{i+1}]$, where $x_0 = 0$, $x_i = x_{i-1} + h$, for $i = 1, 2, \dots, n$. Now, let S be the class of functions which are continuous on [0, 1], linear on each subinterval and satisfy (2). Then if

$$\Lambda_1 = \min_{s} J(u) = \min_{s} \frac{\int_0^1 (u')^2 dx}{\int_0^1 (u^2) dx},$$

and if λ_1 is the lowest eigenvalue of (1) we have

$$\lambda_1 \leq \Lambda_1$$
.

In general, if λ_i are the eigenvalues of (1) arranged in increasing order and if Λ_i are the similarly arranged stationary values of J(u) as u varies over S, then

$$\lambda_i \leq \Lambda_i$$
.

The Λ_i are the eigenvalues of the finite-difference equation

$$u_{i+1}-2u_i+u_{i-1}+\Lambda\frac{h^2}{6}(u_{i+1}+4u_i+u_{i-1})=0, \qquad i=1,2,\cdots,n-1,$$

 $u_0=u_n=0.$

We shall show for two boundary-value problems that a *lower bound* for λ_i can be determined once Λ_i is known. This is done by finding positive numbers A and B such that

$$\Lambda_i \leq \frac{\lambda_i + A}{R},$$

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whence

$$B\Lambda_i - A \leq \lambda_i$$
.

This method of obtaining a lower bound has been used very effectively with a different definition of Λ_i by H. F. Weinberger [4] and B. E. Hubbard [3].

In the last part of the paper we indicate how one might obtain higher-order bounds.

2. The Sturm-Liouville Problem. The general Sturm-Liouville problem is

$$(vy')' + (\lambda p - q)y = 0,$$

(5)
$$a_1y'(0) - b_1y(0) = 0,$$

(6)
$$a_2y'(L) + b_2y(L) = 0,$$

with v and p positive, q non-negative on [0, L], and v piecewise continuously differentiable, p and q piecewise continuous on [0, L]. Also, $a_i \ge 0$, $b_i \ge 0$. We may assume without loss of generality that v(x) = 1, L = 1. This problem has positive eigenvalues $\lambda_1 < \lambda_2 < \cdots$ and corresponding eigenfunctions y_1, y_2, \cdots , normalized so that $\int_0^1 py_i^2 dx = 1$, which are continuously differentiable and have a continuous second derivative at each point of continuity of p and q.

It is well known that

(7)
$$\int_0^1 p y_i y_j dx = \delta_{ij}.$$

For any function f let

$$\langle f \rangle = f(1) - f(0).$$

Let a_1, \dots, a_s be real numbers such that $\sum_{i=1}^s a_i^2 = 1$. Let $y(x) = \sum_{i=1}^s a_i y_i(x)$. Then it is known that

(8)
$$\int_0^1 (y')^2 dx + \int_0^1 qy^2 dx - \langle y'y \rangle \leq \lambda_s$$

(see [3, equation 2.12]).

Note that $-\langle y'y\rangle$ is non-negative for any y(x) which satisfies (5) and (6).

Choose mesh points $0 = x_0 < x_1 < \cdots < x_n = 1$ such that any discontinuity of p or q coincides with some x_j , and let S_1 be the space of functions which are continuous on [0, 1], linear in each $[x_i, x_{i+1}]$, and satisfy (5) and (6). For any continuous and piecewise continuously differentiable function w(x) which satisfies the boundary conditions, let

$$N(w) = \int_0^1 (w')^2 dx - \langle ww' \rangle.$$

The Rayleigh quotient is

$$J(w) = \frac{N(w) + \int_0^1 qw^2 dx}{\int_0^1 pw^2 dx}.$$

Let $0 < \Lambda_1 < \Lambda_2 < \cdots < \Lambda_{n-1}$ be the stationary values of J(w) as w varies over S_1 . Then from the Courant maximum-minimum principle we have

(9)
$$\lambda_i \leq \Lambda_i, \quad i = 1, 2, \dots, n-1.$$

On the other hand, if w_1 , \cdots , w_i are any linearly independent functions in S_1 , and if $\sum_{i=1}^{n} a_i^2 = 1$ and $w(x) = \sum_{i=1}^{n} a_i w_i(x)$, then

(10)
$$\Lambda_s \leq \max_{a_1, \dots, a_s} J(w).$$

Weinberger calls this the Poincaré inequality, and it follows immediately from the minimum-maximum character of the Λ_i .

Now, let $Y_i(x)$ be that function in S_1 which agrees with the eigenfunction $y_i(x)$ at each interior x_i , i.e.,

$$Y_i(x_j) = y_i(x_j), \quad j = 1, 2, \dots, n-1, \quad i = 1, 2, \dots, n-1,$$

and let

$$Y(x) = \sum_{i=1}^{s} a_i Y_i(x).$$

We shall show later that if the intervals are sufficiently small the Y_i are linearly independent. Then from (10) we have

$$\Lambda_{\bullet} \leq \max_{\alpha, \dots, \alpha} J(Y).$$

Let

$$r(x) = y(x) - Y(x).$$

Then

(12)
$$r(x_j) = 0, \quad j = 1, 2, \dots, n-1,$$

and r satisfies (5) and (6). In addition, r(x) is twice continuously differentiable in each (x_i, x_{i+1}) , and r''(x) = y''(x). Let $G_i(x, \xi)$ be the Green's function for the differential operator d^2/dx^2 on the interval $[x_i, x_{i+1}]$, with boundary conditions (12) or (5) or (6), whichever applies. Then

(13)
$$r(x) = \int_{x_i}^{x_{j+1}} G_j(x,\xi) y''(\xi) d\xi, \quad x_j \leq x \leq x_{j+1},$$

Let us first consider the denominator of J(Y). We have

$$(14) Y^2 \ge y^2 - 2|y||r|,$$

and

$$\int_{x_{i}}^{x_{j+1}} p Y^{2} dx \ge \int_{x_{i}}^{x_{j+1}} p y^{2} dx - 2 \int_{x_{i}}^{x_{j+1}} p |y| |r| dr$$

Therefore,

(15)
$$\int_0^1 p Y^2 dx \ge 1 - 2\sqrt{p_M} \sum_{j=0}^{n-1} \int_{x_j}^{x_{j+1}} \sqrt{p} |y| |r| dx,$$

where, for any f(x),

$$f_M = \max_{[0,1]} f(x),$$

$$f_m = \min_{[0,1]} f(x).$$

By Schwartz' inequality,

$$\left(\int_{x_{j}}^{x_{j+1}} \sqrt{p} |y| |r| dx\right)^{2} \leq \int_{x_{j}}^{x_{j+1}} py^{2} dx \int_{x_{j}}^{x_{j+1}} r^{2} dx.$$

But, from (13),

(16)
$$r^{2}(x) \leq \int_{x_{j}}^{x_{j+1}} G_{j}^{2}(x,\xi) d\xi \int_{x_{j}}^{x_{j+1}} (y'')^{2} d\xi.$$

Put

$$G = \max_{j} \int_{x_{j}}^{x_{j+1}} \int_{x_{j}}^{x_{j+1}} G_{j}^{2}(x, \xi) dx d\xi.$$

Then

(17)
$$\int_{x_j}^{x_{j+1}} \sqrt{p} |y| |r| dx \leq \sqrt{G} \left[\int_{x_j}^{x_{j+1}} p y^2 dx \int_{x_j}^{x_{j+1}} (y'')^2 dx \right]^{1/2},$$

and

(18)
$$\sum_{j=0}^{n-1} \int_{x_j}^{x_{j+1}} \sqrt{p} |y| |r| dx \leq \sqrt{G} \left[\int_0^1 (y'')^2 dx \right]^{1/2}.$$

From the differential equation,

$$y'' = \sum_{i=1}^{s} a_i (q - \lambda_i p) y_i.$$

Then for any $\gamma > 0$,

$$\int_0^1 (y'')^2 dx \le (1 + \gamma) \frac{q_M^2}{p_m} + \left(1 + \frac{1}{\gamma}\right) p_M \Lambda_s^2.$$

Let

$$K_s = \text{g.l.b.} \left[(1 + \gamma) \frac{q_M^2}{p_m} + \left(1 + \frac{1}{\gamma}\right) p_M \Lambda_s^2 \right]^{1/2},$$

so that if $q_M = 0$, $K_s = \Lambda_s \sqrt{p_M}$, otherwise $\gamma = \Lambda_s \sqrt{(p_M p_m)/q_M}$. In any event, from (15), (18) we have

(19)
$$\int_{0}^{1} p Y^{2} dx \geq 1 - 2\sqrt{p_{M}} K_{s} \sqrt{G}.$$

The important thing to note at this point is that K_s and G depend only on the data. For example, if q(x) = 0, $a_1 = a_2 = 0$, then

(20)
$$\int_0^1 p Y^2 dx \ge 1 - \frac{2p_M \Lambda_s}{3\sqrt{10}} \max_j |x_{j+1} - x_j|^2.$$

The linear independence of the Y_i is implied by (19), for max $(x_{j+1} - x_j)$ sufficiently small.

By entirely similar methods we find

(21)
$$\int_0^1 q Y^2 dx \leq \int_0^1 q y^2 dx + \frac{2q_M}{\sqrt{p_m}} K_s \sqrt{G} + q_M G K_s^2.$$

We now show that

$$N(y) = N(Y) + N(r).$$

From the identity

$$-\int_{x_{j}}^{x_{j+1}} y''y \ dx = -\int_{x_{j}}^{x_{j+1}} (Y'' + r'')(Y + r) \ dx$$

follows the identity

$$y'y|_{j}^{j+1} + \int_{x_{j}}^{x_{j+1}} (y')^{2} dx = -y'Y|_{j}^{j+1} + rY'|_{j}^{j+1} - r'r|_{j}^{j+1} + \int_{x_{j}}^{x_{j+1}} (Y')^{2} dx + \int_{x_{j}}^{x_{j+1}} (r')^{2} dx.$$

Noting that y, y' and Y are continuous and $r(x_i) = 0$ we obtain, by summing the above,

$$N(y) = -\langle y'Y \rangle + \langle rY' \rangle + \int_0^1 (Y')^2 dx + N(r)$$

$$= -\langle y'Y \rangle + \langle yY' \rangle - \langle YY' \rangle + \int_0^1 (Y')^2 dx + N(r)$$

$$= N(Y) + N(r).$$

But $N(r) \ge 0$, so from (11), (8), (21) and (19), we obtain

(22)
$$\Lambda_s \leq \frac{\lambda_s + \frac{2q_M}{p_m} K_s \sqrt{G} + q_M K_s^2 G}{1 - 2\sqrt{p_M K_s \sqrt{G}}},$$

which is the desired result.

It should be noted that there would have been no terms other than λ_{\bullet} in the numerator of (22) if we could have composed S_1 of solutions of Y'' = qY rather than of Y'' = 0.

3. A Fourth-Order Problem. Certain fourth-order problems can be handled by the methods of Section 2. For example, consider the boundary-value problem

$$(23) (vy'')'' = \lambda py,$$

$$(24) y(0) = y(1) = y'(0) = y'(1) = 0,$$

which describes the fundamental modes of vibration of a clamped beam. The Rayleigh quotient is

$$J(w) = \frac{\int_0^1 (vw'')^2 dx}{\int_0^1 pw^2 dx}.$$

We define Λ_i to be the stationary values of J(w) as w varies over a class of functions which we call T_3 , which is composed of all functions which are continuously differentiable on [0, 1], satisfy (24), and which in each interval (x_{j+1}, x_j) satisfy (vw'')'' = 0. Any discontinuities of v and p must coincide with some x_j . The elements of T_3 have the following form: $w(x) \in T_3$ if and only if there exist real numbers w_j , w_j' , $j = 1, 2, \dots, n-1$, and constants a_j , b_j , c_j , d_j such that

$$w(x) = a_j \int_{x_j}^x \int_{x_j}^t \frac{s \, ds}{v(s)} + b_j \int_{x_j}^x \int_{x_j}^t \frac{ds}{v(s)} + c_j(x - x_j) + d_j,$$

for $x_j \leq x \leq x_{j+1}$, and $w(x_j) = w_j$, $w'(x_j) = w_j'$. J is stationary at some w(x) if

(25)
$$\frac{\partial J}{\partial w_j} = 0, \quad \frac{\partial J}{\partial w_{j'}} = 0, \quad j = 1, 2, \dots, n-1.$$

As before we have $\lambda_i \leq \Lambda_i$. To obtain an upper bound for Λ_i we let y_i be the normalized eigenfunctions of (23) and (24) and let Y_i be the element in T_3 such that

$$Y_{i}(x_{j}) = y_{i}(x_{j}), \ Y_{i}'(x_{j}) = y_{i}'(x_{i}),$$
 $j = 0, 1, \dots, n.$ Then for $Y = \sum_{i=1}^{s} a_{i}Y_{i}, \sum_{i=1}^{s} a_{i}^{2} = 1,$

$$\Lambda_{s} \leq \max_{a_{1}, \dots, a_{s}} J(Y).$$

If we replace $G_i(x, \xi)$ in (13) by the Green's function for the operator

$$\frac{d^2}{dx^2}\,v\,\frac{d^2}{dx^2}\,,$$

with boundary conditions $r(x_j) = r'(x_j) = 0, \quad j = 0, 1, \dots, n$, then

$$\int_0^1 p Y^2 dx \ge 1 - 2p_M \Lambda_s \sqrt{G}.$$

It is easily verified that

$$\int_{0}^{1} v(Y'')^{2} dx \leq \int_{0}^{1} v(y'')^{2} dx \leq \lambda_{s},$$

so

$$\Lambda_s \leq \frac{\lambda_s}{1 - 2n_u \Lambda_s \sqrt{G}}$$

An interesting special case occurs when v(x) is a step function. Then the elements of T_3 are cubic polynomials in each $[x_{j+1}, x_j]$, and

$$\Lambda_s \leq \frac{\lambda_s}{1 - \left(\frac{p_M}{v_m}\right) 4.05 \times 10^{-3} \max \left[x_{j+1} - x_j\right]^4}.$$

The matrix eigenvalue problem defining the λ_i can be found in [5], where it is assumed that both v and p are step functions and that the beam is simply supported. The matrices for the clamped beam are found by discarding the first and last intervals.

4. Higher-Order Bounds. To attempt to obtain higher-order bounds for the Sturm-Liouville problem, rather than use higher-order Lagrange interpolation, as is done in [2], we replace S_1 by the space S_{2k+1} , $k=1, 2, \cdots$, consisting of all functions satisfying (5) and (6) which are k times continuously differentiable on [0, 1] and which are polynomials of degree 2k + 1 in each $[x_{j+1}, x_j]$. If the eigenfunctions are sufficiently smooth, there will be functions $Y_i \in S_{2k+1}$ such that

$$Y_i^{(\alpha)}(x_j) = y_i^{(\alpha)}(x_j), \qquad \alpha = 0, 1, \dots, k.$$

With y = Y + r we have

$$r(x)^{(2k+2)} = y(x)^{(2k+2)}$$
.

with appropriate boundary conditions, so that there are Green's functions $G_j(x, \xi)$ such that

$$r(x) = \int_{x_i}^{x_{j+1}} G_j(x, \xi) y(\xi)^{(2k+2)} d\xi.$$

We proceed as before; however, estimating $\int_0^1 [y^{(2k+2)}]^2 dx$ will be quite difficult for k > 0 unless p(x) and q(x) are step functions, in which case we would have $y_i^{(2k+2)} = (q - \lambda_i p)^{k+1} y_i$, from which estimates can be made.

For the numerator of the Rayleigh quotient we no longer have $N(Y) \leq N(y)$, but

$$\begin{split} N(Y) \, & \leq \, N(y) \, + \, 2 \, \int_0^1 \, | \, \, Y''r \, | \, \, dx \\ \\ & \leq \, N(y) \, + \, 2 \, \int_0^1 \, | \, \, y''r \, | \, \, dx \, + \, 2 \, \, \int_0^1 \, | \, \, r''r \, | \, \, dx, \end{split}$$

which can be estimated if r can.

For the fourth-order problem we could use spaces T_{2k+1} consisting of functions satisfying the boundary conditions such that, in each subinterval,

$$(vw'')'' = \sum_{i=0}^{2k-3} a_i x^i,$$

where the 2k-2 constants a_0 , \cdots , a_{2k-3} and the four constants of integration are determined by the condition that $w^{(\alpha)}$ be continuous for $\alpha=0$, 1, k. We have not obtained any bounds using T_{2k+1} .

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