# On an Accelerated Overrelaxation Iterative Method for Linear Systems With Strictly Diagonally Dominant Matrix 

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#### Abstract

We consider a linear system $A x=b$ of $n$ simultaneous equations, where $A$ is a strictly diagonally dominant matrix. We get bounds for the spectral radius of the matrix $L_{r, \omega}$, which is accociated with the Accelerated Overrelaxation iterative method (AOR).


Sufficient conditions for the convergence of that method will be given, which improve the results of Theorem 3, Section 4 of [2], applied to this type of matrices.

1. Introduction. We want the solution $x$ of a linear system

$$
\begin{equation*}
A x=b \tag{1.1}
\end{equation*}
$$

where $A$ is an $(n, n)$ real-matrix and $x$ and $b$ are $n$-real-vectors. We assume $A$ is strictly diagonally dominant. There are several important iterative methods for the approximation of (1.1). We will take the (AOR) of [1]. For that, the matrix is expressed as the matrix sum

$$
\begin{equation*}
A=I-E-F \tag{1.2}
\end{equation*}
$$

where $I$ is the identity and $E$ and $F$ are respectively strictly lower and upper triangular $(n, n)$ matrices.

From the (AOR) method we can write the following equations:

$$
\begin{align*}
& x^{(i+1)}=(I-r E)^{-1}[(1-\omega) I+(\omega-r) E+\omega F] x^{(i)}+\omega(I-r E)^{-1} b  \tag{1.3}\\
& i=0,1,2, \ldots
\end{align*}
$$

So, $L_{r, \omega}$ will be the point-(AOR)-matrix associated with the matrix $A$,

$$
\begin{equation*}
L_{r, \omega}=(I-r E)^{-1}[(1-\omega) I+(\omega-r) E+\omega F] \tag{1.4}
\end{equation*}
$$

and $\rho\left(L_{r, \omega}\right)$ the corresponding spectral radius.
2. Bounds for $\rho\left(L_{r, \omega}\right)$. As we assume $A$ strictly diagonally dominant, $A$ is nonsingular and verifies

$$
\begin{equation*}
\left|a_{i i}\right|>\sum_{j=1 ; i \neq j}^{n}\left|a_{i j}\right|, \quad i=1,2, \ldots, n \tag{2.1}
\end{equation*}
$$

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Bounds for $\rho\left(L_{r, \omega}\right)$ are obtained from

Theorem 1. If $A$ of (1.1) is a strictly diagonally dominant matrix, then $\rho\left(L_{r, \omega}\right)$ satisfies the following:

$$
\begin{gather*}
\min _{i} \frac{|1-\omega|-|\omega-r| e_{i}-|\omega| f_{i}}{1+|r| e_{i}} \leqslant \rho\left(L_{r, \omega}\right) \leqslant \max _{i} \frac{|\omega-r| e_{i}+|\omega| f_{i}+|1-\omega|}{1-|r| e_{i}},  \tag{2.2}\\
i=1,2, \ldots, n,
\end{gather*}
$$

where $|r|<1 / e_{i}$ and $e_{i}$, $f_{i}$ are respectively the $i$-row sums of the moduli of the entries of $E$ and $F$, respectively.

Proof. Since the eigenvalues of $L_{r, \omega}$ are given from

$$
\begin{equation*}
\operatorname{det}\left(L_{r, \omega}-\lambda I\right)=0 \tag{2.3}
\end{equation*}
$$

after some manipulations, it is easy to verify that to solve (2.3) is equivalent to solving

$$
\begin{equation*}
\operatorname{det} Q=0 \text {, } \tag{2.4}
\end{equation*}
$$

where $Q$ is

$$
Q=I-\frac{r(\lambda-1)+\omega}{\lambda-1+\omega} E-\frac{\omega}{\lambda-1+\omega} F .
$$

If we take the parameter $r, \omega, \lambda$, in order that $Q$ be strictly diagonally dominant, we get

$$
\begin{equation*}
|\lambda-1+\omega|>|\omega+(\lambda-1) r| e_{i}+|\omega| f_{i}, \quad i=1, \ldots, n . \tag{2.5}
\end{equation*}
$$

Then, the values of $\lambda$ satisfying (2.5) will not satisfy (2.4) and cannot be eigenvalues of (2.3). From (2.5), as $\lambda$ can take any value, we have

$$
|\lambda|-|1-\omega|>|\omega-r| e_{i}+|\lambda r| e_{i}+|\omega| f_{i}, \quad i=1, \ldots, n,
$$

or

$$
|\lambda|\left(1-|r| e_{i}\right)>|\omega-r| e_{i}+|\omega| f_{i}+|1-\omega|, \quad i=1, \ldots, n .
$$

Assuming $|r|<1 / e_{i}$, we have

$$
|\lambda|>\max _{i} \frac{|\omega-r| e_{i}+|\omega| f_{i}+|1-\omega|}{1-|r| e_{i}}
$$

If $\lambda$ satisfies this inequality, it cannot be an eigenvalue of $L_{r, \omega}$, and then

$$
\rho\left(L_{r, \omega}\right) \leqslant \max _{i} \frac{|\omega-r| e_{i}+|\omega| f_{i}+|1-\omega|}{1-|r| e_{i}} \quad \text { for }|r|<\frac{1}{e_{i}} .
$$

In order to get the lower bound, from (2.5) we write

$$
|1-\omega|-|\lambda|>|\omega-r| e_{i}+|\lambda r| e_{i}+|\omega| f_{i}, \quad i=1,2, \ldots, n,
$$

and

$$
|\lambda|<\min _{i} \frac{|1-\omega|-|\omega-r| e_{i}-|\omega| f_{i}}{1+|r| e_{i}}
$$

Since the values of $\lambda$ satisfying this inequality are not eigenvalues of $L_{r, \omega}$, then

$$
\rho\left(L_{r, \omega}\right) \geqslant \min _{i} \frac{|1-\omega|-|\omega-r| e_{i}-|\omega| f_{i}}{1+|r| e_{i}}, \quad i=1, \ldots, n \text {. Q.E.D. }
$$

As it is well known, for convenient values of $r$ and $\omega$, the (AOR) method becomes the well-known iterative methods:

$$
\begin{array}{ll}
r=0, \omega=1 & \\
r=1, \omega=1 & \\
\text { Jacobi Method, } \\
r=0, \omega & \\
r=\omega & \\
\text { Simultaneous Overrelaxation Method, } \\
r=\omega & \text { Successive Overrelaxation Method. }
\end{array}
$$

Taking these values, we get from (2.2) the known results

$$
\begin{align*}
& \rho\left(L_{0,1}\right) \leqslant \max _{i}\left(e_{i}+f_{i}\right),  \tag{2.6a}\\
& \rho\left(L_{1,1}\right) \leqslant \max _{i} \frac{f_{i}}{1-e_{i}},  \tag{2.6b}\\
& \rho\left(L_{0, \omega}\right) \leqslant \max _{i}|\omega|\left(e_{i}+f_{i}\right)+|1-\omega|,  \tag{2.6c}\\
& \rho\left(L_{\omega, \omega}\right) \leqslant \max _{i} \frac{|\omega| f_{i}+|1-\omega|}{1-|\omega| e_{i}} . \tag{2.6d}
\end{align*}
$$

## 3. Convergence of the (AOR) Method.

Theorem 2. If $A$ of (1.1) is a strictly diagonally dominant matrix and $\omega \geqslant r \geqslant 0$, then a sufficient condition for the convergence of the (AOR) method is

$$
0<\omega<\frac{2}{1+\max _{i}\left(e_{i}+f_{i}\right)}
$$

Proof. From [1, Section 3], with $A$ strictly diagonally dominant, the (AOR) method is convergent if $0<\omega \leqslant 1,0 \leqslant r \leqslant 1$. From (2.2) we see that $\rho\left(L_{r, \omega}\right)$ will be less than 1 if

$$
\begin{equation*}
|\omega-r| e_{i}+|\omega| f_{i}+|1-\omega|+|r| e_{i}<1, \quad i=1, \ldots, n . \tag{3.1}
\end{equation*}
$$

With $\omega>r \geqslant 0$ these conditions will be fulfilled.
Taking $f(\delta)=(\delta-r) e_{i}+\delta f_{i}+(1-\delta)+r e_{i}$, we see that $f(\delta)$ is a nonincreasing function of $\delta$ if $0 \leqslant \delta \leqslant 1$ and $f(0)=1, f(1)=e_{i}+f_{i}<1$. With $\delta>1, f(\delta)$ is an increasing function with $f(\delta)=1$ for $\delta=2 /\left(1+e_{i}+f_{i}\right)$. Then $\rho\left(L_{r . \omega}\right)<1$ if

$$
0<\omega<\frac{2}{1+\max _{i}\left(e_{i}+f_{i}\right)}
$$

and the (AOR) method will be convergent. Q.E.D.

Let us consider a first-degree linear stationary iterative method

$$
\begin{equation*}
x^{(i+1)}=G x^{(i)}+\left.d\right|_{i=0,1,2, \ldots} \tag{3.2}
\end{equation*}
$$

with $G$ a known $n \times n$ matrix, $d$ a known $n$-vector, and $x^{(0)}$ an arbitrary initial approximation for the solution $x$.

The following method

$$
\begin{equation*}
x^{(i+1)}=[(1-\omega) I+\omega G] x^{(i)}+\left.\omega d\right|_{i=0,1,2, \ldots} \tag{3.3}
\end{equation*}
$$

will be called the extrapolated method of (3.2).
We recall now, the Theorem of Extrapolation [2, p. 2], as we need it in the sequel.

Theorem 3 (Theorem of Extrapolation). The sufficient conditions for the convergence of (3.3) are:
(1) The original (3.2) is convergent,
(2) $0<\omega<2 /(1+\rho(G))$.

Setting $r=0$ in (1.3), we obtain

$$
x^{(i+1)}=[(1-\omega) I+\omega(E+F)] x^{(i)}+\left.\omega b\right|_{i=0,1,2, \ldots}
$$

This is the extrapolated Jacobi method, where $\omega$ is the extrapolation parameter.
After some computation, it is easy to verify that (1.3) is the extrapolated SOR method, when $r \neq 0$ and its extrapolation parameter is $\omega / r$.

Theorem 4. If $A$ from (1.1) is strictly diagonally dominant, then $\rho\left(L_{0, \omega}\right)<1$ provided $0<\omega<2 /\left(1+\rho\left(L_{0,1}\right)\right)$.

Proof. Bearing in mind that $A$ strictly diagonally dominant implies $\rho\left(L_{0,1}\right)<1$ [4, p. 73], it is an immediate consequence of Theorem 3.

Theorem 5. If $A$ of (1.1) is strictly diagonally dominant, then $\rho\left(L_{r}, \omega\right)<1$ with $0<r \leqslant 1$ provided $0<\omega<2 r /\left(1+\rho\left(L_{r, r}\right)\right)$.

Proof. From (2.6d) we easily deduce that the SOR method will converge with $0<r \leqslant 1$ ( $A$ is strictly diagonally dominant).

Then, by the Theorem of Extrapolation, the AOR method will converge for $0<r \leqslant 1$ and $0<\omega<2 r /\left(1+\rho\left(L_{r, r}\right)\right)$.

Theorem 6. The AOR method is convergent, i.e. $\rho\left(L_{r, \omega}\right)<1$, for:
(i) $0 \leqslant r \leqslant \omega$ and $0<\omega<2 /\left(1+\max _{i}\left(e_{i}+f_{i}\right)\right)$ if

$$
\frac{2 r}{1+\rho\left(L_{r, r}\right)} \leqslant \frac{2}{1+\max _{i}\left(e_{i}+f_{i}\right)}
$$

(ii) $0<r \leqslant 1$ and $0<\omega<2 r /\left(1+\rho\left(L_{r, r}\right)\right)$ or $1<r<\omega$ and $0<\omega<$ $2 /\left(1+\max _{i}\left(e_{i}+f_{i}\right)\right)$ if

$$
\frac{2 r}{1+\rho\left(L_{r, r}\right)}>\frac{2}{1+\max _{i}\left(e_{i}+f_{i}\right)}
$$

Proof. These results come from Theorems 2 and 5. They improve the results of Theorem 3, Section 4 of [2], when the matrix $A$ of (1.1) is strictly diagonally dominant:

$$
\rho\left(L_{r, \omega}\right)<1 \quad \text { if } 0 \leqslant r<1 \quad \text { and } \quad 0<\omega \leqslant \max \left\{1, \frac{2 r}{1+\rho\left(L_{r, r}\right)}\right\} .
$$

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