

## MONOTONIC SUBSEQUENCES

JOSEPH B. KRUSKAL, JR.

1. **Introduction.** Hidden in a paper by Erdős and Szekeres<sup>1</sup> is an intriguing result.

**BASIC THEOREM.** *Every sequence  $S = \{x_i\}$  ( $i=1$  to  $n^2+1$ ) of real numbers having  $(n^2+1)$  terms possesses a (perhaps not strictly) monotonic subsequence  $M = \{x_{i_j}\}$  ( $j=1$  to  $n+1$ ) having  $(n+1)$  terms. Furthermore  $(n^2+1)$  is the smallest number for which this is true.*

Briefly, this theorem states that a monotonic subsequence of any desired length can be picked out from a sufficiently long sequence, and gives the precise lengths. An elegant proof of this theorem (unpublished) which is due to Martin D. Kruskal is sketched here.

**NOTATION.** Let  $S$  and  $T$  denote sequences, and let  $M$  and  $N$  denote monotonic sequences. Let  $S(p)$ , etc., denote a sequence having  $p$  terms. Let  $\psi(n)$  denote the least integer  $p$  such that every  $S(p)$  contains an  $M(n)$ . In this notation we may restate the basic theorem thus:

**BASIC THEOREM.** *For sequences of real numbers,  $\psi(n+1) = n^2+1$ .*

To show that  $\psi(n+1) \geq n^2+1$ , it is sufficient to exhibit an  $S(n^2)$  which contains no  $M(n+1)$ . Such a sequence is the following:

$$n, \dots, 1, 2n, \dots, n+1, \dots, n^2, \dots, n^2 - n + 1.$$

To show that  $\psi(n+1) \leq n^2+1$ , assume the contrary and let  $n$  be the least integer such that  $\psi(n+1) > n^2+1$ . Let  $S(n^2+1)$  be a sequence which does not contain any  $M(n+1)$ . Now define a *majorant* (*minorant*) of  $S$  to be a term which is strictly greater (smaller) than all terms following it in  $S$ . The majorants (minorants) form a decreasing (increasing) subsequence of  $S$ ; hence there are at most  $n$  majorants and  $n$  minorants. As the final term of  $S$  is necessarily both a majorant and a minorant, there are at most  $(2n-1)$  *extremants* (majorants and minorants). The last term of every  $M(n)$  contained in  $S$  must be an extremant. Now delete from  $S$  all its extremants. The remainder  $S'$  can contain no  $M(n)$ , yet has at least  $[(n^2+1) - (2n-1)] = [(n-1)^2 + 1]$  terms. Hence  $\psi(n) \equiv \psi(n-1+1) > (n-1)^2+1$ . This contradicts the definition of  $n$  and completes the proof.

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<sup>1</sup> P. Erdős and G. Szekeres, *A combinatorial theorem in geometry*, *Compositio Mathematica* vol. 2 (1935) p. 463. See the theorem on p. 467.

**2. First generalization—real vector spaces.** In the following two sections the concept of a monotonic sequence is generalized to sequences of vectors from a finite-dimensional real vector space and a partial analogue of the Basic Theorem is obtained. (If  $S = \{x_i\}$  is a sequence from a vector space, the subscript still distinguishes terms of the sequence, *not* components of a vector.)

Note that a sequence  $S = \{x_i\}$  of real numbers is monotonic if and only if all the differences  $(x_{i+1} - x_i)$  lie (perhaps not strictly) to the same side of 0 on the real line. This motivates:

**DEFINITION.** A sequence  $S = \{x_i\}$  of terms from a finite-dimensional real vector space is monotonic if there is a hyperplane  $H$  through the origin such that the differences  $d_i \equiv x_{i+1} - x_i$  all lie in one of the closed half-spaces determined by  $H$ .

This definition is further justified by:

**LEMMA 1.** *A sequence  $S$  of vectors is monotonic if and only if there is a directed line  $L$  such that the perpendicular projections of the  $x_i$  on  $L$  form an increasing sequence.*

This lemma is easily proved by taking  $L$  and  $H$  to be perpendicular.

The direction of any such line  $L$  is called a direction of monotonicity of  $S$ . In 1-space there are only two possible directions of monotonicity: increasing and decreasing. In  $r$ -space the possible directions of monotonicity correspond to the points on the  $(r-1)$ -sphere.

Any sequence of two real numbers is monotonic. This generalizes to:

**LEMMA 2.** *In  $r$ -space any sequence of  $(r+1)$  terms is monotonic.*

This can easily be proved geometrically.

**NOTATION.** For convenience, let the function  $\psi(n)$  which applies in  $r$ -space be indicated by  $\psi_r(n)$ .

**LEMMA 3.** (a) *If  $S(n^2+1) = \{x_i\}$  is any sequence of  $(n^2+1)$  terms in  $r$ -space and  $L$  is any directed line in  $r$ -space, then  $S$  contains either a subsequence monotonic in the direction of  $L$  or a subsequence monotonic in the direction opposite to  $L$ .* (b)  $\psi_r(n+1) \leq n^2+1$ .

**PROOF.** (a) follows easily from Lemma 1 and the Basic Theorem; (b) follows from (a). But (a) is much stronger than (b) because (a) says "for any  $L \dots$ " while (b) says implicitly "there exists an  $L$  such that. . . ." This suggests that actually  $\psi_r(n+1)$  is smaller than  $(n^2+1)$  in general.

What is the full generalization of the Basic Theorem to  $r$ -space? In other words, what is the function  $\psi_r(n)$ ?

CONJECTURE.  $\psi_r(n+r) = rn + (n^2 - n + 1)$ .

This conjecture is based solely on the following collection of facts.

BASIC THEOREM.  $\psi_1(n+1) = n + (n^2 - n + 1)$ .

LEMMA 2 (*New Form*).  $\psi_r(1+r) = r + (1 - 1 + 1)$ .

THEOREM 1.  $\psi_r(2+r) \leq 2r + 3 \equiv 2r + (4 - 2 + 1)$ .

LEMMA 4. For  $r=1$  and 2, the  $\leq$  of Theorem 1 becomes  $=$ .

The proof of Theorem 1 is long and occupies the next section. For  $r=1$ , Lemma 4 is trivial. To prove Lemma 4 for  $r=2$ , it is sufficient to exhibit a sequence of 6 vectors from 2-space which contains no monotonic subsequence of 4 terms. That the following is such a sequence may be verified directly:

$$(2, -1), (3, 6), (-3, 12), (-3, -12), (3, -6), (2, 1).$$

**3. Proof of Theorem 1.** The basic tool in proving Theorem 1 is

LEMMA 5. If  $S(p) = \{x_i\}$  is a sequence in  $r$ -space, then at least one of the following conditions is true:

- (a)  $S$  is monotonic;
- (b) there exist real numbers  $\alpha_i > 0$  ( $i=1, \dots, p-1$ ) such that  $\sum \alpha_i d_i = 0$ , where  $d_i \equiv x_{i+1} - x_i$ .

PROOF. It is sufficient to show that the falsity of (b) implies (a). Thus assume that 0 does not belong to the convex cone  $C \equiv \{\sum \alpha_i d_i \mid \text{all } \alpha_i > 0\}$ . Then a well known theorem about convex sets yields that there is a hyperplane  $H$  through 0 such that  $\bar{C}$  (the topological closure of  $C$ ) lies entirely in one of the closed half-spaces determined by  $H$ . Since  $d_i$  is in  $\bar{C}$  for all  $i$ ,  $S(p)$  is monotonic, and the proof is complete.

COMMENT. It is possible to modify (b) into a necessary and sufficient condition for non-monotonicity. This condition might be useful in further investigation of the function  $\psi_r(n)$ .

Lemma 6 follows from Lemma 5.

LEMMA 6. Let

$$S(p) = \{x_i\}$$

be any sequence in  $r$ -space, and let

$$S'(q) = \{x_{s_i}\}$$

be a non-monotonic subsequence of it (of course  $1 \leq s_1 < s_2 < \dots < s_q \leq p$ ). Then there exists a  $(p-1)$ -tuple of real numbers  $g = \{\gamma_i\}$  such

that  $\sum \gamma_s d_s = 0$  where  $g$  satisfies the following "suitability conditions with respect to  $(s_1, \dots, s_q)$ ":

$$\begin{cases} \gamma_1 = \dots = \gamma_{s_1-1} = 0, \\ \gamma_{s_1} = \dots = \gamma_{s_2-1} > 0, \\ \dots \dots \dots \dots \dots \dots, \\ \gamma_{s_{q-1}} = \dots = \gamma_{s_q-1} > 0, \\ \gamma_{s_q} = \dots = \gamma_{p-1} = 0. \end{cases}$$

PROOF. By Lemma 5 there exist strictly positive  $\alpha_i$  ( $i=1, \dots, q-1$ ) such that

$$\sum_1^{q-1} \alpha_i [x_{s_{i+1}} - x_{s_i}] = 0.$$

Hence

$$\sum_1^{q-1} \alpha_i \left[ \sum_{s_i}^{s_{i+1}-1} d_j \right] = 0.$$

Now define  $g = \{\gamma_s\}$  as follows:

$$\begin{cases} \gamma_1 = \dots = \gamma_{s_1-1} = 0, \\ \gamma_{s_1} = \dots = \gamma_{s_2-1} = \alpha_1 > 0, \\ \dots \dots \dots \dots \dots \dots, \\ \gamma_{s_{q-1}} = \dots = \gamma_{s_q-1} = \alpha_{q-1} > 0, \\ \gamma_{s_q} = \dots = \gamma_{p-1} = 0. \end{cases}$$

Clearly  $\sum \gamma_s d_s = 0$ , and the proof is complete.

The structure of the  $(p-1)$ -tuple  $g = (\gamma_1, \dots, \gamma_{p-1})$  can be represented by a  $q$ -block diagram. This is obtained by substituting in  $g$  an "X" for each nonzero  $\gamma$ , and "o" for each zero  $\gamma$ , and an "=" for each comma between two  $\gamma$ 's of one "block" of equal nonzero  $\gamma$ 's. A  $g$  which is suitable with respect to  $(3, 5, 6, 9)$  and which has 10 components is represented by the following 10-dimensional 4-block diagram: (o, o, X=X, X, X=X=X, o, o). Block diagrams will be used extensively in the following arguments.

At this point it becomes necessary to consider the vectors of the fundamental  $r$ -space as  $r$ -tuples of real numbers. We shall write these  $r$ -tuples vertically and call them column vectors. We adopt the specific notation  $d_s$  = the column vector  $(\delta_s^t)$  as  $t=1, \dots, r$ , where  $d_s$  has its usual significance. The sequence  $\{d_s\}$ , with  $s=1$  to

$p-1$ , now becomes a matrix  $D = \|\delta_s^t\|$  in which  $t=1$  to  $r$  is the row index and  $s=1$  to  $p-1$  is the column index. We shall let  $d^t$  ( $t=1, \dots, r$ ) represent the rows of  $D$ .

We now put Lemma 6 into the proper form for actual use:

**LEMMA 7.** *If  $S(p) = \{x_s\}$  is a sequence in  $r$ -space, which does not contain any  $M(q)$ , then for each  $(p-1)$ -dimensional  $q$ -block diagram there exists a  $(p-1)$ -dimensional row vector  $g$  such that  $g$  is perpendicular to all the  $d^t$  ( $t=1, \dots, r$ ) and such that  $g$  has the structure of the given  $q$ -block diagram.*

**PROOF.** The  $q$ -block diagram corresponds to a subsequence  $S'(q) = \{x_{s_i}\}$  of  $S$ . Apply Lemma 6 to  $S'(q)$  and rewrite the equation  $\sum \gamma_s d_s = 0$  as  $r$  equations  $\sum \gamma_s \delta_s^t = 0$ . These may be written  $g \cdot d^t = 0$  or " $g$  is perpendicular to  $d^t$ ." This completes the proof.

The last tool needed to prove Theorem 1 is

**LEMMA 8.** *If  $S(p) = \{x_s\}$  is not monotonic, the vectors  $d^t$  ( $t=1$  to  $r$ ) are linearly independent.*

**PROOF.** As  $S$  is not monotonic, the  $d_s$  do not all lie on a common hyperplane through the origin, hence span the whole ( $r$ -dimensional) space of column vectors. Thus  $D$  has column-rank  $r$ , hence row-rank  $r$ , which completes the proof.

Theorem 1 is proved indirectly. Assume contrary to the theorem that  $S(2r+3) = \{x_s\}$  contains no  $M(r+2)$ .

By Lemma 8, the  $r$   $(2r+2)$ -dimensional row vectors  $d^t$  are linearly independent. Now apply Lemma 7 to the following  $(r+2)$  different  $(2r+2)$ -dimensional  $(r+2)$ -block diagrams, and label the resulting  $g$ 's as shown:

	1	2	$\dots$	$r+1$	$r+2$	$r+3$	$\dots$	$2r+2$
$g(1)$	(X, X, $\dots$ , X,	o,	o,	$\dots$ , o)				
$g(2)$	(o, X, $\dots$ , X,	X,	o,	$\dots$ , o)				
$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$	$\dots$
$g(r+2)$	(o, o, $\dots$ , o,	X,	X,	$\dots$ , X).				

These  $g$ 's are called the fundamental  $g$ 's. Obviously the  $(r+2)$  fundamental  $g$ 's are linearly independent. By Lemma 7 every fundamental  $g$  is perpendicular to every  $d^t$ . Therefore  $[g(1), \dots, g(r+2), d^1, \dots, d^r]$  is a basis for the  $(2r+2)$ -space of row vectors. From this follows

**LEMMA 9.** *Every  $g$  arising from application of Lemma 7 is a linear*

combination of the fundamental  $g$ 's.

At this point the proof of Theorem 1 splits into two cases, depending on whether  $r$  is odd or even; the former case is simpler and will be considered first.

Assume  $r$  is odd. Apply Lemma 7 to the following  $(r+1)$  different  $(2r+2)$ -dimensional  $(r+2)$ -block diagrams and label the resulting  $g$ 's as shown:

	1	2	$\cdots$	$r$	$r+1$	$r+2$	$r+3$	$r+4$	$\cdots$	$2r+2$
$\bar{g}(1)$	$(X, X, \cdots, X, X = X, o, o, \cdots, o)$									
$\bar{g}(2)$	$(o, X, \cdots, X, X = X, X, o, \cdots, o)$									
$\cdots$	$\cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots$									
$\bar{g}(r+1)$	$(o, o, \cdots, o, X = X, X, X, \cdots, X).$									

With the aid of Lemma 9 it is easy to see that

$$\bar{g}(k) = \zeta(k)g(k) + \eta(k)g(k+1)$$

for properly chosen  $\zeta(k) > 0$  and  $\eta(k) > 0$ . Introducing an obvious notation for the components of the  $g$ 's and the  $\bar{g}$ 's, we have

$$\begin{aligned}\bar{\gamma}_{r+1}(k) &= \zeta(k)\gamma_{r+1}(k) + \eta(k)\gamma_{r+1}(k+1) \\ &= \bar{\gamma}_{r+2}(k) = \zeta(k)\gamma_{r+2}(k) + \eta(k)\gamma_{r+2}(k+1),\end{aligned}$$

which yields that

$$[\gamma_{r+1}(k) - \gamma_{r+2}(k)] = -\epsilon(k)[\gamma_{r+1}(k+1) - \gamma_{r+2}(k+1)]$$

where  $\epsilon(k)$  is a positive constant. Now

$$\gamma_{r+1}(1) - \gamma_{r+2}(1) > 0$$

because the first term is positive and the second term is 0. The preceding equation now yields successively

$$\gamma_{r+1}(2) - \gamma_{r+2}(2) < 0, \quad \gamma_{r+1}(3) - \gamma_{r+2}(3) > 0,$$

and so forth. Since  $r$  is odd, we obtain

$$\gamma_{r+1}(r+2) - \gamma_{r+2}(r+2) \equiv -\gamma_{r+2}(r+2) > 0$$

which is false. This completes the proof of Theorem 1 for odd values of  $r$ .

Now assume that  $r$  is even. The following notation is introduced for convenience:

$$\beta(k) \equiv \gamma_{r+1}(k) - \gamma_{r+2}(k), \quad \beta'(k) \equiv \gamma_{r+1}(k) - \gamma_{r+3}(k).$$

Using the same method as in the preceding paragraph, the following inequalities are established (but without contradiction here):

$$\begin{aligned}\beta(k) &> 0 && \text{if } k \text{ is odd;} \\ \beta(k) &< 0 && \text{if } k \text{ is even.}\end{aligned}$$

Now apply Lemma 7 to the following block diagrams and label the resulting  $g$ 's as shown:

	1	2	...	$r$	$r+1$	$r+2$	$r+3$	$r+4$	$r+5$	...	$2r+2$
$\tilde{g}(1)$	$(X, X, \dots, X,$				$X=X=X,$			$o,$	$o,$	$\dots, o)$	
$\tilde{g}(2)$	$(o, X, \dots, X,$				$X=X=X,$			$X,$	$o,$	$\dots, o)$	
$\dots$	$\dots \dots \dots \dots \dots \dots \dots \dots \dots \dots \dots$										
$\tilde{g}(r)$	$(o, o, \dots, X,$				$X=X=X,$			$X,$	$X,$	$\dots, X).$	

With the aid of Lemma 9 and the established inequalities for  $\beta(k)$ , it is not difficult to show that

$$\tilde{g}(k) = \zeta(k)g(k) + \eta(k)g(k+1) + \theta(k)g(k+2)$$

where  $\zeta(k)$ ,  $\eta(k)$ , and  $\theta(k)$  are positive constants. Translating these vector equations into component equations, and using the equalities among the components of the  $\tilde{g}$ 's, we have

$$\begin{aligned}\tilde{\gamma}_{r+1}(k) &= \zeta(k)\gamma_{r+1}(k) + \eta(k)\gamma_{r+1}(k+1) + \theta(k)\gamma_{r+1}(k+2) \\ &= \tilde{\gamma}_{r+2}(k) = \zeta(k)\gamma_{r+2}(k) + \eta(k)\gamma_{r+2}(k+1) + \theta(k)\gamma_{r+2}(k+2) \\ &= \tilde{\gamma}_{r+3}(k) = \zeta(k)\gamma_{r+3}(k) + \eta(k)\gamma_{r+3}(k+1) + \theta(k)\gamma_{r+3}(k+2).\end{aligned}$$

Subtract the second equation from the first, and then the third from the first:

$$\begin{aligned}0 &= \zeta(k)\beta(k) + \eta(k)\beta(k+1) + \theta(k)\beta(k+2), \\ 0 &= \zeta(k)\beta'(k) + \eta(k)\beta'(k+1) + \theta(k)\beta'(k+2).\end{aligned}$$

From these equations it follows that

$$\begin{aligned}\zeta(k) &= \epsilon(k) \begin{vmatrix} \beta(k+1) & \beta(k+2) \\ \beta'(k+1) & \beta'(k+2) \end{vmatrix}, \\ \eta(k) &= \epsilon(k) \begin{vmatrix} \beta(k+2) & \beta(k) \\ \beta'(k+2) & \beta'(k) \end{vmatrix}, \\ \theta(k) &= \epsilon(k) \begin{vmatrix} \beta(k) & \beta(k+1) \\ \beta'(k) & \beta'(k+1) \end{vmatrix}\end{aligned}$$

where  $\epsilon(k)$  is a properly chosen constant of proportionality.

Call the three determinants  $Z(k)$ ,  $H(k)$ , and  $\Theta(k)$  respectively. Since  $\zeta(k)$ ,  $\eta(k)$ , and  $\theta(k)$  are all positive,  $Z(k)$ ,  $H(k)$ , and  $\Theta(k)$  must all have the same sign as  $\epsilon(k)$ . Furthermore, as  $Z(k) \equiv \Theta(k+1)$ , all the determinants have the same sign for all  $k$  (from 1 to  $r$ ). To evaluate the sign of  $\Theta(1)$  we use the already established inequalities for the  $\beta$ 's and find the sign of the  $\beta$ 's from direct examination of the block diagrams of the  $g$ 's. We see that

$$\Theta(1) = \begin{vmatrix} + & - \\ + & + \end{vmatrix} > 0,$$

so that all the determinants are positive.

Similarly, we find that

$$Z(1) = \begin{vmatrix} - & + \\ + & ? \end{vmatrix}.$$

For this to be positive, "?" must be "-", so that  $\beta'(3) < 0$ . Using this result we see that

$$Z(2) = \begin{vmatrix} + & - \\ - & ? \end{vmatrix}.$$

For this to be positive, "?" must be "+," so that  $\beta'(4) > 0$ . Similarly,  $\beta'(5) < 0$ ,  $\beta'(6) > 0$ , and so forth. Since  $r$  is even,  $\beta'(r+2) > 0$ ; however, direct examination of the block diagram shows that  $\beta'(r+2) < 0$ . This contradiction completes the proof of Theorem 1 for even values of  $r$ , and hence the whole proof.

**4. Second generalization—relation spaces.** In the following sections we again generalize the Basic Theorem, but in a manner quite different from that of the preceding sections.

The Basic Theorem is not in essence a statement about the real number system. To see this, consider any set  $X$  with an arbitrary binary relation  $\subset$  over it. (No assumptions are made about  $\subset$ ; for example, it need not be transitive.) Let us say that  $S = \{x_i\}$  is  $\subset$ -monotonic ( $\subset$ -monotonic) if  $x_i \subset x_{i+1}$  ( $x_i \not\subset x_{i+1}$ ) for all  $i$ . Call  $S$  monotonic if it is either  $\subset$ -monotonic or  $\not\subset$ -monotonic. Then for sequences over  $X$  it is still true that  $\psi(n+1) \leq n^2+1$ , and for a "general" space  $X$  it is true that  $\psi(n+1) = n^2+1$ . The inequality may be proved exactly as before.

What is the meaning of the "2" in  $(n^2+1)$ ? The answer is simple: it is the number of relations ( $\subset$  and  $\not\subset$ ) of which at least one must hold between any two elements. The "2" is generalized to a " $k$ " in Theorem 2.



**DEFINITION.** A  $k$ -relation space ( $kR$ -space for short) consists of a set  $X$  and  $k$  binary relations  $\subset_h$  over  $X$  ( $h=1, \dots, k$ ) satisfying one axiom: for every  $x, y$  in  $X$ , there is at least one  $h$  depending on  $x$  and  $y$  such that  $x \subset_h y$ .

**DEFINITION.** A sequence  $S = \{x_i\}$  is  $\subset_h$ -monotonic if  $x_i \subset_h x_{i+1}$  for all  $i$ .

**DEFINITION.** A sequence  $S$  is monotonic if there is at least one  $h$  for which it is  $\subset_h$ -monotonic.

**EXTENDED BASIC THEOREM.** For sequences over a 2-relation space,  $\psi(n+1) \leq n^2 + 1$ . Furthermore, there are 2-relation spaces for which  $\psi(n+1) = n^2 + 1$ .

**THEOREM 2.** For sequences over a  $kR$ -space,  $\psi(n+1) \leq n^k + 1$ . Furthermore, there are  $kR$ -spaces for which  $\psi(n+1) = n^k + 1$ .

In the  $kR$ -space to be described  $\psi(n+1) = n^k + 1$ . Let  $X$  consist of all real polynomials in the variable  $\xi$  of degree  $\leq k-1$ . The relations  $\subset_h$  are defined by

$$p(\xi) \subset_h q(\xi) \quad \text{if } [p(\xi) - q(\xi)] \text{ has exactly degree } (k - h).$$

(The zero polynomial is assigned degree 0.) It is trivial to show that this is a  $kR$ -space, and the following  $S(n^k)$  contains no  $M(n+1)$ :

$$\begin{aligned} & \xi^{k-1} + \xi^{k-2} + \dots + \xi + 1, \\ & \xi^{k-1} + \xi^{k-2} + \dots + \xi + 2, \\ & \dots \dots \dots \dots \dots \dots \dots, \\ & \xi^{k-1} + \xi^{k-2} + \dots + \xi + n, \\ & \xi^{k-1} + \xi^{k-2} + \dots + 2\xi + 1, \\ & \dots \dots \dots \dots \dots \dots \dots, \\ & \xi^{k-1} + \xi^{k-2} + \dots + 2\xi + n, \\ & \dots \dots \dots \dots \dots \dots \dots, \\ & \dots \dots \dots \dots \dots \dots \dots, \\ & n\xi^{k-1} + n\xi^{k-2} + \dots + n\xi + n. \end{aligned}$$

The proof<sup>2</sup> that  $\psi(n+1) \leq n^k + 1$  in a  $k$ -relation space rests on Lemma 10 which (for real numbers) is stated in the paper by Erdős and Szekeres.

<sup>2</sup> For the basic idea of this proof I am indebted to the referee, who suggested a proof far simpler than the one originally contained in my paper. However, by using Lemma 10, not originally in my paper and not known to the referee, I have further simplified his proof.

LEMMA 10. *If  $(X, \subset_1, \subset_2)$  is a 2-relation space, then any sequence  $S(pq+1)$  either contains a  $\subset_1$ -monotonic subsequence  $M(p+1)$  or a  $\subset_2$ -monotonic subsequence  $M(q+1)$ .*

This lemma may easily be proved in the same way as the Extended Basic Theorem.

Now we proceed by an induction on  $k$ . If  $(X, \subset_1, \dots, \subset_{k+1})$  is a  $(k+1)$ -relation space, and  $S(n^{k+1}+1)$  is a sequence over it, define  $\ll_1$  and  $\ll_2$  by

$$\begin{array}{ll} x \ll_1 y, & \text{if } x \subset_h y \text{ for any } h \text{ from } 1 \text{ to } k, \\ x \ll_2 y & \text{if } x \subset_{k+1} y. \end{array}$$

Now  $(X, \ll_1, \ll_2)$  is a 2-relation space. Hence by Lemma 10,  $S$  contains either  $M_1(n^k+1)$  which is  $\ll_1$ -monotonic or  $M_2(n+1)$  which is  $\ll_2$ -monotonic. In the latter case the proof is complete as  $M_2(n+1)$  is also  $\subset_{k+1}$ -monotonic. In the former case, let  $M_1$  denote the set of elements in  $M_1(n^k+1)$  and define  $\subset^h$  over  $M_1$  by

$$x \subset^h y \quad \text{if } x \subset_h y \text{ or if } y \text{ precedes } x \text{ in } M_1(n^k+1).$$

Then  $(M_1, \subset^1, \dots, \subset^k)$  is a  $kR$ -space. Hence by the induction hypothesis  $M_1(n^k+1)$  must contain an  $M(n+1)$  which is  $\subset^h$ -monotonic for some  $h$  from 1 to  $k$ . But then  $M(n+1)$  is  $\subset_h$ -monotonic, which completes the proof.

**5. De Bruijn's Theorem—a generalization.** In some unpublished work N. G. de Bruijn has generalized the Basic Theorem to sequences of  $m$ -tuples of real numbers. He defines such a sequence to be monotonic if each component sequence is monotonic. (Thus there are  $2^m$  "directions" of monotonicity.)

DE BRUIJN'S THEOREM. *Over the space of  $m$ -tuples,  $\psi(n+1) = n^{2^m} + 1$ .*

His proof is simply an  $m$ -fold application of the Basic Theorem. From  $S(n^{2^m}+1)$  pick a subsequence  $S_1(n^{2^{m-1}}+1)$  whose first components are monotonic. From  $S_1$  pick a subsequence  $S_2(n^{2^{m-2}}+1)$  whose second components are monotonic; and so forth. This eventually yields  $S_m(n+1)$  which is monotonic. This shows that  $\psi(n+1) \leq n^{2^m} + 1$ ; the opposite inequality is easily verified.

De Bruijn's Theorem inspires Theorem 3, which is at once a generalization of De Bruijn's Theorem and of Theorem 2.

DEFINITION. A joint relation-space with coefficients  $k_1, \dots, k_m$  consists of  $m$  different relation-spaces over the same set  $X$  such that the  $l$ th space is a  $k_l R$ -space.

The relations are denoted by  $\subset_h^l$ , where  $h=1, \dots, k_l$  and  $l=1, \dots, m$ .

DEFINITION. A sequence is monotonic over a joint relation-space if it is simultaneously monotonic over every one of the  $k_l R$ -spaces.

THEOREM 3. *Over a joint relation-space,  $\psi(n+1) \leq n^{k_1 k_2 \dots k_m} + 1$ .*

De Bruijn's Theorem is a special case of Theorem 3 in which all the coefficients are 2 and the set  $X$  consists of the real  $m$ -tuples. However his proof cannot be extended to prove Theorem 3, for his proof depends on the transitivity of his relations which is not assumed in Theorem 3.

However Theorem 3 may be proved as a trivial corollary to Theorem 2. Simply define  $k_1 k_2 \dots k_m$  new relations over  $X$  by

$$x \ll_{h_1, \dots, h_m} y \text{ only if } x \subset_{h_l}^l y \text{ for all } l.$$

Then  $X$  and the new relations form a  $k_1 k_2 \dots k_m R$ -space. Use of Theorem 2 then completes the proof.

PRINCETON UNIVERSITY