## COMPRESSIONS TO FINITE-DIMENSIONAL SUBSPACES

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Let  $\mathfrak{K}$  be hilbert space (any dimensionality, real or complex scalars). Let P be a hermitian projection. Let A be any hermitian operator. The *compression* of A to  $P\mathfrak{K}$  [3] is PAP, considered as an operator on  $P\mathfrak{K}$ . Compressions of completely continuous positive operators are of interest in connection with estimating eigenvalues: the Fischer-Courant minimax theorem [5, p. 235] says the *k*th highest eigenvalue of PAP is not greater than that of A. Compressions enter in the study of more general mappings of operators, often via Naĭmark's theorem [6].

Especially in the first connection, the case where  $P\mathcal{K}$  is finitedimensional is interesting. But in some problems a finite-dimensional subspace may be known, not via the operator P, but via an arbitrary set of vectors which span it; if they are not orthonormal, one would rather not have to find P. This suggests that the following elementary formulas may be worth pointing out. I suppose that at least Formula 1 must be known already, but not, apparently, very widely.

NOTATION.  $x_1, \dots, x_n$  form a linear basis of P3C. G denotes the determinant of their Gramian  $(n \times n \text{ matrix with } i, j \text{ entry } (x_i, x_j))$ . If the kth row of the Gramian is replaced by  $(z, x_1), \dots, (z, x_n)$ , all other rows being left unchanged, the determinant of the resulting matrix will be denoted  $G(x_k; z)$ .

Evident properties:  $G(x_k; z) = 0$  if z = (1 - P)z or  $z = x_i$   $(i \neq k)$ , while  $G(x_k; x_k) = G$ ; also  $G(x_k; z)$  is linear in z. These may be summed up by saying that  $G(x_k; z) = (z, x_k^*)G$ , where  $\{x_1^*, \dots, x_n^*\}$  is the basis of P3C biorthonormal with  $\{x_1, \dots, x_n\}$ .

FORMULA 1.  $Pz = G^{-1} \sum_{k} G(x_k; z) x_k$ . (This notation here and below means summation over all available values of the index.)

PROOF. Uniquely  $z = \sum_{i} a_i x_i + (1-P)z$ . Substitute this on both sides, and use the evident properties of  $G(x_k; z)$ .

FORMULA 2.  $tr(PAP) = G^{-1} \sum_{k} G(x_k; Ax_k).$ 

PROOF. Let  $\xi_1, \dots, \xi_n$  be orthonormal eigenvectors of *PAP*, and  $\lambda_1, \dots, \lambda_n$  their respective eigenvalues; then  $x_i = \sum_{\rho} T_{i\rho} \xi_{\rho}$ , where T is some nonsingular matrix. Recall that

$$(x_i, x_j) = \sum_{\rho\sigma} T_{i\rho} \overline{T}_{j\sigma}(\xi_{\rho}, \xi_{\sigma}) = \sum_{\rho} T_{i\rho} \overline{T}_{j\rho} = (TT^*)_{ij}$$

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gives  $G = |\det T|^2$ . (\* denotes conjugate transpose.) It remains to prove that, analogously,  $\sum_k G(x_k; Ax_k) = |\det T|^2 \operatorname{tr}(PAP)$ . Now  $(Ax_i, x_j) = (PAPx_i, x_j) = \sum_{\rho} T_{i\rho}\lambda_{\rho}\overline{T}_{j\rho}$ . So if we let  $R^k$  denote the matrix with entries  $R_{i\rho}^k = T_{i\rho} (i \neq k)$  and  $R_{k\rho}^k = T_{k\rho}\lambda_{\rho}$ , we have  $G(x_k; Ax_k)$  $= \det(R^kT^*)$ ,  $\sum_k G(x_k; Ax_k) = \det T^* \sum_k \det R^k$ . In the expansion

$$\sum_{k} \det R^{k} = \sum_{k} \sum_{\rho_{1}, \cdots, \rho_{n}} \epsilon_{\rho_{1}, \cdots, \rho_{n}}^{1 \cdots n} T_{1\rho_{1}} \cdots T_{n\rho_{n}} \lambda_{\rho_{k}}$$

the summation over k may be carried out first:  $\sum_k \lambda_{\rho_k} = \operatorname{tr}(PAP)$  for any  $(\rho_1, \dots, \rho_n)$  giving a nonzero contribution. This gives the result.

The proof would have been simpler if I had exploited the evident properties of  $G(x_k; z)$ . I gave this version because Formula 3 is proved altogether analogously, without introducing any new notions.

Instead of the trace  $c_1$ , consider now  $c_{\nu}$ , where for any B

det 
$$(\lambda + B) = \sum_{\nu} c_{\nu}(B)\lambda^{n-\nu};$$

that is,  $c_{\nu}$  is the  $\nu$ th elementary symmetric polynomial of the eigenvalues. Extend the notation:  $G(x_{k_1}; z_1)(x_{k_2}; z_2)$  is the determinant of the matrix which differs from the Gramian in having  $k_1$ th row  $(z_1, x_1), \dots, (z_1, x_n)$  and in having  $k_2$ th row  $(z_2, x_1), \dots, (z_2, x_n)$ ; and so forth.

FORMULA 3.<sup>2</sup>  $c_{\nu}(PAP) = G^{-1} \sum G(x_{k_1}; Ax_{k_1}) \cdots (x_{k_{\nu}}; Ax_{k_{\nu}})$ . (In this equation summation is over all distinct  $\nu$ -tuples  $\{k_1, \dots, k_{\nu}\}$  from among  $\{1, \dots, n\}$ .)

PROOF. See under Formula 2.

An interesting case is where A is another projection Q. A complete set of unitary-invariants for the *pair* of subspaces  $P\mathcal{K}$  and  $Q\mathcal{K}$  is the spectrum of PQP and its multiplicity function (together with the dimensionalities of  $Q\mathcal{K} \cap (1-P)\mathcal{K}$  and  $(1-Q)\mathcal{K} \cap (1-P)\mathcal{K})$  [1;2].<sup>3</sup> For a simple numerical measure of the closeness of  $P\mathcal{K}$  to being contained in  $Q\mathcal{K}$ , tr(PQP) recommends itself (or, if you like,  $n^{-1} tr(PQP)$ ). If  $Q\mathcal{K}$  is finite-dimensional, one may ask for a modification of Formula 2 which treats P and Q symmetrically.

 $y_1, \dots, y_m$  form a linear basis of Q3C. H denotes the determinant of their Gramian;  $H(y_l; z)$ , etc. are defined in analogy to previous notations.

FORMULA 4. 
$$tr(PQP) = tr(QPQ) = (GH)^{-1} \sum_{kl} G(x_k; y_l) H(y_l; x_k).$$

<sup>&</sup>lt;sup>2</sup> The case  $\nu = n$  shows the equivalence of Theorem 1 of [4] to Weyl's theorem which it generalizes.

<sup>&</sup>lt;sup>8</sup> One might prefer replacing PQP by PQP + (1-P)(1-Q)(1-P) = 1 - P - Q + PQ + QP, making apparent the symmetrical roles of P and Q [1].

**PROOF.** I have proofs of Formulas 4 and 5 along the unsophisticated lines followed above for Formulas 2 and 3, but they are clumsy. Instead, rewrite the right side of Formula 4 in terms of the biorthonormal bases  $\{x_1, \dots, x_n\}, \{x_1^*, \dots, x_n^*\}$  of  $P\mathcal{K}, \{y_1, \dots, y_m\}, \{y_1^*, \dots, y_m^*\}$  of  $Q\mathcal{K}$ . It equals

$$\sum_{kl} (y_l, x_k^*)(x_k, y_l^*) = \sum_{kl} ((x_k, y_l^*)y_l, x_k^*) = \sum_k (Qx_k, x_k^*) = \operatorname{tr}(PQP),$$

by Formulas 1 and 2.

Formula 5.

$$c_{\nu}(PQP) = c_{\nu}(QPQ)$$
  
=  $(GH)^{-1} \sum G(x_{k_1}; y_{l_1}) \cdots (x_{k_{\nu}}; y_{l_{\nu}})H(y_{l_1}; x_{k_1}) \cdots (y_{l_{\nu}}; x_{k_{\nu}}).$ 

(In this equation summation is over all distinct pairs of  $\nu$ -tuples,  $\{k_1, \dots, k_{\nu}\}$  from among  $\{1, \dots, n\}$  and  $\{l_1, \dots, l_{\nu}\}$  from among  $\{1, \dots, m\}$ .)

**PROOF.** The equation

$$G(x_{k_1}; z_1) \cdot \cdot \cdot (x_{k_{\nu}}; z_{\nu}) = G_{\nu}!(z_1 \otimes \cdot \cdot \cdot \otimes z_{\nu}, G^*_{k_1 \cdots k_{\nu}})$$

defines an element  $G_{k_1 \dots k_{\nu}}^*$  of  $\mathfrak{K}^{\nu}$ , the tensor product of  $\nu$  copies of  $\mathfrak{K}$ . Extend  $\{x_1, \dots, x_n\}$  to a basis of  $\mathfrak{K}$  by adjoining an orthonormal basis  $\{x_{n+1}, x_{n+2}, \dots\}$  of  $(1-P)\mathfrak{K}$ . The elements  $x_{\sigma_1} \otimes \cdots \otimes x_{\sigma_{\nu}}$  form a linear basis of  $\mathfrak{K}^{\nu}$ . By considering its scalar products with these basis vectors,  $G_{k_1 \dots k_{\nu}}^*$  is identified as

$$\frac{1}{\nu!}\sum_{l_1\cdots l_{\nu}} \epsilon_{l_1\cdots l_{\nu}} x_{l_1}^* \otimes \cdots \otimes x_{l_{\nu}}^* = x_{\lfloor k_1}^* \otimes \cdots \otimes x_{k_{\nu}\rfloor}^*.$$

(Again  $\epsilon$  is defined by  $\epsilon = \pm 1$  if  $(l_1, \dots, l_r)$  is respectively an even or an odd permutation of  $(k_1, \dots, k_r)$ ,  $\epsilon = 0$  otherwise. The bracket on the subscripts, denoting antisymmetrization, is defined by the equation.)

The easily-proved analog of Formula 1 is

$$Pz_{[1} \otimes \cdots \otimes Pz_{\nu]} = \sum_{k_1 \cdots k_{\nu}} (z_1 \otimes \cdots \otimes z_{\nu}, x_{[k_1}^* \otimes \cdots \otimes x_{k_{\nu}]}^*) x_{k_1} \otimes \cdots \otimes x_{k_{\nu}}.$$

Formula 3 in the new notation reads

$$c_{\nu}(PAP) = \sum_{k_1\cdots k_{\nu}} (Ax_{k_1} \otimes \cdots \otimes Ax_{k_{\nu}}, x_{(k_1}^* \otimes \cdots \otimes x_{k_{\nu}}));$$

this is not disturbed if the subscripts of the  $Ax_{k_i}$  are also bracketed.

The right side of Formula 5 becomes

$$\sum_{k_1\cdots k_{\nu};\,l_1\cdots l_{\nu}} (y_{l_1}\otimes\cdots\otimes y_{l_{\nu}}, x_{\lfloor k_1}^*\otimes\cdots\otimes x_{k_{\nu}\rfloor}^*)(x_{k_1}\otimes\cdots\otimes x_{k_{\nu}}, y_{\lfloor l_1}\otimes\cdots\otimes y_{l_{\nu}\rfloor})$$

By the analog of Formula 1 this is equal to

$$\sum_{k_1\cdots k_{\nu}} (Qx_{[k_1}\otimes\cdots\otimes Qx_{k_{\nu}]}, x_{[k_1}^*\otimes\cdots\otimes x_{k_{\nu}]}^*),$$

and by Formula 3 this is  $c_{\nu}(PQP)$ , as claimed.

The analogy to the special case, Formula 4, could be strengthened by mentioning that  $Pz_{[1} \otimes \cdots \otimes Pz_{\nu]} = P_{\nu}(z_{1} \otimes \cdots \otimes z_{\nu})$ , where  $P_{\nu}$ is the hermitian projection on the subspace of  $\mathcal{K}^{\nu}$  linearly spanned by antisymmetrized products of elements of  $\mathcal{P}\mathcal{K}$ . The  $x_{[k_{1}} \otimes \cdots \otimes x_{k_{\nu}]}$ and the  $x_{[k_{1}}^{*} \otimes \cdots \otimes x_{k_{\nu}]}^{*}$  are almost biorthonormal bases of  $P_{\nu}\mathcal{K}^{\nu}$ :

$$(x_{[l_1}\otimes\cdots\otimes x_{l_{\nu}]}, x_{[k_1}^*\otimes\cdots\otimes x_{k_{\nu}]}^*)=\frac{1}{\nu!} \underset{\epsilon_{k_1}\cdots k_{\nu}}{\overset{l_1\cdots l_{\nu}}{\overset{l_1\cdots l_{\nu}}{\overset{l_$$

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