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University of California, Santa Barbara

ON ERGODIC MEASURES

YAEL NAIM DOWKER AND G. LEDERER

Introduction, notation, definitions and known results. In what follows Ω will be a compact metric space and T a homeomorphism of Ω onto itself. The pair (Ω, T) is called a compact discrete dynamical system. If m is a Borel measure in Ω such that $m(\Omega) = 1$, m is called a normalised Borel measure. Throughout this paper all measures will be assumed to be normalised Borel measures. If for any Borel set B, m(B) = m(TB), m is called an invariant measure. Ergodic invariant measures will simply be referred to as ergodic measures. If, for some set A, T(A) = A, A will be called an invariant set. A nonempty, closed, invariant set which has no proper subset of the same properties is called a minimal set.

The empty set will be denoted by \emptyset . Given two sets A and B, ' $A \subseteq B$ ' will stand for 'A is a subset of B', while ' $A \subset B$ ' for 'A is a proper subset of B'.

The set of points p, T(p), $T^2(p)$, \cdots is called the positive semiorbit of p and will be denoted by O_p^+ . The set of limit points of the sequence p, T(p), $T^2(p)$, \cdots in Ω is called the ω -limit set of p and will be denoted by ω_p . The set of points p, T(p), $T^{-1}(p)$, $T^2(p)$, $T^{-2}(p)$, \cdots is called the orbit of p and will be denoted by O_p . The closure of the semiorbit (orbit) in Ω is called the semiorbit closure (orbit closure) and will be denoted by $\overline{O}_p^+(\overline{O}_p)$. $\mathfrak{N}(p, \rho)$ will denote the open sphere about p of radius p.

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 $C(\Omega)$ will denote the space of all real-valued continuous functions defined on Ω with the norm $||f(x)|| = \operatorname{Max}_{x \in \Omega} |f(x)|$.

For any f(x) in $C(\Omega)$ put $F_n(x) = (1/n) \sum_{i=0}^{n-1} f(T^i(x))$. We call p a mean point $(p \in Q)$, if $\lim_{n \to \infty} F_n(p)$ exists for every f(x) in $C(\Omega)$. In that case we put $\lim_{n \to \infty} F_n(p) = F(p)$. The notion of a mean point is due to Krylov and Bogoljubov who called such a point a quasi-regular point (cf. [2, p. 93]). They showed that $Q \neq \phi$, if $\Omega \neq \phi$. They also showed that to each mean point there corresponds a unique invariant measure. This is obtained in the following manner:

Fix a mean point p and for any f(x) in $C(\Omega)$ put L(f) = F(p). Then L(f) is a positive linear functional on $C(\Omega)$. Moreover, L(f) is invariant, i.e., L(f) = F(p) = F(T(p)) = L(Tf). Hence, by a well-known theorem of F. Riesz (cf. [4]), there is a unique measure μ in Ω such that μ is invariant and

$$L(f) = \int_{\Omega} f(x) d\mu(x)$$

for every f(x) in $C(\Omega)$. μ is the invariant measure corresponding to p which we shall denote by μ_p .

A mean point p is called transitive $(p \in Q_T)$ if μ_p is ergodic. A mean point p is called dense $(p \in Q_D)$ if $\mu_p(U) > 0$ for every open neighbourhood U of p. We put $R = Q_D \cap Q_T$. Points of R are called regular points.

We give now a few theorems due to Krylov and Bogoljubov. See [3] for a concise, comprehensive summary of these.

K.B. 1. Q, Q_T , Q_D and R are nonempty, invariant Borel sets, and for any invariant measure m, m(R) = 1. Hence, there is at least one ergodic measure μ in Ω . ($\mu = \mu_p$ for some p in Q_T .)

Not only does any point p in Q_T determine uniquely an ergodic measure μ_p , but every ergodic measure μ in Ω is determined this way by some point p of R ($R \subset Q_T$). In this manner Q_T can be decomposed into disjoint invariant sets, called quasi-ergodic sets, each of which consists of all transitive points which determine one and the same ergodic measure in Ω . The intersection of each quasi-ergodic set with R is nonempty, invariant and is called an ergodic set. Ergodic sets then form the corresponding decomposition of R. Thus

K.B. 2. There is a 1-1 correspondence between the class of ergodic measures in Ω , the class of quasi-ergodic sets in Q_T and the class of ergodic sets in R. In this correspondence, if E is the ergodic and E' the quasi-ergodic set corresponding to the measure μ , then E and E' are Borel sets, $E \subseteq E'$, $\mu = \mu_p$ for every p in E', and $\mu(E) = 1$. Moreover, for every Borel set B, $\mu_p(B)$ is a Borel-measurable function of p, and for any invariant measure μ

$$\mu(B) = \int_{R} \mu_p(B) d\mu(p) = \int_{Q_T} \mu_p(B) d\mu(p).$$

K.B. 3. If A is a closed invariant set and E any ergodic set, then either $A \cap E = E$ or $A \cap E = \emptyset$. In the former case E is an ergodic set of (A, T).

K.B. 4. If E is an ergodic set and $p \in E$, then $E \subseteq \overline{O}_p$.

K.B. 5. If E_1 and E_2 are two distinct quasi-ergodic sets, there is a function f(x) in $C(\Omega)$ and there are two distinct real numbers c_1 and c_2 such that $F(x) = c_1$ on E_1 and $F(x) = c_2$ on E_2 .

The following theorem follows easily from the Krylov and Bogoljubov theory. See [3, p. 124] for a proof.

O. If all points of Ω are mean points and M is a minimal set, then M is an ergodic set.

The following theorems are due to one of us:

- D. 1. If $p \in Q$, then $\mu_p(\overline{Q}_p^+) = 1$.
- D. 2. If p is not a transitive point, then $\overline{\mathcal{Q}}_p^+$ contains at least two ergodic sets.
- D. 3. Let $p \in \Omega$ and let A be a nonempty, closed, invariant proper subset of \overline{O}_p^+ . Let U be an open set such that $A \subset U$ and $\overline{O}_p^+ \subseteq \overline{U}$. There is then a compact set K such that $A \subset K \subseteq \overline{U}$ and $TK \subseteq K$.

For a proof of theorems D. 1, D. 2, and D. 3, see [1, pp. 126–128]. D. 1 and D. 2 are Lemmas 3 and 7, respectively. D. 3 is an immediate consequence of K and Lemma 8.

One of us has shown (cf. [1]) that if Ω has an infinity of points, it has an infinity of transitive points. In this paper we deal with the question of existence of an infinity of ergodic measures. It is known—as expressed in O—that if Ω is itself a minimal set and all points in Ω are mean points, then there is only one invariant measure in Ω . The question arises whether there can be more than one such measure in Ω if all points of Ω are mean points and Ω contains a single minimal set properly. While this problem is still unsolved, a partial answer is provided in this paper.

THEOREM. Let (Ω, T) be a discrete dynamical system. Let each point of Ω be a mean point and let Ω contain a single minimal set properly. Then the number of ergodic measures in Ω is either one or infinite.

PROOF. Assume that the hypotheses of the theorem hold and denote by M the minimal set. By K.B. 1 there is at least one ergodic measure in Ω . Assume next that the number of ergodic measures in Ω is at least two. Then Ω has at least two ergodic sets of which M is one (O). Let k be the cardinal number of the class of ergodic sets of Ω .

Then $k \ge 2$. Assume now that k is finite. Denote by E one of the ergodic sets of Ω $(E \ne M)$. Fix a point p in E. (p will denote the same point for the rest of the paper.) Then, by K.B. 4, $E \subseteq \overline{O}_p$. Put $\overline{O}_p = X$. Then X is an invariant, closed subset of Ω . We confine our attention to the system (X, T). The symbols Q, R and μ_q (for any q in X) will refer to X. Clearly, all assumptions on (Ω, T) hold for (X, T). By K.B. 3, X has at most k ergodic sets. These clearly include E and M. Denote the quasi-ergodic sets of X by E_1, E_2, \cdots, E_j $(j \le k, E \subseteq E_1 = E', M \subseteq E_j)$.

We assert now that $X = \omega_p$. To prove this, note that for any integer n, $T^n(p) \in E \subset R$, and hence if U is an open neighbourhood of $T^n(p)$, $\mu_p(U) > 0$. Now assume that $X \neq \omega_p$. There is then an open set U contained in $X - \omega_p$ and there are integers n_0 and N such that $T^{n_0}(p) \in U$ while $T^n(p) \in X - U$ for all $n \geq N$. Hence, by D. 1, $\mu_p(X - U) = 1$, while $\mu_p(U) > 0$ —which is absurd. Thus $X = \omega_p$ and hence E is dense in X.

Now if $q \in E'$, then $\mu_q = \mu_p$ in X. Hence if $q \in E'$ and U is any open neighbourhood of q, then since $T^n(p) \in U$ for some n, $\mu_q(U) = \mu_p(U) > 0$. Thus all points of E' are regular. Hence E = E'.

We assert next that for $1 < i \le j$, E_i is nowhere dense in X. To prove this, assume that for some i $(1 < i \le j)$ E_i is dense in an open sphere U of X. Since $X = \omega_p$, there is an integer n_1 such that $T^{n_1}(p) \in U$. Now take any open sphere V of X. Since $X = \overline{O}_{p_n}$, there is some integer n_2 for which $T^{n_2}(p) \in V$. Put $n = n_2 - n_1$. Then $T^n(T^1(p)) \in V$. Hence $V \cap T^n(U)$ is a nonempty, open set. Since $T^n(E_i) = E_i$ and E_i is dense in U, E_i is dense in $T^n(U)$. Hence $E_i \cap V \cap T^n(U) \ne \emptyset$, i.e., $E_i \cap V \ne \emptyset$. Since V was arbitrary, we conclude that if E_i is not nowhere dense in X, it must be dense in X.

Now since E_1 and E_i are distinct quasi-ergodic sets, by K.B. 5 there is a function f(x), continuous on X, and there are real constants c_1 and c_i such that $c_1 \neq c_i$, $F(x) = c_1$ on E_1 and $F(x) = c_i$ on E_i . Now since all points of X are mean points, F(x) is defined for all x in X. Then since E_1 is dense in X, if E_i is also dense in X, F(x) is discontinuous at every point of X. This is impossible, since F(x) is of Baire class 1. Thus E_i is not dense in X. It is therefore nowhere dense.

We conclude that the set $\bigcup_{i=2}^{j} E_i$ is nowhere dense.

Put $H = \bigcup_{i=2}^{r} E_i$. Then \overline{H} is nowhere dense, closed and invariant. There is then a point x in X and a positive number ρ such that $\mathfrak{N}(x, 2\rho) \cap \overline{H} = \emptyset$. Put $U = X - [\mathfrak{N}(x, \rho)]^{-}$. Clearly, U is open. Moreover, since $X = \omega_p$, there is a positive integer n for which $T^n(p) \in \mathfrak{N}(x, \rho) \subseteq X - \overline{U}$. Thus

$$\overline{H} \subset U$$
 and $\overline{O}_p^+ \subseteq \overline{U}$.

Then since U is open and \overline{H} is an invariant closed subset of \overline{O}_p^+ , there is, by D. 3, a compact set K such that

$$\overline{H} \subset K \subseteq \overline{U}$$
 and $TK \subseteq K$.

There is thus a point q in $K - \overline{H}$, such that $\omega_q \subseteq \overline{O}_q^+ \subseteq K \subset X$. Hence $\omega_q \neq X$. We have proved that if $x \in E'$, then $\omega_x = X$. Hence $q \notin E' = E$. Also E is dense in X, ω_q is closed and $\omega_q \neq X$. Thus $E \subseteq \omega_q$. Then, by K.B. 3, since ω_q is invariant and closed, $E \cap \omega_q = \emptyset$.

Since $q \in E'$ and $q \in K - \overline{H}$, $q \in \bigcup_{i=1}^{r} E_i$. Hence q is not transitive nor is any point of O_q . Thus, by D. 2, $\overline{O_q^+}$ contains at least two ergodic sets. Clearly, M is one of these. Also, no point of O_q is regular. Thus ω_q contains at least two ergodic sets of which M is one, while $E \cap \omega_q = \emptyset$. Put $\omega_q = \Omega_1$. Then Ω_1 is an invariant, closed, proper subset of Ω , consisting of mean points only, containing a single minimal set properly and containing (by the above and by K.B. 3) at least two and at most k-1 ergodic sets.

The process can be repeated any number of times yielding a decreasing sequence Ω , Ω_1 , Ω_2 , \cdots , Ω_r , \cdots of invariant closed sets, where for each r Ω_r contains at least two and at most k-r ergodic sets. A contradiction is obtained for r=k-1. Our assumption that k is finite was false and the theorem is proved.

COROLLARY. Let the hypotheses of the theorem hold. Then, if there are two distinct invariant measures in Ω , there is an infinity of distinct ergodic measures in Ω .

PROOF. By K.B. 2, if there is only one ergodic measure in Ω , there can be only one measure in Ω . The corollary follows now from the theorem.

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THE UNIVERSITY, SHEFFIELD AND IMPERIAL COLLEGE