

REFERENCES

1. M. Heins, *Riemann surfaces of infinite genus*, Ann. of Math. (2) **55** (1952), 296-317.
2. W. Hurewicz and H. Wallman, *Dimension theory*, Princeton Univ. Press, Princeton, N. J., 1948; Chapter II.
3. Z. Kuramochi, *On the behaviour of analytic functions on abstract Riemann surfaces*, Osaka Math. J. **7** (1955), 109-127.
4. T. Kuroda, *On analytic functions on some Riemann surfaces*, Nagoya Math. J. **10** (1956), 27-50.
5. K. Noshiro, *Cluster sets*, Chapter IV, §2, Springer, Berlin, 1960.
6. N. Toda and K. Matsumoto, *Analytic functions on some Riemann surfaces*, Nagoya Math. J. **22** (1963), 211-217.

TOKYO INSTITUTE OF TECHNOLOGY, TOKYO, JAPAN

ON THE EIGENVALUES OF A MATRIX WHICH COMMUTES WITH ITS DERIVATIVE

NICHOLAS J. ROSE

Let $V(t)$ be an $n \times n$ matrix whose elements are differentiable functions of t . Epstein [1] has obtained (Theorem 1) necessary and sufficient conditions for $V(t)$ to commute with its derivative $\dot{V}(t)$ in some interval provided that the Jordan canonical form of $V(t)$ maintains the same form throughout the interval (see the definition below). Using this result we show in Theorem 2, under the same restriction, that if $V(t)$ commutes with $\dot{V}(t)$, then the eigenvalues of $\dot{V}(t)$ are the derivatives of the eigenvalues of $V(t)$.

DEFINITION. Let $S(J)$ be the set of all $n \times n$ matrices $V(t)$ defined in the interval $I: t_1 \leq t \leq t_2$ and having the properties:

- (i) the elements $V_{ij}(t)$ of $V(t)$ are differentiable functions in I ,
- (ii) for each $V(t) \in S(J)$ there exists a nonsingular differentiable matrix $P(t)$ such that $V = P^{-1}JP$ for $t \in I$ where J is the Jordan canonical matrix

$$(1) \quad J = \begin{pmatrix} C_1(t) & 0 & \cdot & \cdot & \cdot & 0 \\ 0 & C_2(t) & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & 0 \\ 0 & \cdot & 0 & C_r(t) & & \end{pmatrix}$$

Presented to the Society, April 21, 1964; received by the editors February 17, 1964 and, in revised form, April 22, 1964.

and

$$(2) \quad C_k(t) = \lambda_k(t)I_k + E_k, \quad k = 1, 2, \dots, r$$

where $C_k(t)$ is an $n_k \times n_k$ matrix, n_k being the multiplicity of the eigenvalue $\lambda_k(t)$ of V ; I_k is the $n_k \times n_k$ identity matrix and E_k is an $n_k \times n_k$ matrix all of whose elements equal 0 except possibly on the superdiagonal where some elements may equal 1,

(iii) E_k and n_k are constant for $t \in I$.

(iv) $\lambda_k(t)$ are differentiable in I ,

(v) if $j \neq k$ then $\lambda_j(t) - \lambda_k(t) \neq 0$ for $t \in I$.

In the following $[X, Y]$ stands for the Lie bracket: $[X, Y] = XY - YX$.

THEOREM 1 (EPSTEIN [1]). If $V(t) \in S(J)$ and $V = P^{-1}JP$ then $[V, \dot{V}] = 0$ in I if and only if

$$[J, [J, \dot{P}P^{-1}]] = 0, \quad t \in I.$$

PROOF. Setting $X = \dot{P}P^{-1}$ we have by direct calculation

$$(3) \quad \begin{aligned} V &= P^{-1}(J + [J, X])P, \\ [V, \dot{V}] &= P^{-1}([J, J] + [J, [J, X]])P. \end{aligned}$$

Since $[J, J] = 0$, the theorem follows.

We need the following lemma (see Jacobson [2]).

LEMMA. If A is an $n \times n$ matrix and X is any solution of

$$[A, [A, X]] = 0$$

then $[A, X]$ is nilpotent.

THEOREM 2. If $V(t) \in S(J)$ and $[V, \dot{V}] = 0$ in I , then the eigenvalues of $\dot{V}(t)$ are the derivatives of the eigenvalues of $V(t)$ for $t \in I$.

PROOF. If $V = P^{-1}JP$ then from Theorem 1, J must satisfy

$$[J, [J, X]] = 0$$

where $X = \dot{P}P^{-1}$. We partition X in accordance with (1), that is $X = (X_{ij})$ where X_{ij} is of order $n_i \times n_j$. Using (2) we see that X_{ij} must satisfy

$$(4) \quad C_i^2 X_{ij} - 2C_i X_{ij} C_j + X_{ij} C_j^2 = 0, \quad i, j = 1, 2, \dots, r.$$

The left-hand side of (8) defines a linear operator T acting on X_{ij} . The eigenvalues of T are $(\lambda_i - \lambda_j)^2$ (see Hausner [3]). Therefore if $i \neq j$ the only solution of (4) is $X_{ij} = 0$. Consequently X consists only

of diagonal blocks X_{ii} which satisfy

$$[E_i, [E_i, X_{ii}]] = 0, \quad i = 1, 2, \dots, r.$$

It follows from the Lemma that $[E_i, X_{ii}]$ is nilpotent for $i = 1, \dots, r$. We note that the matrix $[J, X]$ consists only of the nilpotent diagonal blocks $[E_i, X_{ii}]$. From (3) we see that \dot{V} has the same eigenvalues as $\dot{J} + [J, X]$, namely the roots of

$$\det([J, X] + J - \lambda I) = 0.$$

Since $[J, X]$ consists only of the diagonal blocks $[E_i, X_{ii}]$ and \dot{J} consists only of the diagonal blocks $\lambda_i(t)I_i$, we have

$$\begin{aligned} \det([J, X] + J - \lambda I) &= \prod_{i=1}^r \det([E_i, X_{ii}] + (\lambda_i - \lambda)I_i) \\ &= \prod_{i=1}^r (\lambda_i - \lambda)^{n_i} \end{aligned}$$

since $[E_i, X_{ii}]$ is nilpotent. Therefore the eigenvalues of \dot{V} are just λ_i and the theorem is proved.

REFERENCES

1. I. J. Epstein, *Conditions for a matrix to commute with its integral*, Proc. Amer. Math. Soc. **14** (1963), 266-270.
2. N. Jacobson, *Lie algebras*, Interscience, New York, 1962.
3. M. Hausner, *Eigenvalues of certain operators on matrices*, Comm. Pure Appl. Math. **14** (1961), 155-156.

STEVENS INSTITUTE OF TECHNOLOGY