## ON POLYNOMIALS CHARACTERIZED BY A CERTAIN MEAN VALUE PROPERTY

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Let $V$ denote the vector space of continuous real valued functions $f(x)$ satisfying the mean value property

$$
\begin{equation*}
f(x)=\frac{1}{N} \sum_{i=1}^{N} f\left(x+t y_{i}\right) \tag{1}
\end{equation*}
$$

for $x \in R, 0<t<\epsilon_{x}$ ( $R$ denotes an $n$-dimensional region; $x$ and $y_{i}$ are abbreviations for $\left(x_{1}, \cdots, x_{n}\right),\left(y_{i 1}, \cdots, y_{i n}\right)$ ). We assume that the $y_{i}$ 's span $E_{n}$ so that $1 \leqq n \leqq N$. We furthermore assume, without loss of generality, that $y_{1}, \cdots, y_{n}$ are linearly independent.

Friedman and Littman [5] have recently shown that $\vee$ consists of polynomials of degrees $\leqq N(N-1) / 2$. This bound is actually attained when the $y_{i}$ 's form the $N$ vertices of an ( $N-1$ )-dimensional regular simplex [see 4, p. 264]. On the other hand it is known that for $n=2$, $\operatorname{deg} f \leqq N$ [see 4, Theorem 3.2]. The object of this paper is to obtain bounds on deg $\vee$ and $\operatorname{dim} \vee$, the bounds depending on $N$ and $n(1 \leqq n \leqq N)$. We use the term deg $\vee$, to denote the maximum degree of the polynomials contained in $V$. We also characterize for fixed $N$ and varying $n(1 \leqq n \leqq N)$ those configurations for which $\operatorname{deg} \vee$ and $\operatorname{dim} \vee$ attain their maximum.

Theorem. We have

$$
\begin{equation*}
\operatorname{deg} \bigvee \leqq \sum_{j=1}^{n}(N-j), \quad \operatorname{dim} \vee \leqq \prod_{j=0}^{n-1}(N-j) \tag{2}
\end{equation*}
$$

so that for fixed $N$ and varying $n(1 \leqq n \leqq N)$

$$
\begin{equation*}
\operatorname{deg} \bigvee \leqq \frac{N(N-1)}{2}, \quad \operatorname{dim} \bigvee \leqq N! \tag{3}
\end{equation*}
$$

The latter bounds are obtained if and only if

$$
n=N \quad \text { or } \quad n=N-1 \quad \text { and } \quad \sum_{i=1}^{N} y_{i}=0
$$

Remark. The bounds in (2) are not best possible. For instance, we have stated above that for $n=2$, deg $\bigvee \leqq N$ and this bound is best

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possible. For fixed $n$ and $N$ the problem of determining the maximum values of $\operatorname{deg} \vee$, $\operatorname{dim} \vee$ and the configurations for which these maximum values are attained remains open.

Proof. We employ the following notation.

$$
\begin{gathered}
\frac{\partial}{\partial x}=\left(\frac{\partial}{\partial x_{1}}, \cdots, \frac{\partial}{\partial x_{n}}\right), \quad x \cdot y=x_{1} y_{1}+\cdots+x_{n} y_{n}, \\
P_{k}(x)=\sum_{i=1}^{N}\left(x \cdot y_{i}\right)^{k} \quad(1 \leqq k<\infty) .
\end{gathered}
$$

It is shown in [5] that (1) is equivalent to the infinite system of homogeneous partial differential equations

$$
\begin{equation*}
P_{k}\left(\frac{\partial}{\partial x}\right) f=0 \quad(1 \leqq k<\infty) \tag{4}
\end{equation*}
$$

and that $V$, which is thus the solution space of (4), is a finite dimensional space consisting of polynomials. Let $R$ denote the ring of polynomials in $x_{1}, \cdots, x_{n}$ with real coefficients and let $\mathfrak{F}$ denote the ideal generated by the $P_{k}^{\prime}$ 's $(1 \leqq k<\infty) . R, \mathfrak{B}$, and $V$ are vector spaces over the reals and it is known that $R$ is the direct sum of $\mathfrak{B}$ and $\vee$, i.e. $R=\mathfrak{B} \oplus \vee$ [see 2, p. 53]. Thus the vector spaces $R / \mathfrak{ß}$ and $V$ are isomorphic $(R / \mathfrak{\beta} \cong \vee)$.
$\operatorname{deg} V$ and $\operatorname{dim} V$ will thus be determined if we know all the polynomials in $\mathfrak{P}$. We introduce the new variables $\xi_{i}=x \cdot y_{i}(1 \leqq i \leqq N)$. Since the $y_{i}$ 's ( $1 \leqq i \leqq N$ ) are linearly independent we must have $\xi_{n+k}=\sum_{i=1}^{n} a_{k i} \xi_{i}(1 \leqq k \leqq N-n)$ for an appropriate choice of real $a_{k i}$ 's. Let $R^{\prime}$ denote the ring of polynomials in $\xi_{1}, \cdots, \xi_{n}$ with real coefficients and let $\mathfrak{B}^{\prime}$ denote the ideal generated by the $\eta_{k}$ 's where $\eta_{k}$ $=\sum_{i=1}^{n} \xi_{i}^{k}(1 \leqq k \leqq \infty)$. We adopt the following notation:

$$
\xi=\left(\xi_{1}, \cdots, \xi_{n}\right), i=\left(i_{1}, \cdots, i_{n}\right), \quad \xi_{i}^{i}=\xi_{1}^{i_{1}}, \cdots, \xi_{n}^{i_{n}} .
$$

It is known [see 1, p. 41] that every polynomial $Q(\xi)$ can be expressed as

$$
\begin{equation*}
Q(\xi)=\sum^{\prime} R_{i} \xi^{i} \tag{5}
\end{equation*}
$$

where the summation in $\sum^{\prime}$ extends over those $i$ 's for which $0 \leqq i_{j}$ $\leqq N-j(1 \leqq j \leqq n)$ and $R_{i}$ is a polynomial in $\eta_{1}, \cdots, \eta_{N}$. This representation is unique for $n=N$. Let $c_{i}$ denote the constant term in $R_{i}$ and let $S_{i}=R_{i}-c_{i}$. Clearly $S_{i} \in \mathfrak{P}^{\prime}$. It follows from (5) that $Q(\xi)$ $=\sum^{\prime} C_{i} \xi^{i}+\sum^{\prime} S_{i} \xi^{i}$ so that

$$
\begin{equation*}
Q(\xi) \equiv \sum^{\prime} c_{i} \xi^{i}\left(\bmod \mathfrak{P}^{\prime}\right) . \tag{6}
\end{equation*}
$$

As there are $\prod_{j=0}^{n-1}(N-j)$ distinct $\xi^{i}$ 's, (6) shows that $\operatorname{dim} R^{\prime} / \mathfrak{F}^{\prime}$ $\leqq \prod_{j=0}^{n-1}(N-j)$. Since $\vee \cong R / \mathfrak{F} \cong R^{\prime} / \mathfrak{B}^{\prime}$ we have $\operatorname{dim} \vee$ $\leqq \prod_{\substack{n=0}}^{n-1}(N-j)$. It follows furthermore from (6) that if $Q$ is homogeneous and $\operatorname{deg} Q>\sum_{j=1}^{n}(N-j)$, then $Q \in \mathfrak{P}^{\prime}$. This implies that if $P(x)$ is homogeneous and $\operatorname{deg} P>\sum_{j=1}^{n}(N-j)$ then $P \in \mathfrak{P}$. Thus $\operatorname{deg} \vee \leqq \sum_{j=1}^{n}(N-j)$.

If $n \leqq N-2$, then we conclude from (2) that $\operatorname{deg} \vee<N(N-1) / 2$, $\operatorname{dim} \vee<N$ !. It remains to treat the two cases: (a) $n=N$, (b) $n=N-1$. In case (a) the $\xi^{i}$ 's form a basis for $R^{\prime} / \mathfrak{F}^{\prime}$. For suppose that $\sum^{\prime} c_{i} \xi^{i}$ $\equiv 0\left(\bmod \mathfrak{P}^{\prime}\right)$ for some choice of real $c_{i}{ }^{\prime} \mathrm{s}$. Then $\sum^{\prime} c_{i} \xi^{i}=\sum_{j=1}^{n} T_{j}(\xi) \eta_{j}$ where the $T_{j}$ 's are polynomials in $\xi_{1}, \cdots, \xi_{n}$. But each $T_{j}$ has a representation (5). I.e. $T_{j}(\xi)=\sum^{\prime} R_{j i}(\eta) \xi^{i}$ where the $R_{j i}$ 's are polynomials in $\eta_{1}, \cdots, \eta_{n}$. Thus $\sum^{\prime} c_{i} \xi^{i}=\sum_{j=1}^{n} \sum^{\prime} R_{j} \eta_{i} \xi^{i}=\sum^{\prime}\left(\sum_{j=1}^{n} R_{j i} \eta_{j}\right) \xi^{i}$. Since the representation (5) is unique for $n=N$ we have

$$
\begin{equation*}
c_{i}=\sum_{j=1}^{n} R_{j \eta} \eta_{j} \tag{7}
\end{equation*}
$$

The left side of (7) is void of $\eta$ 's so that all $R_{j i}$ 's and $c_{i}$ 's equal 0 . Thus $\operatorname{dim} R^{\prime} / \mathfrak{F}^{\prime}=N$ ! and since $\vee \cong R / \mathfrak{B} \cong R^{\prime} / \mathfrak{F}^{\prime}, \operatorname{dim} \vee=N$ !. Now $\prod_{j=1}^{N-1} \xi_{j}^{N-j}$ has degree $N(N-1) / 2$ and $\in \mathfrak{F}^{\prime}$. This implies that there exists a homogeneous polynomial of degree $N(N-1) / 2 \notin \mathfrak{P}$. Hence $\operatorname{deg} \vee=N(N-1) / 2$.

If $n=N-1$ then we distinguish two cases. If $\sum_{i=1}^{N} y_{i} \neq 0$, then it follows from [1, Theorem 2.2] that there exists an orthogonal transformation $x=T x^{\prime}$ such that $g\left(x^{\prime}\right)=f\left(T x^{\prime}\right)$ is independent of $x_{n}^{\prime}$ and satisfies the equation

$$
\begin{equation*}
g\left(x_{p}^{\prime}\right)=\frac{1}{N} \sum_{i=1}^{N} g\left(x_{p}^{\prime}+t y_{p, i}\right), \tag{8}
\end{equation*}
$$

where $y_{i}=T y_{i}^{\prime}, x_{p}^{\prime}=\left(x_{1}^{\prime}, \cdots, x_{n-1}^{\prime}\right), y_{p i}^{\prime}=\left(y_{t 1}^{\prime}, \cdots, y_{i, n-1}^{\prime}\right)$. Let $\bigvee^{\prime}$ denote the solution space of (8). Clearly $\operatorname{deg} \vee=\operatorname{deg} \bigvee^{\prime}$, $\operatorname{dim} \vee$ $=\operatorname{dim} \bigvee^{\prime}$. It follows from (2) that $\operatorname{deg} \vee=\operatorname{deg} \bigvee^{\prime}<N(N-1) / 2$, $\operatorname{dim} \vee=\operatorname{dim} \bigvee^{\prime}<N!$. If $\sum_{i=1}^{N} y_{i}=0$, then define
$\bar{x}=\left(x_{1}, \cdots, x_{n}, x_{n+1}\right), y_{i}=\left(y_{i 1}, \cdots, y_{i n}, 1\right)(1 \leqq i \leqq N), F(\bar{x})=f(x)$.
We notice that $\sum_{i=1}^{N} \bar{y}_{i} \neq 0$. It therefore follows from [3, Theorem 2.2] that $V$ is identical with the solution space $\bar{V}$ of

$$
\begin{equation*}
F(\bar{x})=\frac{1}{N} \sum_{i=1}^{N} F\left(\bar{x}+t \bar{y}_{i}\right) \tag{9}
\end{equation*}
$$

Equation (9) is included in Case (a). It follows that deg $V=\operatorname{deg} \nabla$ $=N(N-1) / 2, \operatorname{dim} \vee=\operatorname{dim} \bar{V}=N!$.

## References

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