# ON CONFORMALLY-FLAT RIEMANNIAN SPACE OF CLASS ONE 

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1. The purpose of this paper is two-fold; first, to obtain necessary and sufficient conditions that a conformally-flat orientable Riemannian space $C_{n}^{1}$ with $n \geqq 3$ be of class one; second, to obtain a normal form for the metric of such a space. A Riemannian space $V_{n}$ is a conformally-flat space $C_{n}$ if there exists a scalar function $\sigma$ such that the product $\sigma g_{i j}$ of $\sigma$ and the fundamental tensor $g_{i j}$ has zero curvature; it is of class one if it is isometrically embeddable as a hypersurface in a Euclidean space. The conformal flatness property can be expressed by the condition that $s_{i}=\frac{1}{2} \partial_{i} \log \sigma$ is related to the curvature tensor by

$$
\begin{equation*}
R_{h i j k}+g_{h k} s_{i j}+g_{i j} s_{h k}-g_{h j} s_{i k}-g_{i k} s_{h j}=0 \tag{1}
\end{equation*}
$$

where

$$
\begin{equation*}
s_{i j}=\nabla_{i} s_{j}-s_{i} s_{j}+\frac{1}{2} g_{i j} s_{k} s^{k} . \tag{2}
\end{equation*}
$$

The condition of class one, for an orientable space, implies the existence of a (second fundamental) symmetric tensor $b_{i j}$ such that

$$
\begin{equation*}
R_{h i j k}=b_{h j} b_{i k}-b_{h k} b_{i j} ; \quad \nabla_{i} b_{j k}-\nabla_{j} b_{i k} . \tag{3}
\end{equation*}
$$

The converse is true in the local sense.
The algebraic relations (1), (3) lead to a result of J. A. Schouten [1] which states that $n-1$ of the eigenvalues of $b_{i j}$ at each point of a $C_{n}^{1}$ are equal. Denote this value by $\rho$, the remaining eigenvalue by $\tilde{\rho}$ and denote by $e_{i}$ the eigenvector of $b_{i j}$ belonging to $\tilde{\rho}$. The quantities $\rho, \tilde{\rho}$ are also known as the principal normal curvatures and $e_{i}$ the unit vector tangential to the line of curvature corresponding to $\tilde{\rho}$. Assume that $\tilde{\rho} \neq \rho \neq 0$. Then

$$
\begin{equation*}
b_{i j}=\rho g_{i j}+(\tilde{\rho}-\rho) e_{i} e_{j} \tag{4}
\end{equation*}
$$

and by contraction of (3) we express the Ricci tensor in terms of $g_{\imath j}$ and $e_{i} e_{j}$; or in $g_{i j}$ and $b_{i j}$. We thus find (a), (b) below; by the second identity in (3) together with the property of conformal flatness we find (c) below.
(a)

$$
b_{i j}=-\frac{1}{n-2}\left(\frac{1}{\rho} R_{i j}+\tilde{\rho} g_{i j}\right),
$$

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(b)
(c)

$$
\begin{aligned}
R_{h i j k}= & \rho^{2}\left(g_{h j} g_{i k}-g_{h k} g_{i j}\right) \\
& +\rho(\tilde{\rho}-\rho)\left(g_{h j} e_{i} e_{k}+g_{i k} e_{h} e_{j}-g_{h k} e_{i} e_{j}-g_{i j} e_{h} e_{k}\right) \\
& \partial_{i} \rho \text { is proportional to } e_{i} .
\end{aligned}
$$

These formulas are due to Verbickii [2]; he also showed that the existence of scalar functions $\rho, \tilde{\rho}$ and a unit vector field $e_{i}$ such that (b), (c) hold is sufficient that $V_{n}$ be locally a $C_{n}^{1}$.
2. The above results are most easily verified by choosing an orthonormal basis for the tangent space consisting of eigenvectors of $b_{i j}$; we choose $e_{i}$ to be the first of these. Then $g_{i j}$ and $b_{i j}$ take diagonal forms with respect to this basis,

$$
\left[g_{i j}\right]=\operatorname{diag}(1,1, \cdots), \quad\left[b_{i j}\right]=\operatorname{diag}(\tilde{\rho}, \rho, \rho, \cdots)
$$

For brevity we only give the first two diagonal elements:

$$
\left[g_{i j}\right]=\operatorname{diag}(1,1) ; \quad\left[b_{i j}\right]=\operatorname{diag}(\tilde{\rho}, \rho) ; \quad\left[e_{i} e_{j}\right]=\operatorname{diag}(1,0) .
$$

Then

$$
\left[R_{i j}\right]=\operatorname{diag}\left(-(n-1) \rho \tilde{\rho}, \quad-\left\{(n-2) \rho^{2}+\rho \tilde{\rho}\right\}\right) ;
$$

and among $g_{i j}, b_{i j}, R_{i j}, e_{i} e_{j}$ any one can be written as a linear combination of any two. This is how (5) below is proved.

Theorem 1. If $a V_{n}$ is $a C_{n}^{1}$, then there are scalars $E \neq 0$ and $F$ such that

$$
\begin{equation*}
R_{h i j k}=E\left(R_{h j} R_{i k}-R_{h k} R_{i j}\right)+F\left(g_{h j} g_{i k}-g_{h k} g_{i j}\right) . \tag{5}
\end{equation*}
$$

Conversely, if in a $C_{n}$ scalars $E \neq 0, F$ exist such that (5) holds, where

$$
\begin{equation*}
R=-\frac{n-1}{(n-2) E}+(n-1)(n-2) F \tag{6}
\end{equation*}
$$

then $C_{n}$ is a $C_{n}^{1}$.
Proof of the converse. Contraction of (5) with $g^{h k}$ gives

$$
R_{i j}=E R_{j}^{k} R_{i k}-E R R_{i j}-(n-1) F g_{i j} .
$$

Hence, every eigenvalue $\lambda$ of $R_{i j}$ satisfies

$$
\lambda=E \lambda^{2}-E R \lambda-(n-1) F ;
$$

which, by (6), has as its solutions

$$
\lambda=\frac{-1}{(n-2) E}, \quad \tilde{\lambda}=(n-1)(n-2) F
$$

By (6), $\lambda$ has multiplicity $n-1 ; \tilde{\lambda}$ has multiplicity 1 . The situation is now easily reduced to that of a $C_{n}$ involving a second fundamental tensor $b_{i j}$ which is a linear combination of $g_{i j}$ and $e_{i} e_{j}$, where $e_{i}$ is a unit eigenvector of $R_{i j}$ associated with $\bar{\lambda}$. It is a simple exercise to relate the $\lambda, \tilde{\lambda}$ above with $\rho, \tilde{\rho}$ resulting in

$$
\lambda=-\left\{(n-2) \rho^{2}+\rho \tilde{\rho}\right\}, \quad \tilde{\lambda}=-(n-1) \rho \tilde{\rho} .
$$

We thus obtain
Theorem 2. If $a V_{n}$ is $a C_{n}^{1}$, then

$$
\begin{equation*}
R_{h i j k}=\frac{R_{h j} R_{i k}-R_{h k} R_{i j}}{(n-2)\left\{(n-2) \rho^{2}+\rho \tilde{\rho}\right\}}-\frac{\rho \tilde{\rho}}{n-2}\left(g_{h j} g_{i k}-g_{h k} g_{i j}\right), \tag{7}
\end{equation*}
$$

where $\tilde{\rho} \neq \rho \neq 0$ are scalars. Conversely if a $C_{n}$ satisfies (7), then $C_{n}$ is a $C_{n}^{1}$ if $R=-(n-1)\left\{(n-2)^{2} \rho^{2}+2 \rho \tilde{\rho}\right\}$.
3. Theorem 1 of $\S 2$ can be applied to find the metric of a $C_{n}^{1}$. This can be done by taking the fundamental tensor of a $C_{n}$ in the form $g_{i i}=1 / \phi^{2}, g_{i j}=0,(i \neq j)$, and looking for the general form of $\phi$ for which the equations (5) and (6) are satisfied. The fundamental tensor is then obtained in a canonical form as

$$
\begin{align*}
& g_{i i}=1 /[f(U)]^{2}, \quad g_{i j}=0, \quad(i \neq j), \quad \text { where } U=\sum_{i}\left(X^{i}\right)^{2}+c  \tag{8}\\
& \text { and } X^{i}=a x^{i}+b^{i} \text { with } a \neq 0, b, c \text { constants, }
\end{align*}
$$

where $f$ is any real analytical function of $U$ subject to a restriction stated below. The normal form of the metric is now obtained by taking $a=1, b^{i}=c=0$ in (8).

This metric and some properties which have been obtained in previous papers [3], [4] are stated in the following theorem:

Theorem 3. The coordinates of any $C_{n}^{1}$ may be so chosen that its metric assumes the normal form

$$
\begin{equation*}
d s^{2}=\sum_{i}\left(d x^{i}\right)^{2} /[f(\theta)]^{2}, \quad \theta=\sum_{i}\left(x^{i}\right)^{2}, \tag{9}
\end{equation*}
$$

where $f$ is any real analytic function of $\theta$ subject to the restriction

$$
(n-1) f f^{\prime}+\theta f f^{\prime \prime}-(n-1) \theta f^{\prime 2} \neq 0, \quad\left(f^{\prime}=d f / d \theta, \text { etc. }\right) .
$$

If $\rho \neq 0$ and $\tilde{\rho}$ are the eigenvalues of multiplicity $n-1$ and 1 respectively of the second fundamental tensor of the space (9), then

$$
\begin{equation*}
\rho^{2}=4 f^{\prime}\left(f-\theta f^{\prime}\right), \quad \rho \tilde{\rho}=4\left(f f^{\prime}+\theta f f^{\prime \prime}-\theta f^{\prime 2}\right) \tag{10}
\end{equation*}
$$

The eigenvector $e_{i}=x^{i} / \theta^{1 / 2} f$ corresponding to $\tilde{\rho}$ is orthogonal to the hypersurface having constant curvature $\bar{k}^{2}=f^{2} / \theta$. If the $C_{n}^{1}$ is symmetric in the sense of Cartan, then either $f=a \theta+b$ (a space of constant curvature) or $f=c \theta^{1 / 2}$, where $a, b, c$ are nonzero constants. In the second case $e_{1}$ is a parallel vector field and the $C_{n}^{1}$ is reducible.

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