

# OSCILLATION CRITERIA FOR NONLINEAR MATRIX DIFFERENTIAL INEQUALITIES

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ABSTRACT. Oscillation criteria are established for nonlinear matrix differential equations of the form  $[A(x)V']' + B(x, V, V')V = 0$  and associated differential inequalities. The hypothesis used recently by E. C. Tomastik, that  $A$  and  $B$  are positive definite, is weakened to the following:  $A$  is positive semidefinite.

Oscillation criteria for the matrix differential equation

$$(1) \quad LV = [A(x)V']' + B(x, V, V')V = 0,$$

and more generally for the inequality  $V^T L V \leq 0$  (as a form), will be derived by a technique different from that given recently by Tomastik [3]. It will be assumed that  $A$ ,  $B$ , and  $V$  are  $m \times m$  matrix functions,  $A(x)$  is symmetric, positive semidefinite, and continuous on an interval  $[a, \infty)$ , and  $B(x, V, V')$  is symmetric and continuous for  $x$  on  $[a, \infty)$  and for all values of the entries of  $V$  and  $V'$ . Although Tomastik requires  $B(x, V, V')$  to be positive definite on  $a \leq x < \infty$  for every matrix  $V$  with  $\det V \neq 0$ , we require only that  $B(x, V, V')$  satisfies condition (2) below. As already noted, we have weakened the positive definiteness of  $A(x)$  to positive semidefiniteness. The technique used here has the advantage that it can be adapted [2], [1, Chapter 5] to partial differential inequalities of elliptic or parabolic type. As in [3] it is assumed that every solution of (1) can be continued to  $x = \infty$ .

**THEOREM 1.** *The inequality  $V^T L V \leq 0$  is oscillatory if  $A(x)$  is bounded above and there exists a diagonal element  $B_{ii}$  of  $B$  such that*

$$(2) \quad \int_a^\infty B_{ii}[x, V(x), V'(x)]dx = +\infty$$

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for every differentiable matrix  $V(x)$  with  $\det V(x) \neq 0$  for all sufficiently large  $x$ .

PROOF. Suppose to the contrary that  $V^T L V \leq 0$  is not oscillatory, i.e. [3] there exists a number  $b \geq a$  and a prepared matrix  $V(x)$  satisfying  $V^T L V \leq 0$  such that  $\det V(x) \neq 0$  in  $(b, \infty)$ . Then a unique solution  $w(x)$  of  $u(x) = V(x)w(x)$  exists in  $(b, \infty)$  for any  $m$ -vector  $u(x)$ . The following identity is easily verified by differentiation for any piecewise  $C^1$  vector function  $u$ :

$$\begin{aligned} & (Vw')^T A V w' + [(Vw)^T A V' w]' \\ &= u^{T'} A u' - u^T B u + u^T L V w + w^T (V^T A V' - V^{T'} A V) w'. \end{aligned}$$

The last term is identically zero since  $V$  is prepared [3]. Since  $V^T L V \leq 0$ , it follows that

$$(3) \quad F[u, V] \equiv \int_b^c [u^{T'} A(x) u' - u^T B(x, V, V') u] dx \geq 0$$

if  $u$  is any piecewise  $C^1$  vector function satisfying  $u(b) = u(c) = 0$  ( $b < c$ ). In particular, choose  $u$  to be  $u_i$ , where

$$\begin{aligned} u_i(x) &= 0 && \text{if } a \leq x \leq b \\ &= e_i(x - b) && \text{if } b < x \leq b + 1 \\ &= e_i && \text{if } b + 1 < x \leq c - 1 \\ &= e_i(c - x) && \text{if } c - 1 < x \leq c \end{aligned}$$

( $c > b + 2$ ) and  $e_i$  is the unit vector with 1 in the  $i$ th position and 0 elsewhere. Then

$$\begin{aligned} F(u_i, V) &\leq 2\alpha - \frac{\beta}{3} - \int_{b+1}^{c-1} B_{ii}(x, V, V') dx \\ &\quad - \int_{c-1}^c B_{ii}(x, V, V')(c - x)^2 dx \end{aligned}$$

where  $\alpha$  is an upper bound for  $A(x)$  on  $[b, \infty)$  and  $\beta$  is a lower bound for  $B(x, V(x), V'(x))$  on  $[b, b + 1]$ . In view of the hypothesis (2), there exists a number  $c_0$  such that

$$F(u_i, V) \leq - \int_{c-1}^c B_{ii}(x, V, V')(c - x)^2 dx$$

for all  $c \geq c_0$ . Define

$$g(w, x) = \int_w^x B_{ii}(t, V(t), V'(t))dt, \quad w \leq x.$$

We assert there exists a number  $c \geq c_0$  such that  $g(c-1, x) > 0$  for all  $x > c-1$ . In fact,  $g(c_0-1, x)$  has a largest zero  $x = c-1$  by (2) ( $c \geq c_0$ ) and  $g(c_0-1, x) = g(c-1, x) > 0$  for  $x > c-1$ . An easy integration by parts shows that

$$\int_{c-1}^c B_{ii}(x, V, V')(c-x)^2 dx = 2 \int_{c-1}^c (c-x)g(c-1, x)dx > 0.$$

Hence  $F[u_i, V] < 0$ , contradicting (3).

Theorem 1 remains true if (2) is replaced by the obviously stronger condition

$$(4) \quad \int_a^\infty \text{tr } B[x, V(x), V'(x)]dx = +\infty,$$

where  $\text{tr } B$  denotes the trace of  $B$ . In the case that  $B$  is positive definite, Theorem 1 also remains true if (2) is replaced by the equivalent condition

$$(5) \quad \int_a^\infty \lambda[x, V(x), V'(x)]dx = +\infty$$

where  $\lambda$  denotes the largest eigenvalue of  $B$ . In general, it is clear that (4) can be replaced by (5) provided also  $\int_a^\infty \lambda_i(x)dx$  is finite for every negative eigenvalue  $\lambda_i$  of  $B[x, V(x), V'(x)]$ .

If  $A$  is the identity matrix and  $B$  is positive definite, the hypothesis (5) is needed only for matrices  $V(x)$  such that the smallest eigenvalue of  $V^T(x)V(x)$  is bounded away from zero for large  $x$ , as shown by Tomastik [3].

**COROLLARY.** *The equation  $LV=0$  is oscillatory if  $A$  and  $B$  are positive definite,  $A$  is bounded above, and (5) holds for every differentiable matrix  $V$  with  $\det V(x) \neq 0$  for all sufficiently large  $x$ .*

This is an obvious special case of Theorem 1; it is also a specialization of Tomastik's Theorem 3 to the case that  $A$  is bounded above.

The following generalization of Theorem 1 can be proved in the same way.

**THEOREM 2.**  *$V^T L V \leq 0$  is oscillatory if for arbitrary  $b \geq a$  there exists a number  $c$  ( $c > b$ ), an integer  $i$ , and a piecewise  $C^1$  function  $\phi$  on  $[b, c]$  such that  $\phi(b) = \phi(c) = 0$  and*

$$\int_b^c \{ \phi'^2(x) A_{ii}(x) - \phi^2(x) B_{ii}[x, V(x), V'(x)] \} dx < 0$$

for every differentiable matrix  $V(x)$  with  $\det V(x) \neq 0$  on  $[b, \infty)$ .

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