

AN EXACT SOLUTION OF THE NONLINEAR DIFFERENTIAL EQUATION

$$\ddot{y} + p(t)y = q_m(t)/y^{2m-1}$$

JAMES L. REID

ABSTRACT. An exact solution of the nonlinear differential equation $\ddot{y} + p(t)y = q_m(t)/y^{2m-1}$ is found to be $y = [u^m + c(m-1)^{-1}W^{-2}v]^{1/m}$ if $q_m(t) = c(uv)^{m-2}$. u and v are independent solutions of $\ddot{y} + p(t)y = 0$ and W is their Wronskian.

E. Pinney [1] has shown that the nonlinear differential equation

$$(1) \quad \ddot{y} + p(t)y = c/y^3$$

has exact solutions of the form

$$(2) \quad y = [u^2 + cW^{-2}v^2]^{1/2}$$

when $y(t_0) = y_0 \neq 0$ and $\dot{y}(t_0) = \dot{y}_0$, for c an arbitrary constant and $p(t)$ given. The functions u and v are independent solutions of the linear equations

$$(3) \quad \ddot{y} + p(t)y = 0$$

for which $u(t_0) = y_0$, $\dot{u}(t_0) = \dot{y}_0$, $v(t_0) = 0$, $\dot{v}(t_0) \neq 0$, where their Wronskian $W = u\dot{v} - v\dot{u} = \text{const} \neq 0$.

With m real and finite, and $m \neq 0, 1$, it is possible to show that

$$(4) \quad y = [u^m + c(m-1)^{-1}W^{-2}v^m]^{1/m}$$

is an exact solution of

$$(5) \quad \ddot{y} + p(t)y = q_m(t)/y^{2m-1}$$

provided that u and v remain independent solutions of (3) and subject to the same conditions above, except that v_0 need not be zero, and provided that

$$(6) \quad q_m(t) = c(uv)^{m-2}.$$

The proof is simple and will be omitted.

Although $q_m(t)$ clearly restricts the general class of nonlinear equations implied by (5), important physical problems occur with

Received by the editors April 14, 1970.

AMS 1969 subject classifications. Primary 1302, 1304; Secondary 7034, 7834.

Key words and phrases. Exact solution, nonlinear differential equations, homogeneous nonlinear equation, initial conditions.

Copyright © 1971, American Mathematical Society

initial conditions such as to make the solution (4) physically interesting. Moreover, it is interesting to regard the use of uv in $q_m(t)$ as a method for generating nonlinear differential equations, for which an exact solution is (4). The arbitrary choice of $p(t)$ allows a wide range of possibilities. Taking $p(t) = \pm \omega^2 = \text{const}$ provides two immediate examples:

$$(7) \quad \ddot{y} + \omega^2 y = c_1 (\sin \omega t \cos \omega t)^{m-2} / y^{2m-1},$$

$$(8) \quad \ddot{y} - \omega^2 y = c_1 / y^{2m-1},$$

having solutions

$$(9) \quad y = [a^m \cos^m \omega t + c_m b^m \sin^m \omega t]^{1/m},$$

$$(10) \quad y = [a^m e^{m\omega t} + c'_m b^m e^{-m\omega t}]^{1/m},$$

respectively, where

$$c_m = c_1 / [\omega^2 (ab)^m (m-1)] \quad \text{and} \quad c'_m = c_1 / [4\omega^2 (ab)^m (m-1)].$$

Constants a and b are determined by the initial conditions, while c_1 , equal to $c(ab)^{m-2}$, is essentially arbitrary.

REFERENCES

1. E. Pinney, *The nonlinear differential equation $y'' + p(x)y + cy^{-3} = 0$* , Proc. Amer. Math. Soc. 1 (1950), 681. MR 12, 336.

CLEMSON UNIVERSITY, CLEMSON, SOUTH CAROLINA 29631