FURTHER EXTENDING A COMPLETE CONVEX METRIC

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ABSTRACT. A metric D is convex if for every two points x, z there is a third point y such that D(x, y) + D(y, z) = D(x, z). A generalized continuum is a connected, locally compact, metric space. Let M_1 be a nonempty space with a complete convex metric D_1 and let M_2 be a nonempty locally connected generalized continuum. The following condition is shown to be necessary and sufficient for there to exist a complete convex metric for $M_1 \cup M_2$ that extends $D_1: M_1 \cap M_2$ is a nonempty subspace of both M_1 and M_2 which is closed in M_3 and whose M_2 boundary is closed in M_1 .

- 1. Introduction. In this paper we continue the investigation of a previous article [5], regarding the extendability of complete convex metrics. In [5] basic definitions are provided, and a sufficient condition is obtained for the extension of a given complete convex metric across a locally connected generalized continuum. The aim of the present paper is to weaken that sufficient condition so that it is also necessary, as follows: if M_1 is a space with a complete convex metric D_1 and M_2 is a locally connected generalized continuum, a necessary and sufficient condition that D_1 can be extended to a complete convex metric for $M_1 \cup M_2$ is that $M_1 \cap M_2$ be a nonempty subspace of both M_1 and M_2 which is closed in M_2 and whose M_2 boundary is closed in M_1 . The following conventions, in addition to those to be mentioned in §2, will be observed throughout this paper. All given topological spaces are assumed to be nonempty. If D is a metric for a space M, we will write $D(p; \varepsilon)$ to denote the open ball $\{x: D(p, x) < \varepsilon\}$ and $\overline{D}(p; \varepsilon)$ for the closed ball $\{x: D(p, x) \le \varepsilon\}$.
- 2. The union topology. The union of two topological spaces M_1 and M_2 whose topologies agree on their intersection will in this paper be considered to have a certain natural topology, namely the collection τ_0 of all

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sets Q in $M_1 \cup M_2$ such that $Q \cap M_i$ is open in M_i for i=1, 2. Seen otherwise, τ_0 is the largest topology on $M_1 \cup M_2$ for which M_1 and M_2 are subspaces. For the spaces M_1 and M_2 in the propositions of this section, we assume that their topologies do agree on their intersection and that τ_0 has the meaning described above. The simple proofs of these propositions are omitted. The claim of τ_0 to naturalness, at least for the purposes of this paper, is given by (2.1).

PROPOSITION 2.1. If $M_1 \cap M_2$ is M_2 closed, and if the M_2 boundary of $M_1 \cap M_2$ is M_1 closed, then $M_1 \setminus M_2$ and $M_2 \setminus M_1$ are τ_0 separated sets.

PROPOSITION 2.2. If $M_1 \backslash M_2$ and $M_2 \backslash M_1$ are separated sets in some topology τ on $M_1 \cup M_2$ for which M_1 and M_2 are subspaces, then $\tau = \tau_0$.

PROPOSITION 2.3. If R_i is a M_i neighborhood of a point x for i=1, 2, then x is τ_0 interior to $R_1 \cup R_2$.

PROPOSITION 2.4. If M_1 and M_2 are locally compact spaces such that $M_1 \cap M_2$ is closed in M_2 and the M_2 boundary of $M_1 \cap M_2$ is closed in M_1 , and if $M_1 \cup M_2$ is Hausdorff, then $M_1 \cup M_2$ is locally compact.

An example of the union of two locally connected generalized continua in the plane sheds light on both (2.4) and (2.5). If $M_1=E^1\times (-\infty,0]$ and $M_2=(-\infty,0)\times E^1$, we observe that the origin has neither a conditionally compact neighborhood nor a countable local base with respect to τ_0 .

PROPOSITION 2.5. If $M_1 \cup M_2$ is both Hausdorff and first countable, then $B \cap M_1$ is M_1 closed, where B is the M_2 boundary of $M_1 \cap M_2$.

PROPOSITION 2.6. Let M_1 be a space with a complete metric D_1 and let M_2 be any topological space. In order that $M_1 \cup M_2$ be a connected space and admit some metric D_3 extending D_1 , it is necessary that $M_1 \cap M_2$ be a nonempty subspace of both M_1 and M_2 which is closed in M_2 and that the M_2 boundary of $M_1 \cap M_2$ be closed in M_1 .

3. Segmented convex metrics. A metric is segmented convex if each pair of its points are joined by at least one segment. It is clear that the segmented convex metrics occupy an intermediate position between the convex and the complete convex metrics, in that every segmented convex metric is convex and, by a well-known theorem of Menger [8], every complete convex metric is segmented convex. The rationals in E^1 with the euclidean metric form a convex metric space that does not admit a segmented convex metric. Similarly, not every space that admits a segmented convex metric must admit a complete convex metric; indeed, we can embed a metric space of first category isometrically as a closed subset of a

normed linear space, which cannot therefore be topologically complete [1]. However, we observe the following characterization.

THEOREM 3.1. If M is a locally compact space, the following statements are equivalent:

- (i) M is a locally connected generalized continuum.
- (ii) M admits a complete convex metric.
- (iii) M admits a segmented convex metric.

PROOF. The proofs for (i) \Rightarrow (ii) and for (ii) \Rightarrow (iii) are given in [9] and [8] respectively. For (iii) \Rightarrow (i), the admission of a segmented convex metric implies that M is connected and locally connected, since open balls are connected. Thus, M is a locally connected generalized continuum.

In this paper, use is made of segmented convex metrics through the following theorem.

THEOREM 3.2. In a locally compact space with a segmented convex metric, every compact metric ball is a Peano continuum.

PROOF. The proof follows the general scheme of a proof in Hall and Spencer [6, Theorem V. 6.23].

COROLLARY 3.3. In a locally compact space with a complete convex metric, every closed metric ball is a Peano continuum.

Proof. Every closed metric ball is compact [7].

4. Extension theorems. The following theorem is a stronger statement of Theorem 1 of [5].

Theorem 4.1. Let M_1 be a space with complete convex metric D_1 and let M_2 be a locally connected generalized continuum with complete convex metric D_2 , whose intersection with M_1 is a nonempty, compact subspace of both M_1 and M_2 . Then for any $\varepsilon > 0$ and for any two nonempty subsets C and C and C with C with C and C are C and C and C and C are C and C and C are C and C are C and C are C and C and C are C are C and C are C are C and C are C are C and C are C and C are C and C are C are C and C are C and C are C and C are C are C and C are C are C and C are C and C are C are C and C are C are C are C and C are C are C and C are C are C and C are C and C are C are C and C are C are C are C and C are C and C are C are C are C and C are C are C and C are C are C are C and C are C are C are C

PROOF. Let $\delta = D_2(C, H \cup (M_1 \cap M_2))$. The proof of Theorem 1 in [5], following the construction of Bing [2], now suffices for the present theorem, if the initial function F(x) in that proof is chosen to have a first derivative which always exceeds both 1 and ε/δ . For use in the proof of (4.3), we note here that the function $D_0(x, y)$ defined in [5] is never less than either $D_2(x, y)$ or $(\varepsilon/\delta)D_2(x, y)$. From this fact and the definition of the metric D_3 given in [5], the desired properties of D_3 readily follow.

Given a complete convex metric for a locally compact space, not every compact set need be contained in a compact set on which the metric is convex; in fact, there is a noncompact generalized continuum X in the plane that contains three points and has a complete convex metric which is not convex on any closed proper subset of X containing those three points [4]. The following theorem shows, however, that a locally connected generalized continuum can be remetrized with a complete convex metric for which the property in question will in fact hold.

THEOREM 4.2. Let M be a locally connected generalized continuum with complete convex metric D. Given any point p of M, there is a complete convex metric E for M that is convex on $\overline{D}(p;n)$ and has the property that if D(p,x)=n then $E(x,D(p;n-\frac{1}{2}))\geq 1$, for $n=1,2,\cdots$.

PROOF. For each n, we see from (3.3) that $P_n = \bar{D}(p;n)$ is a Peano continuum; moreover, the two sets $C_n = \{x : D(p,x) = n\}$ and $H_{n-1} = \{x : D(p,x) = n - \frac{1}{2}\}$ are compact and disjoint. By (4.1) there is a convex metric E_1 for P_1 such that $E_1(C_1, H_0) \ge 1$ if $C_1 \ne \emptyset$. By repeated use of (4.1), a sequence E_1, E_2, \cdots of convex metrics respectively for P_1, P_2, \cdots may be defined inductively so that E_{n+1} extends E_n and $E_n(C_n, H_{n-1}) \ge 1$ whenever $C_n \ne \emptyset$. If E is the union of all these metrics E_n , then E is a segmented convex metric for the space M. Moreover, since $E(C_n, p) \ge n$ as long as $C_n \ne \emptyset$ and consequently every E bounded set is also D bounded, then E is complete.

Theorem 4.3. Let M_1 be a space with a complete convex metric D_1 and let M_2 be a locally connected generalized continuum. In order for there to be a complete convex metric for $M_1 \cup M_2$ that extends D_1 , it is necessary and sufficient that $M_1 \cap M_2$ be a nonempty subspace of both M_1 and M_2 which is closed in M_2 and that the M_2 boundary of $M_1 \cap M_2$ be closed in M_1 .

PROOF. Necessity is given by (2.6). For the proof of sufficiency, let p be in $M_1 \cap M_2$ and let D be any complete convex metric for M_2 . By (4.2) there is a complete convex metric D_2 for M_2 whose restriction D_2^n to $P_n = \bar{D}(p;n)$ is convex, and which has the property that if D(p,x)=n then $D_2(x, \bar{D}(p;n-\frac{1}{2})) \ge 1$, for $n=1,2,\cdots$.

Since $M_1 \cap M_2$ is closed in M_2 , then $M_1 \cap P_1$ is compact. Hence, (4.1) may be applied by replacing M_1 , D_1 , M_2 , and D_2 by M_1 , D_1 , P_1 , and D_2^1 respectively in the hypothesis; let D_0^1 and D_3^1 be the D_0 and D_3 given respectively by the proof and conclusion. (The sets C and H in (4.1) will not be used here.) We note that $D_0^1(u, v) \ge D_2^1(u, v) = D_2(u, v)$ whenever $D_0^1(u, v)$ is defined, and that if x lies in $P_1 \setminus M_1$ and y in M_1 , $D_3^1(x, y)$ is defined to be the infimum of sums $D_0^1(x, a) + D_1(a, y)$ for certain points a in the P_1 boundary of $M_1 \cap P_1$.

Proceeding inductively, suppose that D_3^n is a complete convex metric for $M_1 \cup P_n$ which extends D_1 . Again apply (4.1) by replacing M_1 , D_1 , M_2 , and D_2 by $M_1 \cup P_n$, D_3^n , P_{n+1} , and D_2^{n+1} respectively, and obtain D_0^{n+1} and D_3^{n+1} in place of D_0 and D_3 . We have that D_3^{n+1} is a complete convex metric for $M_1 \cup P_n$ that extends D_3^n , with the property that whenever $D_3^{n+1}(x, y) < D_2^{n+1}(x, y)$ for points x, y of $P_{n+1} \setminus (M_1 \cup P_n)$, then x and y have a D_3^{n+1} between point in $M_1 \cup P_n$. Again, we should note that $D_0^{n+1}(u, v) \ge D_2^{n+1}(u, v) = D_2(u, v)$ whenever $D_0^{n+1}(u, v)$ is defined; moreover, for points x in $P_{n+1} \setminus (M_1 \cup P_n)$ and y in $M_1 \cup P_n$, the value $D_3^{n+1}(x, y)$ is defined to be an infimum of sums $D_0^{n+1}(x, a) + D_3^n(a, y)$ for certain points a in the P_{n+1} boundary of $(M_1 \cup P_n) \cap P_{n+1}$.

Define D_3 as the union of the metrics D_3^n , and for convenience let $P_0 = M_1 \cap P_1$ and $D_3^0 = D_1$. It is immediate that D_3 is a segmented convex metric which extends D_1 . Assertions (iv) and (vi) below complete the proof.

- (i) For points x in P_n , y in M_1 , and for $\eta > 0$, there is a point z in $M_1 \cap P_n$ such that $D_3^n(x, y) + \eta > D_2(x, z) + D_1(z, y)$. If x is not in M_1 , then z can be chosen in the P_n boundary of $M_1 \cap P_n$.
- (ii) For points x in P_{n+k} , y in $M_1 \cup P_k$ $(k=0, 1, \dots; n=1, 2, \dots)$, and for $\eta > 0$, there is a point z in $(M_1 \cup P_k) \cap P_{n+k}$ such that $D_3^{n+k}(x, y) + \eta > D_2(x, z) + D_3^k(z, y)$.
 - (iii) D_2 is topologically equivalent to D_3 restricted to M_2 .
 - (iv) D_3 is a metric for $M_1 \cup M_2$.
- (v) If point t is in P_n and v is in $M_2 \backslash P_{n+1}$ for some n > 0, there is a D_3 between point u of t and v such that $D(p, u) = n + \frac{1}{2}$ and P_n contains no D_3 between point of u and v.
 - (vi) D_3 is complete.
- For (i) let x in P_n , y in M_1 , and $\eta > 0$ be given. If x is in M_1 , then x itself may be taken for z since $D_3^n(x,y) = D_1(x,y)$. Therefore, with the assumption that x is not in M_1 , the proof of (i) is given by induction on n. If x is in $P_1 \setminus M_1$, then by the definition of $D_3^1(x,y)$ there is a point z on the P_1 boundary of $M_1 \cap P_1$ such that $D_3^1(x,y) + \eta > D_0^1(x,z) + D_1(z,y) \ge D_2(x,z) + D_1(z,y)$. Proceeding inductively, assume that (ii) holds for n = k and arbitrary $\eta' > 0$, and let $x \in P_{k+1} \setminus (M_1 \cup P_k)$ with $\eta > 0$. From the definition of $D_3^{k+1}(x,y)$ there is a point z' on the P_{k+1} boundary of $(M_1 \cup P_k) \cap P_{k+1}$ such that
- (1) $D_3^{k+1}(x, y) + \eta/2 > D_0^{k+1}(x, z') + D_3^k(z', y) \ge D_2(x, z') + D_3^k(z', y)$.

If z' is in $M_1 \cap P_{k+1}$, then z' is on the P_{k+1} boundary of $M_1 \cap P_{k+1}$, and since $D_3^k(z', y) = D_1(z', y)$, inequality (1) shows that z = z' satisfies (i). If however z' is not in M_1 , then z' is in P_k . Thus by the induction hypothesis for the points z' and y, there is a point z on the P_k boundary of $M_1 \cap P_k$, hence on

the P_{k+1} boundary of $M_1 \cap P_{k+1}$, such that

$$D_3^k(z', y) + \eta/2 > D_2(z', z) + D_1(z, y).$$

Upon combining this inequality with (1) and the triangle inequality, we arrive at the desired inequality in x, y, and z, completing the induction.

Assertion (ii) can be proved by double induction by using (i) as the initialization k=0 and an argument similar to the proof of (i) to complete the induction.

To prove for (iii) that D_2 and D_3 give the same topology on M_2 , first let $D_3(x; \varepsilon)$ be given with x a point of M_2 . Since by [7] the set $\bar{D}_2(x; \varepsilon)$ is compact, it lies in P_n for some n. But since $D_3^n(x; \varepsilon) \cap M_2$ is D_2^n open, there is some $\varepsilon \ge \delta > 0$ such that $D_2^n(x; \delta) \subset D_3^n(x; \varepsilon) \cap M_2$. Since $D_2(x; \delta) \subset P_n$, then $D_2(x; \delta) = D_2^n(x; \delta) \subset D_3(x; \varepsilon)$.

Now let $D_2(x; \varepsilon)$ be an arbitrary D_2 ball, and first suppose that x is in $M_1 \cap M_2$. Then there is some $\varepsilon/2 \geqq \delta > 0$ such that $D_1(x; \delta) \cap M_2 \subset D_2(x; \varepsilon/2) \cap M_1$. For any point y of $D_3(x; \delta) \cap M_2$, there is by (i) some point z in $M_1 \cap M_2$ such that $\delta > D_2(y, z) + D_1(z, x)$. Since z is thus in $D_1(x; \delta) \cap M_2$, then $D_2(x, z) < \varepsilon/2$ and the triangle inequality shows that y is in $D_2(x; \varepsilon)$. Hence in this case, $D_3(x; \delta) \cap M_2 \subset D_2(x; \varepsilon)$. If instead x is in $M_2 \setminus M_1$, there is some $\varepsilon/2 \trianglerighteq \mu > 0$ such that the compact set $\bar{D}_2(x; \mu)$ is in $M_2 \setminus M_1$ and in some P_n , so that $D_2(x; \mu) = D_2^n(x; \mu)$. Since D_2^n and D_3^n are equivalent on P_n , there is some $\mu \trianglerighteq v > 0$ for which $D_3^n(x; v) \cap M_2 \subset D_2(x; \mu)$. Since any point y of $D_3(x; v) \cap M_2$ lies in P_{n+k} for some $k \trianglerighteq 1$, by (ii) there is a point z of $(M_1 \cup P_n) \cap P_{n+k}$ satisfying $v > D_2(y, z) + D_3^n(z, x)$. Thus z lies in $D_3^n(x; v) \cap M_2$ and hence in $D_2(x; \mu)$, so that as above the triangle inequality places y in $D_2(x; \varepsilon)$. Therefore $D_3(x; v) \cap M_2 \subset D_2(x; \varepsilon)$, and (iii) is established.

Since M_1 and by (iii) also M_2 are subspaces of $(M_1 \cup M_2, D_3)$, statement (iv) follows from (2.2) as we note, using (i), that $M_1 \setminus M_2$ and $M_2 \setminus M_1$ are separated sets in $(M_1 \cup M_2, D_3)$.

If (v) were false, there would exist sequences of points $\{t_i\}$ and $\{u_i\}$, satisfying $t_i \in P_n$ and $D_3(p, u_i) = n + \frac{1}{2}$, such that $\lim D_3(t_i, u_i) = 0$. But since P_n and $\{x: D_3(p, x) = n + \frac{1}{2}\}$ are disjoint compact sets, this is impossible.

To show for (vi) that D_3 is complete, let $\{x_k\}$ be a D_3 Cauchy sequence. It may be assumed that $\{x_k\}$ lies entirely in $M_2 \backslash M_1$ and has no subsequence that lies entirely in one of the sets P_n . In fact, if x_k lies in $P_{n_k} \backslash P_{n_k-1}$ for each k, it may be assumed that $n_k+1 < n_{k+1}$. Suppose that for only a finite set (here assumed empty) of indices k the points x_k and x_{k+1} have a D_3 between point in M_1 . Then, for each k, (v) shows that there is some D_3 between point u of x_k and x_{k+1} such that $D(p, u) = n_k + \frac{1}{2}$ and P_{n_k} contains no P_3 between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n contains no P_n between point of P_n and P_n between point of P_n betwee

 D_3 between point v of u and x_{k+1} satisfying $D(p,v)=n_k+1$, and moreover P_{n_k} contains no D_3 between point of u and v. Therefore, u and v can have no D_3 between point in $M_1 \cup P_{n_k}$. Because of this fact and the construction of the metrics $D_3^{n_k+1}$ and D_2 , it follows that $D_3(x_k, x_{k+1}) \ge D_3(u, v) = D_3^{n_k+1}(u, v) \ge D_2^{n_k+1}(u, v) = D_2(u, v) \ge 1$, and $\{x_k\}$ cannot be D_3 Cauchy.

Hence, there must be a subsequence $\{x_{k_i}\}$ of $\{x_k\}$ for which the points x_{k_i} and $x_{k_{i+1}}$ have a D_3 between point y_i in M_1 . Then $\{y_i\}$ is a D_1 Cauchy sequence that converges to some point y in M_1 , and it follows that $\{x_k\}$ also converges to y. Therefore, D_3 is complete.

COROLLARY 4.4 If a closed subspace M_1 of a locally connected generalized continuum M_2 has a complete convex metric D_1 , then D_1 can be extended to a complete convex metric for M_2 .

The above corollary is analogous to Bing's classic extension theorem for arbitrary metric spaces [3]. The following theorem now follows easily from (2.4), (3.1), and (4.3).

THEOREM 4.5. Let M_1 and M_2 be locally connected generalized continua. In order for $M_1 \cup M_2$ to be a locally connected generalized continuum and for every complete convex metric for M_1 to extend to a complete convex metric for $M_1 \cup M_2$, it is necessary and sufficient that $M_1 \cap M_2$ be a nonempty subspace of both M_1 and M_2 which is closed in M_2 and that the M_2 boundary of $M_1 \cap M_2$ be closed in M_1 .

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