ON A PROPERTY OF METRIC PROJECTIONS ONTO CLOSED SUBSETS OF HILBERT SPACES

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Dedicated to P. L. Butzer on the occasion of his sixtieth birthday

ABSTRACT. Applying the theory of monotone operators to the metric projection P_K of a Hilbert space H onto a nonempty closed subset K of H we prove a kind of connectedness property of the set $\{x \in H; P_K(x) \text{ is not a singleton or } P_K \text{ is not upper semi-continuous at } x\}$ which is a typical set for investigations in best approximation. A result of Balaganskii is extended.

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Let H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$ and let K be a nonempty closed subset of H . The metric projection $P_K: H \rightarrow 2^K$ is defined by

$$P_K(x) := \{k \in K; \|k - x\| = d_K(x)\},$$

where $d_K: H \rightarrow \mathbb{R}$ is the distance function of K . If $P_K(x)$ is a singleton for each $x \in H$, then K is called a Chebyshev set.

To motivate the purpose of this note let us first restrict ourselves to Chebyshev sets though our general result is concerned with arbitrary closed subsets of H .

The problem of convexity of a Chebyshev set was studied by many authors under various conditions on the continuity of the metric projection, among others by Klee [11, 12], Vlasov [17] and Asplund [1]. In these investigations, continuity was required at all points of H . In a paper of 1982, Balaganskii [2] considered the aspect of cardinality of the set of points of discontinuity of the metric projection. Typical for his results is the following theorem: If K is a Chebyshev set and if the set of points of discontinuity of P_K is countable, then K is convex. The method of proof in [2] is an inversion method developed by Ficken and later used by Klee [12] and Asplund [1].

In the present note we shall prove a more general result concerning a "connectedness" property of the set of discontinuities of the metric projection from

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which Balaganskii's result involving the cardinality of this set is obtained as a corollary.

Our method of proof uses the theory of monotone operators in Hilbert spaces which turns out to be a very elegant tool. A standard reference for monotone operators in Hilbert space is the monograph of Brézis [7].

The aspect of monotony in best approximation in Hilbert spaces was considered by several authors; see e.g. [10, 6, 4, 5, 9]. The fact that the metric projection P_K is a monotone operator for an arbitrary set K follows immediately from Asplund [1] though it is not definitely stated there. Kenderov [10] explicitly formulated this property and gave an elementary proof. For convex sets this property was well-known much earlier.

To describe the purpose of this paper in more detail let us introduce some notations and preliminaries.

If $x \in H$ and $r > 0$, then the open ball, closed ball, and sphere with center x and radius r will be denoted by $B(x; r)$, $\overline{B}(x; r)$ and $S(x; r)$, respectively. The convex hull and closed convex hull of a set $A \subset H$, will be denoted by $\text{co } A$ and $\overline{\text{co}} A$, respectively; $\delta(A)$ is the diameter of A .

Throughout this note, K will be a nonempty closed subset of H , unless otherwise stated. We already introduced the metric projection of H onto K . Evidently,

$$P_K(x) = \overline{B}(x; d_K(x)) \cap K \quad \forall x \in H.$$

As usual, P_K is identified with its graph in $H \times H$. Thus, $(x, k) \in P_K$ if and only if $k \in P_K(x)$. K is said to be proximal if $P_K(x) \neq \emptyset$ for each $x \in H$.

As a generalization of the metric projection we consider the mapping $\Phi_K: H \rightarrow 2^H$ defined by

$$\Phi_K(x) := \bigcap_{\varepsilon > 0} \overline{\text{co}}(\overline{B}(x; d_K(x) + \varepsilon) \cap K).$$

This mapping was introduced independently by Berens [4, 5] and Franchetti and Papini [8] for studying approximative properties of sets in normed linear spaces. It was Berens who pointed out and investigated the monotony of Φ_K in Hilbert spaces. We summarize some properties of this mapping; for proofs we mainly refer to [5].

For each $x \in H$, $\Phi_K(x)$ is a nonempty closed convex subset of H and

$$\overline{\text{co}} P_K(x) \subset \Phi_K(x) \subset \overline{B}(x; d_K(x)).$$

Φ_K is a maximally monotone operator, that means first, Φ_K is monotone:

$$\langle y - y', x - x' \rangle \geq 0 \quad \forall (x, y), (x', y') \in \Phi_K,$$

and second, there is no proper monotone extension of Φ_K in $H \times H$. Denoting the inverse of $I + \Phi_K$ by $J := (I + \Phi_K)^{-1}$, we have: J is a contraction and its domain is the whole space H . This follows by Minty's characterization of maximally monotone operators in Hilbert spaces.

Φ_K is even cyclically monotone which means:

$$\sum_{i=1}^n \langle x_i - x_{i-1}, y_i \rangle \geq 0$$

for any set of pairs $(x_0, y_0), \dots, (x_n, y_n) \in \Phi_K$ satisfying $(x_n, y_n) = (x_0, y_0)$, $n \in \mathbb{N}$ arbitrary.

From the inclusion $P_K \subset \Phi_K$, it is also clear that P_K is a monotone, even a cyclically monotone operator.

It follows from a result of Rockafellar on cyclically monotone operators (cf. [7]) that Φ_K is the subdifferential of a continuous convex real-valued function defined on all of H . Indeed, we have

$$\Phi_K = \partial \varphi_K,$$

where $\varphi_K: H \rightarrow \mathbb{R}$ is the continuous convex function defined by

$$\begin{aligned} \varphi_K(x) &:= \sup \{ \langle x, k \rangle - \tfrac{1}{2} \|k\|^2; k \in K \} \\ &= \tfrac{1}{2} \|x\|^2 - \tfrac{1}{2} d_K^2(x) \end{aligned}$$

which was introduced by Asplund [1] for studying convexity of Chebyshev sets.

As a consequence of these properties Φ_K is norm to weak upper semi-continuous (usc).

Note that if H is a finite-dimensional space, then $\Phi_K(x) = \text{co } P_K(x)$ for each $x \in H$, while in each infinite dimensional Hilbert space there is a proximal set K such that $\overline{\text{co}} P_K(x) \neq \Phi_K(x)$ for some $x \in H$, as was proved by Godini [9]; see also Klee [13] for a nonseparable Hilbert space.

The following result relates the aspect of convexity of a Chebyshev set to the maximal monotony of its metric projection.

(*) For a nonempty subset K of H the following statements are equivalent:

- (i) P_K is maximally monotone, i.e., $P_K = \Phi_K$.
- (ii) K is closed and convex.
- (iii) K is a Chebyshev set, and P_K is continuous.

For convenience, continuity is understood here with respect to the norm topology of H . However, there are known various weaker types of continuity of the metric projection under which the equivalence of (ii) and (iii) was established. The implications (iii) $\Rightarrow$ (i) $\Rightarrow$ (ii) were given by Berens and Westphal [6] in 1977. See also [4] for a discussion of this subject.

Stimulated by the "global" result stated in (*) we now consider the set

$$C_K := \{x \in H; P_K(x) = \Phi_K(x)\}$$

for an arbitrary closed subset K of H . It is equal to the set

$$T'_K := \{x \in H; \lim_{\varepsilon \rightarrow 0+} \delta(\overline{B}(x; d_K(x) + \varepsilon) \cap K) = 0\}$$

known, in particular, from the work of Soviet mathematicians on approximative properties of sets. Stečkin [16] proved that T'_K is a dense G_δ -set; cf. also

[18; p. 9]. Balaganskii [2], too, worked with the set T'_K . Moreover, one can prove the following alternative representations of the set C_K :

$$\begin{aligned} C_K &= \{x \in H; P_K(x) \text{ is a singleton and } P_K \text{ is usc at } x\} \\ &= \{x \in H; \varphi_K \text{ is Fréchet differentiable at } x\}. \end{aligned}$$

The latter is, of course, related to Asplund's work [1] on Chebyshev sets.

It is the purpose of this note to prove a type of connectedness property of the complement of C_K . Indeed, we characterize the isolated points of the complement of C_K and show that if a point of $H \setminus C_K$ is not isolated, then it lies on some nonconstant Lipschitz curve which is completely contained in $H \setminus C_K$. Thus, if a path component of $H \setminus C_K$ consists of a single point, this must be isolated.

In the following sections we prove this result and give some applications.

We are most grateful to H. Berens for stimulating discussions.

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Our main result is the following:

Theorem. *Each point $x \in H \setminus C_K$ lies on some nonconstant Lipschitz curve completely contained in $H \setminus C_K$ unless x is an isolated point of $H \setminus C_K$.*

The point x is an isolated point of $H \setminus C_K$ if and only if $P_K(x) = S(x; d_K(x))$.

Proof. If $x \in H \setminus C_K$ such that $P_K(x) = S(x; d_K(x))$, then for each $z \in \overline{B}(x; d_K(x))$, $z \neq x$, we have

$$P_K(z) = \Phi_K(z) = \left\{ x + d_K(x) \frac{z - x}{\|z - x\|} \right\},$$

i.e., $z \in C_K$. Thus, x is an isolated point of $H \setminus C_K$.

If $x \in H \setminus C_K$ and $P_K(x) \neq S(x; d_K(x))$, there exists a boundary point y of $\Phi_K(x)$ and a unit vector u such that $y \notin P_K(x)$ and $y + \lambda u \notin \Phi_K(x)$ for each $\lambda > 0$. Put $y_\lambda := y + \lambda u$ ($\lambda \geq 0$). We shall show that $J(x + y_\lambda) \in H \setminus C_K$ for λ sufficiently small. Indeed, fix λ_0 such that $0 < \lambda_0 < \frac{1}{2}d_K(y)$. Then, for $0 \leq \lambda \leq \lambda_0$,

$$|d_K(y_\lambda) - d_K(y)| \leq \|y_\lambda - y\| = \lambda \leq \lambda_0 < \frac{1}{2}d_K(y)$$

implying

$$\|y_\lambda - y\| < d_K(y_\lambda)$$

and, as J is a contraction,

$$\begin{aligned} \|(x + y_\lambda - J(x + y_\lambda)) - y_\lambda\| &= \|J(x + y) - J(x + y_\lambda)\| \\ &\leq \|y - y_\lambda\| < d_K(y_\lambda). \end{aligned}$$

Hence, for $0 \leq \lambda \leq \lambda_0$, the element $x + y_\lambda - J(x + y_\lambda)$, by definition an element of $\Phi_K(J(x + y_\lambda))$, does not belong to $P_K(J(x + y_\lambda))$. Noting that $J(x + y_\lambda) = x$ for $\lambda = 0$ and $\neq x$ for $\lambda > 0$ we thus proved that

$$[0, \lambda_0] \ni \lambda \rightarrow J(x + y_\lambda)$$

is a nonconstant Lipschitz curve in $H \setminus C_K$ with initial point x .

Note that in case of the Euclidean plane the above characterization of isolated points of $H \setminus C_K$ was already observed by Motzkin [14] in 1935.

From the Theorem the central result in Balaganskii's paper is deduced as a corollary.

Corollary 1 (= Theorem 2 of [2]). *If K is a nonconvex subset of H such that $H \setminus K$ is connected, then $H \setminus C_K$ is uncountable unless K is the complement of an open ball.*

Proof. As K is nonconvex, $H \setminus C_K \neq \emptyset$. If the set $H \setminus C_K$ is countable, then, by the theorem, it consists of isolated points, and for any $x \in H \setminus C_K$ we have $P_K(x) = S(x; d_K(x))$. Thus, $S(x; d_K(x)) \subset K$ and $B(x; d_K(x)) \subset H \setminus K$. As $H \setminus K$ is connected, it follows that $H \setminus C_K$ consists of a single point x and $K = H \setminus B(x; d_K(x))$.

More general than Corollary 1 is

Corollary 2 (= Theorem 3 of [2]). *If K is a nonconvex subset of H , then $H \setminus C_K$ is uncountable unless K has the form*

$$K = A \setminus \bigcup_{\gamma} B_{\gamma},$$

where A is a closed convex body and (B_{γ}) is a countable family of nonoverlapping open balls contained in A .

Proof. Assume the set $H \setminus C_K$ is countable, and let its points be arranged in an indexed family (x_{γ}) . Then the range of Φ_K is just the set

$$A := K \cup \bigcup_{\gamma} B(x_{\gamma}; d_K(x_{\gamma})),$$

which is closed and thus convex as the closure of the range of a maximally monotone operator is necessarily a convex set. Hence, A satisfies the conditions stated in the corollary for the exceptional case.

If K is a Chebyshev set, then C_K is precisely the set of continuity points of P_K and its complement contains no isolated points. In this case our Theorem reads

Corollary 3. *Let K be a Chebyshev set and x a discontinuity of P_K . Then x lies on some nonconstant Lipschitz curve each point of which is a discontinuity of P_K .*

Finally, Corollary 3 implies Balaganskii's result cited at the beginning.

Corollary 4 (= Theorem 4 of [2]). *Let K be a Chebyshev set. If the set of discontinuities of P_K is countable, then K is convex.*

Let us take a brief glance at the situation in finite-dimensional spaces, in particular in the plane.

If H is the n -dimensional Euclidean space $\mathbb{R}^n$, then

$$C_K = \{x \in \mathbb{R}^n; P_K(x) \text{ is a singleton}\}$$

is just the uniqueness set with respect to the best approximation from K . It is known that its complement which is denoted by N_K , has Lebesgue measure 0 in $\mathbb{R}^n$. Moreover, N_K is the union of a countable family of compact subsets of finite, $(n-1)$ -dimensional Hausdorff measure in $\mathbb{R}^n$. For references see the discussion of these results in [3]. Starting from work of Pauc, Bartke and Berens [3] gave a comprehensive description of the set N_K in the Euclidean plane. Their investigations are based on the initial value problem

$$v'(t) \in v(t) - \Phi_K(v(t)), \quad v(0) = x$$

which has a unique solution $v: [0, \infty) \rightarrow H$, by the theory of monotone operators [7] and its extension to operators of type $\mathfrak{M}(\omega)$ in the sense of Pazy [15].

Among other things, Bartke and Berens showed that in $\mathbb{R}^2$, N_K is a countable union of rectifiable curves, at least if K is compact.

Of course, we can also obtain and slightly generalize their result by parametrizing the curves in question by means of the operator J . Indeed, if $x \in N_K$ is not an isolated point, then the vectors y and u in the proof of our Theorem can be taken such that u or $-u$ is a canonical unit vector, and such that $w := x + y + \lambda_1 u$ has rational coordinates with respect to the canonical basis of $\mathbb{R}^2$ for some λ_1 satisfying $0 < \lambda_1 < \frac{1}{2}d_K(y)$. Hence,

$$[0, \lambda_1] \ni \lambda \rightarrow J(w + \lambda(-u))$$

is a nonconstant Lipschitz curve in N_K with final point x . As the set of such pairs (w, u) is countable, we obtain

Proposition. *If K is a nonempty closed subset of $\mathbb{R}^2$, then N_K is a countable union of isolated points and nonconstant Lipschitz curves.*

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To illustrate the theorem we consider the following simple

Example. Let H be the Hilbert space l^2 of real sequences $x = (x_i)_{i \in \mathbb{N}}$. Let

$$K := \{e^j; j \in \mathbb{N}\}$$

be the set of canonical unit vectors $e^j = (e_i^j)_{i \in \mathbb{N}}$ for which $e_i^j = 0$ if $i \neq j$ and $e_j^j = 1$. Then for each $x \in l^2$

$$P_K(x) = \{e^j; j \in \mathbb{N} \ni x_j = \sup_i x_i\}$$

and, as $\varphi_K(x) = \sup_i x_i - \frac{1}{2}$,

$$\Phi_K(x) = \begin{cases} \text{co } P_K(x), & \text{if } \exists j \in \mathbb{N} \ni x_j > 0 \\ \overline{\text{co}}(P_K(x) \cup \{0\}), & \text{if } \exists j \in \mathbb{N} \ni x_j = \sup_i x_i = 0 \\ \{0\}, & \text{if } \forall j \in \mathbb{N} x_j < 0. \end{cases}$$

Thus,

$$C_K = \{x \in l^2; \exists j \in \mathbb{N} \ni x_j = \sup_i x_i > 0\}$$

and

$$l^2 \setminus C_K = \{x \in l^2; \exists j, k \in \mathbb{N}, j \neq k \ni x_j = x_k = \sup_i x_i > 0\} \\ \cup \{x \in l^2; \sup_i x_i = 0\}.$$

The metric projection P_K is not upper semi-continuous at an $x = (x_i)$ if and only if $\sup_i x_i = 0$ and $x_i < 0$ for infinitely many values of i . Putting

$$V_K := \{x \in l^2; P_K \text{ is not usc at } x\}$$

and

$$N_K := \{x \in l^2; P_K(x) \text{ is not a singleton}\},$$

let us mention that all three sets

$$N_K \setminus V_K, \quad V_K \setminus N_K, \quad N_K \cap V_K$$

are nonempty, their union being the complement of C_K in H .

Now let us consider the behavior of the curves

$$\lambda \rightarrow J(x + y + \lambda u)$$

in case $x = 0$. Then $P_K(0) = K$ and

$$\Phi_K(0) = \left\{ y \in l^2; \forall i \in \mathbb{N} \ y_i \geq 0, \sum_{i=1}^{\infty} y_i \leq 1 \right\}.$$

The origin is a support point of $\Phi_K(0)$ not belonging to $P_K(0)$. If we choose a unit vector $u = (u_i)$ such that $u_i \leq 0$ for each $i \in \mathbb{N}$, then

$$[0, \infty) \ni \lambda \rightarrow J(\lambda u) = \lambda u$$

gives a half-line completely contained in $l^2 \setminus C_K$.

On the other hand, if we take a boundary point y of $\Phi_K(0)$, $y \notin K$, such that a canonical unit vector, say e^j , is a suitable choice of u , then, for λ sufficiently large, the associated curve $\lambda \rightarrow J(y + \lambda e^j)$ runs in C_K with direction e^j . Indeed, we have to take $y = (y_i) \in \Phi_K(0)$ such that $\sum_{i=1}^{\infty} y_i = 1$ implying that $y + \lambda e^j \notin \Phi_K(0)$ for each $\lambda > 0$. Then

$$J(y + \lambda e^j) = y + (\lambda - 1)e^j \in C_K,$$

if $\lambda > 1 - y_j + \sup_{i \neq j} y_i$.

To describe the situation for small values of λ let us assume, for convenience, that the sequence (y_i) is, in addition, monotonically decreasing. Let $u = e^1$. If $\lambda > 1 - y_1 + y_2$, then

$$J(y + \lambda e^1) = y + (\lambda - 1)e^1,$$

and if

$$1 - \sum_{i=1}^k y_i + k y_{k+1} < \lambda \leq 1 - \sum_{i=1}^{k-1} y_i + (k-1) y_k \quad (k \geq 2),$$

then

$$J(y + \lambda e^1) = y + \sum_{j=1}^k \left[\frac{1}{k} \left(\lambda - 1 + \sum_{i=1}^k y_i \right) - y_j \right] e^j$$

is not in C_K since the sequence of coordinates is monotonically decreasing and the first k of them are equal and positive ($k \geq 2$). Hence,

$$[0, 1 - y_1 + y_2] \ni \lambda \rightarrow J(y + \lambda e^1)$$

is a curve in $l^2 \setminus C_K$ composed of a countable family of line segments which is infinite if and only if $y_i > 0$ for each $i \in \mathbb{N}$.

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