

## OSCILLATION CRITERIA FOR HAMILTONIAN MATRIX DIFFERENCE SYSTEMS

L. H. ERBE AND PENGXIANG YAN

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**ABSTRACT.** We obtain some oscillation criteria for the Hamiltonian difference system

$$\begin{cases} \Delta Y(t) = B(t)Y(t+1) + C(t)Z(t), \\ \Delta Z(t) = -A(t)Y(t+1) - B^*(t)Z(t), \end{cases}$$

where  $A, B, C, Y, Z$  are  $d \times d$  matrix functions. As a corollary, we establish the validity of an earlier conjecture for a second-order matrix difference system.

### 1. INTRODUCTION AND PRELIMINARY RESULTS

Consider the linear Hamiltonian difference system

$$(1.1) \quad \begin{aligned} \Delta y(t) &= B(t)y(t+1) + C(t)z(t), \\ \Delta z(t) &= -A(t)y(t+1) - B^*(t)z(t), \end{aligned}$$

the corresponding matrix system

$$(1.2) \quad \begin{aligned} \Delta Y(t) &= B(t)Y(t+1) + C(t)Z(t), \\ \Delta Z(t) &= -A(t)Y(t+1) - B^*(t)Z(t), \end{aligned}$$

and the Riccati equation

$$(1.3) \quad \begin{aligned} \Delta W(t) + A(t) + B^*(t)W(t) + W(t)B(t) - B^*(t)W(t)B(t) \\ + (I - B(t))^*W(t)(C^{-1}(t) + W(t))^{-1}W(t)(I - B(t)) = 0, \end{aligned}$$

where  $A(t), B(t), C(t), W(t), Y(t), Z(t)$  are  $d \times d$  matrices with  $A(t), C(t)$  Hermitian,  $C(t) > 0$ , and  $I - B(t)$  invertible. Here  $y(t), z(t)$  are  $d \times 1$  vectors and  $t$  takes on integer values in  $[M-1, N+1]$ , where  $M, N$  are two integers.

In [4, 5] the authors extended many of the results to equations (1.1)–(1.3) which had been developed for linear Hamiltonian differential systems of the form

$$(1.4) \quad \begin{aligned} y'(x) &= B(x)y(x) + C(x)z(x), \\ z'(x) &= -A(x)y(x) - B^*(x)z(x). \end{aligned}$$

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Here  $x \in I$  is a finite or infinite interval,  $A, B, C$  are continuous  $d \times d$  matrix-valued functions, and  $y, z$  are  $d \times 1$  vector functions. Many of the results for (1.4) may be found in the book of Coppel [2], and in [4, 5] it was shown that discrete analogues of many of these results may be obtained. Related work on symmetric three-term recurrences may be found in [1] and the references therein. In this paper, we shall obtain some oscillation and disconjugacy criterion for (1.1), (1.2) and, as a consequence of our results, shall prove a generalization of a conjecture of Peterson and Ridenhour [7]. We recall some notation and definitions.

We say (1.1) is disconjugate on  $[M-1, N+1]$  iff for any nontrivial prepared solution  $\{y(t), z(t)\}$  of (1.1) there exists at most one integer  $p \in [M-1, N]$  such that either  $y^*(p)C^{-1}(p)(I-B(p))y(p+1) \leq 0$  when  $y(p) \neq 0$  or  $y(p) = 0$ . Recall that a solution  $\{y(t), z(t)\}$  of (1.1) is said to be prepared if  $y^*(t)z(t)$  is real valued and that a solution  $\{Y(t), Z(t)\}$  of (1.2) is said to be prepared if  $Y^*(t)Z(t)$  is Hermitian. We say a prepared solution of (1.2) is a conjoined basis if  $\text{Rank} \begin{bmatrix} Y(t) \\ Z(t) \end{bmatrix} \equiv d$ , and it is said to be recessive at  $\infty$  if there exists an integer  $M_0$  for which

$$(1.5) \quad Y^*(t)C^{-1}(t)(I-B(t))Y(t+1) > 0, \quad t \geq M_0,$$

and

$$(1.6) \quad \lim_{n \rightarrow \infty} \sum_{s=M_0}^n u^*(Y^*(s)C^{-1}(s)(I-B(s))Y(s+1))^{-1}u = \infty$$

for every unit vector  $u$ . A prepared solution of (1.2) is said to be dominant at  $\infty$  if (1.5) holds for some integer  $M_0$  and

$$(1.7) \quad \sum_{s=M_0}^{\infty} u^*(Y^*(s)C^{-1}(s)(I-B(s))Y(s+1))^{-1}u$$

converges for every unit vector  $u$ .

Equation (1.1) is said to be eventually disconjugate in case there exists an integer  $M_0$  such that (1.1) is disconjugate on  $[M_0-1, N_1+1]$  for all integers  $N_1 > M_0$ .

We introduce the following quadratic forms:

$$q[u] = \sum_{t=M}^{N+1} (z^*(t-1)C(t-1)z(t-1) - y^*(t)A(t-1)y(t)),$$

where

$$u = \{y(t), z(t)\} \in \Omega = \{y, z \in C^d: y(M-1) = 0 = y(N+1), \\ \Delta y(t) = B(t)y(t+1) + C(t)z(t)\},$$

and

$$Q[U] = \sum_{t=M}^{N+1} (Z^*(t-1)C(t-1)Z(t-1) - Y^*(t)A(t-1)Y(t)),$$

where

$$U = \{Y(t), Z(t)\} \in \Lambda = \{Y, Z \in C^{d \times d}: Y(M-1) = 0 = Y(N+1), \\ \Delta Y(t) = B(t)Y(t+1) + C(t)Z(t)\}.$$

We introduce the further notation:

$$\Lambda^+ := \{U \in \Lambda : \text{there is a } t_0, M-1 \leq t_0 \leq N-1, \text{ such that } Y(t_0) = 0 \\ \text{and } Y(t_0+1) \text{ is nonsingular or there is } M+1 \leq t_0 \leq N+1 \\ \text{such that } Y(t_0) = 0 \text{ and } Y(t_0-1) \text{ is nonsingular}\}.$$

We say  $q$  is positive on  $\Omega$  provided  $q[u] \geq 0$  for all  $u \in \Omega$  and  $q = 0$  iff  $u \equiv 0$ ;  $Q$  is positive definite on  $\Lambda$  provided, for all  $U \in \Lambda$ ,  $Q[U] \geq 0$  and  $Q = 0$  iff  $U \equiv 0$ ;  $Q$  is strictly positive on  $\Lambda^+$  if  $Q[U] > 0$  for all  $U \in \Lambda^+$ .

The following results were established in [4, 5]: The first theorem may be regarded as a discrete version of the “Reid Roundabout Theorem” (cf. Ahlbrandt [1]).

**Theorem 1.** *The following are equivalent:*

- (i) Equation (1.1) is disconjugate on  $[M-1, N+1]$ .
- (ii)  $q[u]$  is positive definite on  $\Omega$ .
- (iii)  $Q[U]$  is positive definite on  $\Lambda$  and strictly positive on  $\Lambda^+$ .
- (iv) There exists a Hermitian solution of the Riccati equation (3) such that  $C^{-1}(t) + W(t) > 0$ ,  $t \in [M-1, N]$ .
- (v) There exists a solution of equation (1.2) such that

$$Y^*(t)C^{-1}(t)(I - B(t))Y(t+1) > 0, \quad t \in [M-1, N].$$

**Theorem 2.** *Assume (1.1) is eventually disconjugate. Then it follows that:*

- (i) every conjoined basis  $\{Y(t), Z(t)\}$  satisfies

$$Y^*(t)C^{-1}(t)(I - B(t))Y(t+1) > 0, \quad t \geq M_1 \geq M \text{ (} M_1 \text{ large enough)};$$

- (ii) there exists a solution  $\eta_0 = \{Y_0(t), Z_0(t)\}$  of (1.2) which is recessive at  $\infty$ ;
- (iii) if  $\eta_1 = \{Y_1(t), Z_1(t)\}$  is any prepared solution of (1.2) such that  $Z_0^*(t)Y_1(t) - Y_0^*(t)Z_1(t)$  is invertible, then  $\eta_1$  is a dominant solution of (1.2) and  $Y_1^{-1}(t)Y_0(t) \rightarrow 0$  (zero matrix) as  $t \rightarrow \infty$ .

By using Theorem 1, one can obtain a comparison theorem between the two systems:

$$(1.8)_i \quad \begin{aligned} \Delta y(t) &= B_i(t)y(t+1) + C_i(t)z(t), \\ \Delta z(t) &= -A_i(t)y(t+1) - B_i(t)z(t), \end{aligned} \quad i = 1, 2,$$

where we make the assumption on  $(1.8)_i$  as (1.1).

Denote

$$(1.9)_i \quad D_i(t) = \begin{bmatrix} C_i^{-1}(t) & -B_i^* C_i^{-1}(t) \\ -C_i^{-1}(t)B_i(t) & B_i^*(t)C_i^{-1}(t)B_i(t) - A_i(t) \end{bmatrix}, \quad i = 1, 2.$$

The following is then a generalized Sturm Comparison Theorem.

**Theorem 3.** *If  $(1.8)_1$  is disconjugate on  $[M-1, N+1]$  and  $D_2(t) \geq D_1(t)$  on  $[M-1, N+1]$ , then  $(1.8)_2$  is disconjugate also.*

*Proof.* For  $u_1 = \{y_1(t), z_1(t)\}$  with  $y_1(M-1) = 0 = y_1(N+1)$  and  $\Delta y_1(t) = B_1(t)y_1(t+1) + C_1(t)z_1(t)$ , i.e.,  $z_1(t) = C_1^{-1}(t)(\Delta y_1(t) - B_1(t)y_1(t+1))$ , we have

$$\begin{aligned} q_1[u_1] &= \sum_{t=M-1}^N (z_1^*(t)C_1(t)z_1(t) - y_1^*(t+1)A_1(t)y_1(t+1)) \\ &= \sum_{t=M-1}^N (\Delta y_1^*(t), y_1^*(t+1))D_1(t) \begin{pmatrix} \Delta y_1(t) \\ y_1(t+1) \end{pmatrix}, \end{aligned}$$

and for  $u_2 = \{y_1(t), z_2(t)\}$  with  $z_2(t) = C_2^{-1}(t)(\Delta y_1(t) - B_2(t)y_1(t))$ , we have

$$\begin{aligned} q_2[u_2] &= \sum_{t=M-1}^N (\Delta y_1^*(t), y_1^*(t+1))D_2(t) \begin{pmatrix} \Delta y_1(t) \\ y_1(t+1) \end{pmatrix} \\ &\geq \sum_{t=M-1}^N (\Delta y_1^*(t), y_1^*(t+1))D_1(t) \begin{pmatrix} \Delta y_1(t) \\ y_1(t+1) \end{pmatrix} = q_1[u_1]. \end{aligned}$$

By Theorem 1, we know  $q_1[u_1] \geq 0$  and so  $q_2[u_2] \geq 0$ , i.e.,  $(1.8)_2$  is disconjugate.

**Corollary 4.** If  $(1.8)_1$  is disconjugate and  $B_1(t) = B_2(t)$ ,  $A_1(t) \geq A_2(t)$ ,  $C_1(t) \geq C_2(t)$ , then  $(1.8)_2$  is disconjugate.

*Proof.* This can be shown from Theorem 3 and

$$D_i(t) = \begin{pmatrix} I & 0 \\ -B_i^*(t) & I \end{pmatrix} \begin{pmatrix} C_i^{-1}(t) & 0 \\ 0 & -A_i(t) \end{pmatrix} \begin{pmatrix} I & -B_i(t) \\ 0 & I \end{pmatrix}.$$

**Matrix systems.** Next we consider the oscillation of solutions of the matrix system (1.2).

**Definition.** The Hamiltonian matrix difference system (1.2) is said to be nonoscillatory if for each conjoined basis  $\{Y(t), Z(t)\}$  there exists an integer  $t_0$  such that, for  $t \geq t_0 \geq M-1$ , we have

$$Y^*(t)C^{-1}(t)(I - B(t))Y(t+1) > 0.$$

Otherwise we say it is oscillatory.

From Theorem 1, we know if (1.2) is nonoscillatory, then (1.1) is eventually disconjugate. If we suppose that there is a Hermitian solution  $W(t)$  of (1.3) with  $W(t) + C^{-1}(t) > 0$ , then this solution satisfies the rewritten Riccati equation (1.3):

$$(1.10) \quad \Delta W(t) + G^*(t)G(t) + h(t) = 0$$

or

$$(1.11) \quad \Delta W(t) + \rho(t) + h(t) = 0,$$

where

$$\begin{aligned} G(t) &= (C^{-1}(t) + W(t))^{-1/2} W(t) (I - B(t)) + (C^{-1}(t) + W(t))^{1/2} B(t), \\ h(t) &= A(t) - B^*(t) C^{-1}(t) B(t), \\ \rho(t) &= (W(t) + C^{-1}(t) B(t))^* (C^{-1}(t) + W(t))^{-1} (W(t) + C^{-1}(t) B(t)). \end{aligned}$$

Denote by  $F$  the set of all sequences of real numbers  $s = \{s(t)\}_{t=0}^{\infty}$  with  $0 \leq s(t) \leq 1$  and  $\sum_{\tau=0}^{\infty} s(\tau) = +\infty$ .

Let  $S(t) = \sum_{\tau=0}^t s(\tau)$ ,  $S(t, t_0) = \sum_{\tau=t_0}^t s(\tau)$ ,  $l(t) = \lambda_d(C^{-1}(t))$ , and  $L(t) = \lambda_1(C^{-1}(t))$ . Here we suppose that the eigenvalues of  $C^{-1}(t)$  are ordered with

$$\lambda_1(C^{-1}(t)) \geq \lambda_2(C^{-1}(t)) \geq \dots \geq \lambda_d(C^{-1}(t)).$$

We introduce the following conditions which will be used in subsequent results:

- (S<sub>1</sub>)  $\limsup_{t \rightarrow \infty} S^{-1-\alpha}(t) \sum_{\tau=0}^t S(\tau) L(\tau+1) < +\infty$ ;  
 (S<sub>2</sub>)  $\limsup_{t \rightarrow \infty} S^{-\alpha}(t) L(t) < +\infty$ ; where  $\alpha \geq 0$ .

Similar to [3], we can prove

**Theorem 5.** Let (S<sub>1</sub>) hold for some  $s \in F$ . Then equation (1.2) is oscillatory provided

$$\limsup_{t \rightarrow \infty} S^{-1-\alpha}(t) \lambda_1 \left( \sum_{\tau=0}^t S(\tau) \sum_{k=0}^{\tau} (A(k) - B^*(k) C^{-1}(k) B(k)) \right) = +\infty.$$

**Theorem 6.** Let (S<sub>2</sub>) hold for some  $s \in F$ . Then (1.2) is oscillatory provided

$$\limsup_{t \rightarrow \infty} S^{-1-\alpha}(t) \lambda_1 \left( \sum_{\tau=0}^t (A(\tau) - B^*(\tau) C^{-1}(\tau) B(\tau)) \right) = +\infty.$$

**Example.** Let

$$C(t) = \begin{pmatrix} t^{-\alpha-1/2} & 0 \\ 0 & t^{-\alpha} \end{pmatrix}, \quad A(t) = \begin{pmatrix} t^{\alpha+1/2} & \frac{1}{2} \\ \frac{1}{2} & t^{\alpha} \end{pmatrix},$$

$a \geq 0$ ,  $B(t) = \frac{1}{2}I$ . From Theorem 6 it follows that (1.2) is oscillatory in this case.

**Theorem 7.** If (1.2) is nonoscillatory, then there exists  $t_0$  such that, for all  $t \geq t_0$ , we have

$$\begin{aligned} A(t_0) + \sum_{\tau=t_0+1} (A(\tau) - B^*(\tau) C^{-1}(\tau) B(\tau)) \\ < C^{-1}(t+1) + (I - B(t_0))^* C^{-1}(t_0) (I - B(t_0)). \end{aligned}$$

*Proof.* Since (1.2) is nonoscillatory, there exists a sufficiently large integer  $t_0$  and a Hermitian matrix solution of (1.11) with  $C^{-1}(t) + W(t) > 0$  for  $t \geq t_0$ .

Taking the summation of both sides of (1.11) from  $t_0$  to  $t$ , we obtain

$$\begin{aligned}
-W(t+1) &= \sum_{\tau=t_0+1}^t h(\tau) + \sum_{\tau=t_0+1}^t \rho(\tau) + A(t_0) - W(t_0) + W(t_0)B(t_0) \\
&\quad + B^*(t_0)W(t_0) - B^*(t_0)W(t_0)B(t_0) + (I - B(t_0))^*W(t_0) \\
&\quad \times (C^{-1}(t_0) + W(t_0))^{-1}W(t_0)(I - B(t_0)) \\
&\geq \sum_{\tau=t_0+1}^t h(\tau) + A(t_0) \\
&\quad + (I - B(t_0))^*(W(t_0)(C^{-1} + W(t_0))^{-1}W(t_0) - W(t_0))(I - B(t_0)) \\
&= \sum_{\tau=t_0+1}^t h(\tau) + A(t_0) \\
&\quad - (I - B(t_0))^*C^{-1}(t_0)(C^{-1}(t_0) + W(t_0))^{-1}W(t_0)(I - B(t_0)) \\
&= \sum_{\tau=t_0+1}^t h(\tau) + A(t_0) - (I - B(t_0))^*C^{-1}(t_0)(I - B(t_0)) \\
&\quad + (I - B(t_0))^*(C^{-1}(t_0) - C^{-1}(t_0) \\
&\quad \quad \times (C^{-1}(t_0) + W(t_0))^{-1}W(t_0))(I - B(t_0)) \\
&= \sum_{\tau=t_0+1}^t h(\tau) + A(t_0) - (I - B(t_0))^*C^{-1}(t_0)(I - B(t_0)) \\
&\quad + (I - B(t_0))^*C^{-1}(t_0)(C^{-1}(t_0) + W(t_0))^{-1}C^{-1}(t_0)(I - B(t_0)) \\
&> \sum_{\tau=t_0+1}^t h(\tau) + A(t_0) - (I - B(t_0))^*C^{-1}(t_0)(I - B(t_0)).
\end{aligned}$$

From  $-W(t+1) < C^{-1}(t+1)$ , the result follows.

*Note.* Taking  $t = t_0$ , we get [5, Proposition 2.1]. If  $B(t) = 0$ ,  $C(t) \equiv I$ , we get [7, Theorem 1].

From [4] we may express  $Q[U]$  in the equivalent form

$$(1.12) \quad Q[U] = Y^*(t)W(t)Y(t)|_{M-1}^{N+1} + \sum_{t=M-1}^N F^*(t)F(t),$$

where

$$F(t) = (C^{-1}(t) + W(t))^{-1/2}W(t)(I - B(t))Y(t+1) - (C^{-1}(t) + W(t))^{1/2}C(t)Z(t),$$

$U = \{Y(t), Z(t)\} \in \Lambda$ , and (1.2) is nonoscillatory.

**Theorem 8.** Suppose  $C(t) \equiv I$ ,  $B^*(t) + B(t) \leq B^*(t)B(t)$ , and there exists  $U = \{Y(t), Z(t)\}$  with  $\Delta Y(t) = B(t)Y(t+1) + \bar{Z}(t)$  such that

$$(1.13) \quad \limsup_{N \rightarrow \infty} \lambda_1(Q[U]) = -\infty.$$

Then (1.2) is oscillatory.

*Note.* If  $B(t) \equiv 0$ , then this is [7, Theorem 5].

*Proof.* Suppose not, i.e., suppose (1.2) is nonoscillatory. Then by Theorem 2 there exists a solution  $\{Y(t), Z(t)\}$  of (1.2) and an integer  $t_0$  such that

$$(1.14) \quad \sum_{t=t_0}^{\infty} (Y^*(t)(I - B(t))Y(t+1))^{-1} = \tau \quad (\text{constant matrix}).$$

We are going to prove that  $Y^*(t)(I - B(t))Y(t+1)$  is decreasing. To see this, observe that

$$\begin{aligned} (1.15) \quad & \Delta(Y^*(t)(I - B(t))Y(t+1)) \\ &= Y^*(t+1)(\Delta Y(t) + \Delta Z(t)) + \Delta Y^*(t)(I - B(t))Y(t+1) \\ &= Y^*(t+1)[I - (I + W(t))^{-1}(I - B(t)) + W(t+1) \\ &\quad - W(t)(I + W(t))^{-1}(I - B(t)) \\ &\quad \times (I - (I - B^*(t))(I + W(t))^{-1}(I - B(t)))]Y(t+1) \\ &= Y^*(t+1)[I + W(t+1) - (I - B^*(t))(I + W(t))^{-1}(I - B(t))]Y(t+1). \end{aligned}$$

From (1.12)–(1.14) we know that if  $t$  is sufficiently large, we have  $W(t) < 0$ , i.e.,  $0 < I + W(t) < I$ . Furthermore,

$$(1.16) \quad \begin{aligned} & -(I - B(t))^*(I + W(t))^{-1}(I - B(t)) < -(I - B(t))^*(I - B(t)) \\ &= -I + (B^*(t) + B(t)) - B^*(t)B(t). \end{aligned}$$

Combining (1.15), (1.16), and the condition, we see that

$$\Delta(Y^*(t)(I - B(t))Y(t+1)) \leq 0,$$

i.e.,  $(Y^*(t)(I - B(t))Y(t+1))^{-1}$  is increasing. This contradicts (1.14) and completes the proof.

Next we consider two matrix systems:

$$(1.17)_i \quad \begin{aligned} \Delta Y(t) &= B_i(t)Y(t+1) + C_i(t)Z(t), \\ \Delta Z(t) &= -A_i(t)Y(t+1) - B_i^*(t)Z(t), \end{aligned} \quad i = 1, 2.$$

We make the same assumption on  $(1.17)_i$  as  $(1.8)_i$ . Using Theorem 3, it is easy to show:

**Theorem 9.** *If  $(1.17)_1$  is nonoscillatory and  $D_2(t) \geq D_1(t)$  for  $t \geq t_0 \geq M - 1$  for some integer  $t_0$ , then  $(1.17)_2$  is nonoscillatory as well.*

Next we wish to consider certain subsystems of (1.2). To this end we denote  $R = \{i_1, i_2, \dots, i_k\}$ ,  $1 \leq i_1 < i_2 < \dots < i_k \leq d$ ,  $A(t) = (a_{ij})_{d \times d}$ ,  $B(t) = (b_{ij})_{d \times d}$ , and  $C^{-1}(t) = (c_{ij})_{d \times d}$ . We suppose that  $B(t)$  satisfies  $b_{ij} = 0$  if  $i \notin R$  and  $j \in R$ .

Let

$$\tilde{A}(t) = (\tilde{a}_{ij})_{k \times k}, \quad \tilde{B}(t) = (\tilde{b}_{ij})_{k \times k}, \quad \tilde{C}(t) = (\tilde{c}_{ij})_{k \times k}^{-1},$$

where  $\tilde{a}_{ij} = a_{l_i l_j}$ ,  $\tilde{b}_{ij} = b_{l_i l_j}$ ,  $\tilde{c}_{ij} = c_{l_i l_j}$  if  $l_i, l_j \in R$ .

For the  $k \times k$  matrix system,

$$(1.18) \quad \begin{aligned} \Delta \tilde{Y}(t) &= \tilde{B}(t)\tilde{Y}(t+1) + \tilde{C}(t)\tilde{Z}(t), \\ \Delta \tilde{Z}(t) &= -\tilde{A}(t)\tilde{Y}(t+1) - \tilde{B}^*(t)\tilde{Z}(t). \end{aligned}$$

We have

**Theorem 10.** *If (1.18) is oscillatory, so is (1.2).*

*Proof.* Suppose (1.18) is oscillatory. Then by Theorem 1 we can find two integers  $M, N$  such that there exists a nonzero vector sequence  $\tilde{u}(t) = \begin{pmatrix} \tilde{y}(t) \\ \tilde{z}(t) \end{pmatrix} \in \tilde{\Omega}$ ,  $\tilde{y}(t) = (\tilde{y}_j)_k$ ,  $\tilde{z}(t) = (\tilde{z}_i)_k$ , with  $\tilde{q}[\tilde{u}] \leq 0$ . (Here  $\tilde{q}, \tilde{\Omega}$  correspond to (1.18).)

Let

$$u = \begin{bmatrix} y(t) \\ z(t) \end{bmatrix}, \quad y(t) = (y_j)_d, \quad z(t) = (z_i)_d,$$

with

$$y_{i_j} = \begin{cases} \tilde{y}_j & \text{if } i_j \in R, \\ 0 & \text{otherwise,} \end{cases} \quad z_{i_j} = \begin{cases} \tilde{z}_j & \text{if } i_j \in R, \\ 0 & \text{otherwise,} \end{cases}$$

Then from  $q[u] = \tilde{q}[\tilde{u}] \leq 0$  we conclude that (1.2) is oscillatory.

*Remark.* If  $B(t) \equiv 0$ , then Theorem 10 establishes the conjecture of [7].

**Theorem 11.** *If  $C^{-1}(t) \leq M$  (constant Hermitian matrix),  $\sum_{t=M}^{\infty} h(t)$  exists, and (1.2) is nonoscillatory, then*

$$\lim_{t \rightarrow \infty} C^{-1}(t)B(t) = L \quad (\text{constant Hermitian matrix});$$

furthermore,  $L \leq M$ .

*Proof.* Since (1.2) is nonoscillatory, there exists a Hermitian solution  $W(t)$  for  $t \geq t_0$  (some integer  $t_0 \geq M$ ) of (1.3) with  $W(t) + C^{-1}(t) > 0$ .

Taking the summation of both sides of (1.3), we have

$$(1.19) \quad -W(t+1) = W(t_0) + \sum_{\tau=t_0}^t \rho(\tau) + \sum_{\tau=t_0}^t h(\tau).$$

Now since  $-W(t+1) \leq C^{-1}(t+1) \leq M$ , and since  $\sum_{\tau=t_0}^t h(\tau)$  exists, it follows that  $\sum_{\tau=t_0}^{\infty} \rho(\tau)$  exists, so  $\lim_{t \rightarrow \infty} W(t) = W_0$ , a constant Hermitian matrix with  $W_0 \geq -M$ .

Since  $\rho(t) \geq 0$ , we have  $\lim_{t \rightarrow \infty} \rho(t) = 0$ . From (1.19) and  $C^{-1}(t) \leq M$ , it follows that  $W(t)$  is bounded, i.e.,  $\lambda_d((C^{-1}(t) + W(t))^{-1})$  does not go to zero as  $t \rightarrow \infty$ .

From the Courant-Fisher Theorem [6] we get

$$\lambda_1(\rho(t)) \geq \lambda_1[(W(t) + C^{-1}(t)B(t))^*(W(t) + C^{-1}(t)B(t))] \lambda_d[(C^{-1}(t) + W(t))^{-1}].$$

Now let  $t \rightarrow \infty$  to obtain

$$\lim_{t \rightarrow \infty} \lambda_1((W(t) + C^{-1}(t)B(t))^*(W(t) + C^{-1}(t)B(t))) = 0,$$

i.e.,

$$\lim_{t \rightarrow \infty} (W(t) + C^{-1}(t)B(t)) = 0,$$

i.e.,

$$\lim_{t \rightarrow \infty} C^{-1}(t)B(t) = \lim_{t \rightarrow \infty} (-W(t)) = -W_0 \leq M.$$

This completes the proof.

**Corollary 12.** *Suppose  $C^{-1}(t) \leq M$  (constant Hermitian matrix) and  $\liminf_{t \rightarrow \infty} \sum_{\tau=M}^t \lambda_d(h(\tau)) > -\infty$ . Then there exists a Hermitian solution  $W(t)$  for  $t \geq t_0 \geq M$  of (1.3) which satisfies  $\lim_{t \rightarrow \infty} (W(t) + C^{-1}(t)B(t)) = 0$ ; furthermore,  $C^{-1}(t)B(t)$  is bounded.*

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF ALBERTA, EDMONTON, ALBERTA, CANADA  
T6G 2G1