# FIXED POINTS FOR OPERATORS IN A SPACE OF CONTINUOUS FUNCTIONS AND APPLICATIONS 

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#### Abstract

This paper investigates the fixed points for self-maps of a closed set in a space of abstract continuous functions. Our main results essentially extend the Banach contracting mapping principle. An application to integrodifferential equations is given.


## 1. Introduction

Let $E$ be a real Banach space with norm $\|\cdot\|, I=[0, T](T>0)$. Denote $C[I, E]=\{u: I \rightarrow E \mid u(t)$ is continuous on $I\}$. It is easy to see that $C[I, E]$ is a Banach space with the norm $\|u\|_{C}=\max _{t \in I}\|u(t)\|$ for $u \in C[I, E]$. In this paper we investigate the fixed points for self-maps of a closed set in $C[I, E]$. We show that our main theorem extends the Banach contracting mapping principle in $C[I, E]$. Finally, an application to integro-differential equations is given.

## 2. Main Results

Theorem 2.1. Let $F$ be a closed subset of $C[I, E]$ and $A: F \rightarrow F$ an operator. If there exist $\alpha, \beta \in[0,1), K \geq 0$ such that for any $u, v \in F$,

$$
\begin{equation*}
\|A u(t)-A v(t)\| \leq \beta\|u(t)-v(t)\|+\frac{K}{t^{\alpha}} \int_{0}^{t}\|u(s)-v(s)\| d s, \quad \forall t \in(0, T] \tag{2.1}
\end{equation*}
$$

then $A$ has exactly one fixed point $u^{*}$ in $F$. For any $x_{0} \in F$, the iterative sequence $x_{n}=A x_{n-1}(n=1,2,3, \cdots)$ converges to $u^{*}$ in $F$ and for all $s>0$,

$$
\left\|x_{n}-u^{*}\right\|_{C}=o\left(n^{-s}\right) \quad(\text { as } n \rightarrow \infty)
$$

Proof. For any $u_{0} \in F$, set $u_{n}=A u_{n-1}(n=1,2,3, \cdots)$. By (2.1) we get

$$
\left\|u_{2}(t)-u_{1}(t)\right\| \leq\left(\beta+K t^{1-\alpha}\right)\left\|u_{1}-u_{0}\right\|_{C}, \quad \forall t \in(0, T] .
$$

[^0]It follows by induction and (2.1) that, for any $t \in(0, T]$,

$$
\begin{aligned}
\left\|u_{n+1}(t)-u_{n}(t)\right\| \leq & \left(\beta^{n}+\binom{n}{1} \beta^{n-1} K t^{1-\alpha}+\frac{\binom{n}{2} \beta^{n-2} K^{2} t^{2-2 \alpha}}{2-\alpha}+\cdots\right. \\
& \left.+\frac{K^{n} t^{n-n \alpha}}{(2-\alpha)(3-2 \alpha) \cdots(n-(n-1) \alpha)}\right)\left\|u_{1}-u_{0}\right\|_{C}
\end{aligned}
$$

$n=1,2,3, \cdots$. Therefore,
$\left\|u_{n+1}-u_{n}\right\|_{C} \leq\left(\beta^{n}+\binom{n}{1} \beta^{n-1} h+\frac{\binom{n}{2} \beta^{n-2} h^{2}}{2!}+\cdots+\frac{h^{n}}{n!}\right)\left\|u_{1}-u_{0}\right\|_{C}$,
where $h=K T^{1-\alpha}(1-\alpha)^{-1}$. It is easy to see that

$$
\lim _{k \rightarrow \infty}\left(\beta^{k-1} k\left(\frac{k}{k-1}\right)^{k-1}\right)^{1 / k}=\beta<1
$$

hence we can choose a fixed integer $k>2$ such that

$$
\left(\beta^{k-1} k\left(\frac{k}{k-1}\right)^{k-1}\right)^{1 / k} \equiv g<1
$$

For any $n$, set $n=k m+j(0 \leq j<k)$, where $k$ is given as above. Then whenever $n$ is sufficiently large, it follows from the Stirling formula that

$$
\begin{aligned}
S_{1} & \equiv \beta^{n}+\binom{n}{1} \beta^{n-1} h+\frac{\binom{n}{2} \beta^{n-2} h^{2}}{2!}+\cdots+\frac{\binom{n}{m} \beta^{n-m} h^{m}}{m!} \\
& \leq \beta^{n-m}\binom{n}{m}\left(1+h+\frac{h^{2}}{2!}+\cdots+\frac{h^{m}}{m!}\right)=O(1) \beta^{n-m}\binom{n}{m} \\
& =\frac{O(1) \beta^{n-m} n^{n} \sqrt{2 \pi n}\left(1+O\left(\frac{1}{m}\right)\right)}{m^{m} \sqrt{2 \pi m} \sqrt{2 \pi(n-m)}(n-m)^{n-m}}=O\left(\frac{k^{m}}{\sqrt{m}}\right)\left(\frac{\beta n}{n-m}\right)^{n-m} \\
& =O\left(\frac{\left(\beta^{k-1} k\left(\frac{k}{k-1}\right)^{k-1}\right)^{m}}{\sqrt{m}}\right)=O\left(\frac{g^{k m}}{\sqrt{m}}\right)=O\left(\frac{g^{n}}{\sqrt{n}}\right) .
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
S_{2} & \equiv \frac{\binom{n}{m+1} \beta^{n-m-1} h^{m+1}}{(m+1)!}+\cdots+\frac{h^{n}}{n!} \\
& \leq \frac{\binom{n}{\left[\frac{n}{2}\right]}}{(m+1)!}\left(\beta^{n-m-1} h^{m+1}+\cdots+h^{n}\right) \\
& =\frac{O\left(\frac{2^{n}}{\sqrt{n}}\right) e^{m+1}\left(\beta^{n-m-1} h^{m+1}+\cdots+h^{n}\right)}{\sqrt{2 \pi(m+1)}(m+1)^{m+1}\left(1+O\left(\frac{1}{m+1}\right)\right)} \\
& =o\left(\frac{1}{(m+1)^{s}}\right)=o\left(\frac{1}{n^{s}}\right) \quad(\text { as } n \rightarrow \infty)
\end{aligned}
$$

where $s>1$ can be any real constant.
Consequently, by (2.2) we have

$$
\begin{align*}
\left\|u_{n+1}-u_{n}\right\|_{C} & \leq\left(S_{1}+S_{2}\right)\left\|u_{1}-u_{0}\right\|_{C}  \tag{2.3}\\
& =O\left(\frac{g^{n}}{\sqrt{n}}\right)+o\left(\frac{1}{n^{s}}\right)=o\left(\frac{1}{n^{s}}\right) \quad(\text { as } n \rightarrow \infty)
\end{align*}
$$

which implies that, for any fixed $s>0$, there exists $n_{0}>0$ such that

$$
\left\|u_{n+1}-u_{n}\right\|_{C}<\frac{1}{n^{s+1}}, \quad \forall n>n_{0}
$$

Therefore, for any $q>0, n>n_{0}$, we have

$$
\left\|u_{n}-u_{n+q}\right\|_{C} \leq\left\|u_{n}-u_{n+1}\right\|_{C}+\cdots+\left\|u_{n+q-1}-u_{n+q}\right\|_{C}<\sum_{i=n}^{\infty} \frac{1}{i^{s+1}}
$$

Since (see, e.g. [1])

$$
\sum_{i=n}^{\infty} \frac{1}{i^{s+1}}=\frac{1}{s(n-1)^{s}}+o\left(\frac{1}{(n-1)^{s+1}}\right) \quad(\text { as } n \rightarrow \infty)
$$

we have $\left\|u_{n}-u_{n+q}\right\|_{C}=O\left(\frac{1}{n^{s}}\right)(\forall s>0)$. Hence $\left\{u_{n}\right\}$ is a Cauchy sequence and there exists $u^{*} \in F$ such that $\left\|u_{n}-u^{*}\right\|_{C} \rightarrow 0$ as $n \rightarrow \infty$. By (2.1),

$$
\begin{aligned}
\left\|A u^{*}(t)-u^{*}(t)\right\| & \leq\left\|A u^{*}(t)-A u_{n}(t)\right\|+\left\|A u_{n}(t)-u^{*}(t)\right\| \\
& \leq\left(\beta+K t^{1-\alpha}\right)\left\|u_{n}-u^{*}\right\|_{C}+\left\|u_{n+1}-u^{*}\right\|_{C}, \quad \forall t \in(0, T]
\end{aligned}
$$

and so

$$
\left\|A u^{*}-u^{*}\right\|_{C} \leq\left(\beta+K T^{1-\alpha}\right)\left\|u_{n}-u^{*}\right\|_{C}+\left\|u_{n+1}-u^{*}\right\|_{C}
$$

which implies by $\left\|u_{n}-u^{*}\right\|_{C} \rightarrow 0(n \rightarrow \infty)$ that $A u^{*}=u^{*}$.
For any $x_{0} \in F$, set $x_{n}=A x_{n-1}(n=1,2,3, \cdots)$. By (2.1) and using a similar way as establishing (2.3) we can get, for any $s>0$,

$$
\left\|x_{n}-u^{*}\right\|_{C}=o\left(\frac{1}{n^{s}}\right) \quad(\text { as } n \rightarrow \infty)
$$

which means that $u^{*}$ is the unique fixed point of $A$ since $x_{0} \in F$ is arbitrary. This completes the proof.
Remark 2.1. We show that Theorem 2.1 is a generalization of the Banach contraction mapping principle in $C[I, E]$.

On one hand, it is easy to give some self-maps of a closed subset of $C[I, E]$, which satisfy (2.1) but are not contractions. For example, operator $A: C[J, E] \rightarrow$ $C[J, E](J=[0,1])$ defined by

$$
A u(t)=\frac{1}{2} u(t)+2 t^{-\frac{1}{2}} \int_{0}^{t} u(s) d s, \quad \forall t \in(0,1], \quad A u(0)=\frac{1}{2} u(0)
$$

is such a map.
On the other hand, if $F$ is a closed subset of a Banach space $E$, operator $A$ : $F \rightarrow F$ satisfies

$$
\begin{equation*}
\|A u-A v\| \leq \alpha\|u-v\|, \quad \forall u, v \in F \tag{2.4}
\end{equation*}
$$

where $\alpha \in[0,1)$. Then Banach's theorem shows that $A$ has exactly one fixed point in $F$. We assert that this conclusion can also be obtained by Theorem 2.1. In fact, we can embed $F$ into $C[I, E]$ by regarding the elements of $F$ as constant-value functions of $C[I, E]$. Then $F$ is a closed set in $C[I, E]$ and $A: F \rightarrow F$ can be regarded as a map in $C[I, E]$. So (2.4) implies that $A$ satisfies (2.1) for $K=0$ and then, in the subset $F$ of $C[I, E], A$ has exactly one fixed point by Theorem 2.1, which is the unique fixed point of $A$ in the subset $F$ of $E$.
Remark 2.2. Considering the inequality (2.1), it seems that the right side of (2.1) may induce some new norms of $C[I, E]$ such that the contraction mapping principle can be applied in terms of such a new norm. We show that, even in special cases when new norms can be found, Theorem 2.1 cannot yet be replaced by the contraction mapping principle.

For example, let $E=R^{1}, \beta>0, \alpha=0, K=1$. Then a natural norm of $C\left[I, R^{1}\right]$ relative to the right side of $(2.1)$ is $\|\cdot\|_{X}$ defined by

$$
\|u\|_{X}=\frac{\beta}{\theta}\|u\|_{C}+\frac{1}{\theta} \int_{0}^{t_{0}}|u(s)| d s
$$

where $0<\theta<1$ may be any fixed real, $0<t_{0} \leq 1$ is a constant. (Although other norms can also be defined, the analogues of the following discussion are valid for them.) There are examples to show that operator $A$ may satisfy (2.1) and consequently,

$$
\begin{equation*}
\|A u-A v\|_{C} \leq \theta\|u-v\|_{X} \tag{2.5}
\end{equation*}
$$

but does not satisfy

$$
\begin{equation*}
\|A u-A v\|_{X} \leq \theta\|u-v\|_{X} \tag{2.6}
\end{equation*}
$$

Hence the contraction mapping principle cannot be applied to $A$ in terms of $\|\cdot\|_{X}$, but Theorem 2.1 can. The following is such an example:

$$
A u(t)=\beta u(t)+\int_{0}^{t} u(s) d s, \quad u \in C\left[I, R^{1}\right]
$$

where $1>\beta>\left(\left(4 t_{0}-t_{0}^{2}\right)^{1 / 2}-t_{0}\right) / 2$. Clearly, $A$ satisfies (2.1). But for any $u(t), v(t) \in C\left[I, R^{1}\right]$ with $u(t) \equiv u, v(t) \equiv v$ and $u>v$, we have

$$
A u(t)-A v(t)=(\beta+t)(u-v)
$$

So

$$
\|A u-A v\|_{X}=\frac{1}{\theta}\left(\beta^{2}+\beta+\beta t_{0}+\frac{t_{0}^{2}}{2}\right)(u-v), \quad\|u-v\|_{X}=\frac{\beta+t_{0}}{\theta}(u-v)
$$

Hence (2.6) is not satisfied for $A$ in $C\left[I, R^{1}\right]$ since $\beta>\left(\left(4 t_{0}-t_{0}^{2}\right)^{1 / 2}-t_{0}\right) / 2$.

As we proved Theorem 2.1, we can similarly prove
Theorem 2.2. Let $F \subset C[I, E]$ be a closed set and $A: F \rightarrow F$ an operator. If there exist $\alpha, \beta \in[0,1), K \geq 0$, where $\alpha$ satisfies $(-1)^{\alpha}=-1$, such that, for some fixed $\eta \in I=[0, T]$ and for any $u, v \in F$,

$$
\|A u(t)-A v(t)\| \leq \beta\|u(t)-v(t)\|+\frac{K}{(t-\eta)^{\alpha}} \int_{\eta}^{t}\|u(s)-v(s)\| d s, \quad \forall t \in I \backslash\{\eta\}
$$

then the conclusions of Theorem 2.1 hold.

## 3. An application

Consider the integro-differential equation of mixed type:

$$
\begin{equation*}
u^{\prime}(t)=f(t, u, T u, S u), \quad t \in J \equiv[0,1] ; \quad u(0)=u_{0} \tag{3.1}
\end{equation*}
$$

where $f \in C\left[J \times R^{1} \times R^{1} \times R^{1}, R^{1}\right], \quad u_{0} \in R^{1}$ and

$$
T u(t)=\int_{0}^{t} k(t, s) u(s) d s, \quad S u(t)=\int_{0}^{1} h(t, s) u(s) d s
$$

with $k \in C\left[\Omega, R_{+}\right], \Omega=\left\{(t, s) \in R^{2} \mid 0 \leq s \leq t \leq 1\right\}, h \in C\left[J \times J, R_{+}\right]$. Set $k_{0}=\max _{(t, s) \in \Omega} k(t, s), h_{0}=\max _{t, s \in J} h(t, s)$. We will use the following conditions:
$\left(\mathrm{H}_{1}\right)$ There exist $p, q \in C^{1}\left[J, R^{1}\right], p(t) \leq q(t)(t \in J)$ such that

$$
p^{\prime} \leq f(t, p, T p, S p), \quad p(t) \leq u_{0} ; \quad q^{\prime} \geq f(t, q, T q, S q), \quad q(t) \geq u_{0}
$$

$\left(\mathrm{H}_{2}\right)$ There exist $M>0, R \geq 0$ and $Q \geq 0$ such that

$$
f(t, u, v, w)-f(t, \bar{u}, \bar{v}, \bar{w}) \geq-M(u-\bar{u})-R(v-\bar{v})-Q(w-\bar{w})
$$

for $t \in J, p(t) \leq \bar{u} \leq u \leq q(t), T p(t) \leq \bar{v} \leq v \leq T q(t), S p(t) \leq \bar{w} \leq w \leq S q(t)$.
Theorem 3.1. Suppose that $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$ are satisfied and that

$$
\begin{equation*}
\left(R k_{0}+Q h_{0}\right)\left(e^{M}-1\right) \leq M, \quad Q h_{0}\left(e^{M}-1\right)<M \tag{3.2}
\end{equation*}
$$

Then there exist monotone sequences $\left\{p_{n}(t)\right\},\left\{q_{n}(t)\right\} \subset C^{1}\left[J, R^{1}\right]$ such that

$$
p(t)=p_{0}(t) \leq p_{1}(t) \leq \cdots \leq p_{n}(t) \leq \cdots \leq q_{n}(t) \leq \cdots \leq q_{1}(t) \leq q_{0}(t)=q(t)
$$

and $p_{n}(t) \rightarrow u_{*}(t), q_{n}(t) \rightarrow u^{*}(t)$ as $n \rightarrow \infty$ uniformly in $t \in J, u_{*}, u^{*} \in$ $C^{1}\left[J, R^{1}\right]$. Moreover, $u_{*}$ and $u^{*}$ are minimal and maximal solutions of IVP (3.1) on the interval $[p, q]$, respectively.
Proof. For any $\eta \in U \equiv\left\{\eta(t) \in C\left[J, R^{1}\right] \mid p \leq \eta \leq q\right\}$, consider the linear IVP

$$
\begin{equation*}
u^{\prime}=\sigma(t)-M u-R T u-Q S u, \quad u(0)=u_{0} \tag{3.3}
\end{equation*}
$$

where $\sigma(t)=f(t, \eta(t), T \eta(t), S \eta(t))+M \eta(t)+R T \eta(t)+Q S \eta(t)$. It is known that $u \in C^{1}\left[J, R^{1}\right]$ is a solution of (3.1) if and only if $u$ is a solution in $C\left[J, R^{1}\right]$ of the integral equation

$$
\begin{equation*}
u(t)=e^{-M t}\left\{u_{0}+\int_{0}^{t} e^{M s}(\sigma(s)-R T u(s)-Q S u(s)) d s\right\} \equiv B u(t) \tag{3.4}
\end{equation*}
$$

For any $u, v \in C\left[J, R^{1}\right]$,

$$
\begin{aligned}
|B u(t)-B v(t)|= & e^{-M t} \int_{0}^{t} e^{M s}|R T v(s)-R T u(s)+Q S v(s)-Q S u(s)| d s \\
\leq & R e^{-M t} \int_{0}^{t} e^{M s}\left[\int_{0}^{s} k(s, r)|v(r)-u(r)| d r\right] d s \\
& +Q\left|e^{-M t} \int_{0}^{1}(v(r)-u(r)) H(t, r) d r\right| \\
\leq & R k_{0} \frac{e^{M t}-1}{M} \int_{0}^{t}|u(r)-v(r)| d r+|L(u(t)-v(t))| \\
\leq & K \int_{0}^{t}|u(r)-v(r)| d r+|L(u(t)-v(t))|, \quad \forall t \in J
\end{aligned}
$$

where

$$
H(t, r)=\int_{0}^{t} e^{M s} h(s, r) d s, \quad L u(t)=Q \int_{0}^{1} H(t, r) u(r) d r
$$

and

$$
K=R k_{0}\left(e^{M}-1\right) M^{-1}
$$

By (3.2) we know that $\|L\|<1$, and consequently Theorem 2.1 shows that $B$ has exactly one fixed point in $C\left[J, R^{1}\right]$, that is, (3.3) has exactly one solution $u \in C^{1}\left[J, R^{1}\right]$.

Define $A \eta=u$, where $u$ is the unique solution of (3.3). Then $A: U \rightarrow$ $C^{1}\left[J, R^{1}\right] \subset C\left[J, R^{1}\right]$ and $\eta$ is a solution of IVP (3.1) if and only if $\eta=A \eta$.

Finally, a standard argument (see, e.g. [2,3]) shows that the conclusions of Theorem 3.1 hold. This completes the proof.

Remark 3.1. In order to guarantee the existence and uniqueness of the fixed point of $B$ defined by (3.4), we use Theorem 2.1 instead of Banach's theorem, which is widely used in most published papers (see, e.g. [2, 3]) but is invalid here.

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