# EXISTENCE AND NONEXISTENCE OF GLOBAL SOLUTIONS OF SOME NON-LOCAL DEGENERATE PARABOLIC SYSTEMS 

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#### Abstract

This paper establishes a new criterion for global existence and nonexistence of positive solutions of the non-local degenerate parabolic system $$
\begin{aligned} & u_{t}=v^{p}\left(\Delta u+a \int_{\Omega} v d x\right) \\ & v_{t}=u^{q}\left(\Delta v+b \int_{\Omega} u d x\right), \quad x \in \Omega, t>0 \end{aligned}
$$ with homogeneous Dirichlet boundary conditions, where $\Omega \subset \mathbb{R}^{N}$ is a bounded domain with a smooth boundary $\partial \Omega$ and $p, q, a, b$ are positive constants. For all initial data, it is proved that there exists a global positive solution iff $\int_{\Omega} \varphi(x) d x \leq 1 / \sqrt{a b}$, where $\varphi(x)$ is the unique positive solution of the linear elliptic problem $-\Delta \varphi(x)=1, x \in \Omega ; \varphi(x)=0, x \in \partial \Omega$.


## 1. Introduction

In [1], the authors investigate the global existence and nonexistence of positive solutions of the strongly coupled degenerate parabolic system

$$
\begin{align*}
u_{t} & =v^{p}(\Delta u+a u), \\
v_{t} & =u^{q}(\Delta v+b v), \quad x \in \Omega, t>0 \tag{1.1}
\end{align*}
$$

with homogeneous Dirichlet boundary conditions. It is shown that there exists a global positive solution if and only if $\lambda_{1} \geq \min \{a, b\}$, where $\lambda_{1}$ is the first Dirichlet eigenvalue for the Laplacian on $\Omega$.

In this paper, we study a new parabolic system with a non-local source

$$
\begin{align*}
u_{t} & =v^{p}\left(\Delta u+a \int_{\Omega} v d x\right), & & \\
v_{t} & =u^{q}\left(\Delta v+b \int_{\Omega} u d x\right), & & x \in \Omega, t>0,  \tag{1.2}\\
u(x, t) & =v(x, t)=0, & & x \in \partial \Omega, t>0, \\
u(x, 0) & =u_{0}(x), \quad v(x, 0)=v_{0}(x), & & x \in \Omega,
\end{align*}
$$

where $\Omega \subset \mathbb{R}^{N}$ is a bounded domain with a smooth boundary $\partial \Omega$ and $p, q, a, b$ are positive constants.

[^0]Over the past several years, a variety of non-local parabolic equations were studied by many authors (see [2]-[10] and references therein). In particular, some authors [8]-[10] studied a class of non-local degenerate parabolic equations which arise in a model of population that communicates through chemical means.

In order to motivate the main result for system (1.2), we recall a classical result of Galaktionov et al. (see [12], 13]) for the system

$$
\begin{align*}
& u_{t}=\Delta u^{\nu+1}+v^{p} \\
& v_{t}=\Delta v^{\mu+1}+u^{q}, \quad x \in \Omega, t>0 \tag{1.3}
\end{align*}
$$

with homogeneous Dirichlet boundary conditions. It is shown that if $p q<$ $(1+\mu)(1+\nu)$, every solution of (1.3) is global, while if $p q>(1+\mu)(1+\nu)$, there are solutions that blow up and others that are global. In the critical case where $p=1+\mu, q=1+\nu$, they proved that:
(1) If $\lambda_{1}>1$, all solutions of (1.3) are global.
(2) If $\lambda_{1}<1$, there are no nontrivial global solutions of (1.3).

Their results show that the first eigenvalue $\lambda_{1}$ plays a crucial role in the critical case $p q=(1+\mu)(1+\nu)$ (see also [14], [15]).

Similar results have also been obtained for the scalar equation

$$
u_{t}=u^{p}(\Delta u+u)
$$

It was shown that there exists a unique positive solution which blows up in finite time if $\lambda_{1}<1$ and exists globally if $\lambda_{1} \geq 1$ (see [16]-[18] and the references therein). But, for system (1.2), it seems that $\lambda_{1}$ no longer takes action. Motivated by these results, in this paper we will establish a new criterion for global existence and nonexistence of solutions for system (1.2).

Throughout this paper, the initial values and the boundary $\partial \Omega$ are assumed to satisfy

$$
\begin{align*}
& \partial \Omega \in C^{2+\alpha} \\
& u_{0}(x), \quad v_{0}(x) \in C^{1}(\bar{\Omega}), \quad u_{0}(x), \quad v_{0}(x)>0 \text { in } \Omega  \tag{H1}\\
& u_{0}(x)=v_{0}(x)=0, \quad \partial u_{0} / \partial n, \partial v_{0} / \partial n<0 \text { on } \partial \Omega
\end{align*}
$$

Definition 1.1. A positive solution of the system (1.2) is a vector function $(u, v) \in$ $C\left(\bar{\Omega} \times\left[0, T^{*}\right)\right) \cap C^{2,1}\left(\Omega \times\left(0, T^{*}\right)\right)$, positive in $\Omega \times\left(0, T^{*}\right)$ and satisfying (1.2), where $T^{*}$ is the maximal existence time of the solution. If $T^{*}=\infty$, we say $(u, v)$ is global.

In our considerations a crucial role is played by

$$
\begin{equation*}
\mu=\int_{\Omega} \varphi(x) d x \tag{1.4}
\end{equation*}
$$

where $\varphi(x)$ is the unique positive solution of the following linear elliptic problem

$$
\begin{equation*}
-\Delta \varphi(x)=1, x \in \Omega ; \varphi(x)=0, x \in \partial \Omega \tag{1.5}
\end{equation*}
$$

Then, let us state our main result.
Theorem 1.2. Assume that (H1) holds. Then there exists a global positive solution of (1.2) iff $\mu^{2} \leq 1 /(a b)$.

We are also interested in another non-local degenerate parabolic system, which is of the form

$$
\begin{align*}
& u_{t}=v^{p}\left(\Delta u+a \int_{\Omega} u d x\right) \\
& v_{t}=u^{q}\left(\Delta v+b \int_{\Omega} v d x\right), \quad x \in \Omega, t>0 \tag{1.6}
\end{align*}
$$

with similar initial-boundary conditions as in (1.2). For system (1.6), we get a different criterion as follows.

Theorem 1.3. Assume that (H1) holds. Then there exists a global positive solution of (1.6) iff $1 / \mu \geq \min \{a, b\}$.

The result shows that for system (1.6), it is not $\lambda_{1}$ but $1 / \mu$ that plays a crucial role. We will not discuss (1.6) in detail since it can be easily proved by combining the present arguments with those in [1].

Remark 1.4. Combining the arguments in [1] and in the present paper, we can show that $\lambda_{1}^{2} \geq a b$ is the critical condition of system

$$
u_{t}=v^{p}(\Delta u+a v), \quad v_{t}=u^{q}(\Delta v+b u)
$$

We will not give the proof here, since this paper is concerned about the non-local problem.

This paper is organized as follows. Section 2 establishes the local theory. Section 3 gives the proof of the main result.

## 2. Local existence

Set $Q_{T}=\Omega \times(0, T], S_{T}=\partial \Omega \times(0, T]$ for $0<T<\infty$. We first give a maximum principle for non-local systems, of which the proof is standard, and omit its proof.
Proposition 2.1. Suppose that $w_{1}(x, t), w_{2}(x, t) \in C\left(\overline{Q_{T}}\right) \cap C^{2,1}\left(Q_{T}\right)$ satisfy

$$
\begin{array}{ll}
w_{1 t}-d_{1} \Delta w_{1} \geq c_{11} w_{1}+c_{12} w_{2}+c_{13} w_{1} w_{2} & \\
\quad+c_{14} \int_{\Omega} c_{15} w_{1}(x, t) d x+c_{16} \int_{\Omega} c_{17} w_{2}(x, t) d x & \\
w_{2 t}-d_{2} \Delta w_{2} \geq c_{21} w_{1}+c_{22} w_{2}+c_{23} w_{1} w_{2} & \\
\quad+c_{24} \int_{\Omega} c_{25} w_{1}(x, t) d x+c_{26} \int_{\Omega} c_{27} w_{2}(x, t) d x, & (x, t) \in Q_{T} \\
w_{1}(x, t) \geq 0, w_{2}(x, t) \geq 0, & (x, t) \in S_{T} \\
w_{1}(x, 0) \geq 0, w_{2}(x, 0) \geq 0, & x \in \Omega
\end{array}
$$

where $d_{i}(x, t), c_{i j}(x, t)(i=1,2 ; j=1, \ldots, 7)$ are bounded functions and

$$
d_{1}, d_{2}, c_{12}, c_{21}, c_{1 j}, c_{2 j} \geq 0, j=4, \ldots, 7 \quad \text { in } \quad Q_{T}
$$

Then $w_{j}(x, t) \geq 0$ on $\overline{Q_{T}}$.
Proposition 2.2. Let $(\tilde{u}, \tilde{v}) \in C\left(\overline{Q_{T}}\right) \cap C^{2,1}\left(Q_{T}\right)$ and $(\bar{u}, \bar{v}) \in C\left(\overline{Q_{T}}\right) \cap C^{2,1}\left(Q_{T}\right)$ be a nonnegative subsolution and a nonnegative supersolution of (1.2), respectively. Assume that $(\bar{u}, \bar{v}) \geq \delta>0$ and either

$$
\begin{equation*}
\Delta \tilde{u}+a \int_{\Omega} \tilde{v} d x \geq 0, \quad \Delta \tilde{v}+b \int_{\Omega} \tilde{u} d x \geq 0 \tag{2.1}
\end{equation*}
$$

$$
\begin{equation*}
\Delta \bar{u}+a \int_{\Omega} \bar{v} d x \geq 0, \quad \Delta \bar{v}+b \int_{\Omega} \bar{u} d x \geq 0 \tag{2.2}
\end{equation*}
$$

hold. Then $(\tilde{u}, \tilde{v}) \leq(\bar{u}, \bar{v})$ on $\overline{Q_{T}}$ if $\left(\tilde{u}_{0}, \tilde{v}_{0}\right) \leq\left(\bar{u}_{0}, \bar{v}_{0}\right)$.
Proof. This proposition is a direct consequence of Proposition 2.1
Next, in this section, we will give the local existence of the solution for system (1.2) by the same method utilized in 1]. For system (1.2) we introduce, for $n=$ $1,2, \ldots$, the following regularized system:

$$
\begin{align*}
u_{n t} & =v_{n}^{p}\left(\Delta u_{n}+a \int_{\Omega} v_{n} d x\right), & & \\
v_{n t} & =u_{n}^{q}\left(\Delta v_{n}+b \int_{\Omega} u_{n} d x\right), & & x \in \Omega, t>0  \tag{2.3}\\
u_{n}(x, t) & =v_{n}(x, t)=1 / n, & & x \in \partial \Omega, t>0 \\
u_{n}(x, 0) & =u_{0}(x)+1 / n, \quad v_{n}(x, 0)=v_{0}(x)+1 / n, & & x \in \Omega
\end{align*}
$$

By a similar discussion as in [7], under (H1), we can show that (2.3) has a classical solution ( $u_{n}, v_{n}$ ) with $u_{n}, v_{n} \geq 1 / n$, defined on $\bar{\Omega} \times\left[0, T_{n}^{*}\right)$, where $T_{n}^{*}$ is the maximal existence time.

Now we construct a uniform upper bound for $\left(u_{n}, v_{n}\right)$. Consider the ordinary differential equation

$$
\begin{align*}
H^{\prime}(t) & =\hat{a}(H(t))^{\hat{p}} \\
H(0) & =\max \left\{\max _{x \in \bar{\Omega}} u_{0}(x)+1, \max _{x \in \bar{\Omega}} v_{0}(x)+1\right\} \tag{2.4}
\end{align*}
$$

where $\hat{a}=\max \{a|\Omega|, b|\Omega|\}, \hat{p}=\max \{p+1, q+1\}$. Obviously, there exists $T_{0}>0$ such that (2.4) has a non-decreasing solution $H(t)>0$ on $\left[0, T_{0}\right]$; namely, $0<$ $H(0) \leq H(t) \leq H\left(T_{0}\right)<\infty$. Using Proposition 2.2 for system (2.3), we obtain the following lemma.

Lemma 2.3. There exist $T_{0}$ and an a priori bound $H(t)$ depending only on $u_{0}, v_{0}, \hat{a}$ and $\hat{p}$ such that for all $n \geq 1$ the solution of (2.3) satisfies $u_{n}, v_{n} \leq H(t)$ on $\overline{Q_{T_{0}}}$.

Denote by $\lambda_{1}>0$ and $\phi(x)$ the first eigenvalue and the corresponding eigenfunction of the following eigenvalue problem

$$
-\Delta \phi(x)=\lambda \phi(x), x \in \Omega ; \phi(x)=0, x \in \partial \Omega
$$

It is well known that $\phi(x)$ may be normalized as $\phi(x)>0$ in $\Omega$ and $\max _{\Omega} \phi(x)=1$. Thus, by Proposition 2.1, we have

Lemma 2.4. Let $h(x, t)=k e^{-\rho t} \phi(x)$, where $k$ is small such that $u_{0}, v_{0} \geq k \phi(x)$ and $\rho=\max \left\{\lambda_{1}\left(H\left(T_{0}\right)\right)^{p}, \lambda_{1}\left(H\left(T_{0}\right)\right)^{q}\right\}$. Then for all $n \geq 1$, it holds that $u_{n}, v_{n} \geq$ $h(x, t)$ in $\overline{Q_{T_{0}}}$.

In proving there exists a positive solution of (1.2), we still need the following regularity lemma, whose proof is similar to [1, Lemma 2.3].

Lemma 2.5. $u_{n}, v_{n} \in V_{2}^{1,0}\left(Q_{T_{0}}\right)($ see [19, p. 6] $)$.

Then by the so-called extension method (for details see [1]), we have that there exists a subsequence $\left\{n_{i}\right\}$ of $\{n\}$ such that

$$
\begin{equation*}
\lim _{i \rightarrow \infty}\left(u_{n_{i}}, v_{n_{i}}\right)=(u, v) \quad \text { in } \quad C^{2,1}\left(Q_{T_{0}}\right) \tag{2.5}
\end{equation*}
$$

Similarly, we can show that $u, v$ are continuous at any point $(y, t), y \in \partial \Omega$ and $u(y, t)=0$ (see [16], [20]), and continuous up to $\{t=0\}$ (see [21], 22]).

Let $T^{*}$ be the supremum over $T_{0}$ for which $(u, v)$ exists on $\left(0, T_{0}\right)$. Thus, we have

Theorem 2.6. Assume that (H1) holds. Then there exists a positive solution of (1.2) on $\left(0, T^{*}\right)$. Moreover, if $T^{*}<\infty$, then

$$
\limsup _{t \rightarrow T^{*}}\|u(x, t)\|_{L^{\infty}}=+\infty \quad \text { or } \quad \limsup _{t \rightarrow T^{*}}\|v(x, t)\|_{L^{\infty}}=+\infty
$$

Remark 2.7. Obviously, all discussions of this section are applicable to system (1.6).

## 3. Proof of the main result

In order to prove the main result, we give an auxiliary lemma first. Let $G$ be a bounded smooth domain of $\mathbb{R}^{N}$. Consider the problem

$$
\begin{align*}
w_{t} & =d w^{r}\left(\Delta w+a_{0} \int_{G} w d x\right), & & x \in G, t>0, \\
w(x, t) & =c, & & x \in \partial G, t \geq 0  \tag{3.1}\\
w(x, 0) & =c, & & x \in G,
\end{align*}
$$

where $0<r<1$ and $a_{0}, c, d$ are positive constants. By the standard method (see [7], [10]), it follows that (3.1) has a unique classical solution $w(x, t)$ and $w(x, t) \geq c$. Denote by $\varphi_{0}(x)$ the unique positive solution of the linear elliptic problem

$$
-\Delta \varphi_{0}(x)=1, \quad x \in G ; \quad \varphi_{0}(x)=0, \quad x \in \partial G
$$

Set $\mu_{0}=\int_{G} \varphi_{0}(x) d x$. Thus, we have
Lemma 3.1. If $\mu_{0}>1 / a_{0}$, then the positive solution of (3.1) blows up in finite time.
Proof. Set $F(t)=\int_{G} w^{1-r} \varphi_{0} d x$; then

$$
\begin{align*}
\frac{1}{1-r} F^{\prime}(t) & =d\left(\int_{G} \Delta w \varphi_{0} d x+a_{0} \int_{G} w d x \int_{G} \varphi_{0} d x\right) \\
& \geq d\left(a_{0} \mu_{0}-1\right) \int_{G} w d x  \tag{3.2}\\
& \geq d\left(a_{0} \mu_{0}-1\right)\left(\int_{G} w \varphi_{0} d x\right) / M
\end{align*}
$$

where $M=\max _{x \in \bar{G}}\left\{\varphi_{0}(x)\right\}$. Letting $z=w^{1-r}$ in (3.2) yields

$$
\int_{G} z_{t}(x, t) \varphi_{0} d x \geq d(1-r)\left(a_{0} \mu_{0}-1\right)\left(\int_{G} z^{1 /(1-r)} \varphi_{0} d x\right) / M
$$

Since $\frac{1}{1-r}>1$, by the Jensen inequality, it follows that

$$
\int_{G} z_{t}(x, t) \varphi_{0} d x \geq d(1-r)\left(a_{0} \mu_{0}-1\right)\left(\mu_{0}\right)^{-r /(1-r)}\left(\int_{G} z \varphi_{0} d x\right)^{1 /(1-r)} / M
$$

That is,

$$
F^{\prime}(t) \geq C_{0}(F(t))^{1 /(1-r)}
$$

where $C_{0}=d(1-r)\left(a_{0} \mu_{0}-1\right)\left(\mu_{0}\right)^{-r /(1-r)} / M>0$. In view of $1 /(1-r)>1$ and $F(0)>0$, it follows that there exists $T<\infty$ such that $\lim _{t \rightarrow T} F(t)=+\infty$, and hence $w(x, t)$ blows up in finite time.

Lemma 3.2. Assume that (H1) holds. Then there exist positive constants $k_{1}, k_{2}$ such that $u(x, t) \geq k_{1} \varphi, v(x, t) \geq k_{2} \varphi$ for $(x, t) \in \bar{\Omega} \times\left[0, T^{*}\right)$ if $\mu^{2} \geq 1 /(a b)$.
Proof. From (H1), since $\mu^{2} \geq 1 /(a b)$ we see that there exist positive constants $k_{1}$ and $k_{2}$ such that

$$
\begin{equation*}
u_{0}(x) \geq k_{1} \varphi(x), \quad v_{0}(x) \geq k_{2} \varphi(x), \quad x \in \bar{\Omega} \tag{3.3}
\end{equation*}
$$

and

$$
\begin{equation*}
a \mu \geq k_{1} / k_{2} \geq 1 /(b \mu) \tag{3.4}
\end{equation*}
$$

Let $w(x, t)=u(x, t)-k_{1} \varphi(x), s(x, t)=v(x, t)-k_{2} \varphi(x)$. Then we obtain, by (3.4), for any $T \in\left(0, T^{*}\right)$,

$$
\begin{align*}
w_{t} & =u_{t}=v^{p}\left(\Delta u+a \int_{\Omega} v d x\right) \\
& =v^{p}\left(\Delta w+a \int_{\Omega} s d x\right)+v^{p}\left(-k_{1}+a k_{2} \mu\right) \\
& \geq v^{p}\left(\Delta w+a \int_{\Omega} s d x\right),  \tag{3.5}\\
& \\
s_{t} & \geq u^{q}\left(\Delta s+b \int_{\Omega} w d x\right), \\
& x \in \Omega, 0<t \leq T \\
w(x, t) & =s(x, t)=0,
\end{align*}
$$

By Proposition 2.1, it follows from (3.3) and (3.5) that $w \geq 0, s \geq 0$ and hence $u \geq k_{1} \varphi, v \geq k_{2} \varphi$ on $\bar{\Omega} \times[0, T]$. The arbitrariness of $T$ shows that the result holds.

Lemma 3.3. Assume that (H1) holds. Then no global solution of (1.2) exists if $\mu^{2}>1 /(a b)$.

Proof. Denote by $\varphi_{1}(x)$ the unique positive solution of the linear elliptic problem

$$
-\Delta \varphi_{1}(x)=1, \quad x \in \Omega_{1} ; \quad \varphi_{1}(x)=0, \quad x \in \partial \Omega_{1}
$$

Here $\Omega_{1} \subset \subset \Omega$. Since the function $U:=\varphi-\varphi_{1} \geq 0$ is harmonic in $\Omega_{1}$ and satisfies $U \leq \varphi$ on $\partial \Omega_{1}$, we have $\left\|\varphi-\varphi_{1}\right\|_{\infty} \leq\|\varphi\|_{L^{\infty}\left(\partial \Omega_{1}\right)}$ by the maximum principle. By the continuity of $\varphi$ it follows that $\left\|\varphi-\varphi_{1}\right\|_{\infty} \rightarrow 0$, as $\operatorname{dist}\left(\partial \Omega_{1}, \partial \Omega\right) \rightarrow 0$. Let $\mu_{1}=\int_{\Omega_{1}} \varphi_{1}(x) d x$. The above discussion implies, in particular, $\mu_{1} \rightarrow \mu$, as $\operatorname{dist}\left(\partial \Omega_{1}, \partial \Omega\right) \rightarrow 0$.

Therefore, in view of $\mu^{2}>1 /(a b)$, we can choose a smooth sub-domain $\Omega_{1} \subset \subset \Omega$ such that $\mu_{1}^{2}>1 /(a b)$. Denote

$$
\delta=\frac{1}{2} \min \left\{k_{1} \frac{\min }{\bar{\Omega}_{1}} \varphi, k_{2} \frac{\min }{\Omega_{1}} \varphi\right\}
$$

Then $\delta>0$ and

$$
u(x, t) \geq 2 \delta, \quad v(x, t) \geq 2 \delta, \quad \forall(x, t) \in \overline{\Omega_{1}} \times\left[0, T^{*}\right)
$$

by Lemma 3.2 Then $(u, v)$ in $\Omega_{1} \times\left(0, T^{*}\right)$ satisfies

$$
\begin{array}{rlrl}
u_{t} & =v^{p}\left(\Delta u+a \int_{\Omega} v d x\right) & & \\
& \geq v^{p}\left(\Delta u+a \int_{\Omega_{1}} v d x\right), & & \\
v_{t} & \geq u^{q}\left(\Delta v+b \int_{\Omega_{1}} u d x\right), \quad & x \in \Omega_{1}, t \in\left(0, T^{*}\right),  \tag{3.6}\\
u(x, t) & \geq 2 \delta, \quad v(x, t) \geq 2 \delta, & & x \in \partial \Omega_{1}, t \in\left(0, T^{*}\right), \\
u(x, 0) & \geq 2 \delta, \quad v(x, 0) \geq 2 \delta, & & x \in \Omega_{1} .
\end{array}
$$

Now, we consider the system

$$
\begin{align*}
\underline{u}_{t} & =\underline{v}^{p}\left(\Delta \underline{u}+a \int_{\Omega_{1}} \underline{v} d x\right), & & \\
\underline{v}_{t} & =\underline{u}^{q}\left(\Delta \underline{v}+b \int_{\Omega_{1}} \underline{u} d x\right), & & x \in \Omega_{1}, t>0  \tag{3.7}\\
\underline{u}(x, t) & =f(t), \underline{v}(x, t)=g(t), & & x \in \partial \Omega_{1}, t>0, \\
\underline{u}(x, 0) & =\underline{v}(x, 0)=\delta, & & x \in \Omega_{1},
\end{align*}
$$

where $f(t), g(t)$ satisfy

$$
\begin{aligned}
& f(t), g(t) \in C^{\infty}([0, \infty)), f^{\prime}(t), g^{\prime}(t)>0, f(t), g(t) \leq 2 \delta \\
& f(0)=g(0)=\delta, f^{\prime}(0)=a\left|\Omega_{1}\right| \delta^{p+1}, g^{\prime}(0)=b\left|\Omega_{1}\right| \delta^{q+1}
\end{aligned}
$$

A similar discussion as in [7] shows that there exists a unique classical solution $(\underline{u}, \underline{v}) \in C^{2+\beta, 1+\beta / 2}\left(\overline{\Omega_{1}} \times\left[0, T_{1}\right)\right)$ for some $\beta \in(0,1)$, where $T_{1}$ is the maximal existence time, and

$$
\begin{equation*}
\underline{u}, \underline{v} \geq \delta \quad \text { in } \overline{\Omega_{1}} \times\left[0, T_{1}\right) \tag{3.8}
\end{equation*}
$$

Since the initial data is a subsolution of (3.7), we have $\underline{u}_{t}, \underline{v}_{t} \geq 0$ in $\overline{\Omega_{1}} \times\left[0, T_{1}\right.$ ) and hence

$$
\begin{equation*}
\Delta \underline{u}+a \int_{\Omega_{1}} \underline{v} d x \geq 0, \quad \Delta \underline{v}+b \int_{\Omega_{1}} \underline{u} d x \geq 0 \quad \text { in } \overline{\Omega_{1}} \times\left[0, T_{1}\right) \tag{3.9}
\end{equation*}
$$

Thus from Proposition 2.2, we have $T_{1} \geq T^{*}$ and

$$
u(x, t) \geq \underline{u}(x, t), \quad v(x, t) \geq \underline{v}(x, t) \quad \text { in } \overline{\Omega_{1}} \times\left[0, T^{*}\right) .
$$

Therefore, it suffices to show that $(\underline{u}, \underline{v})$ blows up in finite time, because if so, its upper bound $(u, v)$ does exist up to a finite time $T^{*}$.

By (3.8) and (3.9), we have

$$
\begin{align*}
& \underline{u}_{t} \geq \delta^{p-r} \underline{v}^{r}\left(\Delta \underline{u}+a \int_{\Omega_{1}} \underline{v} d x\right) \\
& \underline{v}_{t} \geq \delta^{q-r} \underline{u}^{r}\left(\Delta \underline{v}+b \int_{\Omega_{1}} \underline{u} d x\right) \quad \text { in } \quad \Omega_{1} \times\left(0, T_{1}\right) \tag{3.10}
\end{align*}
$$

with the corresponding initial and boundary conditions and $0<r<1$.
By use of $\mu_{1}^{2}>1 /(a b)$, there exist positive constants $l_{1}, l_{2}$ with $l_{1}, l_{2}>1$, and $l$ such that

$$
\begin{equation*}
a \mu_{1}>\frac{l_{1}}{l_{2}}>\frac{1}{b \mu_{1}}, \mu_{1}>\frac{1}{l}>\frac{l_{1}}{a l_{2}}, \mu_{1}>\frac{1}{l}>\frac{l_{2}}{b l_{1}} . \tag{3.11}
\end{equation*}
$$

Choose

$$
\begin{equation*}
d=\min \left\{\delta^{p-r}, \delta^{q-r}\right\}, \quad \gamma=\min \left\{1 / l_{1}, 1 / l_{2}\right\} \tag{3.12}
\end{equation*}
$$

Denote by $z(x, t)$ the unique positive solution of the problem

$$
\begin{align*}
z_{t} & =d z^{r}\left(\Delta z+l \int_{\Omega_{1}} z d x\right), & & x \in \Omega_{1}, t>0 \\
z(x, t) & =\gamma \delta, & & x \in \partial \Omega_{1}, t \geq 0  \tag{3.13}\\
z(x, 0) & =\gamma \delta, & & x \in \Omega_{1},
\end{align*}
$$

where $l, d, \gamma$ satisfy (3.11) and (3.12). By Lemma 3.1 it follows that $z(x, t)$ blows up in finite time $T_{0}<\infty$. Moreover, $z_{t} \geq 0$, i.e., $\Delta z+l \int_{\Omega_{1}} z d x \geq 0$, since the initial data is a subsolution of (3.13). Let

$$
w(x, t)=l_{1} z(x, t), \quad s(x, t)=l_{2} z(x, t)
$$

Thus, from (3.11) -(3.13) and $l_{1}, l_{2}>1$, we have

$$
\begin{align*}
& w_{t}-\delta^{p-r} s^{r}\left(\Delta w+a \int_{\Omega_{1}} s d x\right)=l_{1} d z^{r}\left(\Delta z+l \int_{\Omega_{1}} z d x\right) \\
& \quad-l_{1} \delta^{p-r}\left(l_{2} z\right)^{r}\left(\Delta z+\left(a l_{2} / l_{1}\right) \int_{\Omega_{1}} z d x\right) \leq 0 \\
& s_{t}-\delta^{q-r} w^{r}\left(\Delta s+b \int_{\Omega_{1}} w d x\right) \leq 0, \quad x \in \Omega_{1}, 0<t<T_{0}  \tag{3.14}\\
& w(x, t)=l_{1} \gamma \delta \leq \delta, s(x, t)=l_{2} \gamma \delta \leq \delta, \quad x \in \partial \Omega_{1}, 0 \leq t<T_{0} \\
& w(x, 0)=l_{1} \gamma \delta \leq \delta, s(x, 0)=l_{2} \gamma \delta \leq \delta, \quad x \in \Omega_{1}
\end{align*}
$$

By use of Proposition [2.2, it follows from (3.8), (3.10), (3.14) and $\Delta z+l \int_{\Omega_{1}} z d x \geq 0$ that

$$
(\underline{u}, \underline{v}) \geq\left(l_{1} z, l_{2} z\right) \quad \text { in } \Omega_{1} \times\left(0, T_{1}\right) .
$$

Hence $(\underline{u}, \underline{v})$ blows up in finite time since $z(x, t)$ does. Therefore, $(u, v)$ exists no later than $T_{0}<\infty$. This completes the proof.

Lemma 3.4. Assume that (H1) holds. Then the positive solution ( $u, v$ ) of (1.2) defined by (2.5) is global if $\mu^{2} \leq 1 /(a b)$.

Proof. Applying $\mu^{2} \leq 1 /(a b)$ and (H1) we see that there exist large positive constants $K_{1}$ and $K_{2}$ such that

$$
\begin{equation*}
a \mu \leq K_{1} / K_{2} \leq 1 /(b \mu) \tag{3.15}
\end{equation*}
$$

and

$$
\begin{equation*}
u_{0}(x) \leq K_{1} \varphi(x), \quad v_{0}(x) \leq K_{2} \varphi(x), \quad \forall x \in \bar{\Omega} \tag{3.16}
\end{equation*}
$$

Let $W(x, t)=K_{1} \varphi(x)-u(x, t), S(x, t)=K_{2} \varphi(x)-v(x, t)$. Then, from (3.15), we obtain, for any $T \in\left(0, T^{*}\right)$,

$$
\begin{align*}
W_{t} & =-u_{t}=-v^{p}\left(\Delta u+a \int_{\Omega} v d x\right) \\
& =v^{p}\left(\Delta W+a \int_{\Omega} S d x\right)+v^{p}\left(K_{1}-a K_{2} \mu\right) \\
& \geq v^{p}\left(\Delta W+a \int_{\Omega} S d x\right),  \tag{3.17}\\
S_{t} & \geq u^{q}\left(\Delta S+b \int_{\Omega} W d x\right), \quad x \in \Omega, 0<t \leq T \\
W(x, t) & =S(x, t)=0,
\end{align*}
$$

By Proposition 2.1 it follows from (3.16) and (3.17) that $W \geq 0, S \geq 0$ and hence $u \leq K_{1} \varphi, v \leq K_{2} \varphi$ on $\bar{\Omega} \times[0, T]$. The arbitrariness of $T$ shows that $u \leq K_{1} \varphi, v \leq$ $K_{2} \varphi$ on $\bar{\Omega} \times\left[0, T^{*}\right)$. Therefore, the solution $(u, v)$ of (1.2) defined by (2.5) exists globally.

From Lemma 3.3 and Lemma 3.4 , it follows that Theorem 1.2 holds.
Remark 3.5. From Lemma 3.2 and Lemma 3.4, we have that if $\mu^{2}=1 /(a b)$, there exist positive constants $k_{1}, k_{2}, K_{1}$ and $K_{2}$ such that $k_{1} \varphi \leq u(x, t) \leq K_{1} \varphi, k_{2} \varphi \leq$ $u(x, t) \leq K_{2} \varphi$ for $x \in \bar{\Omega}$ and $t>0$.

Remark 3.6. Theorem 1.3 for system (1.6) can be proved by combining the present arguments (for system (1.2)) with those in [1] (for system (1.1)).

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