BOREL CLASSES OF SETS OF EXTREME AND EXPOSED POINTS IN $\mathbb{R}^n$

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ABSTRACT. It is known that the sets of extreme and exposed points of a convex Borel subset of $\mathbb{R}^n$ are Borel. We show that for $n \geq 4$ there exist convex G_δ subsets of $\mathbb{R}^n$ such that the sets of their extreme and exposed points coincide and are of arbitrarily high Borel class. On the other hand, we show that the sets of extreme and of exposed points of a convex set $C \subset \mathbb{R}^3$ of additive Borel class α are of ambiguous Borel class $\alpha + 1$. For proving the latter-mentioned results we show that the union of the open and the union of the closed segments of $C \cap \partial C$ are of the additive Borel class α if $C \subset \mathbb{R}^3$ is a convex set of additive Borel class α .

1. INTRODUCTION

Rogers showed in [9] that the set $\text{ext } C$ of all extreme points of every convex Borel subset of $\mathbb{R}^n$ is Borel. Jayne and Rogers proved in the introduction of [5] that also the set $\text{exp } C$ of all exposed points of any convex Borel subset of $\mathbb{R}^n$ is Borel. Thus they improved the result of [1] that $\text{exp } C$ is Borel if C is a closed convex subset of a Euclidean space. The mentioned results and the methods of their proofs in [9] and [5] do not give any information about the dependence of the Borel classes of the sets $\text{ext } C$ and $\text{exp } C$ on the Borel class of C . The only published results in this direction that we know about concern convex F_σ subsets of $\mathbb{R}^n$. Jayne and Rogers explain in [5, p. 252] that even for every convex K_σ subset C of any Banach space, the set $\text{ext } C$ is G_δ in C . Choquet, Corson and Klee give a more detailed description of $\text{exp } C$ for closed convex subsets of $\mathbb{R}^n$ in [1, Theorem 1.1] depending on the dimension n . For arbitrary n their result gives that $\text{exp } C$ is of ambiguous class Δ_3^0 . Theorem 1 and the remark “Added in proof” at the end of Section 1 in [3] give in particular that $\text{exp } C$ is in Π_3^0 for every convex K_σ subset of a Banach space.

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In Example 3.1 we show that for convex G_δ subsets C of $\mathbb{R}^n$, $n \geq 4$, one cannot get any uniform bound on the Borel classes of the sets of extreme and exposed points of C . On the other hand, we prove that in $\mathbb{R}^3$ there is a bound $\beta(\alpha)$ of the Borel classes of $\text{ext } C$ and $\text{exp } C$ depending on the Borel class α of C only. We also give examples showing that our estimates are sharp.

2. PRELIMINARIES

For any two distinct points $a, b \in \mathbb{R}^n$ we use the notation $]a, b[$ for the *open segment* $\{(1-t)a+tb; 0 < t < 1\}$ and $[a, b]$ for the *closed segment* $\{(1-t)a+tb; 0 \leq t \leq 1\}$.

Let us recall that a point x of a convex set C is called an *extreme point* of C if $x \notin]a, b[$ for any distinct elements a and b of C .

The point x is called an *exposed point* of a convex set C if there is a continuous linear functional which attains its maximum on C at x and only at x . (Note that every exposed point of a convex set C is also an extreme point of C , but the converse is not always true.)

As we already mentioned in the introduction, we use $\text{ext } C$ and $\text{exp } C$ to denote the sets of all extreme and exposed points of C , respectively.

Given a nontrivial linear form $L : \mathbb{R}^n \rightarrow \mathbb{R}$ and a real number r , we call the hyperplane $S = \{x \in \mathbb{R}^n; L(x) = r\}$ a *supporting hyperplane* of a convex set C (at point $x \in C$) if $L(x) = r$ and either $L(y) \leq r$ for all $y \in C$ or $L(y) \geq r$ for all $y \in C$. So x is an exposed point of a convex set C if and only if $\{x\} = C \cap S$ for some supporting hyperplane of C .

If S is a supporting hyperplane of C and the affine hull of $S \cap C$ has dimension n , we say that $S \cap C$ is an *n -dimensional face* of C . (Let us notice that our n -dimensional faces do not coincide with n -faces of [1].)

The boundary, the closure and the convex hull of a set A will be denoted by ∂A , $\overline{A}$ and $\text{conv } A$, respectively.

We use the notation Π_α^0 , Σ_α^0 and Δ_α^0 in M for the multiplicative, additive and ambiguous classes $\Pi_\alpha^0(M)$, $\Sigma_\alpha^0(M)$ and $\Delta_\alpha^0(M)$ of Borel subsets of the metric space M , respectively:

$\Pi_1^0(M)$ stands for the closed, $\Sigma_1^0(M)$ for the open and $\Delta_1^0(M)$ for the clopen subsets of M ,

$$\Sigma_\alpha^0(M) = \{\bigcup_{n \in \mathbb{N}} A_n; A_n \in \Pi_{\alpha_n}^0(M), \alpha_n < \alpha\},$$

$$\Pi_\alpha^0(M) = \{M \setminus A; A \in \Sigma_\alpha^0(M)\} \text{ and}$$

$$\Delta_\alpha^0(M) = \Pi_\alpha^0(M) \cap \Sigma_\alpha^0(M)$$

for $1 < \alpha < \omega_1$ (cf. [6, p. 68]). We omit M if $M = \mathbb{R}^n$ and the value of n is clear from the context. We preferably use the more descriptive notation G_δ for Π_2^0 , F_σ for Σ_2^0 , etc.

3. EXAMPLE IN $\mathbb{R}^4$

The following example shows that, if $n \geq 4$, then $\text{ext } C$ and $\text{exp } C$ can belong to arbitrary exact Borel classes (except for Σ_1^0) even if C is a convex G_δ subset of $\mathbb{R}^n$. One has to realize only that in any interval there are Borel subsets of all exact Borel classes [6, Theorem 22.4].

Example 3.1. For any Borel subset E of a circle in $\mathbb{R}^4$ (e.g. $E \subset \{x \in \mathbb{R}^4; x_1^2 + x_2^2 = 1, x_3 = x_4 = 0\}$), there is a bounded convex G_δ set $C \subset \mathbb{R}^4$ such that $\text{ext } C = \text{exp } C = E$.

Proof. There are obvious examples if $E = \emptyset$. Thus we may assume without loss of generality that $E \subset \{x \in \mathbb{R}^4; x_1^2 + x_2^2 = 1, x_3 = x_4 = 0\}$ and $(1, 0, 0, 0) \in E$. Denote $B = \{a \in [0, 2\pi); (\cos a, \sin a, 0, 0) \notin E\}$. We have $0 \notin B$. By a classical theorem (see e.g. [6, p. 83]), there is a one-to-one continuous map $f : F \rightarrow B$ of a G_δ subset F of $[0, 1]$ onto the Borel set B . We denote the graph of f by G and note that it is a G_δ subset of $[0, 1] \times [0, 2\pi)$ and the projection of G onto B is injective.

Now we define our set C by the equality $C = C_0 \cup C_1 \cup C_2$, where

$$\begin{aligned} C_0 &= \{(x, y, q, h) \in \mathbb{R}^4; x^2 + y^2 < 1, q \in (-1, 1), h \in (-1, 1)\}, \\ C_1 &= \{(x, y, 0, 0) \in \mathbb{R}^4; x^2 + y^2 = 1\} \text{ and} \\ C_2 &= \{(\cos a, \sin a, hp, h) \in \mathbb{R}^4; (p, a) \in G, h \in (-1, 1)\}. \end{aligned}$$

It is clear that the set C is bounded and the sets C_0 and C_1 are G_δ sets. We shall use the well-known theorem that homeomorphic images of G_δ subsets of complete metric spaces are always G_δ sets (see e.g. [7, §35, III]). The set $S = \{(a, hp, h) \in \mathbb{R}^3; (p, a) \in G, h \in (-1, 0) \cup (0, 1)\}$ being homeomorphic to $G \times ((-1, 0) \cup (0, 1))$ is a G_δ set, too. Since the map taking each triple $(a, q, h) \in S$ to the quadruple $(\cos a, \sin a, q, h) \in C$ is a homeomorphism of S onto $C_2 \setminus C_1$ (because a cannot be 0 since we assumed that $0 \notin B$), we conclude that $C = C_0 \cup C_1 \cup C_2$ is a G_δ subset of $\mathbb{R}^4$.

The set C_0 is obviously convex. The set C contains C_0 as a subset and it is contained in its closure. Thus, for proving that C is convex, it is enough to prove that any supporting hyperplane of $\overline{C_0}$ intersects C in a convex set. By definition, C consists of C_0 , of open segments $\{(\cos a, \sin a, hp, h) \in \mathbb{R}^4; h \in (-1, 1)\}$ for $a \in B$ (one for each $a \in B$ since the projection of G onto B is injective) and of points $(\cos a, \sin a, 0, 0)$ for $a \in [0, 2\pi) \setminus B$. For fixed $a \in \mathbb{R}$, at the points of ∂C_0 with fixed first coordinates $(\cos a, \sin a)$, the set $\overline{C_0}$ has the same supporting hyperplane and this hyperplane intersects $\overline{C_0}$ in the (2-dimensional) plane $\{(\cos a, \sin a, q, h) \in \mathbb{R}^4; (q, h) \in \mathbb{R}^2\}$. Since the intersection of each such plane with C is either a segment or a point, C is a convex set.

The facts mentioned in the previous paragraph give also that the only exposed points of C are the points $(\cos a, \sin a, 0, 0)$ for $a \in [0, 2\pi) \setminus B$, and thus $\exp C = \text{ext } C = E$. $\square$

4. EXTREME AND EXPOSED POINTS IN $\mathbb{R}^3$

In the sequel we shall prove the following two theorems.

Theorem 4.1. *Let $C \subset \mathbb{R}^3$ be a convex set of Borel class Σ_α^0 . Then the set $\text{ext } C$ is of Borel class Π_α^0 in C .*

Theorem 4.2. *Let $C \subset \mathbb{R}^3$ be a convex set of Borel class Σ_α^0 .*

If $\alpha \neq 2$, then the set $\exp C$ is of Borel class Π_α^0 in C .

If $\alpha = 2$, then $\exp C = (F \cap G) \cup H$, where F is an F_σ set in $\mathbb{R}^3$, G is a G_δ set in $\mathbb{R}^3$ and H is a G_δ set in C .

As an immediate corollary of these theorems we get the following result concerning Borel classes in $\mathbb{R}^3$.

Corollary 4.3. *Let $C \subset \mathbb{R}^3$ be convex.*

If C belongs to the additive Borel class Σ_α^0 , then the sets $\text{ext } C$ and $\exp C$ are of ambiguous class $\Delta_{\alpha+1}^0$ in $\mathbb{R}^3$.

If C belongs to the ambiguous Borel class Δ_α^0 , then the sets $\text{ext } C$ (for any α) and $\text{exp } C$ (for $\alpha \neq 2$) are of multiplicative class Π_α^0 in $\mathbb{R}^3$.

In particular, if C belongs to the multiplicative Borel class Π_α^0 , then the sets $\text{ext } C$ (for any α) and $\text{exp } C$ (for $\alpha \neq 1$) are of multiplicative class $\Pi_{\alpha+1}^0$ in $\mathbb{R}^3$. $\square$

Remark 4.4. In the particular case when C is closed (and more generally also if $C \in \Delta_2^0$), the set H in Theorem 4.2 is G_δ also in $\mathbb{R}^3$ (since it is G_δ in a G_δ set) and we get the same description of $\text{exp } C$ as Choquet, Corson and Klee in [1, Theorem 1.1(b)].

The most complicated description of $\text{exp } C$ for an F_σ set C is necessary. An example of Corson [2] shows that there is a compact convex set $C \subset \mathbb{R}^3$ such that $\text{exp } C$ is not the union of an F_σ set and a G_δ set. Let us also notice that Holický and Laczkovich [4] observed recently that there is a compact convex set $C \subset \mathbb{R}^3$ such that $\text{exp } C$ is not the intersection of an F_σ set and a G_δ set.

Before coming to the proofs of both theorems, we illustrate in the next examples that there is not much space for improving the estimates of the classes of $\text{ext } C$ and $\text{exp } C$ in Theorem 4.1, Theorem 4.2 and Corollary 4.3.

Example 4.5. There is a convex set $D \subset \mathbb{R}^3$ of class Σ_α^0 for $\alpha \geq 2$ such that $\text{ext } D = \text{exp } D$ is not Σ_α^0 in D .

Proof. Let $B \subset S = \{(x, y) \in \mathbb{R}^2; x^2 + y^2 = 1\}$ be in $\Pi_\alpha^0 \setminus \Sigma_\alpha^0$, $\alpha \geq 2$. Put

$$D = \left(\{(x, y) \in \mathbb{R}^2; x^2 + y^2 < 1\} \times (-1, 1) \right) \cup \left((S \setminus B) \times (-1, 1) \right) \cup (S \times \{0\}).$$

Then D is clearly convex and Σ_α^0 , but $\text{ext } D = \text{exp } D = B \times \{0\}$ is not Σ_α^0 in D (otherwise it would be in Σ_α^0 in $\mathbb{R}^3$ because $S \times \{0\} \subset D$ is closed in $\mathbb{R}^3$). $\square$

Example 4.6. For any $\alpha \geq 1$, there is a convex Π_α^0 set $E \subset \mathbb{R}^3$ with $\text{ext } E = \text{exp } E$ not $\Sigma_{\alpha+1}^0$ in E and so not $\Sigma_{\alpha+1}^0$ in $\mathbb{R}^3$.

Proof. Let $S = \{(x, y) \in \mathbb{R}^2; x^2 + y^2 = 1\}$ and F_n , $n \in \mathbb{N}$, in $\Pi_\alpha^0(S)$ be such that their union $\bigcup_{n \in \mathbb{N}} F_n$ is not in $\Pi_{\alpha+1}^0(S)$. We may and shall suppose that $F_n \subset F_{n+1}$ for $n \in \mathbb{N}$.

If $\alpha = 1$, we put

$$E = \text{conv} \left(\bigcup_{n \in \mathbb{N}} \left(F_n \times \left[-\frac{1}{n}, \frac{1}{n} \right] \right) \cup (S \times \{0\}) \right).$$

Using the well-known fact that the convex hull of a compact set is compact (see e.g. in [8, Theorem 17.2]) we get that E is compact. It is easy to check that $\text{ext } E \cap S = \text{exp } E \cap S = S \setminus \bigcup_{n \in \mathbb{N}} F_n$. Since $S \times \{0\} \subset E$ is closed and $\bigcup_{n \in \mathbb{N}} F_n$ is not G_δ in S , this implies that $\text{ext } E$ and $\text{exp } E$ are not F_σ in E . (Let us also note that the stronger examples of [2] or [4] also give the case $\alpha = 1$ for exposed points.)

If $\alpha > 1$, put

$$E = \left(\{(x, y) \in \mathbb{R}^2; x^2 + y^2 < 1\} \times (-1, 1) \right) \cup (S \times \{0\}) \cup \bigcup_{n \in \mathbb{N}} \left(F_n \times \left(-\frac{1}{n}, \frac{1}{n} \right) \right).$$

Let $\alpha_k = \alpha - 1$ if α is a nonlimit ordinal, and let (α_k) be an increasing sequence of ordinals that converges to α if α is a limit ordinal. In both cases there exist sets

G_k^n in $\Sigma_{\alpha_k}^0(S)$ such that $F_n = \bigcap_{k \in \mathbb{N}} G_k^n$ and $G_{k+1}^n \subset G_k^n$ for $n, k \in \mathbb{N}$. Then one can easily check that

$$\bigcup_{n \in \mathbb{N}} F_n \times \left(0, \frac{1}{n}\right) = \bigcap_{k \in \mathbb{N}} \bigcup_{n \in \mathbb{N}} G_k^n \times \left(\frac{1}{n+2}, \frac{1}{n}\right).$$

Hence E is the union of $\left(\left\{(x, y) \in \mathbb{R}^2; x^2 + y^2 < 1\right\} \times (-1, 1)\right) \cup \left(S \times \{0\}\right)$ and

$$\bigcap_{k \in \mathbb{N}} \bigcup_{n \in \mathbb{N}} G_k^n \times \left(\left(\frac{1}{n+2}, \frac{1}{n}\right) \cup \left(-\frac{1}{n}, -\frac{1}{n+2}\right)\right),$$

which implies that E is a Π_{α}^0 set. The set E is clearly convex. However, $\text{ext } E = \text{exp } E = S \setminus \bigcup_{n \in \mathbb{N}} F_n$ is not $\Sigma_{\alpha+1}^0$ in E . $\square$

5. PROOF OF THEOREM 4.1

Lemma 5.1. *Let $C \subset \mathbb{R}^3$ be a convex set of Borel class Σ_{α}^0 , and P_0, P_1 be two distinct parallel planes in $\mathbb{R}^3$. Then the set*

$$S = \bigcup \left\{]a, b[; [a, b] \subset \partial C, a \in C \cap P_0, b \in C \cap P_1 \right\}$$

is of class Σ_{α}^0 , too.

Proof. Since the case $\alpha = 1$ is trivial, we may suppose that $\alpha \geq 2$.

There are at most countably many maximal “quadrangles” $Q_k = \text{conv}(J_0 \cup J_1)$, where $J_i \subset \partial C \cap P_i$, $i = 0, 1$, are bounded or unbounded line segments. Let us denote by G_k the relative interior of Q_k in the affine span of Q_k and put $G = \bigcup_k G_k$. Thus each G_k is an F_{σ} set in $\mathbb{R}^3$ and open in ∂C .

The intersection $S \cap G$ is the countable union of $S \cap G_k$, each of the form $\text{conv}(I_0 \cup I_1) \cap G_k$, where $I_0 \subset J_0$ and $I_1 \subset J_1$ are convex subsets of a line, and so $S \cap G$ is an F_{σ} set.

The map taking each triple $(x_0, x_1, t) \in (\partial C \cap P_0) \times (\partial C \cap P_1) \times (0, 1)$ to the point $(1-t)x_0 + tx_1 \in C$ is continuous. Let us denote by f its restriction to the set

$$K = \{(x_0, x_1, t) \in (\partial C \cap P_0) \times (\partial C \cap P_1) \times (0, 1); \frac{x_0 + x_1}{2} \in \partial C \setminus G\}.$$

Note that if $]x_0, x_1[\cap \partial C \neq \emptyset$ for some $(x_0, x_1) \in (\overline{C} \cap P_0) \times (\overline{C} \cap P_1)$, then $[x_0, x_1] \subset \partial C$.

This implies that

$$f(K \cap (C \times C \times (0, 1))) = S \setminus G.$$

The previous observation also implies that, whenever two distinct open segments with endpoints in $\partial C \cap P_0$ and $\partial C \cap P_1$ have nonempty intersection in ∂C , then their midpoints belong to G . This proves that f is injective.

The set K can be written as the countable union of compact sets K_n . Each restriction $f \upharpoonright K_n$ being continuous and injective on a compact set is a homeomorphism taking the Σ_{α}^0 subset $K_n \cap (C \times C \times (0, 1))$ of K_n to a Σ_{α}^0 set (in the compact set $f(K_n)$ and so in $\mathbb{R}^3$ as well) and thus $S \setminus G = \bigcup_n f(K_n \cap (C \times C \times (0, 1)))$ is also a Σ_{α}^0 set. $\square$

Proof of Theorem 4.1. For $i \in \{1, 2, 3\}$ and a rational number $r \in \mathbb{Q}$, we put $P_i(r) = \{(x_1, x_2, x_3) \in \mathbb{R}^3; x_i = r\}$. Clearly,

$$\begin{aligned} C \cap \partial C \setminus \text{ext } C &= \bigcup \left\{]a, b[;]a, b[\subset C \cap \partial C \right\} \\ &= \bigcup_{i,p,q} \bigcup \left\{]a, b[; [a, b] \subset \partial C, a \in C \cap P_i(p), b \in C \cap P_i(q) \right\}, \end{aligned}$$

where the union $\bigcup_{i,p,q}$ is over all triples $(i, p, q) \in \{1, 2, 3\} \times \mathbb{Q} \times \mathbb{Q}$ such that $p < q$. By Lemma 5.1 with $P_0 = P_i(p)$ and $P_1 = P_i(q)$, and by the countability of the index set $\{1, 2, 3\} \times \mathbb{Q} \times \mathbb{Q}$, the set $C \cap \partial C \setminus \text{ext } C$ is Σ_α^0 in $\mathbb{R}^3$ and thus $\text{ext } C$ is Π_α^0 in C . $\square$

6. PROOF OF THEOREM 4.2

The next lemma enables us to reduce the investigation of the set of exposed points of convex sets $C \subset \mathbb{R}^3$ to the study of the union U^C of the closed segments of $C \cap \partial C$. We get it by modifying a description indicated in the proof of [1, Theorem 1.1].

Lemma 6.1. *Let C be a convex subset of $\mathbb{R}^3$. Then*

$$\exp C = (C \cap \partial C \setminus U^C) \cup \left(E \cap C \setminus \bigcup \{I \cap C \setminus \exp C; I \in \mathcal{I}\} \right),$$

where

$$U^C = \bigcup \{ [a, b]; [a, b] \subset C \cap \partial C \},$$

$$E = \left\{ x; \{x\} = S \cap [x, c] \text{ for an } [x, c] \subset \partial C \text{ and a supporting plane } S \text{ of } \overline{C} \right\}$$

and

$$\begin{aligned} \mathcal{I} &= \left\{ I; I = T \cap S \cap C, S, T \text{ are distinct supporting planes of } \overline{C}, \right. \\ &\quad \left. \dim I = 1, \dim(T \cap \overline{C}) = 2 \right\}. \end{aligned}$$

Moreover, the sets E and $\bigcup \{I \cap C \setminus \exp C; I \in \mathcal{I}\}$ are F_σ sets in $\mathbb{R}^3$.

Proof. Let x be an exposed point of C which belongs to some segment $[a, b] \subset C \cap \partial C$. Then $x \in E$ and thus the inclusion “ $\subset$ ” is proved.

For proving the other inclusion first note that $C \cap \partial C \setminus U^C \subset \exp C$ is clear. Thus it is enough to prove that $x \in \bigcup \mathcal{I}$ if $x \notin \exp C$ and $x \in E \cap C$.

So suppose now that $x \notin \exp C$ and $x \in E \cap C$. Then there is a supporting plane S of $\overline{C}$ with $\{x\} = S \cap [x, t]$ for some $[x, t] \subset \partial C$. Since $x \notin \exp C$ there is an s such that $[x, s] \subset S \cap C$. There is a supporting plane $T \supset [x, t]$ of $\overline{C}$ and since $t \notin S$ we have that $S \neq T$. The point x belongs to the line $T \cap S$ and $T \cap S \cap C \neq \{x\}$ because otherwise x would be an exposed point of C (a suitable rotation P of the plane S around $S \cap T$ would be a supporting plane with $P \cap C = \{x\}$). So $I = S \cap T \cap C$ is a segment on the boundary of C . Moreover, $T \cap \overline{C}$ contains the two-dimensional set $\text{conv}(I \cup \{t\})$, and so $x \in \bigcup \mathcal{I}$ and the equality is proved.

The family $\mathcal{I}$ is countable since the set of two-dimensional faces of $\overline{C}$ is countable and the set of one-dimensional faces of each two-dimensional face is also countable. On the other hand, if I is a segment and C is convex, the set $I \cap C \setminus \exp C$ is also a segment, so it is F_σ . Therefore $\bigcup \{I \cap C \setminus \exp C; I \in \mathcal{I}\}$ is F_σ .

The set E can be written as the countable union of sets E_n of all elements of E such that the plane S and the segment $[x, c]$ from the definition of E can be found

so that $\|c - x\| \leq 1$ and the scalar product of $c - x$ and of the unit normal vector to S does not belong to the open interval $(-\frac{1}{n}, \frac{1}{n})$. Then each E_n is a closed set, which concludes the proof. $\square$

Due to Lemma 6.1 it is enough to prove the following proposition to conclude the proof of Theorem 4.2.

Proposition 6.2. *Let C be a convex Σ_α^0 subset of $\mathbb{R}^3$. Then the set*

$$U^C = \bigcup \{[a, b]; [a, b] \subset C \cap \partial C\}$$

is a Σ_α^0 set in $\mathbb{R}^3$.

Let us realize that we know that $\bigcup \{]a, b[;]a, b[\subset C \cap \partial C\}$ is in Σ_α^0 from (the proof of) Theorem 4.1. The point distinguishing the case of exposed points from the case of extreme points is that we need to include the endpoints in our description, which makes it more delicate (recall that in the proof of Example 3.1 the set S is the union of open segments in $\mathbb{R}^3$, it is a G_δ set but, if we take the union of the closed segments, we get a set which can be in an arbitrarily high Borel class). We are going to describe U^C as the union of countably many sets, which will be studied separately.

It will be useful to note that U^C can also be written as

$$U^C = \{x \in C; \exists c \in C, [x, c] \subset \partial C\}.$$

We call a subset D of $\mathbb{R}^3$ a *rational disc* if it is a closed disc with positive rational radius in a plane $P \subset \mathbb{R}^3$, P is perpendicular to one of the axes and the center of D has rational coordinates. Let $\mathcal{D}$ denote the countable set of all rational discs.

For a fixed rational disc D in a plane P we define the multivalued map Φ_D taking points of $\mathbb{R}^3 \setminus P$ to compact subsets of D by

$$\Phi_D(x) = \{y \in D; [x, y] \subset \partial C\},$$

and we put

$$S_D = \{x \in \mathbb{R}^3 \setminus P; \Phi_D(x) \text{ is a singleton}\}.$$

By restricting Φ_D to S_D , and identifying the singletons $\Phi_D(x)$ with their elements, we define the function $\varphi_D : S_D \rightarrow D$ such that

$$\{\varphi_D(x)\} = \Phi_D(x) \text{ for } x \in S_D.$$

Claim 6.3. *Let $D \in \mathcal{D}$ be arbitrary and $P \supset D$ be a plane. Then the multivalued map Φ_D is upper semi-continuous (i.e. $\Phi_D^{-1}(F) = \{x; \Phi_D(x) \cap F \neq \emptyset\}$ is closed in $\mathbb{R}^3 \setminus P$ for every closed $F \subset D$) and the set S_D is G_δ .*

In particular, we get that $\Phi_D^{-1}(F) \in F_\sigma$ if $F \in F_\sigma$ and the restriction $\varphi_D : S_D \rightarrow D$ of Φ_D to S_D is continuous.

Proof. The first claim follows since ∂C is closed and the disc D is compact. For the other one it is enough to realize that the sets $F_n = \{x \in \mathbb{R}^3 \setminus P; \text{diam } \Phi_D(x) \geq \frac{1}{n}\}$ are closed in $\mathbb{R}^3 \setminus P$ for $n \in \mathbb{N}$, the set $F = \{x \in \mathbb{R}^3 \setminus P; \Phi_D(x) \neq \emptyset\}$ is closed in $\mathbb{R}^3 \setminus P$ and $S_D = F \setminus \bigcup_{n \in \mathbb{N}} F_n$. $\square$

Let

$$U_f = \bigcup \{F; F \text{ is a two-dimensional face of } \overline{C}\}$$

and

$$U_s = \{x \in \partial C; \text{there are at least three disjoint segments }]a_i, x[\subset \partial C \setminus U_f\}.$$

Claim 6.4. *We have the equalities*

$$U^C = C \cap \bigcup_{D \in \mathcal{D}} \Phi_D^{-1}(C \cap D) = \left(C \cap \bigcup_{D \in \mathcal{D}} \varphi_D^{-1}(C \cap D) \right) \cup (U_f \cap U^C) \cup (U_s \cap U^C).$$

Proof. The first equality and the inclusion

$$U^C \supset \left(C \cap \bigcup_{D \in \mathcal{D}} \varphi_D^{-1}(C \cap D) \right) \cup (U_f \cap U^C) \cup (U_s \cap U^C)$$

are clear.

Let $x \in U^C \setminus (U_f \cup U_s)$. Then $[c, x] \subset C \cap \partial C$ for some c . There is a rational disc D with $D \cap]c, x[$ being a singleton and D does not meet any segment $]c', x[\subset \partial C \setminus U_f$ such that $]c', x[\cap]c, x[= \emptyset$. Since $x \notin U_f$, there is no segment $]c'', x[\subset C \cap \partial C \cap U_f$. By noting that for any segment $]a, b[\subset \partial C$ either $]a, b[\subset \partial C \setminus U_f$ or $]a, b[\subset U_f$, this implies that $x \in S_D$ and $\varphi_D(x)$ is the only element of $]c, x[\cap D$. Since $]x, c[\subset C$ we get that $\varphi_D(x) \in C \cap D$, so $x \in \varphi_D^{-1}(C \cap D)$. $\square$

Claim 6.5. *The set $U_f \cap U^C$ is relatively F_σ in C .*

Proof. Note first that there are countably many two-dimensional faces F_k , $k \in \mathbb{N}$, of $\overline{C}$. Let $N_i = \{k \in \mathbb{N}; F_k \cap C \text{ is an } i\text{-dimensional face of } C\}$ for $i = 0, 1, 2$. Then

$$\bigcup_{k \in N_1 \cup N_2} F_k \cap C \subset U_f \cap U^C \subset \bigcup_{k \in N_0 \cup N_1 \cup N_2} F_k \cap C.$$

Since $\bigcup_{k \in N_0} F_k \cap C$ is a countable set and each $F_k \cap C$ is relatively closed in C , this implies that $U_f \cap U^C$ is F_σ in C . $\square$

Lemma 6.6. *Let K be a closed convex set, and let U_f denote the union of the two-dimensional faces of K . Then the set U_s of points x for which there exist three pairwise disjoint segments $]x, b_1[,]x, b_2[,]x, b_3[\subset \partial K \setminus U_f$ is countable.*

Proof. First we claim that an open segment in $\partial K \setminus U_f$ cannot intersect any non-parallel closed segment of ∂K . Indeed, otherwise they would belong to a common supporting plane S of K and $S \cap K$ would be a two-dimensional face of K ; so both segments would be contained in U_f .

For each point $x \in U_s$ take three pairwise disjoint segments $]x, b_1[,]x, b_2[,]x, b_3[\subset \partial K \setminus U_f$, put $a_i = (x + b_i)/2$ and assign the “spider” $S_x = \bigcup_{i=1}^3]x, a_i[$ to x .

First we show that the spiders S_x , $x \in U_s$, are pairwise disjoint. Suppose that $x \neq x'$ and $y \in S_x \cap S_{x'}$. We can suppose that $y \neq x$. Then $y \in]x, a_i[\cap]x', a'_j[$ for some i, j . According to our first observation this may happen only if $]x, a_i[$ and $]x', a'_j[$ lie in the same line. Then we must have $x \in]x', b'_j[$ or $x' \in]x, b_i[$. The assumption $y \neq x$ was used only to get the last statement that is symmetrical with respect to x and x' . So we may and shall suppose now that $x \in]x', b'_j[$. Then for at least one $k \in \{1, 2, 3\}$ the intervals $]x', b'_j[$ and $]x, b_k[$ are non-parallel non-disjoint segments in $\partial K \setminus U_f$, contradicting our first observation.

One can easily write ∂K as a countable union of relatively open (in ∂K) sets T_n such that each T_n can be projected to a plane by an injective projection. By taking the spiders smaller if necessary, we can suppose that each spider is contained in one of the T_n 's. Since the projections are injective and the spiders are pairwise disjoint, we get that the projections of the spiders contained in a fixed T_n are also pairwise disjoint.

By the injectivity, the projection of a spider is of the form $\bigcup_{i=1}^3 [y, c_i[$, where $]y, c_1[$, $]y, c_2[$ and $]y, c_3[$ are pairwise disjoint open segments. We call such plane sets “plane-spiders” for a while.

Therefore what remains to prove is the (probably well-known) fact that there can be only countably many pairwise disjoint plane-spiders in a fixed plane. For proving this, assign to each plane-spider a triangle such that the “head” of the spider is inside the triangle, each “leg” intersects one of the sides of the triangle and all coordinates of all vertices of the triangle are rational.

The observation that to two disjoint plane-spiders distinct “rational” triangles are assigned concludes the proof. $\square$

Proof of Proposition 6.2. By the first equality of Claim 6.4 and the upper semi-continuity of the multivalued map Φ_D (Claim 6.3), we have that for $\alpha = 2$ the set U^C is indeed F_σ .

The $\alpha = 1$ case is obvious, so let $\alpha > 2$. Then by Claim 6.5, $U_f \cap U^C$ is in Σ_α^0 . Applying Lemma 6.6 for $K = \overline{C}$, we get that U_s is countable, so $U^C \cap U_s \in F_\sigma \subset \Sigma_\alpha^0$. By the continuity of φ_D (Claim 6.3), the set $\varphi_D^{-1}(C \cap D)$ is Σ_α^0 in S_D . Since (by Claim 6.3) the set S_D is G_δ and $\alpha > 2$, this means that $\varphi_D^{-1}(C \cap D)$ is in Σ_α^0 in $\mathbb{R}^3$, too. Therefore, by Claim 6.4, we get that U^C is indeed in Σ_α^0 . $\square$

Let us recall that Lemma 6.1 and Proposition 6.2 imply Theorem 4.2.

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