# A MINIMAL LAMINATION WITH CANTOR SET-LIKE SINGULARITIES 

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#### Abstract

Given a compact closed subset $M$ of a line segment in $\mathbb{R}^{3}$, we construct a sequence of minimal surfaces $\Sigma_{k}$ embedded in a neighborhood $C$ of the line segment that converge smoothly to a limit lamination of $C$ away from $M$. Moreover, the curvature of this sequence blows up precisely on $M$, and the limit lamination has non-removable singularities precisely on the boundary of $M$.


## 1. Introduction

Let $\Sigma_{k} \subset B_{R_{k}}=B_{R_{k}}(0) \subset \mathbb{R}^{3}$ be a sequence of compact embedded minimal surfaces with $\partial \Sigma_{k} \subset \partial B_{R_{k}}$ and curvature blowing up at the origin. In [1], Colding and Minicozzi showed that when $R_{k} \rightarrow \infty$, a subsequence converges off a Lipshitz curve to a foliation by parallel planes. In particular, the limit is a smooth, proper foliation. By contrast, in 2 Colding and Minicozzi constructed a sequence as above with $R_{k}$ uniformly bounded and converging to a limit lamination of the unit ball with a non-removable singularity at the origin. Later, B. Dean in [3 found a similar example where the limit lamination has a finite set of singularities along a line segment, and S. Khan in 4 found a limit lamination consisting of a nonproperly embedded minimal disk in the upper half ball spiraling into a foliation by parallel planes of the lower half ball. Both Dean and Khan used methods that are analogous to those in [1]. Recently, using a variational method, D. Hoffman and B . White in [5] were able to construct a sequence converging to a non-proper limit lamination and with curvature blowup occurring along an arbitrary compact subset of a line segment. In this paper we do the same, but with a method that is derivative of that in [1] and [4]. The main theorem is:
Theorem 1. Let $M$ be a compact subset of $\left\{x_{1}=x_{2}=0,\left|x_{3}\right| \leq 1 / 2\right\}$ and let $C=$ $\left\{x_{1}^{2}+x_{2}^{2} \leq 1,\left|x_{3}\right| \leq 1 / 2\right\}$. Then there is a sequence of properly embedded minimal disks $\Sigma_{k} \subset C$ with $\partial \Sigma_{k} \subset \partial C$ and containing the vertical segment $\{(0,0, t) \| t \mid \leq$ $1 / 2\}$ so that:
(A) $\lim _{k \rightarrow \infty}\left|A_{\Sigma_{k}}\right|^{2}(p)=\infty$ for all $p \in M$.
(B) For any $\delta>0$ it holds that $\sup _{k} \sup _{\Sigma_{k} \backslash M_{\delta}}\left|A_{\Sigma_{k}}\right|^{2}<\infty$, where $M_{\delta}=$ $\bigcup_{p \in M} B_{\delta}(p)$.

[^0](C) $\Sigma_{k} \backslash\left\{x_{3}-\right.$ axis $\}=\Sigma_{1, k} \cup \Sigma_{2, k}$ for multi-valued graphs $\Sigma_{1, k}, \Sigma_{2, k}$.
(D) For each interval $I=\left(t_{1}, t_{2}\right)$ of the compliment of $M$ in the $x_{3}$-axis, $\Sigma_{k} \cap$ $\left\{t_{1}<x_{3}<t_{2}\right\}$ converges to an imbedded minimal disk $\Sigma_{I}$ with $\Sigma_{I} \backslash \Sigma_{I}=$ $C \cap\left\{x_{3}=t_{1}, t_{2}\right\}$. Moreover, $\Sigma_{I} \backslash\left\{x_{3}-\right.$ axis $\}=\Sigma_{1, I} \cup \Sigma_{2, I}$ for $\infty$-valued graphs $\Sigma_{1, I}$ and $\Sigma_{2, I}$, each of which spirals into the planes $\left\{x_{3}=t_{1}\right\}$ from above and $\left\{x_{3}=t_{2}\right\}$ from below.
It follows from (D) that a subsequence of the $\Sigma_{k} \backslash M$ converge to a limit lamination of $C \backslash M$. The leaves of this lamination are given by the multi-valued graphs $\Sigma_{I}$ given in (D), indexed by intervals $I$ of the complement of $M$, taken together with the planes $\left\{x_{3}=t\right\} \cap C$ for $(0,0, t) \in M$. This lamination does not extend to a lamination of $C$, however, as every boundary point of $M$ is a non-removable singularity. Theorem 1 was inspired by the result of Hoffman and White in [5].

Throughout we will use coordinates $\left(x_{1}, x_{2}, x_{3}\right)$ for vectors in $\mathbb{R}^{3}$, and $z=x+i y$ on $\mathbb{C}$. For $p \in \mathbb{R}^{3}$ and $s>0$, the ball in $\mathbb{R}^{3}$ is $B_{s}(p)$. We denote the sectional curvature of a smooth surface $\Sigma$ by $K_{\Sigma}$. When $\Sigma$ is immersed in $\mathbb{R}^{3}, A_{\Sigma}$ will be its second fundamental form. In particular, for $\Sigma$ minimal we have that $\left|A_{\Sigma}\right|^{2}=-2 K_{\Sigma}$. Also, we will identify the set $M \subset\left\{x_{3}\right.$-axis $\}$ with the corresponding subset of $\mathbb{R} \subset \mathbb{C}$; that is, the notation will not reflect the distinction, but will be clear from context. Our example will rely heavily on the Weierstrass representation, which we introduce here.

## 2. The Weierstrass Representation

Given a domain $\Omega \subset \mathbb{C}$, a meromorphic function $g$ on $\Omega$ and a holomorphic oneform $\phi$ on $\Omega$, one obtains a (branched) conformal minimal immersion $F: \Omega \rightarrow \mathbb{R}^{3}$, given by (cf. [6])

$$
\begin{equation*}
F(z)=\operatorname{Re}\left\{\int_{\zeta \in \gamma_{z_{0}, z}}\left(\frac{1}{2}\left(g^{-1}(\zeta)-g(\zeta)\right), \frac{i}{2}\left(g^{-1}(\zeta)+g(\zeta)\right), 1\right) \phi(\zeta)\right\} \tag{1}
\end{equation*}
$$

the so-called Weierstrass representation associated to $\Omega, g, \phi$. The triple $(\Omega, g, \phi)$ is referred to as the Weierstrass data of the immersion $F$. Here, $\gamma_{z_{0}, z}$ is a path in $\Omega$ connecting $z_{0}$ and $z$. By requiring that the domain $\Omega$ be simply connected and that $g$ be a non-vanishing holomorphic function, we can ensure that $F(z)$ does not depend on the choice of path from $z_{0}$ to $z$ and that $d F \neq 0$. Changing the base point $z_{0}$ has the effect of translating the immersion by a fixed vector in $\mathbb{R}^{3}$.

The unit normal $\mathbf{n}$ and the Gauss curvature $K$ of the resulting surface are then (see sections 8, 9 in [6)

$$
\begin{align*}
\mathbf{n} & =\left(2 \operatorname{Re} g, 2 \operatorname{Im} g,|g|^{2}-1\right) /\left(|g|^{2}+1\right)  \tag{2}\\
K & =-\left[\frac{4\left|\partial_{z} g\right||g|}{|\phi|\left(1+|g|^{2}\right)^{2}}\right]^{2} \tag{3}
\end{align*}
$$

Since the pullback $F^{*}\left(d x_{3}\right)$ is $\operatorname{Re} \phi, \phi$ is usually called the height differential. The two standard examples are

$$
\begin{equation*}
g(z)=z, \phi(z)=d z / z, \Omega=\mathbb{C} \backslash\{0\} \tag{4}
\end{equation*}
$$

giving a catenoid, and

$$
\begin{equation*}
g(z)=e^{i z}, \phi(z)=d z, \Omega=\mathbb{C} \tag{5}
\end{equation*}
$$

giving a helicoid.


Figure 1. A schematic of a helicoid-like apparently 3 -valued graph spiraling between two horizontal planes. (Image due to Siddique Khan.)

We will always write our non-vanishing holomorphic function $g$ in the form $g=$ $e^{i h}$, for a potentially vanishing holomorphic function $h$, and we will always take $\phi=d z$. For such Weierstrass data, the differential $d F$ may be expressed as

$$
\begin{align*}
\partial_{x} F & =(\sinh v \cos u, \sinh v \sin u, 1)  \tag{6}\\
\partial_{y} F & =(\cosh v \sin u,-\cosh v \cos u, 0) \tag{7}
\end{align*}
$$

## 3. An outline of the proof

Fix a compact subset $M$ of the real line. We will be dealing with a family of immersions $F_{k, a}: \Omega_{k, a} \rightarrow \mathbb{R}^{3}$ that depend on a parameter $0<a<1 / 2$ given by Weierstrass data of the form $\Omega_{k, a}, G_{k, a}=e^{i H_{k, a}}, \phi=d z$, and a sequence $M_{k} \subset M$ that converge to a dense subset of $M$. Each function $H_{k, a}$ will be real-valued when restricted to the real line in $\mathbb{C}$. That is, writing $H_{k, a}=U_{k, a}+i V_{k, a}$ for real-valued functions $U_{k, a}, V_{k, a}: \Omega_{k} \rightarrow \mathbb{R}$, we have that $H_{k, a}(x, 0)=U_{k, a}(x, 0)$. Moreover, we will show that $V_{k, a}(x, y)>0$ when $y>0$. A look at the expression for the unit normal given above in (2) then shows that all of the surfaces $\Sigma_{k, a}:=F_{k, a}\left(\Omega_{k, a}\right)$ will be multi-valued graphs over the $\left(x_{1}, x_{2}\right)$ plane away from the $x_{3}$-axis (since $|g(x, y)|=1$ is equivalent to $y=0)$. The dependence on the parameter $0<a<1 / 2$ will be such that $\lim _{a \rightarrow 0}\left|A_{\Sigma_{k, a}}\right|^{2}(p)=\infty$ for all $p \in M_{k}$ and such that $\left|A_{\Sigma_{k, a}}\right|^{2}$ remains uniformly bounded in $k$ and $a$ away from $M$. We will then choose a suitable sequence $a_{k} \rightarrow 0$ and set $F_{k}=F_{k, a_{k}}, \Omega_{k}=\Omega_{k, a_{k}}, G_{k}=G_{k, a_{k}}$, and $H_{k}=H_{k, a_{k}}$. Immediately, (A), (B) and (C) of Theorem 1 are satisfied by the diagonal subsequence. In fact, we will show that any suitable sequence is a sequence
$a_{k} \rightarrow 0$ satisfying $a_{k}<\gamma^{-k}$ for a parameter $\gamma>1$ which we introduce later. The bulk of the work will go towards establishing (D). To this end, we will show that

## Lemma 2.

(a) The horizontal slice $\left\{x_{3}=t\right\} \cap F_{k}\left(\Omega_{k}\right)$ is the image of the vertical segment $\{x=t\}$ in the plane, i.e., $x_{3}\left(F_{k}(t, y)\right)=t$.
(b) The image of $F_{k}(\{x=t\})$ is a graph over a line segment in the plane $\left\{x_{3}=t\right\}$ (the line segment will depend on $t$ ).
(c) The boundary of the graph in (b) is outside the ball $B_{r_{0}}\left(F_{k}(t, 0)\right)$ for some $r_{0}>0$.

This gives the fact that the immersions $F_{k}: \Omega_{k} \rightarrow \mathbb{R}^{3}$ are actually embeddings and that the surfaces $\Sigma_{k}$ given by $F_{k}\left(\Omega_{k}\right)$ are all embedded in a fixed cylinder $C_{r_{0}}=\left\{x_{1}^{2}+x_{2}^{2} \leq r_{0}^{2},\left|x_{3}\right|<1 / 2\right\}$ about the $x_{3}$-axis in $\mathbb{R}^{3}$. This will then imply that the surfaces $\Sigma_{k}$ converge smoothly on compact subsets of $C_{r_{0}} \backslash M$ to a limit lamination of $C_{r_{0}}$. The claimed structure of the limit lamination (that is, that on each interval of the complement it consists of two multi-valued graphs that spiral into planes from above and below) will be established at the end.


Figure 2. The functions $F_{k}$ map vertical rays of the form $\{x=t\}$ contained in the domain $\Omega_{k}$ to planes perpendicular to the $x_{3}$-axis given by $\left\{x_{3}=t\right\}$. Note that this induces an identification of the closed set $M$, thought of as lying in the complex plane along the real axis, with its image in the $x_{3}$-axis.

Throughout the paper, all computations will be carried out and recorded only on the upper half plane in $\mathbb{C}$, as the corresponding computations on the lower half plane are completely analogous. By scaling it suffices to prove Theorem 1 (D) for some $C_{r_{0}}$, not $C_{1}$ in particular.

## 4. Definitions

Let $M \subset[0,1]$ be a closed set. Fix $\gamma>1$, and take $M_{-1}$ to be the empty set. Then for $k$ a non-negative integer, we inductively define two families of sets $m_{k}$ and $M_{k}$ as follows: Assuming $M_{k-1}$ is already defined, take $m_{k}$ to be any
maximal subset of $M$ with the property that, for $p, q \in m_{k}, r \in M_{k-1}$, it holds that $|p-q|,|p-r| \geq \gamma^{-k}$. Then define $M_{k}=M_{k-1} \cup m_{k}$ and $M_{\infty}=\bigcup_{k} M_{k}$. Also, for $x \in \mathbb{R}$ define $p_{k}(x)$ to be the closest element in $M_{k}$ to $x$. Note that there are at most two such points, and we take $p_{k}(x)$ to be the closest point on the left, equivalently the smaller of the two points. For $p \in M_{\infty}$, we define $e(p)$ to be the unique natural number such that $p \in m_{e(p)}$. Note that $e\left(p_{k}(x)\right) \leq k$. We take

$$
\begin{equation*}
h_{a}(z)=\int_{0}^{z} \frac{d z}{\left(z^{2}+a^{2}\right)^{2}}=u_{a}(z)+i v_{a}(z) \tag{8}
\end{equation*}
$$

and

$$
y_{0, a}(x)=\epsilon\left(x^{2}+a^{2}\right)^{5 / 4}
$$

for $\epsilon$ to be determined. For $p \in \mathbb{R}$ we define

$$
h_{p, a}(z)=h_{a}(z-p)=u_{p, a}(z)+i v_{p, a}(z)
$$

and

$$
y_{p, a}(x)=y_{0, a}(x-p)
$$

We then take

$$
\begin{equation*}
h_{l, a}(z)=\sum_{p \in m_{l}} h_{p, a}(z)=u_{l, a}(z)+i v_{l, a}(z) \tag{9}
\end{equation*}
$$

and

$$
y_{l, a}(x)=\min _{p \in m_{l}} y_{p, a}(x)
$$

We take

$$
\begin{equation*}
H_{k}(z)=\sum_{l=0}^{k} \mu^{-l} h_{l, a_{k}}(z)=U_{k}(z)+i V_{k}(z) \tag{10}
\end{equation*}
$$

for a parameter $\mu>\gamma$ to be determined. We take

$$
Y_{k}(x)=\min _{l \leq k} y_{l, a_{k}}(x)
$$



Figure 3. A schematic rendering of the domain $\Omega_{k}$ in the case of $M=\left\{p_{l}=-2^{-l} \mid l \in \mathbb{N}\right\}$. The solid line indicates the function $Y_{k}(x)$, and the shaded region indicates the domain $\Omega_{k}$ itself. Note that in this case, the sets $m_{l}=\left\{p_{l}\right\}$ consist of a single point.

We take

$$
\omega_{a}=\left\{x+i y \| y \mid \leq y_{0, a}(x)\right\}, \omega_{p, a}=\left\{x+i y \| y \mid \leq y_{p, a}(x)\right\}
$$

and

$$
\omega_{l, a}=\left\{x+i y| | y \mid \leq y_{l, a}(x)\right\}, \Omega_{k}=\left\{x+i y \| y \mid \leq Y_{k}(x)\right\}
$$

and lastly set $\Omega_{\infty}=\cap_{k} \Omega_{k}$.
Note that in the above definitions, objects bearing the subscript " $k$ " (as opposed to " $l$ ") always enumerate an (as yet undetermined) diagonal sequence. Consequently, the dependence on the parameter $a$ is omitted from the notation. At times, the dependence on $a$ will be suppressed from the notation for objects without the subscript " $k$ ". Also, note that for each $x$ we have that $Y_{k}(x)=y_{p_{k}, a_{k}}(x)$. Again, when it is clear, the subscript " $a_{k}$ " will be suppressed. Keep in mind throughout that $\left\{a_{k}\right\}$ will always denote a sequence with $a_{k} \leq \gamma^{-k}$. Also, the parameters $\gamma$ and $\mu$ introduced in this section must satisfy $\mu^{2 / 3}<\gamma<\mu<\gamma^{3}$. The reasons are technical and should become clear later in the paper.

## 5. Preliminary Results

We record some elementary properties of the sets $M_{k}$ and $m_{k}$ defined above which will be needed later.

Lemma 3. $\left|m_{k}\right| \leq \gamma^{k}+1$.
Proof. Let $p_{1}<\ldots<p_{n}$ be $n$ distinct elements of $m_{k}$, ordered least to greatest. By construction we have that $p_{k+1}-p_{k} \geq \gamma^{-k}$. Also, since $p_{1}, p_{n} \in M$ we get

$$
1 \geq p_{n}-p_{1}=\sum_{k=1}^{n-1} p_{k+1}-p_{k} \geq(n-1) \gamma^{-k}
$$

Lemma 4. For all $p$ in $M$, there is a $q$ in $M_{k}$ such that $|p-q|<\gamma^{-k}$.
Proof. If not, $m_{k}$ is not maximal.
Lemma 5. The union $\bigcup_{k=0}^{\infty} m_{k}=\bigcup_{k=0}^{\infty} M_{k} \equiv M^{\infty}$ is a dense subset of $M$.
Proof. Suppose not. Then there is a $q \in M$ and a positive integer $k$ such that $|p-q|>\gamma^{-k}, \forall p \in M^{\infty}$. In particular, this implies that $m_{k}$ is not maximal.

In order to avoid disrupting the narrative, the proofs of the remaining results in this section will be recorded later in the Appendix. The proofs are somewhat tedious, though easily verified.

Lemma 6. For $\epsilon$ sufficiently small, $h_{p}(z)$ is holomorphic on $\omega_{p}, h_{l}$ is holomorphic on $\omega_{l}$, and $H_{k}$ is holomorphic on $\Omega_{k}$.

We will also need the following estimates:
Lemma 7. On the domain $\omega_{p}$ it holds that

$$
\left|\frac{\partial}{\partial y} u_{p}(x, y)\right| \leq \frac{c_{1}|x-p||y|}{\left((x-p)^{2}+a^{2}\right)^{3}}
$$

and

$$
\frac{\partial}{\partial y} v_{p}(x, y)>\frac{c_{2}}{\left((x-p)^{2}+a^{2}\right)^{2}}
$$

Integrating the above estimates from 0 to the upper boundary of $\omega_{p}$ gives

$$
\left|u_{p}\left(x, y_{p}(x)\right)-u_{p}(x, 0)\right| \leq \epsilon^{2} c_{1}
$$

and

$$
\min _{\left[y_{p}(x) / 2, y_{p}(x)\right]} v_{p}(x, y)>\frac{\epsilon c_{2}}{2\left((x-p)^{2}+a^{2}\right)^{3 / 4}}
$$

These estimates immediately give
Corollary 8. We have the bounds

$$
\begin{equation*}
\left|U_{k}\left(x, Y_{k}(x)\right)-U_{k}(x, 0)\right| \leq \epsilon^{2} c_{1}\left\{\sum_{l=0}^{k}(\gamma / \mu)^{l}+\mu^{-l}\right\} \leq \epsilon^{2} c_{1}^{\prime} \tag{11}
\end{equation*}
$$

and

$$
\begin{align*}
V_{k}\left(x, Y_{k}(x) / 2\right) & \geq \frac{\epsilon c_{2}}{2} \sum_{l=0}^{k} \mu^{-l} \sum_{p \in m_{l}} \frac{Y_{k}(x)}{y_{p}(x)}\left((x-p)^{2}+a_{k}^{2}\right)^{-3 / 4}  \tag{12}\\
& \geq y_{p_{k}, a_{k}}(x) \frac{\epsilon c_{2}}{2} \sum_{l=0}^{k} \mu^{-e\left(p_{l}(x)\right)} \frac{1}{y_{p_{l}, a_{k}}(x)}\left(\left(x-p_{l}(x)\right)^{2}+a_{k}^{2}\right)^{-3 / 4} \\
& =\frac{\epsilon c_{2}}{2} q_{k}(x)
\end{align*}
$$

where $q_{k}(x)$ is defined by the last equality above.

## 6. Proof of Lemma 2

We will first concern ourselves with establishing Lemma 2, (a) follows from (11) and the choice of $z_{0}=0$. Choosing $\epsilon<\epsilon_{0}<c_{1}^{\prime-1 / 2}$, where $c_{1}^{\prime}$ is the constant in (11), and using (7) we get

$$
\begin{align*}
\left\langle\partial_{y} F_{k}(x, y), \partial_{y} F_{k}(x, 0)\right\rangle & =\cosh V_{k}(x, y) \cos \left(U_{k}\left(x, y_{0}(x)\right)-U_{k}(x, 0)\right) \\
& >\cosh V_{k}(x, y) / 2 \tag{13}
\end{align*}
$$

Here we have used the fact that $\cos (1)>1 / 2$. This gives that all of the maps $F_{k}: \Omega_{k} \rightarrow \mathbb{R}^{3}$ are indeed embeddings (for all values of $a$ ) and proves (b) of Lemma 2

Now, integrating (13) from $Y_{k}(x) / 2$ to $Y_{k}(x)$ gives

$$
\begin{equation*}
\left\langle F_{k}\left(x, Y_{k}(x)\right)-F_{k}(x, 0), \partial_{y} F_{k}(x, 0)\right\rangle>\frac{Y_{k}(x)}{2} e^{\min _{\left[Y_{k} / 2, Y_{k}\right]} V_{k}} \tag{14}
\end{equation*}
$$

Using the bound for $V_{k}$ recorded in (12), we get that

$$
\begin{equation*}
\left\langle F_{k}\left(x, Y_{k}(x)\right)-F_{k}(x, 0), \partial_{y} F_{k}(x, 0)\right\rangle>\frac{\epsilon}{2} s_{k}^{5 / 3} e^{\epsilon \frac{c_{2}}{2} q_{k}(x)} \tag{15}
\end{equation*}
$$

with $s_{k}(x)=\left(\left(x-p_{k}(x)\right)^{2}+a_{k}^{2}\right)^{3 / 4}$. Take $r_{k}(x) \equiv \frac{\epsilon}{2} s_{k}^{5 / 3} e^{\frac{1}{2} \epsilon c_{2} q_{k}(x)}$. We will show that $r_{k}(x)$ remains uniformly large in $k$; this establishes (c) of Lemma 2, First, we need Lemmas 9 and 10 below. In the following, take $\Phi(\xi)=\xi^{5 / 3} e^{\frac{1}{2} c_{2} c_{2} \xi^{-1}}$.
Lemma 9. For all $\alpha>0$, there exists a $\delta=\delta(\alpha)$ such that

$$
\begin{equation*}
\Phi(\xi) \geq \xi^{-\alpha} \tag{16}
\end{equation*}
$$

for $0<\xi<\delta$.

Proof.

$$
\lim _{\xi \rightarrow 0} \frac{\epsilon}{2} \xi^{5 / 3+\alpha} e^{\frac{1}{2} \epsilon c_{2} \xi^{-1}}=\infty
$$

for all $\alpha$.
We now choose $\mu$ and $\sigma$ so that $\mu^{2 / 3}<\mu^{(1+\sigma) 2 / 3}<\gamma<\mu<\gamma^{3}$. We must also choose $\alpha$ so that $\alpha \sigma-5 / 3 \geq 0$, as will be seen in the following. In fact, for later applications, we demand $\alpha \sigma-5 / 3 \geq 1$.

Lemma 10. For $\left|x-p_{k}\right|, a_{k} \leq \mu^{-2 / 3(1+\sigma) k}\left(\frac{\delta(\alpha)^{2 / 3}}{\sqrt{2}}\right)$, we have that

$$
r_{k}(x)>1
$$

Proof. The assumptions immediately give that

$$
s_{k}(x)=\left(\left(x-p_{k}\right)^{2}+a_{k}^{2}\right)^{3 / 4}<\mu^{-(1+\sigma) k} \delta<\delta
$$

which we rewrite as

$$
\mu^{k} s_{k} \leq \mu^{-\sigma k} \delta
$$

Applying (16) and using the fact that $e\left(p_{k}(x)\right) \leq k$, we find that

$$
\Phi\left(\mu^{e\left(p_{k}\right)} s_{k}\right)>\left(\mu^{-\sigma k} \delta\right)^{-\alpha}
$$

Equivalently,

$$
r_{k}(x) \geq \frac{\epsilon}{2} s_{k}^{5 / 3} e^{\frac{\epsilon}{2} c_{2} \mu^{-e\left(p_{k}\right)} s_{k}^{-1}}>\mu^{(\alpha \sigma-5 / 3) k} \delta^{-\alpha}>1
$$

since we have chosen $\alpha \sigma-5 / 3 \geq 1$, and we may assume $\delta<1$.
We are ready to prove:
Lemma 11 (Lemma2(c)). There exists a sequence $\left\{c_{k}\right\}$ with $c_{k}>0$ and $\prod_{l=0}^{\infty} c_{l}>$ 0 such that if $r_{k}(x)<1$, then

$$
r_{k}(x)>c_{k} r_{k-1}(x)
$$

Proof. Recall that $Y_{k}(x)=y_{p_{k}}(x)$ and $Y_{k-1}(x)=y_{p_{k-1}}(x)$. If

$$
\left|x-p_{k}\right|<\mu^{-2 / 3(1+\sigma) k} \delta^{2 / 3} / \sqrt{2}
$$

then

$$
r_{k}(x)>1
$$

by Lemma 10. So we assume that $\left|x-p_{k}\right|>c_{0} \mu^{-2 / 3(1+\sigma) k}$ with $c_{0}=\delta^{2 / 3} / \sqrt{2}$. By the construction of the sets $m_{k}, M_{k}$, we have that $\left|p_{k}-p_{k-1}\right|<\gamma^{-k+1}$. We also have that $\left|p_{k-1}(x)-x\right|>c_{0} \mu^{-2 / 3(1+\sigma) k}$. Then we may estimate that

$$
\begin{equation*}
\left[\frac{y_{p_{k-1}, a_{k}}(x)}{y_{p_{k-1}, a_{k-1}}(x)}\right]^{4 / 5}=\frac{\left(\left(x-p_{k-1}\right)^{2}+a_{k}^{2}\right)}{\left(\left(x-p_{k-1}\right)^{2}+a_{k-1}^{2}\right)}>\frac{1}{1+c_{0}^{-2} \gamma^{-2} \tau^{2 k-1}} \tag{17}
\end{equation*}
$$

and that

$$
\begin{align*}
{\left[\frac{y_{p_{k}, a_{k}}(x)}{y_{p_{k-1}, a_{k}}(x)}\right]^{4 / 5} } & \geq \frac{\left|x-p_{k}\right|^{2}+a_{k}^{2}}{\left(\left|x-p_{k}\right|+\left|p_{k}-p_{k-1}\right|\right)^{2}+a_{k}^{2}}  \tag{18}\\
& \geq \frac{1+a_{k}^{2} /\left|x-p_{k}\right|^{2}}{\left(1+\left|p_{k}-p_{k-1}\right| /\left|x-p_{k}\right|\right)^{2}+a_{k}^{2} /\left|x-p_{k}\right|^{2}} \\
& \geq \frac{1}{\left(1+\left|p_{k}-p_{k-1}\right| /\left|x-p_{k}\right|\right)^{2}} \\
& \geq \frac{1}{\left(1+\gamma c_{0}^{-1} \tau^{k}\right)^{2}}
\end{align*}
$$

This then gives

$$
\begin{align*}
{\left[\frac{Y_{k}(x)}{Y_{k-1}(x)}\right]^{4 / 5} } & =\left[\frac{y_{p_{k-1}, a_{k}}(x)}{y_{p_{k-1}, a_{k-1}}(x)}\right]^{4 / 5}\left[\frac{y_{p_{k}, a_{k}}(x)}{y_{p_{k-1}, a_{k}}(x)}\right]^{4 / 5}  \tag{19}\\
& >\left[\frac{1}{1+c_{0}^{-2} \gamma^{-2} \tau^{2 k-1}}\right]\left[\frac{1}{\left(1+\gamma c_{0}^{-1} \tau^{k}\right)^{2}}\right] \\
& =\theta_{k}^{4 / 5},
\end{align*}
$$

where $\theta_{k}$ is defined by the last equality above. We also get that

$$
\begin{align*}
q_{k}(x) & \geq \frac{y_{p_{k}, a_{k}}(x)}{y_{p_{k-1}, a_{k-1}}(x)} q_{k-1}(x)  \tag{20}\\
& \geq \theta_{k} q_{k-1}(x)
\end{align*}
$$

Using (19) above, we obtain

$$
\begin{aligned}
r_{k}(x) & =\frac{\epsilon}{2} s_{k}^{5 / 3} e^{\frac{1}{2} \epsilon c_{2} q_{k}(x)} \\
& \geq\left[\frac{y_{p_{k}, a_{k}}(x)}{y_{p_{k-1}, a_{k-1}}(x)}\right] \frac{1}{2} \epsilon y_{p_{k-1}, a_{k-1}}(x) e^{\frac{1}{2} \epsilon c_{2} \theta_{k} q_{k-1}(x)} \\
& \geq \theta_{k} \frac{1}{2} \epsilon s_{k-1}^{5 / 3}(x) e^{\frac{1}{2} \epsilon c_{2} \theta_{k} q_{k-1}(x)} \\
& =\theta_{k}\left[\frac{1}{2} \epsilon s_{k-1}^{5 / 3}(x)\right]^{1-\theta_{k}}\left[r_{k-1}(x)\right]^{\theta^{k}} .
\end{aligned}
$$

Now, since $\left|x-p_{k-1}(x)\right| \geq c_{0} \mu^{-2 / 3(1+\sigma) k}$ and $1-\theta_{k} \leq c \tau^{k}$ for $c$ sufficiently large, we get

$$
r_{k}(x)>\theta_{k}\left[\frac{\epsilon}{2} c_{0}^{5 / 2} \mu^{-5 / 3(1+\sigma) k}\right]^{c \tau^{k}}\left[r_{k-1}(x)\right]^{\theta_{k}}
$$

Now, set $c_{k}=\theta_{k}\left[\frac{\epsilon}{2} c_{0}^{5 / 2} \mu^{-5 / 3(1+\sigma) k}\right]^{c \tau^{k}}$. It is easily seen that $\prod_{l=1}^{\infty} c_{l}>0$. This gives the bound

$$
\begin{equation*}
r_{k}(x)>c_{k}\left(r_{k-1}(x)\right)^{\theta_{k}} \tag{21}
\end{equation*}
$$

and the conclusion follows by considering the separate cases $r_{k-1}(x) \geq 1$ and $r_{k-1}(x)<1\left(\right.$ since $\left.\theta_{k}<1\right)$.

The immediate corollary is

Corollary 12. Either

$$
\begin{equation*}
r_{k}(x) \geq 1 \tag{22}
\end{equation*}
$$

or

$$
\begin{equation*}
r_{k}(x)>\left(\prod_{0}^{\infty} c_{l}\right) r_{0}(x) \tag{23}
\end{equation*}
$$

This establishes (c) of Lemman. 2.
7. Proof of Theorem 1 (A), (B) and (C)

Note that (3) and our choice of Weierstrass data gives that

$$
\begin{equation*}
K_{\Sigma_{k}}(z)=\frac{-\left|\partial_{z} H_{k}\right|^{2}}{\cosh ^{4} V_{k}} \tag{24}
\end{equation*}
$$

For $p \in m_{l}$, it is clear that $F_{k}(p)=(0,0, p)$ for all $k$. Thus, for $k>l$ we can then estimate

$$
\begin{equation*}
\left|\partial_{z} H_{k}(p)\right|>\frac{\mu^{-l}}{a_{k}^{4}} \tag{25}
\end{equation*}
$$

since $V_{k}(x, 0)=0$ for all $x \in \mathbb{R}$, and hence $\left|A_{\Sigma_{k}}(p)\right|^{2} \rightarrow \infty$. For $x \in M \backslash M_{\infty}$, consider the sequence of points $p_{l}(x) \in m_{l}$. Recall that $\left|p_{l}(x)-x\right|<\gamma^{-l}$. We then get

$$
\begin{equation*}
\left|\partial_{z} H_{l}(p)\right|>\frac{\mu^{-l}}{\left(\left(p-p_{l}\right)^{2}+a_{l}^{2}\right)^{2}}>\frac{\mu^{-l}}{\left(\gamma^{-2 l}+a_{l}^{2}\right)^{2}} . \tag{26}
\end{equation*}
$$

Taking $l \rightarrow \infty$ and $a_{l}<\gamma^{-l}$ gives that $\left|A_{\Sigma_{l}}(p)\right|^{2} \rightarrow \infty$ and proves (A) of Theorem 1
Since $V_{k}(x, y)>0$ for $y>0$, we see that $x_{3}(\mathbf{n}(x, y)) \neq 0$, and hence $\Sigma_{k}$ is graphical away from the $x_{3}$-axis, which proves (C) of Theorem 1

Now, for $\delta>0$ set $S_{\delta}=\{z \mid \operatorname{dist}(\operatorname{Re} z, M)<\delta\}$. From (3), it is immediate that

$$
\begin{equation*}
\sup _{k} \sup _{\Omega_{k} \backslash S_{\delta}}\left|A_{\Sigma_{k}}(z)\right|^{2}<\infty \tag{27}
\end{equation*}
$$

for any $\delta>0$. This combined with Heinz's curvature estimate for minimal graphs gives (B).

## 8. Proof of Theorem (D)

and the structure of the limit lamination
Lemma 13. A subsequence of the embeddings $F_{k}: \Omega_{k} \rightarrow \mathbb{R}^{3}$ converges to a minimal lamination of $C \backslash M$.

Proof. Let $K$ be a compact subset of the interior of $\Omega_{\infty}$. Then for $z \in K$, we have that $\sup _{k}\left|\frac{d}{d z} H_{k}(z)\right|<\infty$. Montel's theorem then gives a subsequence converging smoothly to a holomorphic function on $K$. By continuity of integration this gives that the embeddings $F_{k}: K \rightarrow \mathbb{R}^{3}$ converge smoothly to a limiting embedding. Thus the surfaces $\Sigma_{k}$ converge to a limit lamination of $C \backslash M$ that is smooth away from the $M$.

Let $I=\left(t_{1}, t_{2}\right) \subset \mathbb{R}$ be an interval of the complement of the $M$ in $\mathbb{R}$ and consider $\Omega_{I}=\Omega_{\infty} \cap\{\operatorname{Re} z \in I\}$. Then $\Omega_{I}$ is topologically a disk, and by Lemma 13 the surfaces $\Sigma_{k, I} \equiv F_{k}\left(\Omega_{I}\right)$ are contained in $\left\{t_{1}<x_{3}<t_{2}\right\} \subset \mathbb{R}^{3}$ and converge to an embedded minimal disk $\Sigma_{I}$. Now, Theorem 1 (C) (which we have already
established) gives that $\Sigma_{I}$ consists of two multi-valued graphs $\Sigma_{I}^{1}, \Sigma_{I}^{2}$ away from the $x_{3}$-axis. We will show that each graph $\Sigma_{I}^{j}$ is $\infty$-valued and spirals into the $\left\{x_{3}=t_{1}\right\}$ and $\left\{x_{3}=t_{2}\right\}$ planes, as claimed.

Note that by (7) and Theorem(1) (C), the level sets $\left\{x_{3}=t\right\} \cap \Sigma_{I}^{j}$ for $t_{1}<t<t_{2}$ are graphs over lines in the direction

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left(\sin U_{k}(t, 0),-\cos U_{k}(t, 0), 0\right) \tag{28}
\end{equation*}
$$

First, suppose $t_{1} \in m_{l}$ for some $l$. Then we get that, for any $k>l$ and any $t<\frac{t_{2}-t_{1}}{2}$,
$U_{k}\left(t_{1}+2 t, 0\right)-U_{k}\left(t_{1}+t, 0\right)=\int_{t_{1}+t}^{t_{1}+2 t} \partial_{s} U_{k}(s, 0) d s>c_{2} \mu^{-l} \int_{t_{1}+t}^{t_{1}+2 t} \frac{d s}{\left(\left(s-t_{1}\right)^{2}+a_{k}^{2}\right)^{2}}$
(by the Cauchy-Reimann equations $U_{k, x}=V_{k, y}$ ). Then, since $a_{k} \rightarrow 0$ as $k \rightarrow \infty$, we get that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} U_{k}\left(t_{1}+2 t, 0\right)-U_{k}\left(t_{1}+t, 0\right)>c_{2} \mu^{-l} \int_{t_{1}+t}^{t_{1}+2 t} \frac{d s}{\left(s-t_{1}\right)^{4}}>\frac{c_{2} \mu^{-l}}{64 t^{3}} \tag{30}
\end{equation*}
$$

and hence $\left\{t_{1}+t<\left|x_{3}\right|<t_{1}+2 t\right\}$ contains an embedded $N_{t}$-valued graph, where

$$
\begin{equation*}
N_{t}>\frac{c \mu^{-l}}{t^{3}} \tag{31}
\end{equation*}
$$

Note that $N_{t} \rightarrow \infty$ as $t \rightarrow 0$ from above and hence $\Sigma_{I}$ spirals into the plane $\left\{x_{3}=t_{1}\right\}$.

Now, suppose that $t_{1} \notin M_{\infty}$. Then consider the sequence of points $p_{l}\left(t_{1}\right) \in m_{l}$ and recall that $t_{1}-p_{l}\left(t_{1}\right)<\gamma^{-l}$. Then set $t^{l}=t_{1}+\gamma^{-l}$ and consider the intervals

$$
\begin{equation*}
I_{l}=\left[t^{l+1}, t^{l}\right] \tag{32}
\end{equation*}
$$

Note that for $l$ large $I_{l} \subset I$. Then, for $k>l$ and $s \in I_{l}$ we may estimate

$$
\begin{equation*}
\partial_{s} U_{k}(s, 0)>\frac{c_{2} \mu^{-l}}{\left(\left(s-p_{l}\left(t_{1}\right)\right)^{2}+a_{k}^{2}\right)^{2}}>\frac{c_{2} \mu^{-l}}{\left(4 \gamma^{-2 l}+a_{k}^{2}\right)^{2}} \tag{33}
\end{equation*}
$$

since $s-p_{l}<2 \gamma^{-l}$. We then get

$$
\begin{equation*}
U_{k}\left(t^{j}, 0\right)-U_{k}\left(t^{j+1}, 0\right)>\left|I_{j}\right| \frac{c_{2} \mu^{-l}}{\left(4 \gamma^{-2 l}+a_{k}^{2}\right)^{2}} \geq \frac{c_{2} \mu^{-l}\left(1-\gamma^{-1}\right) \gamma^{-l}}{\left(4 \gamma^{-2 l}+a_{k}^{2}\right)^{2}} \tag{34}
\end{equation*}
$$

Taking limits, we get

$$
\begin{equation*}
\lim _{k \rightarrow \infty} U_{k}\left(t^{l}, 0\right)-U_{k}\left(t^{l+1}, 0\right)>\frac{c_{2}\left(1-\gamma^{-1}\right)}{16}\left(\frac{\gamma^{3}}{\mu}\right)^{l} \tag{35}
\end{equation*}
$$

Thus we see that $\left\{t^{l+1}<x_{3}<t^{l}\right\} \cap \Sigma_{I}^{l}$ contains an embedded $N_{l}$-valued graph, where

$$
\begin{equation*}
N_{l} \approx c\left(\frac{\gamma^{3}}{\mu}\right)^{l} \tag{36}
\end{equation*}
$$

This again shows that $\Sigma_{I}$ spirals into the plane $\left\{x_{3}=t_{1}\right\}$ since as $j \rightarrow \infty, t^{l} \rightarrow t_{1}$ and $N_{l} \rightarrow \infty$. Now for $t$ in the interior of $M$, every singly graphical component of $F_{l}$ contained in the slab $\left\{t-\gamma^{-l}<x_{3}<t+\gamma^{-l}\right\}$ (by (36) there are many) is graphical over $\left\{x_{3}=0\right\} \cap B_{r_{l}}(0)$ where Lemma 10 gives $r_{l} \rightarrow \infty$, which implies that each component converges to the plane $\left\{x_{3}=t\right\}$. This proves Theorem 1 (D).

## Appendix

Here we provide the computations that were omitted from section 5. 5 .
Proof of Lemma 6. It suffices to show that $h=u+i v$ is holomorphic on $\omega$. Recall that

$$
\begin{equation*}
h(z)=\int_{0}^{z} \frac{d z}{\left(z^{2}+a^{2}\right)^{2}} \tag{37}
\end{equation*}
$$

It is clear that the points $\pm i a$ lie outside of $\omega$. Moreover, $\omega$ is obviously simply connected so that $\int_{0}^{z} \frac{d z}{\left(z^{2}+a^{2}\right)^{2}}$ gives a well-defined holomorphic function on $\omega$.

Proof of Lemma 7. We compute the real and imaginary components of $\left(z^{2}+a^{2}\right)^{2}$ :

$$
\begin{gathered}
z^{2}+a^{2}=x^{2}-y^{2}+a^{2}+2 i x y \\
\left(z^{2}+a^{2}\right)^{2}=\left(x^{2}-y^{2}+a^{2}\right)^{2}-4 x^{2} y^{2}+4 i x y\left(x^{2}-y^{2}+a^{2}\right)
\end{gathered}
$$

Set

$$
\begin{gathered}
d=\operatorname{Re}\left\{\left(z^{2}+a^{2}\right)^{2}\right\}=\left(x^{2}-y^{2}+a^{2}\right)^{2}-4 x^{2} y^{2} \\
b=\operatorname{Im}\left\{\left(z^{2}+a^{2}\right)^{2}\right\}=4 x y\left(x^{2}-y^{2}+a^{2}\right)
\end{gathered}
$$

and

$$
\begin{aligned}
c^{2}= & \left|\left(z^{2}+a^{2}\right)^{2}\right|^{2}=d^{2}+b^{2}=\left\{\left(x^{2}-y^{2}+a^{2}\right)^{2}-4 x^{2} y^{2}\right\}^{2} \\
& +16 x^{2} y^{2}\left(x^{2}-y^{2}+a^{2}\right)^{2}
\end{aligned}
$$

Now on $\omega$ (that is, on the set where $|y| \leq y_{0}(x)$ ), we get the bounds

$$
\begin{gathered}
d \geq\left(1-\epsilon^{2}\right)^{2}\left(x^{2}+a^{2}\right)^{2}-4 \epsilon^{2}\left(x^{2}+a^{2}\right)^{2}=\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}\left(x^{2}+a^{2}\right)^{2} \\
d \leq\left(x^{2}+a^{2}\right)^{2} \\
b \leq 4 \epsilon\left(x^{2}+a^{2}\right)^{11 / 4} \leq 4 \epsilon\left(x^{2}+a^{2}\right)^{2}
\end{gathered}
$$

since by assumption $|x|, a<\frac{1}{2}$. Using the fact that $c^{2}=d^{2}+b^{2}$,

$$
\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}^{2}\left(x^{2}+a^{2}\right)^{4} \leq c^{2} \leq\left\{1+16 \epsilon^{2}\right\}\left(x^{2}+a^{2}\right)^{4}
$$

Recalling that

$$
\frac{\partial}{\partial y} u(x, y)=\operatorname{Im}\left\{\frac{1}{\left(z^{2}+a^{2}\right)^{2}}\right\}=\frac{-b}{c^{2}}, \frac{\partial}{\partial y} v(x, y)=\operatorname{Re}\left\{\frac{1}{\left(z^{2}+a^{2}\right)^{2}}\right\}=\frac{d}{c^{2}}
$$

we get

$$
\left|\frac{\partial}{\partial y} u_{p}(x, y)\right| \leq \frac{4}{\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}^{2}} \frac{|x-p \| y|}{\left((x-p)^{2}+a^{2}\right)^{3}}
$$

and

$$
\frac{\partial}{\partial y} v_{p}(x, y) \geq \frac{\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}}{1+16 \epsilon^{2}} \frac{1}{\left((x-p)^{2}+a^{2}\right)^{2}}
$$

If we restrict $\epsilon<\epsilon_{0}$ for $\epsilon_{0}$ sufficiently small, we get that

$$
\frac{4}{\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}^{2}}<c_{1}
$$

and

$$
\frac{\left\{\left(1-\epsilon^{2}\right)^{2}-4 \epsilon^{2}\right\}}{1+16 \epsilon^{2}}>c_{2}
$$

for constants $c_{1}$ and $c_{2}$, which immediately gives the lemma.
Proof of Corollary 8. Recalling definitions (9) and (10), we get

$$
\begin{align*}
\left|U_{k}\left(x, Y_{k}(x)\right)-U_{k}(x, 0)\right| & \leq \sum_{l=0}^{k} \mu^{-l} \int_{0}^{Y_{k}(x)}\left|\frac{\partial}{\partial y} u_{l}(x, y)\right|  \tag{38}\\
& \leq \sum_{l=0}^{k} \mu^{-l} \sum_{p \in m_{l}} \int_{0}^{Y_{k}(x)}\left|\frac{\partial}{\partial y} u_{p}(x, y)\right| \\
& \leq \sum_{l=0}^{k} \mu^{-l} \sum_{p \in m_{l}} \int_{0}^{y_{p}(x)}\left|\frac{\partial}{\partial y} u_{p}(x, y)\right| \\
& \leq c_{1} \epsilon^{2} \sum_{l=0}^{k} \mu^{-l}\left(\gamma^{l}+1\right)
\end{align*}
$$

and
(39) $\min _{\left[Y_{k}(x) / 2, Y_{k}(x)\right]} V_{k}(x, y) \geq \sum_{l=0}^{k} \int_{0}^{Y_{k}(x) / 2} \frac{\partial}{\partial y} v_{l}(x, y)$

$$
\begin{aligned}
& \geq \sum_{l=0}^{k} \mu^{-l} \sum_{p \in m_{l}} \int_{0}^{Y_{k}(x) / 2} \frac{\partial}{\partial y} v_{p}(x, y) \\
& \geq \frac{\epsilon c_{2}}{2} \sum_{l=0}^{k} \mu^{-l} \sum_{p \in m_{l}} \frac{Y_{k}(x)}{y_{p}(x)}\left((x-p)^{2}+a^{2}\right)^{-3 / 4} \\
& =\epsilon \frac{c_{2}}{2} q_{k}(x)
\end{aligned}
$$

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