STABILITY OF THE REVERSE BLASCHKE-SANTALÓ INEQUALITY FOR UNCONDITIONAL CONVEX BODIES

JAEGIL KIM AND ARTEM ZVAVITCH

(Communicated by Thomas Schlumprecht)

ABSTRACT. Mahler’s conjecture asks whether the cube is a minimizer for the volume product of a body and its polar in the class of symmetric convex bodies in $\mathbb{R}^n$. The inequality corresponding to the conjecture is sometimes called the reverse Blaschke-Santaló inequality. The conjecture is known to be true in $\mathbb{R}^2$ and for several special cases. In the class of unconditional convex bodies, Saint-Raymond confirmed the conjecture, and Meyer and Reisner, independently, characterized the equality case. In this paper we present a stability version of these results and also show that any symmetric convex body, which is sufficiently close to an unconditional body, satisfies the reverse Blaschke-Santaló inequality.

1. INTRODUCTION

As usual, we denote by $\langle x, y \rangle$ the inner product of two vectors $x, y \in \mathbb{R}^n$ and by $|x|$ the length of a vector $x \in \mathbb{R}^n$. A *convex body* is a compact convex subset of $\mathbb{R}^n$ with non-empty interior. We say that a set K is *symmetric* if it is centrally symmetric with center at the origin, i.e. for every $x \in K$ we get $-x \in K$. A set $K \subset \mathbb{R}^n$ is said to be *unconditional* if it is symmetric with respect to any coordinate hyperplane, i.e., $(\pm x_1, \pm x_2, \dots, \pm x_n) \in K$, for any $x \in K$ and any choice of $\pm$ signs.

We write $|A|$ for the k -dimensional Lebesgue measure (volume) of a measurable set $A \subset \mathbb{R}^n$, where $k = 1, \dots, n$ is the dimension of the minimal flat containing A . The *polar* body K° of a symmetric convex body K is defined by

$$K^\circ = \{y \in \mathbb{R}^n \mid \langle x, y \rangle \leq 1 \text{ for all } x \in K\}.$$

The *volume product* of a symmetric convex body K is defined by

$$\mathcal{P}(K) = |K| |K^\circ|.$$

We note that the notion of the volume product (as well as polarity) can be generalized to the non-symmetric setting (see for example [42, p. 419]), but in this paper we will focus on the questions related to the centrally symmetric bodies. It turns out that the volume product is invariant under the polarity and under invertible

Received by the editors March 2, 2013 and, in revised form, August 12, 2013 and August 15, 2013.

2010 *Mathematics Subject Classification.* Primary 52A20, 53A15, 52B10.

Key words and phrases. Convex bodies, polar bodies, unconditional convex bodies, Hanner polytopes, volume product, Mahler’s conjecture, Blaschke-Santaló inequality.

The authors were supported in part by U.S. National Science Foundation grant DMS-1101636, and the first author is also supported in part by NSERC.

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linear transformations on $\mathbb{R}^n$, that is, for any $T \in \text{GL}(n)$,

$$(1) \quad \mathcal{P}(TK) = \mathcal{P}(K) \quad \text{and} \quad \mathcal{P}(K^\circ) = \mathcal{P}(K).$$

The above property makes the *Banach-Mazur distance* between symmetric convex bodies K and L

$$d_{\mathcal{BM}}(K, L) = \inf \left\{ d \geq 1 : L \subset TK \subset dL, \text{ for some } T \in \text{GL}(n) \right\},$$

extremely useful in studying the properties of the volume product. For example, F. John's theorem [19] and the continuity of the volume function with respect to the Banach-Mazur distance guarantee that the volume product attains its maximum and minimum. The maximum for the volume product is provided by the Blaschke-Santaló inequality:

$$(2) \quad \mathcal{P}(K) \leq \mathcal{P}(B_2^n), \text{ for all symmetric convex bodies } K \subset \mathbb{R}^n,$$

where B_2^n is the Euclidean unit ball and equality in the above inequality holds only for ellipsoids [29, 34, 40]. Recently, the stability versions of the Blaschke-Santaló inequality were studied in [3, 5].

For the minimum of the volume product, it was conjectured by Mahler in [24, 25] that $\mathcal{P}(K)$ is minimized at the cube in the class of symmetric convex bodies in $\mathbb{R}^n$. In other words, the conjecture asks whether the following inequality is true:

$$(3) \quad \mathcal{P}(K) \geq \mathcal{P}(B_\infty^n), \text{ for all symmetric convex bodies } K \subset \mathbb{R}^n,$$

where B_∞^n is the unit cube. The case of $n = 2$ was proved by Mahler [24]. It was also proved in several special cases, like, e.g., unconditional bodies [27, 36, 43], convex bodies having hyperplane symmetries which fix only one common point [4], zonoids [6, 16, 35], bodies of revolution [30] and bodies with some positive curvature assumption [15, 38, 44]. An isomorphic version of the conjectures was proved by Bourgain and Milman [8]: there is a universal constant $c > 0$ such that $\mathcal{P}(K) \geq c^n \mathcal{P}(B_2^n)$; see also different proofs in [14, 23, 32]. Functional versions of Blaschke-Santaló inequality and Mahler's conjecture in terms of log-concave functions were investigated by Ball [2], Artstein, Klartag, Milman [1], Fradelizi, Meyer [10–12]. The case of equality for unconditional log-concave functions was established by Fradelizi, Gordon, Meyer and Reisner [9]. For more information on Mahler's conjecture, see expository articles [26, 39, 45].

The local minimality of the volume product was first studied in [33] by proving that the cube is a strict local minimizer of the volume product in the class of symmetric convex bodies endowed with the Banach-Mazur distance (see [22] for the local minimality at the simplex in the non-symmetric setting). The result was used by Böröczky and Hug [6] to provide a stability version of (3) for zonoids, namely, a zonoid Z is close in the Banach-Mazur distance to the cube whenever $\mathcal{P}(Z)$ is close to $\mathcal{P}(B_\infty^n)$.

The main goal of this paper is to provide a stability version of (3) for unconditional convex bodies. Before stating the theorem we need to recall the definition of a Hanner polytope [17, 18]: a symmetric convex body H is called a *Hanner polytope* if H is one-dimensional, or it is the ℓ_1 or ℓ_∞ sum of two (lower dimensional) Hanner polytopes. It can be calculated (see for example [39]) that the volume product of the cube is the same as that of Hanner polytopes. Thus every Hanner polytope is also a candidate for being a minimizer of the volume product among symmetric

convex bodies. It was also shown in [27, 36] that Hanner polytopes are the only possible minimizers in the class of unconditional bodies.

In Section 2 we will prove that if the volume product of an unconditional convex body is sufficiently close to that of the cube, then the body must be close to a Hanner polytope:

Theorem 1. *Let K be an unconditional convex body in $\mathbb{R}^n$. If*

$$|\mathcal{P}(K) - \mathcal{P}(B_\infty^n)| \leq \varepsilon$$

for $0 < \varepsilon \leq \varepsilon(n)$, then there exists a Hanner polytope $H \subset \mathbb{R}^n$ such that

$$d_{\mathcal{BM}}(K, H) \leq 1 + c(n)\varepsilon,$$

where $\varepsilon(n), c(n) > 0$ are constants depending on n only.

We would like to note that the $\mathbb{R}^2$ -case of Theorem 1 was proved as a part of more general stability result on $\mathbb{R}^2$ by Böröczky, Makai, Meyer and Reisner in [7], so in this paper we will mainly concentrate on the case $n \geq 3$.

Recently it was proved in [20] that a Hanner polytope is a local minimizer of the volume product in the symmetric setting (see the exact statement of the theorem in the beginning of Section 3). In Section 3 we will use this fact and Theorem 1 to prove that any symmetric convex body, which is sufficiently close to an unconditional body, satisfies (3):

Theorem 2. *Let K be a symmetric convex body in $\mathbb{R}^n$ with*

$$\min \left\{ d_{\mathcal{BM}}(K, L) : L \subset \mathbb{R}^n \text{ unconditional convex body} \right\} = 1 + \varepsilon,$$

for $0 < \varepsilon \leq \varepsilon(n)$. Then,

$$\mathcal{P}(K) \geq (1 + c(n)\varepsilon) \cdot \mathcal{P}(B_\infty^n),$$

where $\varepsilon(n), c(n) > 0$ are constants depending on dimension n only.

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Let $e_1, \dots, e_n$ be the standard orthonormal basis of $\mathbb{R}^n$. Denote by $\theta^\perp$ the hyperplane orthogonal to a unit vector θ , and by $K \cap \theta^\perp$, $K|\theta^\perp$ the section of K by $\theta^\perp$, the orthogonal projection of K to $\theta^\perp$, respectively. Let $\mathbb{R}_+^n = \{x \in \mathbb{R}^n : x_i \geq 0, \forall i = 1, \dots, n\}$ and $K^+ = K \cap \mathbb{R}_+^n$. To prove Theorem 1 we first prove the following lemma which is based on the inductive argument of Meyer (see [27] or [39]):

Lemma 1. *Consider $\varepsilon \geq 0$ and an unconditional convex body $K \subset \mathbb{R}^n$, $n \geq 2$ such that*

$$\mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^n).$$

Then

$$(4) \quad \mathcal{P}(K \cap e_j^\perp) \leq (1 + n\varepsilon)\mathcal{P}(B_\infty^{n-1}), \quad j = 1, \dots, n.$$

Proof. Consider $x \in K^+$ and n pyramids created by taking the convex hull of x and the intersection of K^+ with each coordinate hyperplane. More precisely, let

$K_i^+ = \text{conv}\{x, K^+ \cap e_i^\perp\}$ for $i = 1, \dots, n$. Then, using symmetry of K with respect to coordinate hyperplanes,

$$|K| = 2^n |K^+| \geq 2^n \left| \bigcup_{i=1}^n K_i^+ \right| = 2^n \sum_{i=1}^n \frac{1}{n} \langle x, e_i \rangle \frac{|K \cap e_i^\perp|}{2^{n-1}} = \sum_{i=1}^n \langle x, e_i \rangle \cdot \frac{2|K \cap e_i^\perp|}{n},$$

or equivalently,

$$\left\langle x, \sum_{i=1}^n \frac{2|K \cap e_i^\perp|}{n|K|} e_i \right\rangle \leq 1, \text{ for all } x \in K^+.$$

Note that, by the unconditionality of K , the above inequality holds for all $x \in K$, so

$$\sum_{i=1}^n \frac{2|K \cap e_i^\perp|}{n|K|} e_i \in K^\circ.$$

Applying the same argument to K° we get

$$\sum_{i=1}^n \frac{2|K^\circ \cap e_i^\perp|}{n|K^\circ|} e_i \in K.$$

Thus, using the definition of polarity we get

$$(5) \quad \sum_{i=1}^n \frac{2|K \cap e_i^\perp|}{n|K|} \times \frac{2|K^\circ \cap e_i^\perp|}{n|K^\circ|} \leq 1.$$

Next notice that

$$(6) \quad K^\circ \cap e_i^\perp = (K|e_i^\perp)^\circ = (K \cap e_i^\perp)^\circ,$$

where the last equality follows from the unconditionality of K . Finally from (5), (6) we get

$$(7) \quad \mathcal{P}(K) \geq \frac{4}{n^2} \sum_{i=1}^n |K \cap e_i^\perp| \times |(K \cap e_i^\perp)^\circ| = \frac{4}{n^2} \sum_{j=1}^n \mathcal{P}(K \cap e_j^\perp).$$

Now, we will use (7) to prove our lemma. Since $\mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^n)$ and $\mathcal{P}(B_\infty^n) = \frac{4}{n^2} \sum_{j=1}^n \mathcal{P}(B_\infty^{n-1})$, we get

$$\frac{4}{n^2} \sum_{j=1}^n (1 + \varepsilon)\mathcal{P}(B_\infty^{n-1}) = (1 + \varepsilon)\mathcal{P}(B_\infty^n) \geq \mathcal{P}(K) \geq \frac{4}{n^2} \sum_{j=1}^n \mathcal{P}(K \cap e_j^\perp).$$

It implies that

$$\mathcal{P}(K \cap e_j^\perp) \leq (1 + n\varepsilon)\mathcal{P}(B_\infty^{n-1}), \quad j = 1, \dots, n.$$

Indeed, if $\mathcal{P}(K \cap e_1^\perp) > (1 + n\varepsilon)\mathcal{P}(B_\infty^{n-1})$, then

$$(8) \quad \sum_{j=1}^n \mathcal{P}(K \cap e_j^\perp) > (1 + n\varepsilon)\mathcal{P}(B_\infty^{n-1}) + (n-1)\mathcal{P}(B_\infty^{n-1}) = \frac{n^2}{4}(1 + \varepsilon)\mathcal{P}(B_\infty^n),$$

where in the first inequality we used our assumption for the $e_1^\perp$ -section and the reverse Blaschke-Santaló inequality (3) for unconditional convex bodies $K \cap e_i^\perp$, $i = 2, \dots, n$. Finally note that (8) together with (7) gives $\mathcal{P}(K) > (1 + \varepsilon)\mathcal{P}(B_\infty^n)$; a contradiction! $\square$

The next lemma will help us to treat the case of a convex body $K \subset \mathbb{R}^n$ whose sections by coordinate hyperplanes are close to the $(n-1)$ -dimensional cube.

Lemma 2. *Let $K \subset B_\infty^n$ be a convex body in $\mathbb{R}^n$, $n \geq 3$, satisfying*

$$(9) \quad K \cap e_j^\perp = B_\infty^n \cap e_j^\perp, \quad \forall j = 1, \dots, n.$$

Let $p = (t, \dots, t) \in \partial K \cap \mathbb{R}_+^n$. Then

$$|K||K^\circ| \geq (1 + c(1 - t)) |B_1^n| |B_\infty^n|,$$

where $c = c(n) > 0$ is a constant depending on n only.

Remark. The proof of Lemma 2 does not require the assumption of unconditionality of K . Such assumption would make the proof a bit shorter and would improve the constant $c(n)$.

Proof. Using (9) we claim that K contains n vectors of the form $(1, \dots, 1, 0, 1, \dots, 1)$ (i.e. $n - 1$ coordinates are equal to 1 and one coordinate is equal to 0). Moreover, K must contain the convex hull of those points. Thus $\{x : \langle x, e_1 + \dots + e_n \rangle = n - 1\} \cap B_\infty^n \subset K$, which gives $t \geq (n - 1)/n$. Next we choose $q \in \partial K^\circ$ such that $\langle p, q \rangle = 1$. Here, (9) guarantees that the normal vector to ∂K at p belongs to $\mathbb{R}_+^n$, and thus we may assume $q \in \mathbb{R}_+^n$. Let

$$\begin{aligned} P &= \text{conv}(\{p\} \cup \{x \in B_\infty^n \cap \mathbb{R}_+^n : \langle x, e_1 + \dots + e_n \rangle \leq n - 1\}), \\ Q &= \text{conv}(\{q\} \cup B_1^n \cap \mathbb{R}_+^n). \end{aligned}$$

Then $K \cap \mathbb{R}_+^n \supset P$. Also from $K \subset B_\infty^n$ we get $K^\circ \supset B_1^n$ and thus $K^\circ \cap \mathbb{R}_+^n \supset Q$. Next we notice that q belongs to the hyperplane with normal vector $(1/\sqrt{n}, \dots, 1/\sqrt{n})$ whose distance from the origin is $1/(t\sqrt{n})$. Thus

$$\begin{aligned} |P| &= 1 - \frac{1}{n!} + \frac{1}{n!} \cdot \frac{t\sqrt{n} - \frac{n-1}{n}\sqrt{n}}{1/\sqrt{n}} = 1 - \frac{1-t}{(n-1)!}, \\ |Q| &= \frac{1}{n!} \cdot \frac{1/(\sqrt{n}t)}{1/\sqrt{n}} = \frac{1}{n!t}. \end{aligned}$$

It gives

$$(10) \quad |P||Q| = \frac{1}{n!} \left(1 + \left[1 - \frac{1}{(n-1)!} \right] \frac{1-t}{t} \right) \geq 4^{-n} |B_\infty^n| |B_1^n| (1 + c_n(1-t)),$$

where $c_n = 1 - \frac{1}{(n-1)!}$ is a positive constant in case of $n \geq 3$. Note also that we have $|P||Q| \geq 4^{-n} |B_\infty^n| |B_1^n|$, independently of the position of p (i.e. independently of the lower/upper bounds on t).

If we would assume that K is unconditional then we would be able to finish the proof by simply multiplying (10) by 4^n . In all other cases we must split K and K° into 4^n parts each depending on the choice of signs of coordinates. Construct P and Q corresponding to each part, compute the corresponding volumes, and take the sum. We may apply (10) to the part corresponding to $\mathbb{R}_+^n$. In all other parts we do not care about the exact position of the point on the boundary, so we can

estimate the volume using the remark after (10). More precisely,

$$|K||K^\circ| = \left(\sum_{\delta} |K_{\delta}| \right) \left(\sum_{\delta} |K_{\delta}^\circ| \right) \geq \left(\sum_{\delta} |P_{\delta}| \right) \left(\sum_{\delta} |Q_{\delta}| \right) \geq \left(\sum_{\delta} \sqrt{|P_{\delta}||Q_{\delta}|} \right)^2,$$

where the sum is taken over all possible choices of n signs δ and K_{δ} is a subset of K corresponding to δ . Finally,

$$\begin{aligned} |K||K^\circ| &\geq \left(\sqrt{4^{-n}|B_{\infty}^n||B_1^n|(1+c_n(1-t))} + (2^n-1)\sqrt{4^{-n}|B_{\infty}^n||B_1^n|} \right)^2 \\ &= |B_{\infty}^n||B_1^n| \left[1 + 2^{-n} \left(\sqrt{1+c_n(1-t)} - 1 \right) \right]^2 \\ &\geq |B_{\infty}^n||B_1^n| (1 + 2^{-n-1}c_n(1-t)). \end{aligned} \quad \square$$

Next we would like to review some properties and definitions about ℓ_1 and ℓ_{∞} sums, Hanner polytopes and their connections to graphs. We refer to [20, 37] for more details.

Let A, B be convex subsets of $\mathbb{R}^n$. The ℓ_1 -sum of A and B is defined by $\text{conv}(A \cup B)$, the convex hull of the set $A \cup B$, and the ℓ_{∞} -sum is defined by $A + B$, the Minkowski sum of A and B .

We recall that every Hanner polytope in $\mathbb{R}^n$ can be obtained from n symmetric intervals in $\mathbb{R}^n$ by forming the ℓ_1 or ℓ_{∞} sums. In particular, a Hanner polytope in $\mathbb{R}^n$ is called *standard* if it is obtained from the intervals $[-e_1, e_1], \dots, [-e_n, e_n]$. It is easy to see that every Hanner polytope is a linear image of a standard Hanner polytope. Moreover, each coordinate of any vertex of a standard Hanner polytope is 0 or ± 1 .

The definition of a dual 0-1 polytope was given in [37] (the term “a dual 0-1 space” is used there, as a normed space whose unit ball is a dual 0-1 polytope): an unconditional polytope P in $\mathbb{R}^n$ is called a *dual 0-1 polytope* if each coordinate of any vertex of P and P° is 0 or ± 1 . Every dual 0-1 polytope P in $\mathbb{R}^n$ can be associated with the graph $G = G(P)$ with the vertex set $\{1, \dots, n\}$ and the edge set defined as follows:

$$i, j \in \{1, \dots, n\} \text{ are connected by an edge of } G \text{ if } e_i + e_j \notin P.$$

We note that for each $i, j \in \{1, \dots, n\}$ and for any dual 0-1-polytope P both the section and the orthogonal projection of P by two-dimensional subspace spanned by e_i and e_j are dual 0-1 polytopes, that is, 2-dimensional ℓ_1 - or ℓ_{∞} -balls. It gives that $e_i + e_j \notin P$ if and only if $e_i + e_j \in H^\circ$, and thus $G(P^\circ) = \overline{G(P)}$ where $\overline{G}$ denotes the complement of G .

In addition, it turned out (see Theorem 2.5, [37]) that dual 0-1 polytopes in $\mathbb{R}^n$ are in one-to-one correspondence with perfect graphs on $\{1, \dots, n\}$. In particular, as a special family of dual 0-1 polytopes, the standard Hanner polytopes in $\mathbb{R}^n$ are in one-to-one correspondence with the graphs on $\{1, \dots, n\}$ which do not contain any induced path of edge length 3 (see [41] or Lemma 3.5 in [37]). Here, an induced path of a graph G means a sequence of different vertices of G such that each two adjacent vertices in the sequence are connected by an edge of G , and each two nonadjacent vertices in the sequence are not connected. Let G be the graph associated with a

dual 0-1 polytope P as above. It turns out (Lemma 2.5, [37]) that a point $v \in \mathbb{R}^n$ is a vertex of P if and only if each coordinate of v is -1 , 0 , or 1 , and the support

$$\text{supp}(v) = \{j : \langle v, e_j \rangle \neq 0\}$$

of v is a maximal *independent set* of G , i.e., a maximal set with respect to the set-inclusion such that no pair of elements is connected by an edge.

Note that if K is unconditional, then we may apply a diagonal transformation to K to get $B_1^n \subset K \subset B_\infty^n$. Indeed, this follows immediately from the fact that a tangent hyperplane with a normal vector e_i touches K at point y_i which is a dilate of e_i . Thus to prove Theorem 1 it is enough to prove the following statement:

Equivalent form of Theorem 1: *Let K be an unconditional convex body in $\mathbb{R}^n$ satisfying $B_1^n \subset K \subset B_\infty^n$. If $\mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^n)$ for some $\varepsilon > 0$, then there exists a standard Hanner polytope H in $\mathbb{R}^n$ such that $d_{\mathcal{H}}(K, H) = O(\varepsilon)$.*

Here $d_{\mathcal{H}}$ is the *Haussdorff distance* $d_{\mathcal{H}}$ of two sets $K, L \subset \mathbb{R}^n$ defined by

$$d_{\mathcal{H}}(K, L) = \max \left(\max_{x \in K} \min_{y \in L} |x - y|, \max_{y \in L} \min_{x \in K} |x - y| \right).$$

Proof of Theorem 1. We use induction on the dimension n to prove the above statement. It is trivial if $n = 1$, and the case $n = 2$ was proved in [7]. Assume that the statement is true for all unconditional convex bodies of dimension $(n - 1)$, $n \geq 3$. For the inductive step, consider an unconditional convex body $K \subset \mathbb{R}^n$ satisfying

$$B_1^n \subset K \subset B_\infty^n \quad \text{and} \quad \mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^n).$$

We apply Lemma 1 and the inductive hypothesis to get standard Hanner polytopes $H_1 \subset \mathbb{R}^n \cap e_1^\perp, \dots, H_n \subset \mathbb{R}^n \cap e_n^\perp$ such that

$$(11) \quad d_{\mathcal{H}}(H_j, K \cap e_j^\perp) = O(\varepsilon), \quad \text{for } j = 1, \dots, n.$$

Now we would like to show that we can “glue” these $(n - 1)$ -dimensional Hanner polytopes to create an n -dimensional Hanner polytope which is $O(\varepsilon)$ -close to K . For each j , let $G_j = G(H_j)$ be the graph associated with H_j . Note that $\{1, \dots, n\} \setminus \{j\}$ is the vertex set of G_j and that G_j does not contain an induced path of edge-length 3.

Consider the graph G with vertex set $\{1, \dots, n\}$ and containing all edges of $G_1, \dots, G_n$. Our goal is to show that the polytope P corresponding to G is a Hanner polytope which is $O(\varepsilon)$ -close to K .

We claim that the graph G satisfies the following three properties.

1. Each G_j is an induced subgraph of G (i.e. for any $k, l \in \{1, \dots, n\}$, k and l are connected by an edge of G_j if and only if they are connected by an edge of G).
2. If G is not the path of edge-length 3, then G does not contain any path of edge-length 3 as an induced subgraph.

If G is the path of edge-length 3, then it is a perfect graph. Otherwise, the second property implies that G does not contain any path of edge-length 3, that is, G is the graph associated with a Hanner polytope. Thus, in any cases G must be a perfect graph.

Let P be the 0-1 polytope associated with G , i.e., $G = G(P)$.

3. If G is neither the complete graph nor its complement, then $d_{\mathcal{H}}(K, P) = O(\varepsilon)$.

Indeed, to show the first property consider different $i, j, k \in \{1, \dots, n\}$. Note that the existence of the ij edge depends only on the properties of $K \cap \text{span}\{e_i, e_j\}$, so i, j are connected by an edge of G_k if and only if they are connected by an edge of G . It implies that each G_k is an induced subgraph of G .

To prove the second property, assume that G is not the path of edge-length 3. If G contains a path of edge-length 3, then there is $j \in \{1, \dots, n\}$ which does not belong to this path. Thus, G_j , as an induced subgraph of G , must also contain the path of edge-length 3, which contradicts with the definition of G_j .

To show the third property, we first note that if G is not the complete graph, then every maximal independent set of G is a proper subset of $\{1, \dots, n\}$. The vertices of P have coordinates 0, 1 or -1 and the support of a vertex of P is a maximal independent set of G . This implies that every vertex of P has at least one zero coordinate, i.e. every vertex of P is contained in one of coordinate hyperplanes. This, together with the inductive hypothesis, gives that each vertex of P is $O(\varepsilon)$ -close to the boundary of K , which means that P is contained in $O(\varepsilon)$ -neighborhood of K . It gives $K \supset (1 + O(\varepsilon))P$. Repeating the same argument for $\bar{G}$ we get $K^\circ \supset (1 + O(\varepsilon))P^\circ$ and thus $d_{\mathcal{H}}(K, P) = O(\varepsilon)$.

Using the above three properties, we finish the proof of Theorem 1, modulo two pathological cases:

- I. G or $\bar{G}$ is the complete graph.
- II. G is the path of edge-length 3.

Therefore, it remains to consider those cases:

Case I (G (respectively $\bar{G}$) is the complete graph, so all $H_1, \dots, H_n$ are the $(n-1)$ -dimensional cubes (respectively $(n-1)$ -dimensional cross-polytopes)). Taking the polar if necessary, we may assume, without loss of generality, that all $H_1, \dots, H_n$ are the $(n-1)$ -dimensional cubes. Let $\tilde{K} = \left(\frac{1}{1-\delta}K\right) \cap B_\infty^n$, where

$$\delta = \min \{d : (1-d)H_j \subset K \cap e_j^\perp, \forall j = 1, \dots, n\}.$$

Notice that $\delta = O(\varepsilon)$ and hence $d_{\mathcal{H}}(K, \tilde{K}) = O(\varepsilon)$. By (linear order) continuity of the volume product in the Hausdorff metric, we get $\mathcal{P}(\tilde{K}) \leq (1 + O(\varepsilon))\mathcal{P}(K)$. Thus, the assumption $\mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^n)$ gives

$$(12) \quad \mathcal{P}(\tilde{K}) \leq (1 + O(\varepsilon))\mathcal{P}(B_\infty^n).$$

Also, using $H_j = B_\infty^n \cap e_j^\perp$ and the definition of δ we get

$$(13) \quad \tilde{K} \cap e_j^\perp = B_\infty^n \cap e_j^\perp, \quad \forall j = 1, \dots, n.$$

Consider $p = (t, \dots, t) \in \partial\tilde{K}$. Then Lemma 2 gives

$$\mathcal{P}(\tilde{K}) \geq (1 + c(1-t))\mathcal{P}(B_\infty^n).$$

Together with (12) the above inequality implies that $1-t = O(\varepsilon)$. Thus p is in $O(\varepsilon)$ -neighborhood of the vertex $(1, \dots, 1)$ of B_∞^n . The unconditionality of $\tilde{K}$ and (13) give that $d_{\mathcal{H}}(\tilde{K}, B_\infty^n) = O(\varepsilon)$ and hence $d_{\mathcal{H}}(K, B_\infty^n) = O(\varepsilon)$.

Case II (G is the path of edge-length 3). The direct computation below will show that this case contradicts with the assumption on the volume product of K . Indeed in this case $K \subset \mathbb{R}^4$ is $O(\varepsilon)$ -close to the polytope P which is associated with the path of edge-length 3. The volume product of P is strictly greater than that of the cube B_∞^4 . Thus selecting ε small enough we will be able to contradict the

assumption of Theorem 1. The details of calculation may be found in [27], [36]; for the sake of completeness we also present them here. Let G be represented by the vertex set $\{1, 2, 3, 4\}$ and the edge set $\{12, 23, 34\}$; then $\overline{G}$ has the same vertex set and the edge set $\{24, 41, 13\}$. Applying the characterization of vertices of a polytope by maximal independent sets, we can get

$$P = \operatorname{conv}\{(\pm 1, 0, \pm 1, 0), (0, \pm 1, 0, \pm 1)\}$$

and

$$P^\circ = \operatorname{conv}\{(\pm 1, \pm 1, 0, 0), (0, 0, \pm 1, \pm 1)\}.$$

Then we have $|P| = |P^\circ|$ and

$$\begin{aligned} |P| &= \left| \operatorname{conv}\{(\pm 1, 0, \pm 1, 0), (0, \pm 1, 0, \pm 1)\} \right| \\ &= \left| \left\{ x \in \mathbb{R}^4 : |x_1| + |x_2| \leq 1, |x_2| + |x_3| \leq 1, |x_3| + |x_4| \leq 1 \right\} \right| \\ &= 2 \int_0^1 \left| \left\{ x \in \mathbb{R}^3 : |x_1| + |x_2| \leq 1, |x_2| + |x_3| \leq 1, |x_3| \leq 1 - s \right\} \right| ds \\ &= 4 \int_0^1 \int_0^{1-s} \left| \left\{ x \in \mathbb{R}^3 : |x_1| + |x_2| \leq 1, |x_2| \leq 1 - t \right\} \right| dt ds \\ &= 8 \int_0^1 \int_0^{1-s} (1 - t^2) dt ds = \frac{10}{3}. \end{aligned}$$

Thus $\mathcal{P}(P) = \left(\frac{10}{3}\right)^2 > \frac{4^4}{4!} = \mathcal{P}(B_\infty^4)$. On the other hand, note that in this case G and $\overline{G}$ are not complete graphs, so we may apply the Property 3 from above to claim that K is $O(\varepsilon)$ -close to P . Therefore, $\mathcal{P}(K) > \mathcal{P}(B_\infty^4)$, which contradicts the assumption $\mathcal{P}(K) \leq (1 + \varepsilon)\mathcal{P}(B_\infty^4)$ for $\varepsilon > 0$ small enough. $\square$

3. MINIMALITY NEAR UNCONDITIONAL CONVEX BODIES

The following local minimality result, proved in [20], is the main tool of this section

Theorem 3. *Let K be a symmetric convex body in $\mathbb{R}^n$ close to one of Hanner polytopes in $\mathbb{R}^n$ in the sense that*

$$\min \left\{ d_{\mathcal{BM}}(K, H) : H \text{ is a Hanner polytope in } \mathbb{R}^n \right\} = 1 + \varepsilon$$

for $0 < \varepsilon \leq \varepsilon(n)$. Then

$$\mathcal{P}(K) \geq \mathcal{P}(B_\infty^n) + c(n)\varepsilon$$

where $c(n) > 0$ is a constant depending on the dimension n only.

Let $\gamma_n > 0$ be a common threshold of ε to satisfy both Theorem 1 and Theorem 3. More precisely, the constant γ_n satisfies the following:

If K is a symmetric convex body in $\mathbb{R}^n$ with $d_{\mathcal{BM}}(K, H) = 1 + \varepsilon$, $\varepsilon \leq \gamma_n$, for some Hanner polytope H , then

$$(14) \quad \mathcal{P}(K) \geq (1 + \alpha_n \varepsilon) \mathcal{P}(B_\infty^n).$$

If K is an unconditional convex body in $\mathbb{R}^n$ with $d_{\mathcal{BM}}(K, H) \geq 1 + \varepsilon$, $\varepsilon \leq \gamma_n$, for every Hanner polytope H , then

$$(15) \quad \mathcal{P}(K) \geq (1 + \beta_n \varepsilon) \mathcal{P}(B_\infty^n).$$

where $\alpha_n, \beta_n > 0$ are constants depending on n only.

Proof of Theorem 2. We will use γ_n to select the constant ε_n , a threshold of ε in the statement of the Theorem 2. Consider a convex symmetric body $K \subset \mathbb{R}^n$. Let $L \subset \mathbb{R}^n$ be an unconditional convex body with the smallest, among unconditional bodies, Banach-Mazur distance to K and let $\varepsilon \geq 0$ be such that $d_{\mathcal{BM}}(K, L) = 1 + \varepsilon$. Also consider a Hanner polytope H_0 with the smallest, among Hanner polytopes, Banach-Mazur distance to L and let $\delta \geq 0$ be such that $d_{\mathcal{BM}}(L, H_0) = 1 + \delta$.

We will consider two cases: $\delta \leq \gamma_n/3$ and $\delta > \gamma_n/3$.

1. Assume $\delta \leq \frac{\gamma_n}{3}$ and thus $d_{\mathcal{BM}}(L, H_0) \leq 1 + \frac{\gamma_n}{3}$. Then

$$\begin{aligned} d_{\mathcal{BM}}(K, H_0) &\leq d_{\mathcal{BM}}(K, L) d_{\mathcal{BM}}(L, H_0) = (1 + \varepsilon)(1 + \delta) \\ &\leq 1 + \varepsilon + (1 + \varepsilon)\gamma_n/3 \leq 1 + \gamma_n/3 + 2\gamma_n/3 = 1 + \gamma_n, \end{aligned}$$

where, to guarantee the above inequalities, we select $\varepsilon_n \leq \min\{\frac{\gamma_n}{3}, 1\}$. Thus, by (14),

$$\mathcal{P}(K) \geq (1 + \alpha_n \varepsilon) \mathcal{P}(B_\infty^n).$$

2. Now assume that $\delta > \frac{\gamma_n}{3}$ and thus $d_{\mathcal{BM}}(L, H) > 1 + \frac{\gamma_n}{3}$ for every Hanner polytope H . We will require $\varepsilon_n \leq \min\left\{\frac{\beta_n \gamma_n}{12n}, \frac{1}{2n}\right\}$. Since $L \subset TK \subset (1 + \varepsilon)L$ for some $T \in \text{GL}(n)$,

$$\begin{aligned} \mathcal{P}(K) &= \mathcal{P}(TK) \geq |L|(1 + \varepsilon)^{-1} L^\circ = (1 + \varepsilon)^{-n} \mathcal{P}(L) \\ &\geq (1 - \varepsilon)^n \mathcal{P}(L) \geq (1 - n\varepsilon) \mathcal{P}(L). \end{aligned}$$

Moreover, since $\mathcal{P}(L) \geq (1 + \beta_n \gamma_n/3) \mathcal{P}(B_\infty^n)$ by (15),

$$\begin{aligned} \mathcal{P}(K) &\geq (1 - n\varepsilon) \mathcal{P}(L) \geq (1 - n\varepsilon)(1 + \beta_n \gamma_n/3) \mathcal{P}(B_\infty^n) \\ &\geq (1 - n\varepsilon)(1 + 4n\varepsilon) \mathcal{P}(B_\infty^n) = (1 + 3n\varepsilon - 4n^2\varepsilon^2) \mathcal{P}(B_\infty^n) \\ &\geq (1 + n\varepsilon) \mathcal{P}(B_\infty^n). \end{aligned}$$

Finally we combine the above two cases by taking

$$\begin{aligned} \varepsilon_n &= \min\left\{\frac{\gamma_n}{3}, \frac{\beta_n \gamma_n}{12n}, \frac{1}{2n}\right\} \\ \tau_n &= \min\{\alpha_n, n\}. \end{aligned}$$

Then, $\mathcal{P}(K) \geq (1 + \tau_n \varepsilon) \mathcal{P}(B_\infty^n)$ whenever $\varepsilon \leq \varepsilon_n$. □

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DEPARTMENT OF MATHEMATICAL AND STATISTICAL SCIENCES, UNIVERSITY OF ALBERTA, EDMONTON, ALBERTA, T6G 2G1, CANADA

E-mail address: `jaegil@ualberta.ca`

DEPARTMENT OF MATHEMATICAL SCIENCES, KENT STATE UNIVERSITY, KENT, OHIO 44242

E-mail address: `zvavitch@math.kent.edu`