SUBGROUP OF INTERVAL EXCHANGES GENERATED BY TORSION ELEMENTS AND ROTATIONS

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ABSTRACT. Denote by G the group of interval exchange transformations (IETs) on the unit interval. Let $G_{per} \subset G$ be the subgroup generated by torsion elements in G (periodic IETs), and let $G_{rot} \subset G$ be the subset of 2-IETs (rotations).

The elements of the subgroup $H = \langle G_{per}, G_{rot} \rangle \subset G$ (generated by the sets G_{per} and G_{rot}) are characterized constructively in terms of their Sah-Arnoux-Fathi (SAF) invariant. The characterization implies that a non-rotation type 3-IET lies in H if and only if the lengths of its exchanged intervals are linearly dependent over \mathbb{Q} . In particular, $H \subseteq G$.

The main tools used in the paper are the SAF invariant and a recent result by Y. Vorobets that G_{per} coincides with the commutator subgroup of G.

1. A group of IETs

Denote by \mathbb{R} , \mathbb{Q} , \mathbb{N} the sets of real, rational and natural numbers. By a *standard interval* we mean a finite interval of the form $X = [a, b) \subset \mathbb{R}$ (left closed - right open). We write |X| = b - a for its length.

By an IET (interval exchange transformation) we mean a pair (X, f) where X = [a, b) is a standard interval and f is a right continuous bijection $f: X \to X$ with a finite set D of discontinuities and such that the translation function $\gamma(x) = f(x) - x$ is piecewise constant.

The map f itself is referred to as an IET, and then X = domain(f) and D = disc(f) denote the domain (also the range) of f and the discontinuity set of f, respectively.

Given an IET $f: X \to X$, the set $\operatorname{disc}(f)$ partitions X into a finite number of subintervals X_k in such a way that f restricted to each X_k is a translation

$$(1.1) f|_{X_k}: x \to x + \gamma_k,$$

so that the action of f reduces to a rearrangement of the intervals X_k . The number r of exchanged intervals X_k can be specified by calling f an r-IET.

Denote by \mathcal{G} the set of IETs. Then

$$\mathcal{G} = \bigcup_{r \ge 1} \mathcal{G}_r,$$

where \mathcal{G}_r stands for the set of r-IETs:

(1.3)
$$\mathcal{G}_r = \{ f \in \mathcal{G} \mid \mathbf{card}(\mathrm{disc}(f)) = r - 1 \}.$$

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For a standard interval X = [a, b), the subset

(1.4)
$$G(X) = \{ f \in \mathcal{G} \mid \operatorname{domain}(f) = X \}$$

forms a group under composition (of bijections of X). Its identity is $\mathbf{1}_{G(X)} \in \mathcal{G}_1$, the identity map on X. Given two standard intervals X and Y, there is a canonical isomorphism

$$\phi_{X,Y}: G(X) \to G(Y)$$

defined by the formula

(1.6)
$$\phi_{X,Y}(f) = l \circ f \circ l^{-1} \in G(Y), \text{ for } f \in G(X),$$

where $l = l_{X,Y}$ stands for the unique affine order preserving bijection $X \to Y$.

By the group of IETs we mean the group G := G([0,1)). (It is isomorphic to G(X), for any standard interval X.)

The interval exchange transformations have been a popular subject of study in ergodic theory. (We refer the reader to the book [12] by Marcelo Viana which may serve as a nice introduction and survey reference in the subject.) Most papers on IETs study these as dynamical systems; they concern specific dynamical properties (like minimality, ergodicity, mixing properties, etc.) the IETs may satisfy.

The focus of the present paper is different; we address certain questions on the group-theoretical structure of the group G of IETs. (For recent results on this general area see [13] and [7].) In particular, we discuss possible generator subsets of the group G.

It was known for a while that the subgroup G_{per} generated by periodic IETs forms a proper subgroup of G; in particular, G_{per} contains no irrational rotations. (The SAF invariant introduced in the next section vanishes on G_{per} but has nonzero value on irrational rotations.) On the other hand, the set G_{per} contains some uniquely ergodic, even pseudo-Anosov (self-similar) IETs (see [2]).

We show that the subgroup $H = \langle G_{per}, G_{rot} \rangle$ generated by G_{per} and the set of rotations $G_{rot} \subset G$ is still a proper subgroup of G. On the other hand, H is large enough to contain all rank 2 IETs (see Section 4), in particular the IETs over quadratic number fields.

We present a constructive criterion (in terms of the SAF invariant) for a given IET to lie in H. It follows from this criterion that a 3-IET lies in H if and only if the lengths of its exchanged subintervals are linearly independent. Note that 3-IETs generate the whole group of IETs. (More precisely, $\mathcal{G}_3 \cap G$ is a generating set for the group G.)

2. The SAF invariant and subgroups of G(X)

Throughout the paper (whenever vector spaces or linear dependence/independence are discussed) the implied field (if not specified) is always meant to be \mathbb{Q} , the field of rationals.

Denote by \mathbb{T} the tensor product of two copies of \mathbb{R} viewed as vector spaces (over \mathbb{Q}). Denote by \mathbb{K} the skew symmetric tensor product of two copies of reals:

$$\mathbb{T}:=\mathbb{R}\otimes_{\mathbb{Q}}\mathbb{R};\qquad \mathbb{K}:=\mathbb{R}\wedge_{\mathbb{Q}}\mathbb{R}\subset\mathbb{T}.$$

Recall that \mathbb{K} is the vector subspace of \mathbb{T} spanned by the wedge products

$$u \wedge v := u \otimes v - v \otimes u, \qquad u, v \in \mathbb{R}.$$

The Sah-Arnoux-Fathi (SAF) invariant (sometimes also called the scissors congruence invariant) of $f \in \mathcal{G}_r$ is defined by the formula

(2.1)
$$SAF(f) := \sum_{k=1}^{r} \lambda_k \otimes \gamma_k \in \mathbb{T},$$

where the vectors $\vec{\lambda} = (\lambda_1, \lambda_2, \dots, \lambda_r)$, $\vec{\gamma} = (\gamma_1, \gamma_2, \dots, \gamma_r) \in \mathbb{R}^r$ encode the lengths $\lambda_k = |X_k|$ of exchanged intervals X_k and the corresponding translation constants γ_k , respectively (see (1.1)).

The SAF invariant was introduced independently by Sah [9] and Arnoux and Fathi [1]. The following lemma makes this invariant a useful tool in the study of IETs

Lemma 1. Let X be a standard interval. Then

- (a) SAF: $G(X) \to \mathbb{T}$ is a group homomorphism. Ž
- (b) SAF: $G(X) \to \mathbb{K}$ is a surjective group homomorphism: SAF(G(X)) = $\mathbb{K} \subset \mathbb{T}.\check{\mathbb{Z}}$
- (c) If $f \circ h = h \circ g$ holds for $f, g, h \in G(X)$, then SAF(f) = SAF(g). (The SAF invariant does not distinguish between conjugate IETs.)

Clearly, (c) follows from (b) because both \mathbb{T} and \mathbb{K} are Abelian groups.

2.1. Subgroups of G(X). Let X be a standard interval. An IET $f \in G(X)$ is called periodic if f is an element of finite order in the group G(X) (defined in (1.4)). Set

$$(2.2) \mathcal{G}_r(X) := \mathcal{G}_r \cap G(X), \quad r > 1,$$

(see notation (1.2)). Note that $\mathcal{G}_1(X) = \{\mathbf{1}_{G(X)}\}$ is a singleton.

Consider the following subgroups of G(X):

- G'(X) = [G(X), G(X)] is the commutator subgroup of G (generated by the commutators $f^{-1}g^{-1}fg$, with $f,g\in G(X)$);
- $G_{per}(X)$ is the subgroup of G(x) generated by periodic IETs $f \in G(X)$; $\check{5}$
- $G_0(X) = \{ f \in G(X) \mid SAF(f) = 0 \} \text{ (see (2.1))}; \check{3}$
- $G_{rot}(X) = \mathcal{G}_1(X) \cup \mathcal{G}_2(X) = \mathcal{G}_2(X) \cup \{\mathbf{1}_{G(X)}\}$ is the group of rotations on X. (It contains all IETs $f \in G(X)$ with at most one discontinuity.)

Observe that (a) in Lemma 1 implies immediately the inclusions

$$G'(X) \subset G_0(X); \quad G_{per}(X) \subset G_0(X),$$

as well as the fact that the set $G_0(X)$ forms a subgroup of G(X).

An unpublished theorem of Sah [9] (mentioned by Veech in [11]) contains Lemma 1 and the equality $G'(X) = G_0(X)$. This equality has been recently extended by Vorobets [13] to also include $G_{per}(X)$ as an additional set:

(2.3)
$$G'(X) = G_0(X) = G_{ner}(X).$$

We refer to Vorobets' paper [13] for a nice self-contained introduction to the SAF invariant. In particular, the paper contains the proof of Lemma 1 and of the equality (2.3).

The results of the present paper concern the subgroup

$$(2.4) H(X) = \langle G_{ner}(X), G_{rot}(X) \rangle \subset G(X)$$

generated by periodic IETs and the rotations in G(X). The elements of H(X) are classified in terms of their SAF invariant; see Theorem 2. It is shown that "most" 3-IETs do not lie in H(X) (Lemma 5 and Theorem 4). In particular, it follows that $H(X) \neq G(X)$.

3. Subgroup H and its SAF invariant characterization

For $u \in \mathbb{R}$, denote

$$\mathbb{K}(u) = \{ u \wedge v \mid v \in \mathbb{R} \} \subset \mathbb{K} = \mathbb{R} \wedge_{\mathbb{O}} \mathbb{R}.$$

 $\mathbb{K}(u)$ forms a vector subspace of \mathbb{K} . If $u \neq 0$, $\mathbb{K}(u)$ is isomorphic to \mathbb{R}/\mathbb{Q} .

In the next lemma we compute the SAF invariant for 2-IETs. This is known and follows immediately from the definition (2.1), but is included for completeness.

In what follows X denotes a standard interval. Recall that $\mathcal{G}_r(X) = \mathcal{G}_r \cap G(X)$ stands for the set of r-IETs on X.

Lemma 2. Assume that $f \in \mathcal{G}_2(X)$ exchanges two subintervals of lengths λ_1 and λ_2 (with $\lambda_1 + \lambda_2 = |X|$). Then

$$SAF(f) = |X| \wedge \lambda_1 \in \mathbb{K}(|X|).$$

Proof. For such f the traslation constants are $\gamma_1 = -\lambda_2$ and $\gamma_2 = -\lambda_2 + 1 = \lambda_1$ (see (1.1)). It follows that

$$SAF(f) = \lambda_1 \otimes \gamma_1 + \lambda_2 \otimes \gamma_2 = \lambda_1 \otimes (-\lambda_2) + \lambda_2 \otimes \lambda_1$$
$$= \lambda_2 \wedge \lambda_1 = (\lambda_2 + \lambda_1) \wedge \lambda_1 = |X| \wedge \lambda_1.$$

Lemma 3. Let $\beta \in \mathbb{K}(|X|)$. Then there exists $f \in \mathcal{G}_2(X)$ such that $SAF(F) = \beta$.

Proof. Let $\beta = |X| \wedge t$. Select a rational $r \in \mathbb{Q}$ such that 0 < r|X| + t < |X|. Set $\lambda_1 = r|X| + t$ and $\lambda_2 = |X| - \lambda_1$. Take $f \in \mathcal{G}_2(X)$ which exchanges two intervals of lengths λ_1 and λ_2 . Then, by Lemma 2,

$$SAF(f) = |X| \wedge \lambda_1 = |X| \wedge (r|X| + t) = |X| \wedge t,$$

completing the proof.

Corollary 1. $SAF(G_{rot}(X)) = SAF(G_2(X)) = \mathbb{K}(|X|).$

Proof. Follows from Lemmas 2 and 3.

Theorem 1. Let $f \in G(X)$. Assume that $SAF(f) \in \mathbb{K}(|X|)$. Then there exists a rotation $g \in \mathcal{G}_2(X)$ and $h_1, h_2 \in G_{per}(X)$ such that

$$f = g \circ h_2 = h_1 \circ g$$
.

Note that in the above theorem $G_{per}(X)$ can be replaced by G'(X) or $G_0(X)$ (see (2.3)).

Proof of Theorem 1. By Lemma 3 there exists $g \in \mathcal{G}_2(X)$ such that $SAF(g) = SAF(f) \in \mathbb{K}(|X|)$. Take $h_1 = f \circ g^{-1}$, $h_2 = g^{-1} \circ f$. Then $h_1, h_2 \in G_0(X) = G_{per}(X)$ in view of Lemma 1.

Theorem 2. Let $f \in G(X)$. Then

$$f \in H(X) \iff SAF(f) \in \mathbb{K}(|X|).$$

Proof. Direction \Rightarrow . In view of (2.4), it is enough to show the following two inclusions:

$$S_1 = \operatorname{SAF}(G_{rot}(X)) \in \mathbb{K}(|X|); \quad S_2 = \operatorname{SAF}(G_0(X)) \in \mathbb{K}(|X|).$$

Both are immediate: $S_1 = \mathbb{K}(|X|)$ by Corollary 1, and $S_2 = 0$.

Direction \Leftarrow . Follows from Theorem 1.

4. Rank 2 IETs lie in H

By the span of a subset $A \subset \mathbb{R}$ (notation: $\mathbf{span}(A)$) we mean the minimal vector subspace of \mathbb{R} (over \mathbb{Q}) containing A.

By the rank of an IET f (notation rank(f)) we mean the dimension of the span of the set the lengths of the intervals exchanged by f:

$$\operatorname{rank}(f) := \dim_{Q}(L(f)),$$

where

(4.1)
$$L(f) := \mathbf{span}(\{\lambda_1, \lambda_2, \dots, \lambda_r\}) \quad (\text{if } f \in \mathcal{G}_r).$$

The following implication is immediate: $\mathbf{rank}(f) = 1 \implies f \in G_{per} = G_0$.

Theorem 3. For $f \in G(X)$, the following implication holds:

$$\operatorname{rank}(f) \leq 2 \implies f \in H(X).$$

Proof. We may assume that $\operatorname{rank}(f) = \dim(L(f)) = 2$. Since all $\lambda_k \in L(f)$, it follows that $|X| = \sum_{k=1}^r \lambda_k \in L(F)$. Let $B = \{|X|, u\}$ be a basis in L(F). Then

$$SAF(f) \in L(f) \wedge_{\mathbb{Q}} L(f) = \{ q | X | \wedge u \mid q \in \mathbb{Q} \}$$
$$= \{ | X | \wedge qu \mid q \in \mathbb{Q} \} \subset \mathbb{K}(|X|),$$

whence $f \in H(X)$, in view of Theorem 2.

5. Criterion for 3-IETs to Lie in H

Let $f \in \mathcal{G}_3(X)$. Then f has 2 discontinuities, and f acts by reversing the order of three subintervals, X_1 , X_2 and X_3 . Set $\lambda_i = |X_i|$. Then $X = \text{domain}(f) = [a, a + \lambda_1 + \lambda_2 + \lambda_3)$, with some $a \in \mathbb{R}$. Set for convenience a = 0 so that $X = [0, \lambda_1 + \lambda_1 + \lambda_3)$.

The corresponding translation constants are easily computed:

$$\gamma_1 = f(0) - 0 = \lambda_2 + \lambda_3 = |X| - \lambda_1;
\gamma_2 = f(\lambda_1) - \lambda_1 = \lambda_3 - \lambda_1;
\gamma_3 = f(\lambda_1 + \lambda_2) - (\lambda_1 + \lambda_2) = 0 - (\lambda_1 + \lambda_2) = \lambda_3 - |X|.$$

(The above short computation follows general receipt for computing the translation constants γ_k in terms of the constants λ_k and the permutation specifying the way intervals X_k are rearranged; see e.g. [10, Section 0]. The permutation here must be (321).)

Since $\lambda_2 = |X| - \lambda_1 - \lambda_3$, we can compute SAF(X) in terms of linear combinations of the wedge products involving only X, λ_1 and λ_3 :

(5.1)
$$SAF(X) = \sum_{k=1}^{3} \lambda_k \otimes \gamma_k = |X| \wedge (\lambda_1 - \lambda_3) - \lambda_1 \wedge \lambda_3.$$

We need the following known basic fact (see e.g. [13, Lemma 3.1]).

Lemma 4. If v_1, v_2, \ldots, v_n are $n \geq 2$ linearly independent real numbers, then the $\frac{n(n-1)}{2}$ wedge products $v_i \wedge v_j$, $1 \leq i < j \leq n$, are linearly independent.

Corollary 2. Let $v_1, v_2, v_3 \in \mathbb{R}$ be linearly independent. Then $v_1 \wedge v_2 \neq v_3 \wedge u$ for all $u \in \mathbb{R}$.

Proof. Assume to the contrary that

$$v_1 \wedge v_2 = v_3 \wedge u$$

for some $u \in \mathbb{R}$. If $u \notin \text{span}(\{v_1, v_2, v_3\})$, then the set $\{u, v_1, v_2, v_3\}$ is linearly independent, contradicting Lemma 4.

And if $u \in \mathbf{span}(\{v_1, v_2, v_3\})$, then $u = q_1v_1 + q_2v_2 + q_3v_3$ with some $q_i \in \mathbb{Q}$ whence

$$v_1 \wedge v_2 = q_1 \, v_3 \wedge v_1 + q_2 \, v_3 \wedge v_2,$$

a contradiction with Lemma 4 again.

Lemma 5. Let $f: X \to X$ be a 3-IET and assume that $\operatorname{rank}(f) = 3$. (Equivalently, the set $\{\lambda_1, \lambda_1, \lambda_3\}$ is linearly independent.) Then $f \notin H(X)$.

Proof. Assume to the contrary that $f \in H(X)$. Then, by Theorem 2, $SAF(f) \in \mathbb{K}(|X|)$. It follows from (5.1) that $\lambda_1 \wedge \lambda_3 \in \mathbb{K}(|X|)$, i.e., that

$$(5.2) \lambda_1 \wedge \lambda_3 = |X| \wedge u,$$

for some $u \in \mathbb{R}$. Since the numbers λ_1, λ_3 and $|X| = \lambda_1 + \lambda_2 + \lambda_3$ are linearly independent, (5.2) contradicts Corollary 2.

Theorem 4 (Criterion for a 3-IET to lie in H). Let $f: X \to X$ be a 3-IET. Then

$$f \in H(X) \iff \mathbf{rank}(f) \leq 2.$$

Proof. The direction \Rightarrow is a contrapositive restatement of Lemma 5. The direction \Leftarrow is given by Theorem 3.

6. Validation of the membership in classes $G_0(X)$ and H(X)

Given $f \in G(X)$, we describe constructive procedures to decide whether $f \in G_{per}(X)$ and whether $f \in H(X)$.

6.1. Does the inclusion $f \in G_{per}(X)$ hold? Since $G_{per}(X) = G_0(X)$ (see (2.3)), one only has to test the equality

$$SAF(f) := \sum_{k=1}^{r} \lambda_k \otimes \gamma_k = 0.$$

We assume that the $linear\ structure$ of f is known. By the linear structure of f we mean: I

(a) a basis $B = \{v_1, v_2, \dots, v_n\}$ of the finite dimensional space

$$L(f) := \mathbf{span}(\{\lambda_1, \lambda_2, \dots, \lambda_r\});$$

(b) the (unique) linear representations $\lambda_k = \sum_{i=1}^n q_{k,i} v_i$, $1 \le k \le r$, with all $q_{k,i} \in \mathbb{Q}$.

Observe that all translation constants γ_k also lie in L(f), and their linear representation in terms of basis B can be computed. This way one can get the representation

(6.1)
$$SAF(f) = \sum_{1 \le i \le j \le n} p_{i,j} \ v_i \wedge v_j,$$

with known $p_{i,j} \in \mathbb{Q}$. By Lemma 4, SAF(f) = 0 if and only if all the constants $p_{i,j}$ vanish. Then

$$f \in G_{per}(X) = G_0(X) \iff p_{i,j} = 0$$
, for all i, j .

6.2. Does the inclusion $f \in H(X)$ hold? Again we assume that the linear structure of f is known. To answer the question, we proceed as follows.

First, we modify the basis B of L(f) to make $v_1 = |X|$. Then we proceed just as before and get (6.1) with known $p_{i,j} \in \mathbb{Q}$. By Theorem 2 and Lemma 4,

$$f \in H(X) \iff SAF(f) \in \mathbb{K}(|X|) \iff p_{i,j} = 0, \text{ for } 2 \le i < j \le n.$$

7. Class H is not preserved under induction

An IET (X, f) is called minimal if its every orbit is dense in X. For a sufficient condition for an IET to be minimal see [5].

Let (X, f) be an r-IET and assume that $Y \subset X$ is a standard subinterval. It is well known (see e.g. [4] or [5]) that the (first return) map $f_Y \colon Y \to Y$ induced by f on Y is also an IET (exchanging at most r+1 subintervals). It is also known that, under the minimality assumption, the SAF invariant is preserved under induction.

Proposition 1 ([1, Part II, Proposition 2.13]). Let (X, f) be a minimal IET and assume that $Y \subset X$ is a standard subinterval. Then

$$SAF(f) = SAF(f_Y).$$

Corollary 3. Let (X, f) be a minimal IET and assume that $Y \subset X$ is a standard subinterval. Then

$$f \in G_{per}(X) \iff f_Y \in G_{per}(Y).$$

Proof. Follows from Proposition 1 and the fact that $G_{per}(X) = G_0(X)$.

Corollary 4. Let (X, f) be a minimal IET and assume that $Y \subset X$ is a standard subinterval such that $\frac{|Y|}{|X|} \in \mathbb{Q}$. Then

$$f \in H(X) \iff f_Y \in H(Y).$$

Proof. Follows from Proposition 1 because $\mathbb{K}(|X|) = \mathbb{K}(|Y|)$ assuming that $\frac{|Y|}{|X|} \in \mathbb{Q}$.

Theorem 5. Let (X, f) be a minimal IET. Then the following two assertions are equivalent:

- (a) There exists a standard subinterval $Y \subset X$ such that $f_Y \in H(Y)$;
- (b) $SAF(X) = u \wedge v$, for some $u, v \in \mathbb{R}$.

One can show that if (b) of the above theorem holds and $SAF(X) \neq 0$, then $u, v \in L(f)$.

Proof. (a) \Rightarrow (b). $SAF(X) = SAF(Y) \in \mathbb{K}([Y])$ whence $SAF(X) = |Y| \land v$, for some $v \in \mathbb{R}$.

(b) \Rightarrow (a). Let SAF(X) = $u \land v$, for some $u, v \in \mathbb{R}$. Without loss of generality, both u, v can be selected positive (using the identities $u \land v = (-v) \land u$ and $1 \land 1 = 0$). Select $q \in \mathbb{Q}$ so that 0 < qu < |X|. Select any standard subinterval $Y \subset X$ of length |Y| = qu. Then SAF(f_Y) = $u \land v = |Y| \land (q^{-1}v) \in SAF(|Y|)$, and hence $f_Y \in H(Y)$.

Let $K \subset \mathbb{R}$ be a subfield of reals. An IET f is said to be over K if $L(f) \subset K$ (see (4.1)), i.e., if all (lengths of exchanged intervals) λ_k lie in K.

We complete the paper by the following result.

Theorem 6. Let K be a real quadratic number field and let (X, f) be a minimal IET over K. Let $Y \subset X$ be a standard subinterval. Then

$$f_Y \in H(Y) \iff |Y| \in K.$$

Proof. Since $\operatorname{rank}(f) = \dim(L(f)) \le \dim(F) = 2$, and $\operatorname{rank}(f) \ne 1$ (because f is not periodic), we conclude that $\operatorname{rank}(f) = 2$ and L(f) = K.

Proof of the \Leftarrow implication. Select a basis $B = \{|Y|, u\}$ in K. Then

$$SAF(f_Y) = SAF(f) \in K \land K = \{q \mid Y \mid \land u \mid q \in \mathbb{Q}\} \subset \mathbb{K}(|Y|).$$

By Theorem 2, $f_Y \in H(Y)$.

Proof of the \Rightarrow implication. It has been proved in [3] that minimal rank 2 IETs must be uniquely ergodic. Thus f is uniquely ergodic. By McMullen's result [6, Theorem 2.1], $SAF(f) \neq 0$. (McMullen uses the "Galois flux" invariant for the IETs over a quadratic number field which, in his setting, is equivalent to the SAF invariant.)

Select a basis $B = \{|X|, u\}$ in K. Then

$$SAF(f_Y) = SAF(f) \in K \land K = \{q \mid X \mid \land u \mid q \in \mathbb{Q}\}.$$

Since $SAF(f) \neq 0$, $SAF(f_Y) = q|X| \wedge u$, with some $q \in \mathbb{Q}$, $q \neq 0$.

By Theorem 2, $f_Y \in H(Y)$ implies that $q|X| \wedge u = |Y| \wedge v$, for some $v \in \mathbb{R}$. This is incompatible with the assumption $Y \notin K$ in view of Corollary 2, completing the proof.

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