

## C-CYCLICAL MONOTONICITY AS A SUFFICIENT CRITERION FOR OPTIMALITY IN THE MULTIMARGINAL MONGE–KANTOROVICH PROBLEM

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ABSTRACT. This paper establishes that a generalization of  $c$ -cyclical monotonicity from the Monge–Kantorovich problem with two marginals gives rise to a sufficient condition for optimality also in the multimarginal version of that problem. To obtain the result, the cost function is assumed to be bounded by a sum of integrable functions. The proof rests on ideas from martingale transport.

### 1. INTRODUCTION AND RESULT

Let  $X_1, \dots, X_d$  be Polish spaces, and let  $\mu_1, \dots, \mu_d$  be probability measures on their Borel- $\sigma$ -fields. By  $\mathcal{M}(\mu_1, \dots, \mu_d)$  we denote the set of probability measures on the space  $E = X_1 \times \dots \times X_d$  with marginal distributions  $\mu_1, \dots, \mu_d$ . Writing  $p_i$  for the canonical projections  $E \rightarrow X_i$ , a measure  $\mu$  on  $E$  is in  $\mathcal{M}(\mu_1, \dots, \mu_d)$  if and only if

$$p_i(\mu) = \mu_i \quad \text{for } i = 1, \dots, d.$$

These measures are called transports or transport plans. Given a measurable cost function  $c : E \rightarrow \mathbb{R}$ , the cost of a transport  $\mu$  is the integral  $\int c \, d\mu$ . The multimarginal Monge–Kantorovich problem is to minimize the cost amongst transports, i.e., to solve

$$(\text{mmMK}) \quad \underset{\mu \in \mathcal{M}(\mu_1, \dots, \mu_d)}{\text{minimize}} \int c \, d\mu.$$

There is a huge literature for the case  $d = 2$ , *the* Monge–Kantorovich problem; see, e.g., [Vil03], [Vil09], or [AG12] for an overview. The literature on the case  $d > 2$  is more recent and less voluminous. For an overview the reader is referred to [Pas15].

For  $d = 2$ , a characterization of optimal transport plans is given by the concept of  $c$ -cyclical monotonicity (see [Vil09, Ch. 5]): under fairly weak assumptions on the cost function, a transport is optimal if and only if it is  $c$ -cyclically monotone. A transport is  $c$ -cyclically monotone if it is concentrated on a  $c$ -cyclically monotone set  $\Gamma \subseteq X_1 \times X_2 = X \times Y$ , i.e., a set  $\Gamma$  such that for any pairs  $(x_1, y_1), \dots, (x_n, y_n) \in \Gamma$

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one has, with  $y_{n+1} = y_1$ ,

$$(1) \quad \sum_{i=1}^n c(x_i, y_i) \leq \sum_{i=1}^n c(x_i, y_{i+1}).$$

Does such a characterization also hold for the case  $d > 2$ ?

We start with a definition with a built-in minitheorem that is well known for  $d = 2$  and similarly easy to show for  $d > 2$ .<sup>1</sup>

**Definition 1.1.** A set  $\Gamma \subseteq E$  is  $c$ -cyclically monotone if it fulfills any of the two following equivalent conditions:

- (i) for any  $n$  and any points  $(x_1^{(1)}, \dots, x_d^{(1)}), \dots, (x_1^{(n)}, \dots, x_d^{(n)}) \in \Gamma$  and permutations  $\sigma_2, \dots, \sigma_d : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$ , one has

$$\sum_{i=1}^n c(x_1^{(i)}, \dots, x_d^{(i)}) \leq \sum_{i=1}^n c(x_1^{(i)}, x_2^{(\sigma_2(i))}, \dots, x_d^{(\sigma_d(i))});$$

- (ii) any finite measure  $\alpha$  concentrated on finitely many points in  $\Gamma$  is a cost-minimizing transport plan between its marginals; i.e., if  $\alpha'$  has the same marginals as  $\alpha$ , then

$$\int c d\alpha \leq \int c d\alpha'.$$

A weaker notion of  $c$ -monotonicity allowing only comparisons of two points in (i) was shown to be a necessary condition for optimality in [Pas12]; see also [CDPDM15]. The necessity of  $c$ -cyclical monotonicity in the sense of (i) is included in the results of [BG14, Zae15]. Cyclical monotonicity was also discussed in [KP14], where cost functions that satisfy the twist condition on cyclically monotone or on splitting sets are shown to have a unique Monge solution of (mmMK), but the exact connection between splitting sets and cyclically monotone sets remains an open question. It is answered here as a byproduct in Proposition 2.5.

The question of sufficiency of cyclical monotonicity of a transport plan for optimality was open, although there was an early result in [KS94] for quadratic costs in the case  $d = 3$ . The situation is hence somewhat similar to the two-marginals case, where the sufficiency of  $c$ -cyclical monotonicity was open for some time and is now known to require more regularity of the cost function; see [AP03, Pra08, ST09, BGMS09, BC10, Bei15].

In order to prove the sufficiency of  $c$ -cyclical monotonicity for optimality, we assume  $c$  to be continuous and *bounded by a sum of integrable functions*. This means that there are functions  $f_i \in L_1(\mu_i)$  such that

$$c(x_1, \dots, x_d) \leq f_1(x_1) + \dots + f_d(x_d) \text{ for all } x_1, \dots, x_d.$$

Essentially the same condition was employed by Kellerer in [Kel84] to show the existence of dual maximizers. It will be used here to obtain the desired integrability properties of the  $c$ -splitting functions defined and constructed in the next section as the crucial step to the following theorem.

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<sup>1</sup>In order to show (ii) from (i) it is enough to deal with measures  $\alpha$  and  $\alpha'$  that assume only rational values. One multiplies both  $\int c d\alpha$  and  $\int c d\alpha'$  with the integer  $\tau$  which is defined as the product of all the denominators appearing in the values of  $\alpha$  and  $\alpha'$ . It is then possible to write  $\tau \int c d\alpha$  as a sum of the form  $\sum_{i=1}^n c(x_1^{(i)}, \dots, x_d^{(i)})$ , and because of the assumptions on  $\alpha$  and  $\alpha'$  one can find permutations to write  $\tau \int c d\alpha'$  as  $\sum_{i=1}^n c(x_1^{(i)}, x_2^{(\sigma_2(i))}, \dots, x_d^{(\sigma_d(i))})$ .

**Theorem 1.2.** *Let  $c$  be a continuous cost-function  $E \rightarrow [0, \infty)$  which is bounded by a sum of integrable functions. Let  $\mu$  be a  $c$ -cyclically monotone transport plan in  $\mathcal{M}(\mu_1, \dots, \mu_d)$ . Then  $\mu$  is optimal.*

2. PROOF OF THEOREM 1.2

The proof of Theorem 1.2 takes the proof for the case  $d = 2$  in [ST09] as a blueprint: we show that  $c$ -cyclically monotone sets are  $c$ -splitting sets. Optimality then follows easily from the assumptions on  $c$ . We exploit ideas found in [BJ16], where a notion of finite optimality is introduced as a generalization of  $c$ -cyclical monotonicity to the martingale-transport problem (with two marginals). The compactness argument to show that  $c$ -cyclically monotone sets are  $c$ -splitting is an adapted version of the argument in [BJ16] to show that finitely optimal sets are “ $c$ -good”. It is perhaps worth mentioning that, although the arguments from [BJ16] can be adapted to the multimarginal Monge–Kantorovich problem, it is an open question whether this is also possible for the multimarginal martingale problem.

**Definition 2.1.** A set  $G \subseteq E$  is called  $c$ -splitting if there exist  $d$  functions  $\varphi_i : X_i \rightarrow [-\infty, \infty)$  such that

$$\varphi_1(x_1) + \varphi_2(x_2) + \dots + \varphi_d(x_d) \leq c(x_1, x_2, \dots, x_d)$$

holds for all  $(x_1, x_2, \dots, x_d) \in E$ , and

$$\varphi_1(x_1) + \varphi_2(x_2) + \dots + \varphi_d(x_d) = c(x_1, x_2, \dots, x_d)$$

holds for all  $(x_1, \dots, x_d) \in G$ . We call the functions  $(\varphi_1, \dots, \varphi_d)$  a  $(G, c)$ -splitting tuple.

The definition of splitting tuples comes without regularity assumptions on the functions  $\varphi_i$ . If the functions in a  $(G, c)$ -splitting tuple are measurable, we call it a measurable tuple. The next lemma shows that for continuous  $c$  measurability comes at no cost.

**Lemma 2.2.** *If  $G$  is a  $c$ -splitting set and  $c$  is continuous, then there is a measurable  $(G, c)$ -splitting tuple.*

*Proof.* There is a  $c$ -splitting tuple  $(\varphi_1, \dots, \varphi_d)$  by assumption. Set

$$\tilde{\varphi}_1(x_1^0) = \inf_{x_2, \dots, x_d} \{c(x_1^0, x_2, \dots, x_d) - \varphi_2(x_2) - \dots - \varphi_d(x_d)\}.$$

If  $\tilde{\varphi}_1, \dots, \tilde{\varphi}_i$  are already defined, set

$$\begin{aligned} \tilde{\varphi}_{i+1}(x_{i+1}^0) = & \inf_{x_1, \dots, x_i, x_{i+2}, \dots, x_d} \{c(x_1, \dots, x_i, x_{i+1}^0, x_{i+2}, \dots, x_d) \\ & - \tilde{\varphi}_1(x_1) - \dots - \tilde{\varphi}_i(x_i) \\ & - \varphi_{i+2}(x_{i+2}) - \dots - \varphi_d(x_d)\}. \end{aligned}$$

The functions  $\tilde{\varphi}_1, \dots, \tilde{\varphi}_d$  are measurable (in fact, upper semicontinuous) and constitute a  $(G, c)$ -splitting tuple. □

**Lemma 2.3.** *If  $G$  is  $c$ -cyclically monotone and finite, then it is  $c$ -splitting.*

*Proof.* Immediate application of the definition of  $c$ -cyclical monotonicity and LP duality; cf. [BJ16]. □

**Lemma 2.4.** *Let  $c$  be continuous, let  $G$  be a  $c$ -splitting set, and let  $x^0 = (x_1^0, \dots, x_d^0) \in G$ . Then there exists a measurable  $(G, c)$ -splitting tuple  $(\varphi_1, \dots, \varphi_d)$ , such that*

$$\varphi_i(x_i) \leq c(x_1^0, \dots, x_{i-1}^0, x_i, x_{i+1}^0, \dots, x_d^0) \text{ for all } x_i \in X_i, i = 1, \dots, d.$$

*Proof.* By the assumptions there is a measurable  $(G, c)$ -splitting-tuple  $(\tilde{\varphi}_1, \dots, \tilde{\varphi}_d)$ . As  $x^0 \in G$ , we have

$$\sum_{i=1}^d \tilde{\varphi}_i(x_i^0) = c(x^0).$$

Hence, the values  $\tilde{\varphi}_i(x_i^0)$  are all in  $\mathbb{R}$ . Now define

$$\begin{aligned} \varphi_1 : x_1 &\mapsto \tilde{\varphi}_1(x_1) + \tilde{\varphi}_2(x_2^0) + \dots + \tilde{\varphi}_d(x_d^0), \\ \varphi_i : x_i &\mapsto \tilde{\varphi}_i(x_i) - \tilde{\varphi}_i(x_i^0), \text{ for } i = 2, \dots, d. \end{aligned}$$

We have  $\sum_{i=1}^d \varphi_i(x_i) = \sum_{i=1}^d \tilde{\varphi}_i(x_i)$ , and hence  $(\varphi_1, \dots, \varphi_d)$  is a  $(G, c)$ -splitting tuple with  $\varphi_1(x_1^0) = c(x^0) \geq 0$  and  $\varphi_i(x_i^0) = 0$  for  $i = 2, \dots, d$ . We hence have

$$\begin{aligned} \varphi_1(x_1) &\leq c(x_1, x_2^0, \dots, x_d^0) \text{ for all } x_1 \in X_1, \\ \varphi_i(x_i) &\leq c(x_1^0, \dots, x_{i-1}^0, x_i, x_{i+1}^0, \dots, x_d^0) - \varphi_1(x_1^0) \\ &\leq c(x_1^0, \dots, x_{i-1}^0, x_i, x_{i+1}^0, \dots, x_d^0) \text{ for all } x_i \in X_i. \end{aligned} \quad \square$$

**Proposition 2.5.** *Every  $c$ -cyclically monotone set  $\Gamma$  is  $c$ -splitting.*

*Proof.* (The result is trivial if  $\Gamma$  is empty.)

We fix an element  $x^0 \in \Gamma$ . Define the functions  $c_i : X_i \rightarrow [0, \infty)$ :

$$c_i : x_i \mapsto c(x_1^0, \dots, x_{i-1}^0, x_i, x_{i+1}^0, \dots, x_d^0).$$

For each finite subset  $G$  of  $\Gamma$ , set  $G' = G \cup \{x^0\}$ . By the previous two lemmas, for each such  $G'$  there is a  $(G', c)$ -splitting tuple with the components of the tuple bounded from above by  $c_1, \dots, c_d$ , respectively. Now we define

$$\begin{aligned} \mathcal{G}_G &= \{ \varphi \equiv (\varphi_1, \dots, \varphi_d) : \varphi \text{ is a } (G', c)\text{-splitting tuple with} \\ &\varphi_i(x_i) \leq c_i(x_i) \text{ for all } x_i \in X_i, \ i = 1, \dots, d \}. \end{aligned}$$

The sets  $\mathcal{G}_{G'}$  are nonempty by our previous considerations. Note that they are closed in the topology of pointwise convergence on the compact function space  $\overline{\mathbb{R}}^{X_1} \times \dots \times \overline{\mathbb{R}}^{X_d}$ . Also, the sets  $\mathcal{G}_{G'}$  have the finite intersection property: this is clear from

$$\mathcal{G}_{(G_1 \cup G_2)'} \subseteq \mathcal{G}_{G_1'} \cap \mathcal{G}_{G_2'}.$$

Consequently, the set

$$\mathcal{G} = \bigcap_{G \subseteq \Gamma, G \text{ finite}} \mathcal{G}_{G'}$$

is nonempty. It is easy to check that each of the tuples in  $\mathcal{G}$  is  $(\Gamma, c)$ -splitting.  $\square$

*Proof of Theorem 1.2.*  $\mu$  is concentrated on a  $c$ -cyclically monotone, and hence a  $c$ -splitting set  $\Gamma$ . By the assumption on  $c$ , for any  $x^0 = (x_1^0, \dots, x_d^0)$  in  $\Gamma$  the functions

$$c_i : x_i \mapsto c(x_1^0, \dots, x_{i-1}^0, x_i, x_{i+1}^0, \dots, x_d^0)$$

are in  $L_1(\mu_i)$ . By Lemma 2.4, there is a measurable  $(\Gamma, c)$ -splitting tuple  $(\varphi_1, \dots, \varphi_d)$  such that

$$\varphi_i(x_i) \leq c_i(x_i) \text{ for all } x_i \in X_i, \ i = 1, \dots, d.$$

Hence, the functions  $\varphi_i$  are all integrable against  $\mu_i$ , with the value of the integral in  $[-\infty, \infty)$ . Now take any  $\mu' \in \mathcal{M}(\mu_1, \dots, \mu_d)$ . We have, as  $\mu$  is concentrated on the  $c$ -splitting set  $\Gamma$ , and  $(\varphi_1, \dots, \varphi_d)$  is  $(\Gamma, c)$ -splitting,

$$\int c \, d\mu = \sum \int \varphi_i \, d\mu_i \leq \int c \, d\mu'. \quad \square$$

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