

exponentially growing term as well as a damping term. With the exception of very special initial conditions, both terms will be present and the tube will be unstable.

**4. Further remarks.** It appears that the behavior of the higher order perturbation terms cannot be obtained as simply as those discussed above. These may require explicit determination of the function  $F_0, F_1, F_2, \dots$ . It should be noted, however, that if  $F_0, \dots, F_{n-1}$  have been found,  $D_n$  can be determined by quadratures. Furthermore, the differential equation for  $F_n$  will be of the form

$$F_n^{IV} - D_0^2 F_n = \text{previously determined functions.}$$

The Green's function for this equation, in the case of simply supported ends is known [5], and can be determined for the other boundary conditions by standard methods. Thus  $F_n$  can be found by integration.

These comments indicate that the perturbation terms can be computed step-by-step by quadratures. Furthermore, in the supported end cases the critical velocity can be determined beforehand and perturbation from this point in powers of  $D$  will serve as a check on the perturbation solution in terms of powers of  $u$ .

#### REFERENCES

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- [3] Lothar Collatz, *Eigenwertprobleme*, Chelsea Publishing Co., New York, 1948, p. 305 ff.
- [4] L. Collatz, *Ibid*, p. 54
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### ON AN OSCILLATION CRITERION OF DE LA VALLÉE POUSSIN\*

BY PHILIP HARTMAN AND AUREL WINTNER (*The Johns Hopkins University*)

An oscillation criterion of de la Vallée Poussin<sup>1</sup> on homogeneous, linear differential equations of order  $n$ , when particularized<sup>2</sup> to  $n = 2$ , runs as follows: Let both coefficient functions of

$$x'' + g(t)x' + f(t)x = 0 \tag{1}$$

be real-valued and continuous on a  $t$ -interval and suppose that (1) has a solution  $x(t) \not\equiv 0$  which vanishes for at least two points of that  $t$ -interval, say at  $t = 0$  and at  $t = h > 0$  (so that

$$x(0) = 0, \quad x(h) = 0, \tag{2}$$

where, without loss of generality,  $x(t) \neq 0$  when  $0 < t < h$ ). Then

$$1 < M_1 h + M_2 h^2 / 2, \tag{3}$$

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<sup>1</sup>G. Sansone, *Equazioni differenziali nel campo reale*, vol. 1, 1948, p. 183.

<sup>2</sup>F. Tricomi, *Equazioni differenziali*, 1948, p. 110.

where

$$M_1 = \max_{0 \leq t \leq h} |g(t)|, \quad M_2 = \max_{0 \leq t \leq h} |f(t)|. \quad (4)$$

It will be shown in this note that (3) can be improved to

$$1 < M_1 h/2 + M_2 h^2/6. \quad (5)$$

Incidentally, it will also follow that the assumption that  $g(t)$  and  $f(t)$  are real-valued, an assumption used in de la Vallée Poussin's proof, can be omitted.

It will also follow that, instead of assuming (5) for the numbers (4), it is sufficient to assume

$$1 < \int_0^h |g(t)| dt + \frac{h}{4} \int_0^h |f(t)| dt \quad (6)$$

for the coefficient functions  $g, f$  of (1).

In order that (1) has a solution  $x(t) \not\equiv 0$  satisfying (2), a necessary condition for (1), containing both (5) and (6), can be formulated as follows:

$$h < \max \left\{ \int_0^h t |g(t)| dt, \int_0^h (h-t) |g(t)| dt \right\} + \int_0^h t(h-t) |f(t)| dt. \quad (7)$$

If  $g(t) \equiv 0$ , then (1) reduces to

$$x'' + f(t)x = 0 \quad (8)$$

and (6) to

$$4 < h \int_0^h |f(t)| dt. \quad (9)$$

Hence the criterion (7) to be proved generalizes the following well-known fact, which goes back to Liapounoff<sup>3</sup>: If  $f(t)$  is continuous for  $0 \leq t \leq h$ , then a necessary condition for (8) to have a solution ( $\not\equiv 0$ ) satisfying (2) is (9).

The proof of the statement concerning (7) depends on a device used by Nehari<sup>4</sup> for a similar purpose and proceeds as follows:

First, if  $x(t)$ , where  $0 \leq t \leq h$ , is any function possessing a continuous second derivative and satisfying (2), then it is readily verified that

$$hx(t) = (h-t) \int_0^t sx''(s) ds + t \int_t^h (h-s)x''(s) ds$$

is an identity for  $0 \leq t \leq h$ . A differentiation gives

$$hx'(t) = - \int_0^t sx''(s) ds + \int_t^h (h-s)x''(s) ds. \quad (10)$$

Next, it is clear from (2) that both  $\mu t$  and  $\mu(h-t)$  are majorants for  $|x(t)|$  if  $0 \leq t \leq h$  and

$$\mu = \max_{0 \leq t \leq h} |x'(t)|. \quad (11)$$

<sup>3</sup>P. Hartman and A. Wintner, *On an oscillation criterion of Liapounoff*, Amer. J. Math. **73**, 885-890 (1951), where further references will be found.

<sup>4</sup>Z. Nehari, *On the zeros of solutions of second order linear differential equations*, Amer. J. Math. **76**, 690 (1954).

Thus

$$|x(t)| \leq \mu \varphi(t), \quad (12)$$

where

$$\varphi(t) = \min(t, h - t), \quad (13)$$

and it is clear that the  $\leq$  in (12) is a  $<$  for some  $t$ .

If  $x''$  is substituted from (1) into (10) (as  $-gx' - fx$ ), it is seen from (11) and (12) that

$$h |x'(t)| \leq \mu \int_0^t s(|g(s)| + \varphi(s)|f(s)|) ds + \mu \int_t^h (h-s)(|g(s)| + \varphi(s)|f(s)|) ds. \quad (14)$$

Let the maximum of  $|x'(t)|$  on  $0 \leq t \leq h$  be attained at  $t = t_0$ . Then (14) and the remark made after (13) imply that

$$h < \int_0^{t_0} s(|g(s)| + \varphi(s)|f(s)|) ds + \int_{t_0}^h (h-s)(|g(s)| + \varphi(s)|f(s)|) ds, \quad (15)$$

since  $|x'(t_0)| = \mu$ , by (11), and since  $\mu \neq 0$ , by (2), where  $x(t) \neq 0$ .

The definition (13) of  $\varphi(t)$  shows that both  $s\varphi(s)$  and  $(h-s)\varphi(s)$  are majorized by  $s(h-s)$  for  $0 \leq s \leq h$ . Hence (15) can be written as

$$h < \int_0^{t_0} s |g(s)| ds + \int_{t_0}^h (h-s) |g(s)| ds + \int_0^h s(h-s) |f(s)| ds. \quad (16)$$

If the sum  $S$  of the first two integrals is considered as a function of  $t_0$ , it is seen that its derivative is

$$dS/dt_0 = t_0 |g(t_0)| - (h - t_0) |g(t_0)| = (2t_0 - h) |g(t_0)|,$$

which is non-positive or non-negative according as  $t_0 \leq \frac{1}{2}h$  or  $t_0 \geq \frac{1}{2}h$ . Hence the maximum of  $S = S(t_0)$  for  $0 \leq t_0 \leq h$  is attained either at  $t_0 = 0$  or at  $t_0 = h$ . This fact, when combined with (16), leads to the criterion (7).

*Ad (6).* Since neither  $s$  nor  $h - s$  exceeds  $h$  for  $0 \leq s \leq h$  and since  $s(h-s) \leq (h/2)^2$ , condition (6) is contained in (7).

*Ad (5).* In view of (4), the inequality (7) implies that

$$h < M_1 \max \left\{ \int_0^h s ds, \int_0^h (h-s) ds \right\} + M_2 \int_0^h s(h-s) ds.$$

Here the factor of  $M_1$  is  $h^2/2$  and that of  $M_2$  is  $h^2/6$ . Hence (5) is contained in (7).