

ON SPECTRUM GAPS  
OF SOME DIVERGENT ELLIPTIC OPERATORS  
WITH PERIODIC COEFFICIENTS

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*Dedicated to Mikhail Shlyomovich Birman on the occasion of his anniversary*

§1. INTRODUCTION

More than 10 years ago physicists gave a theoretic description of the so-called photonic crystal, an optic analog of a semiconductor. In contrast to a semiconductor, the photonic crystal is an artificial material, a composite. The dominant requirement for the photonic crystal is that electromagnetic waves of a certain length cannot propagate in it. It was also predicted that the photonic crystal is a material with high-contrast periodic structure [1]. In the mathematical sense, here we have a periodic Maxwell operator in the entire space  $L^2(\mathbb{R}^d)$ , and this operator must have gaps in its spectrum. Since the Maxwell operator is quite difficult from the viewpoint of spectral theory, scalar second-order elliptic operators (“acoustic approximations”) are often considered.

There are many mathematical publications on this subject, in which different methods are applied depending on what specific geometric and physical model of the photonic crystal is chosen. For a detailed statement of the problem and a review of mathematical methods and models, see the paper [2] by Figotin and Kuchment and the papers [3, 4] by Kuchment and Kunyansky.

1. We recall the description of the spectrum of an operator with periodic coefficients. Let

$$A = -\operatorname{div}(a\nabla) = -\nabla^*(a\nabla),$$

where the coefficient  $a = a(x)$  is measurable and periodic,

$$a(x+n) = a(x), \quad n \in \mathbb{Z}^d,$$

and satisfies the following condition of boundedness and ellipticity:

$$(1.1) \quad 0 < \alpha \leq a(x) \leq \alpha^{-1}.$$

We consider a family of problems with quasiperiodic conditions on the boundary of the periodicity cell  $\square = [0, 1]^d$ , namely,

$$\begin{aligned} -\operatorname{div}(a\nabla u) &= \lambda u, \\ u(x) &= e^{ik \cdot x} v(x), \quad v \in H_{\text{per}}^1(\square), \end{aligned}$$

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where  $k \in \mathbb{R}^d$  is a quasimomentum and  $H^1_{\text{per}}(\square)$  is the Sobolev space of periodic functions. Then we have the following periodic problem for  $v(x)$ :

$$A(k)v = \lambda v, \quad A(k) = -(\nabla + ik)^* a(\nabla + ik).$$

By definition, the function  $v \in H^1_{\text{per}}(\square)$  is a solution of this problem if the following integral identity is satisfied:

$$\int_{\square} a(\nabla v + ikv) \cdot (\nabla \bar{\varphi} - ik\bar{\varphi}) \, dx = \lambda \int_{\square} v \bar{\varphi} \, dx, \quad \varphi \in H^1_{\text{per}}(\square),$$

where the bar means complex conjugation. Putting  $\varphi = v$ , we obtain

$$(1.2) \quad \int_{\square} a|\nabla u|^2 \, dx = \lambda \int_{\square} |u|^2 \, dx.$$

Each operator  $A(k)$  is selfadjoint in  $L^2(\square)$  and has a compact resolvent. We order the eigenvalues of the operator  $A(k)$  in accordance with the minimax principle, i.e.,

$$0 \leq E_1(k) \leq E_2(k) \leq \dots$$

The band functions  $E_n(k)$  are continuous and  $2\pi$ -periodic with respect to  $k \in \mathbb{R}^d$ , and the spectrum of  $A$  is the union of the segments (bands) that are the images of the band functions

$$\text{Sp } A = \bigcup [\alpha_n, \beta_n], \quad \alpha_n = \min_k E_n, \quad \beta_n = \max_k E_n.$$

Successive segments  $[\alpha_n, \beta_n]$  and  $[\alpha_{n+1}, \beta_{n+1}]$  may overlap, but if they are disjoint, then we have a gap in the spectrum.

The existence of gaps in the spectrum is of interest from a physical viewpoint; this is related to wave propagation. Consider the wave equation

$$u''_{tt} - Au = f_0 e^{i\omega t}, \quad f_0 \in L^2(\mathbb{R}^d),$$

the solution of which is

$$u(t) = u_0 e^{i\omega t}, \quad u_0 = -(A + \omega^2 I)^{-1} f_0.$$

If  $\omega^2$  is in a spectral gap, then  $u_0 \in L^2(\mathbb{R}^d)$ , and the wave is localized. In experiments, the amplitude  $f_0$  is very small and the wave  $u(t)$  is also small and usually cannot be observed (is perceived as identically zero). However, if the number  $\omega^2$  belongs to the spectrum, then the amplitude  $u_0$  is not localized and can take considerably large values depending on the location of the point  $\omega^2$  in  $\text{Sp } A$ .

The presence of gaps in the spectrum is the main characteristic property of the “photonic crystal”. Recently, this subject has attracted considerable interest of physicists and mathematicians.

In the present paper, we discuss a method for the study of spectral gaps. This method is based on averaging theory and was suggested in the paper [5] without any association with photonic crystals.

**2.** First, we restrict ourselves to the simplest geometric model studied in [5, 6]. In [6], Hempel and Lienau considered the operator

$$A^t = -\text{div}(a^t(y)\nabla), \quad t \rightarrow \infty,$$

where the coefficient  $a^t$  has period 1 and is defined by

$$a^t(y) = \begin{cases} 1 & \text{on the periodic disperse set } F_0, \\ t^2 & \text{outside of } F_0 \end{cases}$$

(see Figure 1, where the periodicity cell is shown by a dashed line).

They proved that, as  $t \rightarrow \infty$ , the operator  $A^t$  has at least one gap in its spectrum; this paper contains many other valuable observations.

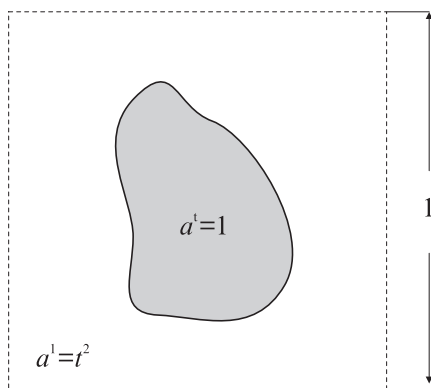


FIGURE 1.

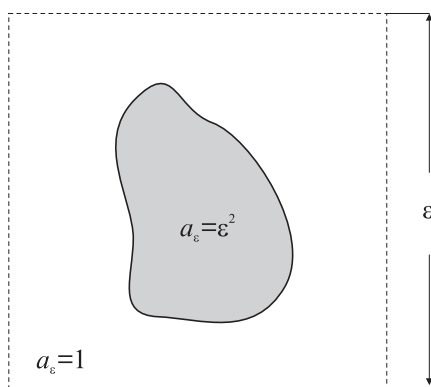


FIGURE 2.

In [5], the present author considered the operator

$$(1.3) \quad A_\varepsilon = -\operatorname{div}(a_\varepsilon(x)\nabla),$$

where the coefficient  $a_\varepsilon(x)$  has period  $\varepsilon$  and is defined as follows:

$$(1.4) \quad a_\varepsilon(x) = \begin{cases} \varepsilon^2 & \text{on } F_0^\varepsilon \text{ (soft phase),} \\ 1 & \text{on } \mathbb{R}^d \setminus F_0^\varepsilon \text{ (rigid phase),} \end{cases}$$

where  $F_0^\varepsilon = \varepsilon F_0 = \{\varepsilon x, x \in F_0\}$  is a homothetic contraction of the disperse set  $F_0$  (Figure 2). The operator  $A_\varepsilon$  corresponds to the double-porosity model.

It was proved that, as  $\varepsilon \rightarrow 0$ , the operator  $A_\varepsilon$  has gaps in the spectrum, and that the number of gaps increases unboundedly as  $\varepsilon \rightarrow 0$ .

It can easily be seen that the spectra of  $A^t$  and  $A_\varepsilon$  coincide. Indeed, if  $\lambda \in \operatorname{Sp} A^t$  and

$$-\operatorname{div}_y(a^t(y)\nabla_y u) = \lambda u(y),$$

then, using the change of variables  $y = \varepsilon^{-1}x$ , we obtain

$$-\operatorname{div}(a_\varepsilon(x)\nabla u(x)) = \lambda u(x),$$

so that

$$\operatorname{Sp} A^t = \operatorname{Sp} A_\varepsilon \quad \text{for } t = \varepsilon^{-1}.$$

This is the only common feature of the operators  $A^t$  and  $A_\varepsilon$ ; in all other respects they differ considerably. For example, the operator  $A^t$  is bounded from below by the operator

$-\Delta$  (because  $a^t \geq 1$ ). Therefore, the density of states is bounded as  $t \rightarrow \infty$ ; the corresponding limit was found in [6], see also [7]. On the contrary, the operator  $A_\varepsilon$  is unbounded from below, and the density of states is unbounded as  $\varepsilon \rightarrow 0$ . The methods used in the two papers mentioned above are entirely different.

We prefer to operate with real function spaces and real solutions of elliptic equations; only the Bloch eigenfunctions are regarded as complex solutions.

## §2. RESOLVENT CONVERGENCE

1. Many homogenization problems are of the form

$$(2.1) \quad A_\varepsilon u_\varepsilon + s u_\varepsilon = f,$$

where  $s > 0$ , and the  $A_\varepsilon$  are nonnegative selfadjoint operators in the Hilbert space  $H$ ,  $f \in H$ . The result itself of homogenization means the strong convergence  $u_\varepsilon \rightarrow u$  and the identity

$$A u + s u = f,$$

where  $A$  is also a nonnegative selfadjoint operator, which is said to be a *homogenized* or a *limit operator*. This situation corresponds to the so-called strong resolvent convergence

$$(A_\varepsilon + s)^{-1} f \rightarrow (A + s)^{-1} f$$

for all  $f \in H$  and all  $s > 0$  (it suffices to have this for  $s = 1$ ).

As an example, we can take the operator

$$A_\varepsilon = -\operatorname{div} \left( a \left( \frac{x}{\varepsilon} \right) \nabla \right), \quad H = L^2(\mathbb{R}^d),$$

where the coefficient  $a(y)$  is periodic and measurable and satisfies condition (1.1). Then homogenization theory gives the strong convergence

$$(A_\varepsilon + 1)^{-1} f \rightarrow (A + 1)^{-1} f, \quad f \in L^2(\mathbb{R}^d), \quad A = -\operatorname{div}(\mathbf{a}^{\text{hom}} \nabla),$$

where  $\mathbf{a}^{\text{hom}}$  is a constant positive definite matrix.

Recently, Birman and Suslina ([8]; see also [18]) refined this result by proving the convergence in norm and the estimate

$$\|(A_\varepsilon + 1)^{-1} - (A + 1)^{-1}\| \leq c\varepsilon.$$

For the operator  $A_\varepsilon$  with the coefficient  $a_\varepsilon$  defined by (1.4), nothing of this kind can be stated. Since the coefficient  $a_\varepsilon$  is asymptotically degenerate, the family  $u_\varepsilon$  of solutions of the resolvent equation

$$u_\varepsilon \in H^1(\mathbb{R}^d), \quad -\operatorname{div}(a_\varepsilon \nabla u_\varepsilon) + u_\varepsilon = f \in L^2(\mathbb{R}^d)$$

is not compact in  $L^2(\mathbb{R}^d)$  and even in  $L^2(\Omega)$ , where  $\Omega$  is a bounded region.

In this case, strong convergence is out of the question. The family  $u_\varepsilon$  is bounded in  $L^2(\mathbb{R}^d)$ , and we can try to find an equation satisfied by the weak limit  $\lim_{\varepsilon \rightarrow 0} u_\varepsilon$ . However, this way is not efficient since weak convergence has many pathologies; in particular, the limit equation can lose its resolvent character.

As was shown in [5], the sequence  $u_\varepsilon$  is compact in the sense of the so-called strong two-scale convergence. The two-scale limit of the sequence of solutions  $u_\varepsilon$  is not a function in  $L^2(\mathbb{R}^d)$ , but a function  $u = u(x, y)$  of two variables periodic in  $y$  and belonging to  $L^2(\mathbb{R}^d \times \square)$ . In accordance with this, the limit operator is defined not in  $L^2(\mathbb{R}^d)$  but in a wider Hilbert space  $H \subset L^2(\mathbb{R}^d \times \square)$ .

2. We give the definition of two-scale convergence (see [9]). First, we recall the mean value property of a periodic function.

**The mean value property.** Let  $\Phi(x)$  be a periodic function defined on  $\mathbb{R}^d$ , and let  $\Phi \in L^1_{\text{per}}(\square)$  and  $\langle \Phi \rangle = \int_{\square} \Phi dy$ . Then, for each  $\varphi \in C_0^\infty(\mathbb{R}^d)$  we have

$$\lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^d} \varphi(x) \Phi\left(\frac{x}{\varepsilon}\right) dx = \langle \Phi \rangle \int_{\mathbb{R}^d} \varphi(x) dx.$$

Let  $\Omega$  be an arbitrary region in  $\mathbb{R}^d$ , e.g.,  $\Omega = \mathbb{R}^d$ . We say that a sequence  $v_\varepsilon$  bounded in  $L^2(\Omega)$  is *weakly two-scale convergent* to a function  $v \in L^2(\Omega \times \square)$ ,  $v_\varepsilon(x) \xrightarrow{2} v(x, y)$ , if

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega} v_\varepsilon(x) \varphi(x) b\left(\frac{x}{\varepsilon}\right) dx = \int_{\square} \int_{\Omega} v(x, y) \varphi(x) b(y) dx dy$$

for all  $\varphi \in C_0^\infty(\Omega)$  and all  $b \in C^\infty_{\text{per}}(\square)$ .

**Example.** If  $f \in C_0^\infty(\Omega)$  and  $\Phi \in L^2_{\text{per}}(\square)$ , then  $v_\varepsilon(x) = f(x) \Phi\left(\frac{x}{\varepsilon}\right) \xrightarrow{2} f(x) \Phi(y)$ . This follows from the mean value property.

We say that a sequence  $u_\varepsilon$  bounded in  $L^2(\Omega)$  is *strongly two-scale convergent* to a function  $u \in L^2(\Omega \times \square)$ ,  $u_\varepsilon(x) \xrightarrow{2} u(x, y)$ , if

$$(2.2) \quad \lim_{\varepsilon \rightarrow 0} \int_{\Omega} u_\varepsilon(x) v_\varepsilon(x) dx = \int_{\square} \int_{\Omega} u(x, y) v(x, y) dx dy \quad \text{if } v_\varepsilon(x) \xrightarrow{2} v(x, y).$$

We list some properties of two-scale convergence:

- (i) a sequence bounded in  $L^2(\Omega)$  is compact in the sense of weak two-scale convergence;
- (ii) if  $v_\varepsilon(x) \xrightarrow{2} v(x, y)$ , then

$$(2.3) \quad \liminf_{\varepsilon \rightarrow 0} \int_{\Omega} |v_\varepsilon|^2 dx \geq \int_{\Omega} \int_{\square} |v|^2 dx dy;$$

- (iii)  $v_\varepsilon(x) \xrightarrow{2} v(x, y)$  if and only if  $v_\varepsilon(x) \xrightarrow{2} v(x, y)$  and

$$(2.4) \quad \lim_{\varepsilon \rightarrow 0} \int_{\Omega} |v_\varepsilon|^2 dx = \int_{\Omega} \int_{\square} |v|^2 dx dy;$$

- (iv) if  $f_\varepsilon(x) \rightarrow f(x)$  in  $L^2(\Omega)$ , then  $f_\varepsilon(x) \xrightarrow{2} f(x)$ ;
- (v) if  $f \in C_0^\infty(\Omega)$  and  $b \in L^2_{\text{per}}(\square)$ , then  $f(x) b\left(\frac{x}{\varepsilon}\right) \xrightarrow{2} f(x) b(y)$ ;
- (vi) for every  $f \in L^2(\Omega \times \square)$  there is a family  $f_\varepsilon \in C_0^\infty(\Omega)$  such that  $f_\varepsilon \xrightarrow{2} f$ .

Now, we give the corresponding generalization of the strong resolvent convergence.

Let  $H$  be a subspace of  $L^2(\mathbb{R}^d \times \square)$ , and let  $P: L^2(\mathbb{R}^d \times \square) \rightarrow H$  be the orthogonal projection.

**Definition 2.1.** If  $A_\varepsilon$  and  $A$  are nonnegative selfadjoint operators in  $L^2(\mathbb{R}^d)$  and in  $H$ , respectively, then the strong two-scale resolvent convergence  $A_\varepsilon \xrightarrow{2} A$  means that

$$(2.5) \quad (A_\varepsilon + 1)^{-1} f_\varepsilon \xrightarrow{2} (A + 1)^{-1} P f \quad \text{if } f_\varepsilon \xrightarrow{2} f, f \in L^2(\mathbb{R}^d \times \square).$$

To study the spectrum of the operator  $A_\varepsilon$  for small  $\varepsilon$ , it is necessary to know the spectrum of the limit operator  $A$ , together with some facts concerning the “convergence” of the spectra of  $A_\varepsilon$  to the spectrum of  $A$ .

The convergence of the spectra in the sense of Hausdorff is most desired. By definition, this means that

- (i) for all  $\lambda \in \text{Sp } A$  there are  $\lambda_\varepsilon \in \text{Sp } A_\varepsilon$  such that  $\lambda_\varepsilon \rightarrow \lambda$ ;
- (ii) if  $\lambda_\varepsilon \in \text{Sp } A_\varepsilon$  and  $\lambda_\varepsilon \rightarrow \lambda$ , then  $\lambda \in \text{Sp } A$ .

**Proposition 2.2.** Property (i) is always valid under the strong two-scale resolvent convergence.

*Proof.* We put  $T_\varepsilon = (A_\varepsilon + 1)^{-1}$  and  $T = (A + 1)^{-1}$ .

If  $\lambda \in \text{Sp } A$ , then  $\mu = (1 + \lambda)^{-1} \in \text{Sp } T$ , and, therefore, for each  $\delta > 0$  there is an element  $f$  in  $H$  such that

$$\|f\|_H = 1, \quad \|Tf - \mu f\|_H \leq \frac{\delta}{4}.$$

We take  $f_\varepsilon \in L^2(\mathbb{R}^d)$  so that  $f_\varepsilon \xrightarrow{2} f$ , and, in particular,  $\lim_{\varepsilon \rightarrow 0} \|f_\varepsilon\|_{L^2(\mathbb{R}^d)} = \|f\|_H$  (see (2.4)). Then, by the resolvent convergence (2.5), we have

$$\lim_{\varepsilon \rightarrow 0} \|(T_\varepsilon - \mu)f_\varepsilon\|_{L^2(\mathbb{R}^d)} = \|(T - \mu)f\|_H \leq \frac{\delta}{4}.$$

We obtain  $\|(T_\varepsilon - \mu)f_\varepsilon\|_{L^2(\mathbb{R}^d)} \leq \delta/2$ ,  $\|f_\varepsilon\|_{L^2(\mathbb{R}^d)} \geq 1/2$  for sufficiently small  $\varepsilon$ . It is well known that this implies that the interval  $(-\delta + \mu, \mu + \delta)$  contains a point of the spectrum of  $T_\varepsilon$ . We see that every interval centered at  $\lambda$  contains points of the spectrum of  $A_\varepsilon$  if  $\varepsilon$  is sufficiently small. The proposition is proved.  $\square$

Resolvent convergence implies the convergence of spectral projections. We consider the spectral expansions of the operators  $A_\varepsilon$  and  $A$ ,

$$A_\varepsilon = \int_0^\infty \lambda dE_\varepsilon(\lambda) \text{ in } L^2(\mathbb{R}^d), \quad A = \int_0^\infty \lambda dE(\lambda) \text{ in } H.$$

**Proposition 2.3.** *If  $\lambda$  is not an eigenvalue of the operator  $A$ , then*

$$(2.6) \quad E_\varepsilon(\lambda)f_\varepsilon \xrightarrow{2} E(\lambda)f \quad \text{whenever } f_\varepsilon \xrightarrow{2} f, f \in H.$$

We do not dwell on the proof of this statement, which, of course, implies the Hausdorff convergence property (i). Property (ii) is subtler; mostly, it does not occur under resolvent convergence.

Now, we can describe our approach to the problem of gaps in spectra.

Let  $A_\varepsilon$  be the operator of double porosity (1.3), (1.4).

**Proposition 2.4.** *We have the two-scale resolvent convergence  $A_\varepsilon \xrightarrow{2} A$ .*

This result was proved in [5] and is quite general. Here, it does not matter what the soft phase is: it can be a dispersed set or a structure of three-dimensional lattice type. It is only required that the rigid phase  $\mathbb{R}^d \setminus F_0$  be connected.

**Proposition 2.5.** *The spectrum of the limit operator has infinitely many gaps.*

We prove this for a dispersed  $F_0$ . In the case of a structure of three-dimensional lattice type, this is also true, but the description of gaps looks somewhat differently.

**Proposition 2.6.** *If the soft phase is dispersed, then property (ii) of the Hausdorff convergence of spectra is satisfied.*

This is a key point, and the dispersity of the soft phase is essential here.

It remains to use the following quite obvious statement.

**Proposition 2.7.** *Let  $K_\varepsilon$  and  $K$  be closed sets on the real line, and suppose we have the Hausdorff convergence  $K_\varepsilon \rightarrow K$ . If the limit set  $K$  has infinitely many gaps, then, for sufficiently small  $\varepsilon$ , the set  $K_\varepsilon$  has gaps close to gaps in  $K$ , and the number of gaps grows unboundedly as  $\varepsilon \rightarrow 0$ .*

Hempel and Lienau proved also that, as  $t \rightarrow \infty$ , the spectrum of  $A^t$  converges in the sense of Hausdorff to a closed set that has at least one gap. However, they did not identify this limit set with the spectrum of an operator.

We make some remarks concerning resolvent convergence, which, however, will not be used directly.

For our purposes, it suffices to have the strong convergence (2.5) only for  $f \in H$ , and then the projection  $P$  can be dropped. However, in homogenization problems, convergence with projection occurs, and it is important that this strong convergence is equivalent to a certain special weak convergence of operators.

**Proposition 2.8.** *Let  $T_\varepsilon$  and  $T$  be bounded selfadjoint operators in  $L^2(\mathbb{R}^d)$  and  $L^2(\mathbb{R}^d \times \square)$ , respectively, and let  $\|T_\varepsilon\| \leq 1$  and  $\|T\| \leq 1$ . Then the convergence*

$$(2.7) \quad T_\varepsilon f_\varepsilon \xrightarrow{2} T f \quad \text{whenever } f_\varepsilon \xrightarrow{2} f$$

is equivalent to the convergence

$$(2.8) \quad T_\varepsilon g_\varepsilon \xrightarrow{2} T g \quad \text{whenever } g_\varepsilon \xrightarrow{2} g.$$

*Proof.* 1°. Suppose (2.7) is valid. Since  $T_\varepsilon g_\varepsilon$  is bounded in  $L^2(\mathbb{R}^d)$ , we may assume that  $T_\varepsilon g_\varepsilon \xrightarrow{2} z$ , and we must prove that  $z = Tg$ . We have

$$\int_{\mathbb{R}^d} T_\varepsilon g_\varepsilon f_\varepsilon \, dx \rightarrow \int_{\mathbb{R}^d} \int_{\square} z \cdot f \, dx dy$$

because  $f_\varepsilon \xrightarrow{2} f$ . On the other hand,

$$\int_{\mathbb{R}^d} T_\varepsilon g_\varepsilon \cdot f_\varepsilon \, dx = \int_{\mathbb{R}^d} g_\varepsilon T_\varepsilon f_\varepsilon \, dx \rightarrow \int_{\square} \int_{\mathbb{R}^d} g \cdot T f \, dx dy = \int_{\square} \int_{\mathbb{R}^d} T g \cdot f \, dx dy$$

by (2.7). Consequently,  $z = Tg$ .

2°. Suppose (2.8) is valid. Then

$$\int_{\mathbb{R}^d} T_\varepsilon f_\varepsilon \cdot g_\varepsilon \, dx = \int_{\mathbb{R}^d} f_\varepsilon \cdot T_\varepsilon g_\varepsilon \, dx \rightarrow \int_{\square} \int_{\mathbb{R}^d} f \cdot T g \, dx dy = \int_{\square} \int_{\mathbb{R}^d} T f \cdot g \, dx dy.$$

Since the sequence  $g_\varepsilon$  with  $g_\varepsilon \xrightarrow{2} g$  is arbitrary, we have  $T_\varepsilon f_\varepsilon \rightarrow T f$  by the definition of strong convergence (see (2.3)). The proposition is proved.  $\square$

Thus, the strong convergence of the resolvents (2.5) is equivalent to the convergence

$$(A_\varepsilon + 1)^{-1} f_\varepsilon \xrightarrow{2} (A + 1)^{-1} P f \quad \text{whenever } f_\varepsilon \xrightarrow{2} f, f \in L^2(\mathbb{R}^d \times \square).$$

In homogenization theory, this “weak convergence” is proved first, and then the “strong convergence” (2.5) is deduced from it.

It should be noted that the convergence (2.5) does not imply a similar convergence for spectral projections, i.e., we cannot replace  $f$  by  $Pf$  in (2.6) and assume that  $f$  is an arbitrary element of  $L^2(\mathbb{R}^d \times \square)$ . The same is true for the Trotter–Kato theorem: for  $t \geq 0$  we have

$$e^{-tA_\varepsilon} f_\varepsilon \xrightarrow{2} e^{-tA} f \quad \text{whenever } f_\varepsilon \xrightarrow{2} f, f \in H.$$

We cannot find an equivalent “weak” statement for this strong operator convergence.

### §3. THE LIMIT OPERATOR

We consider the set  $V$  of functions of the form

$$(3.1) \quad \begin{aligned} u(x, y) &= u_1(x) + u_0(x, y), \quad u_1 \in H^1(\mathbb{R}^d), \\ u_0 &\in L^2(\mathbb{R}^d, H^1_{\text{per}}(\square)), \quad u_0(x, \cdot)|_{\mathbb{R}^d \setminus F_0} = 0. \end{aligned}$$

For clarity, we restrict ourselves to the case where the soft phase  $F_0$  is dispersed. Let  $B = F_0 \cap \square$  be the soft insertion in the periodicity cell. We assume that the boundary

of  $B$  is Lipschitz. Then the component  $u_0(x, \cdot)$  is a function of class  $H_0^1(B)$ , extended by zero to  $\square \setminus B$ , and we have

$$V = H^1(\mathbb{R}^d) + L^2(\mathbb{R}^d, H_0^1(B)).$$

In the Hilbert space  $L^2(\mathbb{R}^d \times \square) = L^2(\mathbb{R}^d, L^2(\square))$ , we consider the subspace

$$H = L^2(\mathbb{R}^d) + L^2(\mathbb{R}^d, L^2(B)),$$

which is closed because if  $f(x, y) = f_1(x) + f_0(x, y)$ , where  $f_1 \in L^2(\mathbb{R}^d)$  and  $f_0 \in L^2(\mathbb{R}^d, L^2(B))$ , then

$$(3.2) \quad \int_{\square} \int_{\mathbb{R}^d} |f|^2 dx dy \geq (1 - |B|^{1/2}) \left[ \int_{\mathbb{R}^d} |f_1|^2 dx + \int_B \int_{\mathbb{R}^d} |f_0|^2 dx dy \right].$$

It is also obvious that the set  $V$  is dense in  $H$ .

On the set  $V$ , we define the quadratic form

$$(3.3) \quad Q(u, u) = \int_{\mathbb{R}^d} \mathbf{a}^{\text{hom}} \nabla u_1 \cdot \nabla \bar{u}_1 dx + \int_B \int_{\mathbb{R}^d} \nabla_y u_0 \cdot \nabla_y \bar{u}_0 dx dy,$$

where  $\mathbf{a}^{\text{hom}}$  is the homogenized matrix

$$\mathbf{a}^{\text{hom}} \xi \cdot \xi = \inf_{w \in C_{\text{per}}^\infty(\square)} \int_{\square \setminus B} |\xi + \nabla w|^2 dy, \quad \xi \in \mathbb{R}^d,$$

which is positive definite, because the rigid phase  $\mathbb{R}^d \setminus F_0$  is connected in  $\mathbb{R}^d$ .

Inequality (3.2) implies that the form  $Q$  is closed. Therefore, this form determines a nonnegative selfadjoint operator  $A$  in  $H$ . The equation  $Au = Pf$ , where  $f \in L^2(\mathbb{R}^d \times \square)$  and  $P : L^2(\mathbb{R}^d \times \square) \rightarrow H$  is an orthogonal projection, means that the following integral identity is valid:

$$\int_{\mathbb{R}^d} \mathbf{a}^{\text{hom}} \nabla u_1 \cdot \nabla \varphi_1 dx + \int_B \int_{\mathbb{R}^d} \nabla_y u_0 \cdot \nabla_y \varphi_0 dx dy = \int_{\square} \int_{\mathbb{R}^d} f \varphi dx dy$$

for every test function  $\varphi = \varphi_1 + \varphi_0 \in V$ . Putting  $\varphi_0 = 0$  in the above identity, and then  $\varphi_1 = 0$ , we obtain the following two relations:

$$(3.4) \quad \begin{cases} -\operatorname{div}(\mathbf{a}^{\text{hom}} \nabla u_1) = \langle f \rangle & \text{in } \mathbb{R}^d, \\ -\Delta_y u_0 = f & \text{in } \mathbb{R}^d \times \square. \end{cases}$$

For the projection  $P: L^2(\mathbb{R}^d \times \square) \rightarrow H$ , we have the relation

$$Pf = g(x, y) = \begin{cases} f(x, y) & \text{if } y \in F_0, \\ \int_{\square \setminus B} f(x, z) dz & \text{if } y \in \mathbb{R}^d \setminus F_0. \end{cases}$$

Obviously, if we replace  $f$  by  $Pf$ , we do not change equations (3.4). We represent these equations in a shorter form:

$$(3.5) \quad \begin{cases} A_1 u_1 = \langle f \rangle & \text{in } L^2(\mathbb{R}^d) \text{ (space operator),} \\ A_0 u_0 = f & \text{in } L^2(\mathbb{R}^d, L^2(B)) \text{ (Bloch operator).} \end{cases}$$

The ‘‘space operator’’  $A_1 = -\operatorname{div}(\mathbf{a}^{\text{hom}} \nabla)$  is an elliptic second-order operator with constant coefficients. Regarded as an operator in  $L^2(\mathbb{R}^d)$ , it has an absolutely continuous spectrum that fills the entire nonnegative axis. The Bloch operator  $A_0$  reduces to the Laplace–Dirichlet operator  $-\Delta_y$  in  $L^2(B)$  (we preserve the same notation  $A_0$  for this operator). Below, we prove that the spectrum of  $A$  (including the gaps in it) is determined by the Bloch operator  $A_0$ .



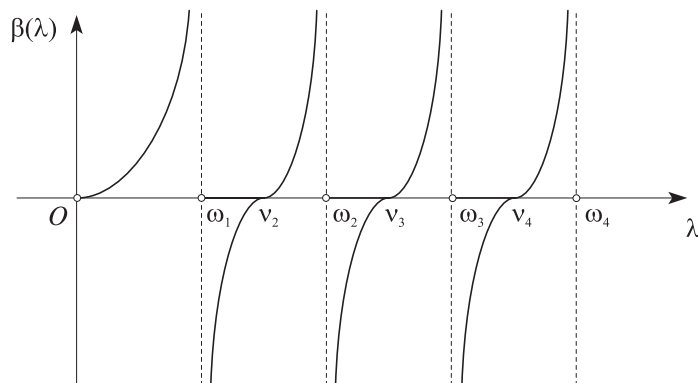


FIGURE 3.

We consider the following eigenvalue problem:

$$(3.6) \quad \begin{cases} Au = \lambda u, & u = u_1 + u_0, \\ A_0 u_0 = \lambda(u_1 + u_0), \\ A_1 u_1 = \lambda(u_1 + u_0). \end{cases}$$

We note that if  $u_0$  is an eigenfunction of the Laplace–Dirichlet operator,  $A_0 u_0 = \lambda u_0$ , and  $\langle u_0 \rangle = 0$ , then  $u(x, y) = u_0(y)$  is an eigenfunction of  $A$ . Obviously, for  $l \in L^2(\mathbb{R}^d)$  the function  $l(x)u_0(y)$  is also an eigenfunction. These are purely Bloch eigenfunctions, and, as shown below, they exhaust the point spectrum of  $A$ .

The Laplace–Dirichlet operator  $A_0$  has discrete spectrum. We split this spectrum into two disjoint parts:

$$(3.7) \quad \text{Sp } A_0 = \{\omega_1, \omega_2, \dots\} \cup \{\omega'_1, \omega'_2, \dots\}.$$

The second part consists of the eigenvalues for which all corresponding eigenfunctions have zero mean. We consider the expansion

$$1 = \sum_{n=1}^{\infty} c_n \varphi_n, \quad c_n = \langle \varphi_n \rangle \neq 0,$$

where the  $\varphi_n$  are the eigenfunctions of  $A_0$ ,  $A_0 \varphi_n = \omega_n \varphi_n$ , normalized in  $L^2(B)$ . Then

$$(3.8) \quad b = b(y, \lambda) = \sum_{n=1}^{\infty} \frac{c_n \varphi_n(y)}{\omega_n - \lambda}$$

is a solution of the equation

$$(3.9) \quad A_0 b = \lambda b + 1, \quad \lambda \notin \{\omega_1, \omega_2, \dots\}.$$

We put

$$(3.10) \quad \beta(\lambda) = \lambda(1 + \lambda \langle b \rangle) = \lambda + \sum_{n=1}^{\infty} \frac{c_n^2 \lambda^2}{\omega_n - \lambda}.$$

**Lemma 3.1.** *All eigenfunctions of the operator  $A$  are among the purely Bloch eigenfunctions mentioned above.*

*Proof.* Let  $u = u_1 + u_0$  be an eigenfunction of  $A$  (see (3.6)). If  $u_1 \equiv 0$ , then  $\langle u_0 \rangle = 0$ . Therefore,  $u = u_0$  is a purely Bloch eigenfunction. We prove that the relation  $u_1 \equiv 0$  is always valid.

Let  $u_1 \neq 0$ . We consider the orthogonal expansion

$$u_0 = \sum v_n(x)\varphi_n(y) + \sum v'_n(x)\varphi'_n(y),$$

where the  $\varphi_n$  and  $\varphi'_n$  are the eigenfunctions of  $A_0$  corresponding to the eigenvalues in  $\{\omega_1, \omega_2, \dots\}$  and in  $\{\omega'_1, \omega'_2, \dots\}$ , respectively. By (3.6), we have

$$(A_0 - \lambda)u_0 = \lambda u_1,$$

$$\sum (\omega_n - \lambda)v_n\varphi_n + \sum (\omega'_n - \lambda)v'_n\varphi'_n = \lambda u_1 \sum c_n\varphi_n.$$

It follows that  $\lambda \notin \{\omega_1, \omega_2, \dots\}$ , because

$$(\omega_n - \lambda)v_n = \lambda u_1 c_n \neq 0,$$

and if  $\lambda = \omega'_k$ , then

$$u_0(x, y) = \lambda u_1(x) \sum_{n=1}^{\infty} \frac{c_n\varphi_n(y)}{\omega_n - \lambda} + v'_k(x)\varphi'_k(y).$$

Since  $\langle \varphi'_k \rangle = 0$ , we have

$$\lambda \langle u_1 + u_0 \rangle = \beta(\lambda)u_1(x),$$

and (3.6) implies the relation  $A_1 u_1 = \beta(\lambda)u_1$ , from which it is clear that  $u_1 \equiv 0$ , because the operator  $A_1$  has no eigenfunctions in  $L^2(\mathbb{R}^d)$ . The lemma is proved.  $\square$

The graph of  $\beta(\lambda)$  is shown in Figure 3. The function  $\beta$  strictly increases on the intervals between the points  $0, \omega_1, \omega_2, \dots$ .

**Lemma 3.2.** *A point  $\lambda$  belongs to the resolvent set of  $A$  if  $\beta(\lambda) < 0$  and  $\lambda \notin \text{Sp } A_0$ .*

*Proof.* We must prove that the problem

$$(3.11) \quad \begin{cases} A_0 u_0 - \lambda(u_1 + u_0) = f, \\ A_1 u_1 - \lambda \langle u_1 + u_0 \rangle = \langle f \rangle \end{cases}$$

has a solution for every  $f \in H$  provided  $\lambda$  satisfies the assumptions of the lemma. Since  $\lambda \notin \text{Sp } A_0$ , we can put

$$u_0 = g + \lambda u_1 b,$$

where  $g = (A_0 - \lambda)^{-1}f$  and  $b$  is a solution of (3.9). Hence,

$$(3.12) \quad A_1 u_1 - \beta(\lambda)u_1 = \langle f \rangle + \lambda \langle g \rangle.$$

It remains to observe that, by the inequality  $\beta(\lambda) < 0$ , the operator  $A_1 - \beta(\lambda)I$  is invertible in  $L^2(\mathbb{R}^d)$  and equation (3.12) is solvable. Consequently, problem (3.11) has a solution for every  $f \in H$ . The lemma is proved.  $\square$

**Lemma 3.3.** *The segments on which  $\beta \geq 0$  belong to the spectrum of  $A$ .*

*Proof.* Assuming the contrary, we find a point  $\lambda$  lying inside one of the segments indicated and belonging to the resolvent set of  $A$ . Then problem (3.11) is solvable for every  $f \in H$ . We consider this problem in the specific case where  $f = \langle f \rangle$ . It is easy to realize that  $\lambda \notin \text{Sp } A_0$ . Therefore, (3.11) implies

$$u_0 = (\lambda u_1 + f)b,$$

$$A_1 u_1 - \beta(\lambda)u_1 = f(1 + \lambda \langle b \rangle).$$

Since  $(1 + \lambda \langle b \rangle) = \lambda^{-1}\beta(\lambda) > 0$ , we see that the equation  $A_1 u_1 - \beta(\lambda)u_1 = g$  has a solution in  $L^2(\mathbb{R}^d)$  for every  $g \in L^2(\mathbb{R}^d)$ , which is impossible because  $\beta(\lambda) > 0$ . The lemma is proved.  $\square$

We describe the zeros  $0 = \nu_1 < \nu_2 < \nu_3 < \dots$  of  $\beta(\lambda)$  (see Figure 3) with the help of the so-called electrostatic problem. On the set  $\mathbb{C}^1 + H_0^1(B)$ , we consider the quadratic form

$$Q(u, u) = \int_B \nabla u_0 \cdot \nabla \bar{u}_0 \, dy, \quad u = t + u_0, \quad t \in \mathbb{C}^1, \quad u_0 \in H_0^1(B),$$

and study the spectrum of the corresponding selfadjoint operator  $\Gamma$  in the Hilbert space  $\mathbb{C}^1 + L^2(B)$  regarded as a subspace of  $L^2(\square)$ . By definition, the equation

$$\Gamma u = \lambda u, \quad u = t + u_0,$$

means that

$$(3.13) \quad \int_B \nabla \varphi_0 \cdot \nabla \varphi_0 \, dy = \lambda \int_{\square} (t + u_0)(c + \varphi_0) \, dy, \quad c \in \mathbb{C}^1, \quad \varphi_0 \in H_0^1(B).$$

For  $\lambda = 0$ , the eigenfunction  $u \equiv t$  is constant. For  $\lambda > 0$ , (3.13) implies that  $t = -\langle u_0 \rangle$  and

$$(3.14) \quad -\Delta u_0 = \lambda(u_0 - \langle u_0 \rangle) \quad \text{in } B.$$

If  $\langle u_0 \rangle = 0$ , then  $u = u_0$  is an eigenfunction of  $A_0$  with eigenvalue  $\lambda \in \{\omega'_1, \omega'_2, \dots\}$ . This trivial part of the spectrum of the electrostatic problem belongs also to the spectrum of the Dirichlet problem. In the case where  $\langle u_0 \rangle \neq 0$ , we necessarily have  $\lambda \notin \{\omega_1, \omega_2, \dots\}$ . Indeed, if  $\lambda = \omega_n$ , then the equation  $-\Delta \varphi_n = \omega_n \varphi_n$  and (3.14) imply

$$\begin{aligned} \int_B \nabla u_0 \cdot \nabla \varphi_n \, dy &= \omega_n \int_B (u_0 - \langle u_0 \rangle) \varphi_n \, dy, \\ \int_B \nabla \varphi_n \cdot \nabla u_0 \, dy &= \omega_n \int_B \varphi_n u_0 \, dy. \end{aligned}$$

Therefore,  $\omega_n \langle u_0 \rangle \langle \varphi_n \rangle = 0$ . Since  $\omega_n > 0$  and  $\langle \varphi_n \rangle \neq 0$ , we have  $\langle u_0 \rangle = 0$ .

Thus,  $\lambda \notin \{\omega_1, \omega_2, \dots\}$ . Then equation (3.14) can easily be solved,

$$u_0(y) = -\lambda \langle u_0 \rangle b(y, \lambda),$$

and we see that

$$\langle u_0 \rangle (1 + \lambda \langle b \rangle) = 0 \implies \beta(\lambda) = 0.$$

Conversely, if  $\beta(\lambda) = 0$ , then the function  $u_0 = -\lambda b(y, \lambda)$  satisfies the equation

$$-\Delta u_0 = \lambda(u_0 - 1) \quad \text{in } B,$$

and  $\langle u_0 \rangle = 1$ , i.e.,  $u_0 - 1$  is an eigenfunction of the operator  $\Gamma$ . Thus, we have proved the following statement.

**Lemma 3.4.** *The zeros of  $\beta(\lambda)$  are nontrivial eigenvalues of the electrostatic problem (i.e., they are not eigenvalues of the Dirichlet problem).*

Now, we can describe the spectrum of the operator  $A$ .

1. Some eigenvalues of the Laplace–Dirichlet operator  $A_0$  (namely, those for which the corresponding eigenfunctions have zero mean) are eigenvalues (of infinite multiplicity) of the operator  $A$ . The operator  $A$  does not have other eigenvalues. Thus, the point spectrum of  $A$  contains the points  $\omega'_1, \omega'_2, \dots$  (see (3.7)) and also all multiple eigenvalues in  $\{\omega_1, \omega_2, \dots\}$ . It is well known (see [10]) that, for a “typical” region  $B$ , the spectrum of the Laplace–Dirichlet operator is simple and the eigenfunctions have zero mean; therefore, the set  $\{\omega'_1, \omega'_2, \dots\}$  is empty. In this case,  $A$  has no eigenvalues.

2. Consider the restriction of  $A$  to the orthogonal complement of the set of all its eigenfunctions. The spectrum of this restriction is the union of the segments on which  $\beta \geq 0$ , and the intervals between them are gaps. It can easily be proved that the

spectrum is absolutely continuous inside the latter intervals, and the “eigenfunctions of the continuous spectrum” look like this:

$$u(x, y, \lambda) = e^{ip \cdot x} \{1 + \lambda b(y, \lambda)\}, \quad \mathbf{a}^{\text{hom}} p \cdot p = \beta(\lambda).$$

3. The interval  $(\omega_i, \nu_{i+1})$  ( $i = 1, 2, \dots$ ) is not necessarily a gap because it can contain an eigenvalue among  $\{\omega'_1, \omega'_2, \dots\}$ . Then this interval splits into several gaps. In any case, the spectrum of  $A$  contains infinitely many gaps.

Similar results are valid in the case where the scalar conductivity coefficient  $a_\varepsilon(x)$  (see (1.4)) is replaced by the matrix coefficient

$$\mathbf{a}_\varepsilon(x) = \begin{cases} \varepsilon^2 \mathbf{a}(\frac{x}{\varepsilon}) & \text{on } F_0^\varepsilon \text{ (soft phase),} \\ \mathbf{a}(\frac{x}{\varepsilon}) & \text{on } \mathbb{R}^d \setminus F_0^\varepsilon \text{ (rigid phase),} \end{cases}$$

where  $\mathbf{a}(y)$  is a measurable periodic symmetric matrix satisfying the usual conditions of boundedness and ellipticity,

$$\alpha \xi^2 \leq \mathbf{a} \xi \cdot \xi \leq \alpha^{-1} \xi^2, \quad \alpha > 0.$$

The homogenized matrix  $\mathbf{a}^{\text{hom}}$  is defined by the equation

$$\mathbf{a}^{\text{hom}} \xi \cdot \xi = \inf_{w \in C^\infty_{\text{per}}(\square)} \int_{\square \setminus B} \mathbf{a}(y) (\xi + \nabla w) \cdot (\xi + \nabla w) dy,$$

and for the role of  $A_0$  we must take the operator  $-\text{div}_y(\mathbf{a}(y)\nabla_y)$  corresponding to the Dirichlet problem in the region  $B$ .

§4. CONVERGENCE OF SPECTRA

1. Here we prove the missing property (ii) of the Hausdorff convergence of spectra. Let  $\lambda_\varepsilon \in \text{Sp } A_\varepsilon$  be such that  $\lambda_\varepsilon \rightarrow \lambda$ ; we must prove that  $\lambda \in \text{Sp } A$ . Since we know that  $\text{Sp } A_0 \subset \text{Sp } A$ , we assume that  $\lambda \notin \text{Sp } A_0$ . We have

$$A_\varepsilon u_\varepsilon = \lambda_\varepsilon u_\varepsilon,$$

where the eigenfunction  $u_\varepsilon$  is quasiperiodic on the cell  $\varepsilon \square$  and satisfies the normalization condition

$$\int_{\varepsilon \square} |u_\varepsilon|^2 dx = \frac{1}{\varepsilon^d} \int_{\varepsilon \square} |u_\varepsilon|^2 dx = 1.$$

Then (see (1.2))

$$\int_{\varepsilon \square} a_\varepsilon |\nabla u_\varepsilon|^2 dx = \lambda_\varepsilon,$$

and for each cube  $\Omega = [-t, t]^d$ ,  $t \geq 1$ , we have

$$(4.1) \quad \begin{aligned} \frac{1}{2} &\leq \int_{\Omega} |u_\varepsilon|^2 dx \leq 2, \\ \int_{\Omega} a_\varepsilon |\nabla u_\varepsilon|^2 dx &\leq 2\lambda_\varepsilon, \end{aligned}$$

provided  $\varepsilon$  is sufficiently small.

Homogenization in double-porosity models was studied in the papers [10]–[13] and [5]. We need the following result.

**Theorem 4.1.** *Let  $\Omega$  be a closed Lipschitz region, and let  $u_\varepsilon \in H^1(\Omega)$  be a sequence such that*

- 1)  $\limsup_{\varepsilon \rightarrow 0} \int_{\Omega} (|u_\varepsilon|^2 + a_\varepsilon |\nabla u_\varepsilon|^2) dx < \infty$ ;
- 2)  $-\text{div}(a_\varepsilon \nabla u_\varepsilon) = g_\varepsilon$ ,  $g_\varepsilon$  is bounded in  $L^2(\Omega)$ ,  $g_\varepsilon(x) \xrightarrow{2} g(x, y)$ .

Then (up to extraction of a subsequence) we have the two-scale convergence

$$u_\varepsilon(x) \xrightarrow{2} u(x, y) = u_1(x) + u_0(x, y), \quad u_1 \in H^1(\Omega), \quad u_0 \in L^2(\Omega, H_0^1(B)),$$

and the limit function satisfies the integral identity

$$\int_\Omega \mathbf{a}^{\text{hom}} \nabla u_1 \cdot \nabla \varphi_1 \, dx + \int_\Omega \int_B \nabla_y u_0 \cdot \nabla_y \varphi_0 \, dx dy = \int_\Omega \int_\square g(\varphi_1 + \varphi_0) \, dx dy$$

for all  $\varphi_1 \in C_0^\infty(\Omega)$  and all  $\varphi_0 \in L^2(\Omega, H_0^1(B))$ .

In a concise form, we can write

$$\begin{cases} A_1 u_1 = -\operatorname{div}(\mathbf{a}^{\text{hom}} \nabla u_1) = \langle g \rangle & \text{in } \Omega, \\ A_0 u_0 = -\Delta_y u_0 = g & \text{in } \Omega \times \square. \end{cases}$$

Applying Theorem 4.1 to the sequence of eigenfunctions  $u_\varepsilon$ , we obtain the two-scale convergence

$$u_\varepsilon(x) \xrightarrow{2} u(x, y) = u_1(x) + u_0(x, y), \quad u_1 \in H_{\text{loc}}^1(\mathbb{R}^d), \quad u_0 \in L_{\text{loc}}^2(\mathbb{R}^d, H_0^1(B)),$$

and equations (3.6). Formally, the equation  $Au = \lambda u$  is fulfilled. However, the function  $u$  is not an element of  $L^2(\mathbb{R}^d \times \square)$ , and, above all, it is unclear whether  $u \neq 0$ .

The following statement plays a key role.

**Lemma 4.2** (compactness lemma). *Let  $\lambda_\varepsilon \rightarrow \lambda \notin \operatorname{Sp} A_0$ . Then the sequence of eigenfunctions  $u_\varepsilon$  is compact in the sense of strong two-scale convergence in every bounded region  $\Omega \subset \mathbb{R}^d$ .*

Using this lemma, inequality (4.1), and property (2.4), we obtain  $\int_{\Omega \times \square} |u|^2 \, dx dy \geq 1/2$ . Then also  $u_1 \neq 0$  because otherwise (3.6) implies  $\lambda \in \operatorname{Sp} A_0$ . Now, property (ii) of the Hausdorff convergence can easily be obtained. Indeed, by (3.6), we have the following equation for  $u_1$ :

$$(4.2) \quad -\operatorname{div}(\mathbf{a}^{\text{hom}} \nabla u_1) = \beta(\lambda) u_1,$$

and if we assume that  $\lambda \notin \operatorname{Sp} A$ , then  $\beta(\lambda) < 0$  by Lemma 3.3. Relation (4.1) and property (2.3) of semicontinuity yield

$$\int_\Omega \int_\square |u|^2 \, dx dy \leq 2.$$

Now, an inequality of the form (3.2) (with  $\Omega$  instead of  $\mathbb{R}^d$ ) leads to the estimate

$$\int_\Omega |u_1|^2 \, dx \leq \frac{2}{1 - |B|^{1/2}},$$

which shows that the solution  $u_1$  is of “moderate” growth, i.e., it corresponds to a “tempered distribution” (a continuous functional on the Schwartz space on  $\mathbb{R}^d$ ). Then  $u_1 \equiv 0$ , which becomes clear if we pass to the Fourier transform in (4.2) and recall that  $\beta(\lambda) < 0$ .

**2.** To prove the compactness lemma, we need the following well-known result concerning extension of functions (see [14, Chapter III]).

**Proposition 4.3.** *Suppose  $B_1$  is a sufficiently smooth region such that  $\overline{B_1} \subset \square$ ,  $\overline{B} \subset B_1$ , and  $B_1 \setminus B$  is connected. Then there is an extension of  $u \in H^1(B_1 \setminus B)$  up to a function  $\tilde{u} \in H^1(B_1)$ , and we have the estimates*

$$(4.3) \quad \int_B |\nabla \tilde{u}|^2 \, dx \leq C \int_{B_1 \setminus B} |\nabla u|^2 \, dx, \quad \int_B |\tilde{u}|^2 \, dx \leq C \int_{B_1 \setminus B} (|u|^2 + |\nabla u|^2) \, dx$$

with a constant  $C$  independent of  $u$ . Moreover, we may assume that the function  $\tilde{u}$  is harmonic in  $B$ .

Estimates (4.3) only improve under a homothety, and we can apply them to each component of  $F_0^\varepsilon$ . As a result, we obtain an extension of  $u_\varepsilon|_{\mathbb{R}^d \setminus F_0^\varepsilon}$  to  $\mathbb{R}^d$ ,

$$\tilde{u}_\varepsilon \in H_{\text{loc}}^1(\mathbb{R}^d), \quad \int_{\Omega} (|\tilde{u}_\varepsilon|^2 + |\nabla \tilde{u}_\varepsilon|^2) dx \leq C_1.$$

Without loss of generality, we may assume that

$$\tilde{u}_\varepsilon \rightharpoonup u_1 \quad \text{in } H_{\text{loc}}^1(\mathbb{R}^d).$$

Since  $\tilde{u}_\varepsilon \rightharpoonup u_1$  strongly in  $L^2(\Omega)$ , we have  $\tilde{u}_\varepsilon(x) \xrightarrow{2} u(x)$  (see property (iv) of two-scale convergence in §2). Therefore, it remains to prove that the difference  $v_\varepsilon = u_\varepsilon - \tilde{u}_\varepsilon$  is compact in the sense of strong two-scale convergence in  $\Omega$ . Assuming that  $\tilde{u}_\varepsilon$  is harmonic on each inclusion, we obtain

$$(4.4) \quad v_\varepsilon \in H_0^1(F_0^\varepsilon), \quad -\varepsilon^2 \Delta v_\varepsilon = \lambda_\varepsilon (\tilde{u}_\varepsilon + v_\varepsilon) \text{ in } F_0^\varepsilon.$$

Consider the operator  $T_\varepsilon = -\varepsilon^2 \Delta$  corresponding to the Dirichlet problem in  $F_0^\varepsilon$ . Since  $F_0^\varepsilon$  splits into separate components, the operator  $T_\varepsilon$  also splits, and its spectrum coincides with that of the operator  $A_0$  in  $L^2(B)$ . Since the points  $\lambda_\varepsilon$  are separated away from  $\text{Sp } A_0$  by a distance  $\rho_0 > 0$ , we obtain  $\|(T_\varepsilon - \lambda_\varepsilon)^{-1}\| \leq \frac{1}{\rho_0}$ , and for the solution of the equation

$$T_\varepsilon z_\varepsilon - \lambda_\varepsilon z_\varepsilon = g_\varepsilon$$

we have the estimate

$$(4.5) \quad \|z_\varepsilon\|_{L^2(\Omega \cap F_0^\varepsilon)} \leq \frac{1}{\rho_0} \|g_\varepsilon\|_{L^2(\Omega \cap F_0^\varepsilon)},$$

where  $\Omega \cap F_0^\varepsilon$  means the totality of inclusions entirely lying in  $\Omega$ .

Below, we use the following obvious property of two-scale convergence.

**Proposition 4.4.** *Suppose  $v_\varepsilon \in L^2(\Omega)$  and  $v \in L^2(\Omega \times \square)$ . Assume that the following condition is fulfilled: for every  $\delta > 0$  there exist elements  $z_\varepsilon \in L^2(\Omega)$  and  $z \in L^2(\Omega \times \square)$  such that*

$$z_\varepsilon \xrightarrow{2} z, \quad \|v - z\|_{L^2(\Omega \times \square)} \leq \delta, \quad \limsup_{\varepsilon \rightarrow 0} \|v_\varepsilon - z_\varepsilon\|_{L^2(\Omega)} \leq \delta.$$

Then  $v_\varepsilon \xrightarrow{2} v$ .

**Proposition 4.5.** *Let  $v_\varepsilon$  be a solution of (4.4). Then*

$$(4.6) \quad v_\varepsilon(x) \xrightarrow{2} \lambda u_1(x) b(y, \lambda) \equiv v(x, y),$$

where  $b$  is a solution of (3.9).

*Proof.* We use estimate (4.5) to simplify equation (4.4). Let  $f \in C_0^\infty(\mathbb{R}^d)$  be such that  $\|\tilde{u}_\varepsilon - f\|_{L^2(\Omega)} \leq \delta$  for all  $\varepsilon$ . The existence of such a function follows from the strong convergence  $\tilde{u}_\varepsilon \rightharpoonup u_1$  in  $L^2(\Omega)$ . Then estimate (4.5) allows us to replace  $\tilde{u}_\varepsilon$  by  $f$ . Next, we consider the function  $f_\varepsilon(x)$  that coincides with  $f$  on  $\mathbb{R}^d \setminus F_1^\varepsilon$  and that, on each component of  $F_0^\varepsilon$ , is equal to the mean value on this component. Then  $|f - f_\varepsilon| \rightarrow 0$  uniformly on  $\Omega$ , and we can replace  $f$  by  $f_\varepsilon$ . For the same reason, we can replace  $\lambda_\varepsilon$  by  $\lambda$ . After these simplifications, we obtain the equation

$$T_\varepsilon z_\varepsilon - \lambda z_\varepsilon = \lambda f_\varepsilon.$$

However, in this case,

$$z_\varepsilon(x) = \lambda f_\varepsilon(x) b(\varepsilon^{-1}x, \lambda)$$

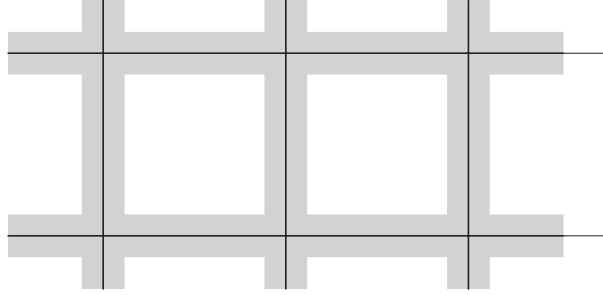


FIGURE 4.

(see (3.9)), and the strong convergence  $z_\varepsilon(x) \xrightarrow{2} z(x, y) = \lambda f(x)b(y, \lambda)$  is obvious. As a result, we have

$$\limsup_{\varepsilon \rightarrow 0} \|v_\varepsilon - z_\varepsilon\|_{L^2(\Omega)} \leq C\delta,$$

$$\int_{\Omega} \int_{\square} |v - z|^2 dx dy \leq \lambda^2 \int_{\Omega} |u_1 - f|^2 dx \cdot \langle b^2 \rangle \leq C\delta^2,$$

and Proposition 4.4 gives (4.6). Thus, the compactness lemma is proved.  $\square$

§5. OTHER GEOMETRIC MODELS

We describe a simplest plane model in which the rigid phase is not a fixed periodic set as before, but is a “fine” structure with relative area tending to zero.

In Figure 4, we have a square 1-periodic net  $F^h$  consisting of strips of width  $2h > 0$ . In the same figure, an infinitely thin (singular) net corresponding to the width  $h = 0$  is depicted.

On  $\mathbb{R}^2$ , we define a periodic function  $\rho^h(y)$  such that

$$2\rho^h(y) = \begin{cases} 1 + \frac{1}{|\square \cap F^h|} & \text{on } \square \cap F^h, \\ 1 & \text{off } F^h. \end{cases}$$

As  $h \rightarrow 0$ , we have

$$\rho^h dy \rightharpoonup d\mu, \quad d\mu = \frac{1}{2} dy + \frac{1}{2} dm,$$

in the sense of weak convergence of measures, where  $dy$  is the planar Lebesgue measure and  $dm$  is the periodic measure concentrated on the singular net and proportional to the one-dimensional Lebesgue measure on this net,  $\int_{\square} dm = 1$ . It can be said that we “reinforce” the plane with a thin net the mass of which is half the total mass. In the limit as  $h \rightarrow 0$ , the plane is reinforced with the singular net, which is also half the total mass. The limit measure  $\mu$  can be called the *composite* or *junction measure*.

Now, we assume that  $h(\varepsilon) \rightarrow 0$  and define an  $\varepsilon$ -periodic thin structure  $F^\varepsilon$  and the corresponding density  $\rho_\varepsilon(x)$  by the formulas

$$F^\varepsilon = \varepsilon F^{h(\varepsilon)}, \quad \rho_\varepsilon(x) = \rho^{h(\varepsilon)}(\varepsilon^{-1}x).$$

By construction,

$$2\rho_\varepsilon(x) = \begin{cases} 1 & \text{off } F^\varepsilon, \\ 1 + \frac{1}{|\square_\varepsilon \cap F^\varepsilon|} & \text{on } \square_\varepsilon \cap F^\varepsilon, \end{cases}$$

where  $\square_\varepsilon = \varepsilon \square$ . Obviously, we have  $\int_{\varepsilon \square} \rho_\varepsilon dx = \varepsilon^2$ , whence  $\rho_\varepsilon dx \rightharpoonup dx$ .

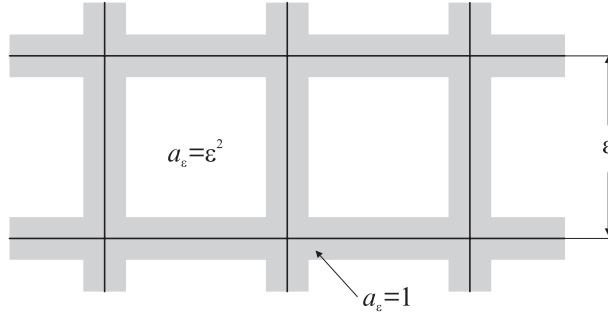


FIGURE 5.

We define the *permeability ratio* as

$$a_\varepsilon(x) = \begin{cases} 1 & \text{on } F^\varepsilon \text{ (rigid phase),} \\ \varepsilon^2 & \text{on } \mathbb{R}^2 \setminus F^\varepsilon = F_0^\varepsilon \text{ (soft phase)} \end{cases}$$

(see Figure 5) and study the spectrum of the operator

$$A_\varepsilon = -\operatorname{div}(a_\varepsilon \rho_\varepsilon \nabla)$$

in the space  $L^2(\mathbb{R}^d, \rho_\varepsilon dx)$ . The resolvent equation has the form

$$-\operatorname{div}(a_\varepsilon \rho_\varepsilon \nabla u_\varepsilon) + \rho_\varepsilon u_\varepsilon = f, \quad f \in L^2(\mathbb{R}^d, \rho_\varepsilon dx).$$

First, we introduce an appropriate definition of the two-scale convergence. Let  $v_\varepsilon$  be a bounded sequence in  $L^2(\mathbb{R}^d, \rho_\varepsilon dx)$ , i.e.,

$$\limsup_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^d} |v_\varepsilon|^2 \rho_\varepsilon dx < \infty.$$

A function  $v \in X = L^2(\mathbb{R}^d \times \square, dx \times d\mu) = L^2(\mathbb{R}^d, L^2(\square, d\mu))$  is the weak two-scale limit of  $v_\varepsilon$ ,  $v_\varepsilon(x) \overset{2}{\rightharpoonup} v(x, y)$  if

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^d} v_\varepsilon(x) \varphi(x) b\left(\frac{x}{\varepsilon}\right) \rho_\varepsilon(x) dx \\ = \int_{\mathbb{R}^d} \int_{\square} v(x, y) \varphi(x) b(y) dx d\mu(y), \quad \varphi \in C_0^\infty(\mathbb{R}^d), \quad b \in C_{\text{per}}^\infty(\square). \end{aligned}$$

In a similar way, we can define strong two-scale convergence. The definitions given in §2 correspond to the case where  $\rho_\varepsilon \equiv 1$  and  $d\mu = dy$ . All properties listed there remain valid also in the general case (see [15], where the general idea of two-scaled convergence was presented). For example, the lower semicontinuity property (2.3) looks like this:

$$\liminf_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^d} |v_\varepsilon|^2 \rho_\varepsilon dx \geq \int_{\mathbb{R}^d} \int_{\square} |v|^2 dx d\mu.$$

Now, we make a remark concerning the space  $X$  to which the two-scale limits belong. The space  $L^2(\mathbb{R}^d)$  is naturally identified with a subspace of  $X$ , and since  $2d\mu = dm + dy$  and  $dm$  is singular with respect to the Lebesgue measure  $dy$ , we see that the space  $L^2(\mathbb{R}^d, L^2(\square, dy))$  can also be regarded as a subspace of  $X$ .

It can be shown that we have the strong two-scale convergence  $A_\varepsilon \overset{2}{\rightharpoonup} A$ . The limit operator  $A$  acts in the subspace  $H \subset X$ ,

$$H = L^2(\mathbb{R}^d) + L^2(\mathbb{R}^d, L^2(\square, dy)),$$



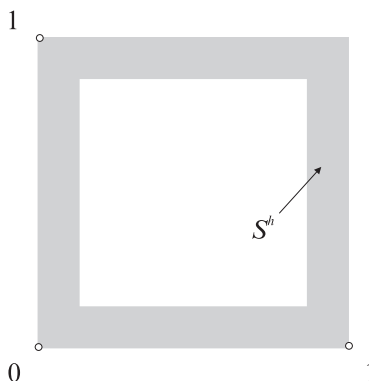


FIGURE 6.

which is closed because of an inequality of the form (3.2), namely, if  $f(x, y) = f_1(x) + f_0(x, y)$ , then

$$\|f\|_X^2 \geq \left(1 - \frac{\sqrt{2}}{2}\right) \left[ \int_{\mathbb{R}^d} |f_1|^2 dx + \int_{\square} \int_{\mathbb{R}^d} |f_0|^2 dx dy \right].$$

In this case, the homogenized matrix defined by

$$2\mathbf{a}^{\text{hom}} \xi \cdot \xi = \inf_{w \in C_{\text{per}}^\infty(\square)} \int_{\square} |\xi + \nabla w|^2 dm$$

can be calculated explicitly:  $\mathbf{a}^{\text{hom}} = \frac{1}{4}I$ . The quadratic form  $Q(u, u) = (Au, u)$  is given on the set  $V = H^1(\mathbb{R}^d) + L^2(\mathbb{R}^d, H_0^1(\square))$  by the formula

$$\begin{aligned} Q(u, u) &= \int_{\mathbb{R}^d} \mathbf{a}^{\text{hom}} \nabla u_1 \cdot \nabla \bar{u}_1 dx + \int_{\square} \int_{\mathbb{R}^d} \nabla_y u_0 \cdot \nabla_y \bar{u}_0 dx d\mu \\ &= \frac{1}{4} \int_{\mathbb{R}^d} \nabla u_1 \cdot \nabla \bar{u}_1 dx + \frac{1}{2} \int_{\square} \int_{\mathbb{R}^d} \nabla_y u_0 \cdot \nabla_y \bar{u}_0 dx dy, \end{aligned}$$

and the relation  $Au = Pf$ , where  $f \in X$ , reduces to the following two relations:

$$\begin{cases} -\frac{1}{4}\Delta u_1 = \langle f \rangle & \text{in } \mathbb{R}^d, \langle f \rangle = \int_{\square} f d\mu, \\ -\Delta_y u_0 = f & \text{in } \mathbb{R}^d \times \square. \end{cases}$$

Now the operator  $A_0$  is the Laplace–Dirichlet operator in the unit square  $\square$ . Thus, we have a complete analogy with the case where the soft phase is dispersed, and the interior of the square  $\square$  plays the role of the inclusion  $B$ .

In the proof of the compactness lemma, we must use the following extension result. Let  $S^h$  be the frame of width  $h$  shown in Figure 6. Then any function  $u \in H^1(S^h)$  can be extended up to a function  $\tilde{u} \in H^1(\square)$  satisfying the estimate

$$\int_{\square} |\nabla \tilde{u}|^2 dx \leq \frac{C}{h} \int_{S^h} |\nabla u|^2 dx, \quad \int_{\square} |\nabla \tilde{u}|^2 dx \leq \frac{C}{h} \int_{S^h} (|u|^2 + |\nabla u|^2) dx,$$

where the constant  $C$  is independent of  $u$ .

The same results are valid for the three-dimensional model where the thin periodic net is replaced by a thin periodic box structure. The operator  $A_0$  (by which the spectrum of  $A$  and gaps in it are constructed) is the Laplace–Dirichlet operator in the unit cube.

Other net double-porosity models were discussed in [16, 17].

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