## THE FREDHOLM METHOD IN POTENTIAL THEORY(1)

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**Introduction.** Let G be an open set with a compact boundary B in  $R^m$ , the Euclidean m-space. If h is a harmonic function in G such that

$$\int_{P} |\operatorname{grad} h(x)| \ dx < \infty$$

for every bounded open set  $P \subseteq G$ , one may form the distribution Nh over the space D of all infinitely differentiable functions  $\psi$  with compact support in  $R^m$  defining

$$\langle \psi, Nh \rangle = \int_G \operatorname{grad} \psi(x) \cdot \operatorname{grad} h(x) dx.$$

This distribution will be termed the generalized normal derivative of h (compare [CC], [M], [Y]). It is easily seen that Nh has support in B. In general, Nh need not be a measure in the sense usual in distribution theory [S]. §1 of the present paper deals with generalized normal derivatives of Newtonian potentials. We denote by  $C^*(B)$  the Banach space of all finite signed Borel measures with support in B; total variation is taken as a norm in  $C^*(B)$ . With every  $\mu \in C^*(B)$  we associate the corresponding Newtonian potential

$$U\mu(x) = \int_{\mathbb{R}^m} p(x-y) \ d\mu(y),$$

where  $p(z)=|z|^{2-m}/m-2$  or  $p(z)=\log{(1/|z|)}$  according as m>2 or m=2, and we ask what necessary and sufficient condition is to be imposed on G in order that  $NU\mu$  be a measure for every  $\mu \in C^*(B)$ . For this purpose it is useful to introduce the concept of a hit of a half-line  $\{y+t\theta:t>0\}$  on G (cf. Definition 1.5). If  $n(\theta, y)$  denotes the number of such hits, then  $n(\theta, y)$  is a Baire function of the variable  $\theta$  on  $\Gamma=R^m\cap\{\theta:|\theta|=1\}$  and the above mentioned condition reads as follows:

(2) 
$$\sup_{y\in B}\int_{\Gamma}n(\theta,y)\,dH_{m-1}(\theta)<\infty,$$

where  $H_{m-1}$  stands for the (m-1)-dimensional Hausdorff measure.

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If G fulfills (2), then the operator

$$NU: \mu \rightarrow NU\mu$$

is bounded on  $C^*(B)$  and has the form  $\frac{1}{2}AI + \overline{W}^*$ , where  $A = H_{m-1}(\Gamma)$ , I is the identity operator and  $\overline{W}^*$  is adjoint to an operator  $\overline{W}$  acting on the space C(B) of all continuous functions on B. Some properties of  $\overline{W}$ , which is connected with the classical double-layer potential, are investigated in §§2-3. In particular, in §3 we show that, in case B has no isolated points, the Fredholm radius of  $\overline{W}$  is the reciprocal of the quantity

$$V_0 = \lim_{r \downarrow 0} \sup_{y \in B} \left[ A | d(y) - \frac{1}{2} | + \int_{\Gamma} n_r(\theta, y) dH_{m-1}(\theta) \right],$$

where d(y) denotes the *m*-density of G at y and  $n_r(\theta, y)$  is the number of hits of  $\{y+t\theta: 0 < t < r\}$  on G. Relations between  $V_0$  and the geometric structure of B are also investigated in §3. In case  $V_0$  is sufficiently small, these results apply to the Neumann problem where the boundary condition is given by an arbitrary measure  $v \in C^*(B)$ , as treated in §4. By duality based on the Fredholm theory one obtains, as a by-product, representation of solutions of the Dirichlet problem by means of double-layer potentials.

Methods and concepts employed here are those of geometric measure theory; they have their origin in investigations connected with the Gauss-Green theorem, sets with finite perimeter and functions whose partial derivatives are measures [DG], [F], [FL], [FY], [KR], [MA], [P].

#### 1. Normal derivatives of potentials.

1.1. Terminology and notation. The symbols  $R^m$ ,  $C^*(B)$ , p,  $U\mu$ , D will have the meaning described in the introduction. For  $M \subseteq R^m$  we shall denote by cl M, int M, fr M and diam M the closure, interior, boundary and diameter of M, respectively.  $H_k$  will stand for the k-dimensional Hausdorff measure;  $H_m$  coincides with the Lebesgue measure in  $R^m$ . We put  $\Omega_r(y) = R^m \cap \{z : |z-y| < r\}$ ,  $\Omega = \Omega_1(0)$ ,  $\Gamma_r(y) = \text{fr } \Omega_r(y)$ ,  $\Gamma = \Gamma_1(0)$ ,  $A = H_{m-1}(\Gamma)$ . Throughout this paragraph  $G \subseteq R^m(m \ge 2)$  will be a fixed set with a compact boundary B. We shall tacitly assume that G is open. On several places, however, it will be useful to allow G to be a Borel set; this will be always pointed out explicitly.

The generalized normal derivative of a harmonic function h (satisfying (1) for every bounded open  $P \subseteq G$ ) is defined as in the introduction; we shall write  $N^G h$  instead of Nh if it is necessary to specify G. The reason for the terminology is obvious: if G has a smooth boundary with exterior normal n and h is smooth up to B, then

$$\langle \psi, Nh \rangle = \int_{R} \psi(\partial h/\partial n) dH_{m-1}.$$

If spt  $\psi$  (= the support of  $\psi$ ) does not meet B, then there is an open set Q with a smooth boundary such that spt  $\psi \cap G \subseteq Q$ , cl  $Q \subseteq G$ , so that

$$\langle \psi, N^G h \rangle = \langle \psi, N^Q h \rangle = 0.$$

In particular, if  $N^{G}h$  is a (Borel) measure  $\nu$ , which means that

$$\langle \psi, N^G h \rangle = \int_{\mathbb{R}^m} \psi \, d\nu$$

for every  $\psi \in D$ , then  $\nu \in C^*(B)$ .

Variation of a (signed) measure  $\mu$  on a Borel set M will be denoted by  $|\mu|(M)$ ; for  $\mu \in C^*(B)$ ,  $|\mu|(B) = ||\mu||$  is the norm of  $\mu$ .

Simple calculation shows that, for  $\mu \in C^*(B)$  and  $x \in G$ ,

$$|\operatorname{grad} U\mu(x)| \leq \int_{\mathbb{R}} |x-y|^{1-m} d|\mu|(y),$$

whence we obtain for any bounded Borel  $P \subseteq G$ 

(1.1) 
$$\int_{P} |\operatorname{grad} U\mu(x)| \ dx \leq A \operatorname{diam} (B \cup P) \|\mu\|.$$

We see that  $NU\mu$  is meaningful for every  $\mu \in C^*(B)$ . Our main objective in §1 is to answer the following question:

- 1.2. What necessary and sufficient restrictions are to be imposed on G in order that  $NU\mu$  be a measure for every  $\mu \in C^*(B)$ ?
- 1.3. REMARK. Let us agree to denote by  $\delta_y$  the Dirac measure concentrated at  $y \in R^m$ . We have for any  $\psi \in D$  and any  $y \in B$

$$\langle \psi, NU\delta_y \rangle = \int_G \operatorname{grad} \psi(x) \cdot \frac{y-x}{|y-x|^m} dx.$$

Direct calculation shows that, in case  $Q = R^m - \{y\}$ ,  $N^Q U \delta_y = A \delta_y$ . Let us also observe that, for  $\psi \in D$  and  $\mu \in C^*(B)$ ,

(1.2) 
$$\langle \psi, NU\mu \rangle = \int_{\mathbb{R}} \langle \psi, NU\delta_y \rangle d\mu(y).$$

Indeed, if  $P = G \cap \operatorname{spt} \psi$  and  $K = \sup |\operatorname{grad} \psi|$ , then

$$\iint\limits_{\Omega \setminus P} \left| \operatorname{grad} \ \psi(x) \cdot \frac{y - x}{|y - x|^m} \right| dx \ d|\mu|(y) \le KA \ \operatorname{diam} \ (P \cup B) \|\mu\|,$$

so that Fubini's theorem applies to

(1.3) 
$$\iint_{G \times B} \operatorname{grad} \psi(x) \cdot (y-x) |y-x|^{-m} dx d\mu(y);$$

it remains to notice that the two repeated integrals derived from (1.3) occur in (1.2).

Before investigating the problem 1.2 we shall answer the following simpler question:

- 1.4. Fix  $y \in B$ . What must be the shape of G in order that  $NU\delta_y$  be a measure? Let us first introduct a concept which will be useful later.
- 1.5. DEFINITION. If  $M \subseteq R^k$  is a Borel set and  $S \subseteq R^k$  is an open segment or half-line then  $z \in S$  will be termed a hit of S on M provided both  $S \cap M \cap \Omega_r(z)$  and  $(S-M) \cap \Omega_r(z)$  have a positive linear measure for every r > 0.

An answer to 1.4 is included in the following proposition, which will be needed later.

1.6. Proposition. Suppose that G is a Borel set. Fix  $y \in R^m$ , r > 0 and put

$$E_r(y) = D \cap \{\psi : \operatorname{spt} \psi \subset \Omega_r(y), |\psi| \leq 1\},$$
  
$$D_r(y) = E_r(y) \cap \{\psi : y \notin \operatorname{spt} \psi\}.$$

If  $n_r(\theta, y)$  denotes the number (possibly 0 or  $\infty$ ) of all hits of  $\{y + \rho\theta : 0 < \rho < r\}$  on G, then  $n_r(\theta, y)$  is a Baire function of the variable  $\theta$  on  $\Gamma$ , the integral

$$v_r(y) = \int_{\Gamma} n_r(\theta, y) dH_{m-1}(\theta)$$

is equal to

$$\sup \left\{ \int_{G} \operatorname{grad} \psi(x) \cdot \frac{y-x}{|y-x|^{m}} dx : \psi \in D_{r}(y) \right\}$$

and

$$\sup \left\{ \int_G \operatorname{grad} \psi(x) \cdot \frac{y - x}{|y - x|^m} dx : \psi \in E_r(y) \right\} \leq A + v_r(y).$$

If  $y \in B$  and G is open, then  $NU\delta_y$  is a measure if and only if  $v_\infty(y) < \infty$ .

1.7. REMARK. If it is necessary to specify the set G, we write  $n_r^G(\theta, y)$  and  $v_r^G(y)$  instead of  $n_r(\theta, y)$  and  $v_r(y)$ .

We postpone the proof of Proposition 1.6 to 1.11. First we establish two lemmas.

1.8. Notation. If f is a function in  $R^1$  we denote by var [f; (a, b)] its variation on  $(a, b) = R^1 \cap \{t : a < t < b\}$ . If f is known to be summable over every compact subset in (a, b), we shall use var ess [f; (a, b)] to denote  $\sup_{\psi} \int_a^b \psi'(t) f(t) dt$ ,  $\psi$  ranging over all infinitely differentiable functions with compact spt  $\psi \subset (a, b)$  such that  $|\psi| \le 1$ .

REMARK. It follows easily from the Riesz representation theorem and elementary distribution theory that var ess  $[f; (a, b)] < \infty$  implies the existence of a function g in (a, b) such that g = f a.e. in (a, b) and var [g; (a, b)] = var ess [f; (a, b)].

Clearly, var [f; (a, b)] = var ess [f; (a, b)] whenever f is continuous in (a, b).

1.9. LEMMA. If  $c_M$  is the characteristic function of a Borel set  $M \subseteq \mathbb{R}^1$ , then var ess  $[c_M; (a, b)]$  equals the number of hits of (a, b) on M.

**Proof.** Let q stand for the number of all hits of (a, b) on M. If  $q < \infty$  and  $a_1 < \cdots < a_q$  are all the hits, then no  $(a_j, a_{j+1})$  can meet both M and (a, b) - M in a set of positive linear measure. It follows that either M or (a, b) - M is equivalent with  $\bigcup_k (a_{2k-1}, a_{2k})$ , where  $1 \le k$ ,  $2k \le q$ . Consequently, var ess  $[c_M; (a, b)] = q$ . Conversely, if var ess  $[c_M; (a, b)] < \infty$ , then there is a g with var  $[g; (a, b)] < \infty$  such that  $g = c_M$  a.e. in (a, b).

Clearly, this implies  $q < \infty$ .

1.10. LEMMA. Let f be a bounded Baire function in  $R^m$ ,  $y \in R^m$ ,  $0 \le a < b \le \infty$ . For  $\theta \in \Gamma$  put

$$(1.4) f_{\theta}(t) = f(y+t\theta), t \in R^1.$$

Then var ess  $[f_{\theta};(a,b)]$  is a Baire function of the variable  $\theta$  on  $\Gamma$  and the integral

$$\int_{\mathbb{R}} \text{var ess } [f_{\theta}; (a, b)] dH_{m-1}(\theta)$$

equals

$$v(a, b, f) = \sup_{\psi} \int_{\mathbb{R}^m} f(x) \operatorname{grad} \psi(x) \cdot \frac{y - x}{|y - x|^m} dx,$$

 $\psi$  ranging over all functions in D with

(1.5) 
$$\operatorname{spt} \psi \subset R^m \cap \{x : a < |x - y| < b\}, \quad |\psi| \le 1.$$

**Proof.** We may assume y=0,  $b<\infty$ . Using the notation from (1.4) we obtain for any  $\psi \in D$  satisfying (1.5)

$$\int_{\mathbb{R}^m} f(x) \operatorname{grad} \psi(x) \cdot \frac{x}{|x|^m} dx = \int_{\Gamma} \left( \int_a^b f_{\theta}(t) \psi_{\theta}'(t) dt \right) dH_{m-1}(\theta),$$

$$\int_a^b f_{\theta}(t) \psi_{\theta}'(t) dt \leq \operatorname{var ess} [f_{\theta}; (a, b)].$$

Assuming that we know already that var ess  $[f_{\theta}; (a, b)]$  is measurable  $(H_{m-1})$  on  $\Gamma$  we get

$$v(a, b, f) \leq \int_{\Gamma} \text{var ess } [f_{\theta}; (a, b)] dH_{m-1}(\theta).$$

It remains to prove that var ess  $[f_{\theta}; (a, b)]$  is a Baire function of  $\theta$  and

(1.6) 
$$\int_{\Gamma} \operatorname{var ess} \left[ f_{\theta}; (a, b) \right] dH_{m-1}(\theta) \leq v(a, b, f).$$

To show this we first assume, in addition, that

(I).  $f_{\theta}$  has a continuous derivative on (a, b) for every  $\theta \in \Gamma$  and

$$\sup \{|f'_{\theta}(t)| : \theta \in \Gamma, c < t < d\} = K(c, d) < \infty$$

whenever a < c < d < b.

For every positive integer N we subdivide (a, b) by means of points

$$a_k = a_k^N = a + k2^{-N}(b-a), \qquad 1 \le k < 2^N.$$

Consider  $k < 2^N - 2$ . Since sign  $[f_{\theta}(a_{k+1}) - f_{\theta}(a_k)]$  is a Baire function of  $\theta$ , there are functions  $\phi_{ks} \in D$  such that  $|\phi_{ks}| \le 1$  and

$$\lim_{s\to\infty}\phi_{ks}(\theta)=\mathrm{sign}\left[f_{\theta}(a_{k+1})-f_{\theta}(a_k)\right]\qquad\text{a.e. }(H_{m-1})$$

on  $\Gamma$ . Further express the characteristic function of  $(a_k, a_{k+1})$  as  $\lim_{s\to\infty} \rho_{ks}$ , where  $\rho_{ks}$  are infinitely differentiable functions in  $R^1$  with

spt 
$$\rho_{ks} \subset (a_k, a_{k+1}), |\rho_{ks}| \leq 1$$
,

and define

$$\psi_s(t\theta) = -\sum_{k=1}^{2^N-2} \phi_{ks}(\theta) \rho_{ks}(t), \qquad t \geq 0, \ \theta \in \Gamma.$$

Then

$$\psi_s \in D$$
,  $|\psi_s| \leq 1$ , spt  $\psi_s \subset R^m \cap \{x : a < |x| < b\}$ .

Consequently,

$$v(a,b,f) \geq \int_{\Gamma} \left[ \int_{a}^{b} f_{\theta}(t) \psi'_{s\theta}(t) dt \right] dH_{m-1}(\theta).$$

The sequence of integrals

$$\int_{a}^{b} f_{\theta}(t) \psi_{s\theta}'(t) dt = \sum_{k=1}^{2^{N}-2} \phi_{ks}(\theta) \int_{a_{k}}^{a_{k+1}} \rho_{ks}(t) f_{\theta}'(t) dt$$

is dominated by  $(b-a)K(a_1, a_{2^{N}-1})$  and converges, as  $s \to \infty$ , to

$$\sigma_N(\theta) = \sum_{k=1}^{2^N-2} |f_{\theta}(a_{k+1}) - f_{\theta}(a_k)|$$

a.e.  $(H_{m-1})$  on  $\Gamma$ . Hence we conclude

$$v(a, b, f) \geq \int_{\Gamma} \sigma_{N}(\theta) dH_{m-1}(\theta).$$

Noting that  $\sigma_N(\theta) \uparrow \text{ var } [f_\theta; (a, b)]$  as  $N \to \infty$  we see that var  $[f_\theta; (a, b)]$  is a Baire function of  $\theta$  and (1.6) holds in this special case.

Let us now drop the additional assumptions (I) on f. For every positive integer N we fix a symmetric infinitely differentiable function  $\omega_N$  in  $R^1$  with

spt 
$$\omega_N \subset (-1/N, 1/N), \int_{\mathbb{R}^1} \omega_N(t) dt = 1$$

and define  $f_N$  so that  $f_{N\theta} = f_{\theta} * \omega_N$  (= the convolution of  $f_{\theta}$  and  $\omega_N$ ) on the positive real axis,  $f_N(0) = 0$ . Let  $a^N = a + 1/N$ ,  $b^N = b - 1/N$ , 2/N < b - a. It follows from the first part of the proof that

(1.7) 
$$\int_{\Gamma} \operatorname{var} \left[ f_{N\theta}; (a^{N}, b^{N}) \right] dH_{m-1}(\theta) = v(a^{N}, b^{N}, f_{N}).$$

If  $\psi_N$  is obtained from  $\psi$  in the same way as  $f_N$  from f, then

$$\psi \in D$$
,  $|\psi| \leq 1$ , spt  $\psi \subset \mathbb{R}^m \cap \{x : a^N < |x| < b^N\}$ 

imply

$$\psi_N \in D$$
,  $|\psi_N| \leq 1$ , spt  $\psi_N \subset R^m \cap \{x : a < |x| < b\}$ 

and

$$\int_{a^{N}}^{b^{N}} \psi'_{\theta}(t) f_{N\theta}(t) dt = \int_{a}^{b} \psi'_{N\theta}(t) f_{\theta}(t) dt.$$

Consequently,

(1.8) 
$$v(a^N, b^N, f_N) \le v(a, b, f).$$

The same argument shows that

(1.9) 
$$\operatorname{var ess} [f_{N\theta}; (a^N, b^N)] \leq \operatorname{var ess} [f_{\theta}; (a, b)].$$

It is easy to see that

$$\lim_{N\to\infty}\inf \text{ var ess } [f_{N\theta};(a^N,b^N)] \geq \text{ var ess } [f_{\theta};(a,b)],$$

which together with (1.9) yields

(1.10) 
$$\lim_{N\to\infty} \operatorname{var} \operatorname{ess} [f_{N\theta}; (a^N, b^N)] = \operatorname{var} \operatorname{ess} [f_{\theta}; (a, b)].$$

In particular, var ess  $[f_{\theta}; (a, b)]$  is a Baire function of  $\theta$ . (1.7), (1.8), and (1.10) imply (1.6).

REMARK. The above lemma could also be derived from general theorems on functions, whose partial derivatives are measures; cf. [FL], [KR], [P] on the subject.

Now it is easy to present the following.

1.11. **Proof of Proposition 1.6.** Let f be the characteristic function of G. By 1.9 and 1.10

var ess 
$$[f_{\theta}; (0, r)] = n_r(\theta, y),$$
  
$$v_r(y) = v(0, r, f).$$

If  $n_r(\theta, y) < \infty$ , then  $G \cap \{y + t\theta : 0 < t < r\}$  is equivalent  $(H_1)$  with a finite union

of disjoint segments, whose end points are hits of  $\{y+t\theta: 0 < t < r\}$  on G and, possibly, y and  $y+r\theta$ . Hence we conclude for  $\psi \in E_r(y)$ 

$$\left| \int_0^\infty f_{\theta}(t) \psi_{\theta}'(t) \ dt \right| \le 1 + n_r(\theta, y), \qquad \theta \in \Gamma,$$

$$\int_G \operatorname{grad} \psi(x) \cdot (y - x) |y - x|^{-m} \ dx \le \int_\Gamma \left[ 1 + n_r(\theta, y) \right] dH_{m-1}(\theta) = A + v_r(y).$$

It remains to note that, in case  $y \in B$  and G is open,  $NU\delta_y$  is a measure if and only if

$$\sup \{\langle \psi, NU\delta_{\psi} \rangle : \psi \in D, |\psi| \leq 1\} < \infty.$$

1.12. REMARK. Let us observe that, in case  $y \in B$  and  $NU\delta_y \in C^*(B)$ ,

$$(1.11) v_{\infty}(y) \leq ||NU\delta_y|| \leq A + v_{\infty}(y).$$

Now we are in position to answer the question raised in 1.2.

1.13. THEOREM.  $NU\mu$  is a measure for every  $\mu \in C^*(B)$  if and only if

$$(1.12) V = \sup_{y \in P} v_{\infty}(y) < \infty.$$

If this is the case, then

$$NU: \mu \rightarrow NU\mu$$

is a bounded linear operator on  $C^*(B)$ ,

$$||NU|| \leq A + V$$

and (1.2) holds for every bounded Baire function  $\psi$  on B. In particular,

$$NU\mu(M) = \int_B NU\delta_y(M) d\mu(y)$$

for  $\mu \in C^*(B)$  and every Borel set  $M \subseteq B$ .

**Proof.** With every  $\psi \in D$  we associate a linear functional  $L_{\psi}$  over  $C^*(B)$  defined by

$$\langle \mu, L_{\psi} \rangle = \langle \psi, NU\mu \rangle, \qquad \mu \in C^*(B).$$

Denoting

$$P_{\psi} = G \cap \operatorname{spt} \psi, \quad s_{\psi} = \sup |\operatorname{grad} \psi|,$$

we obtain from (1.1)

$$|\langle \mu, L_{\mu} \rangle| \leq s_{\mu} A \operatorname{diam} (B \cup P_{\mu}) \|\mu\|$$

which shows that every  $L_{\psi}$  is bounded on  $C^*(B)$ . Let  $E = D \cap \{\psi : |\psi| \le 1\}$ . Then  $NU\mu$  is a measure if and only if

$$\sup_{\psi\in E}\langle\psi,NU\mu\rangle<\infty.$$

In particular, if  $NU\mu$  is a measure for every  $\mu \in C^*(B)$ , then the class of functionals  $\{L_{\psi}\}_{\psi \in E}$  must be pointwise bounded on  $C^*(B)$  and, by the uniform boundedness principle,

$$\sup_{\psi\in K}\|L_{\psi}\|=K<\infty.$$

Employing (1.11) we get for every  $y \in B$ 

$$v_{\infty}(y) \leq \sup_{\psi \in \mathbb{R}} \langle \psi, NU\delta_{\psi} \rangle \leq K.$$

Conversely, if (1.12) holds, then (1.2) together with (1.11) imply

$$\sup_{\psi \in \mathbb{R}} |\langle \psi, NU\mu \rangle| \leq (A+V) \|\mu\|$$

for every  $\mu \in C^*(B)$ . It is also easily seen that in this case (1.2) extends to any bounded Baire function  $\psi$ .

#### 2. Double layer potentials.

2.1. Notation. Throughout this paragraph  $C \subseteq R^m$  will denote a Borel set with a compact boundary B. Given  $z \in R^m$  we put

$$D(z) = D \cap \{\psi : z \notin \operatorname{spt} \psi\}$$

and define

(2.1) 
$$W_{\psi}(z) = \int_{C} \operatorname{grad} \psi(x) \cdot \frac{x-z}{|x-z|^{m}} dx, \quad \psi \in D(z).$$

If it is necessary to specify C we write  $W_{\psi}^{C}$  instead of  $W_{\psi}$ . In case C has a smooth boundary with exterior normal n the integral (2.1) reduces to

$$\int_{\mathbb{R}} \psi(y) \frac{(y-z) \cdot n(y)}{|y-z|^m} dH_{m-1}(y),$$

which is the classical double-layer potential. If  $\psi$  vanishes in some neighborhood of B then there is a  $Q \subseteq R^m$  with a smooth boundary such that

$$\operatorname{spt} \psi \cap C \subset \operatorname{int} Q$$
,  $\operatorname{cl} Q \subset \operatorname{int} C$ ,

whence

$$W_{\psi}(z) = W_{\psi}^{Q}(z) = 0.$$

If  $z \notin B$ , we use this observation to extend  $W_{\psi}(z)$  from D(z) to D defining

$$W_{\downarrow}(z) = W_{\bar{\downarrow}}(z),$$

where  $\bar{\psi}$  is an arbitrary function in D(z) coinciding with given  $\psi \in D$  in some neighborhood of B.  $W_{\psi}(z)$  may thus be considered as a distribution over D with support in B (compare [D, Chapter III, p. 157]).

For fixed  $\psi \in D$ ,  $W_{\psi}(z)$  is a harmonic function of z in  $R^m - B$ . Indeed, if O is an open set with  $B \cap cl\ O = \emptyset$ , then there is a  $\overline{\psi} \in D$  coinciding with  $\psi$  in some neighborhood of B and vanishing on O; clearly,

$$W_{\psi}(z) = W_{\overline{\psi}}(z) = \int_{C-0} \operatorname{grad} \overline{\psi}(x) \cdot \frac{x-z}{|x-z|^m} dx$$

is a harmonic function of z in O.

Our main objective in this paragraph is to find necessary and sufficient geometric conditions on C securing natural extendability of  $W_{\psi}$  from D to broader class of continuous functions and also "nice behaviour" (e.g., boundedness) of  $W_{\psi}$  near B for each continuous  $\psi$ .

2.2. LEMMA. Fix  $z \in \mathbb{R}^m$ . Then

$$(2.2) v_{\infty}^{C}(z) < \infty$$

is a necessary and sufficient condition to secure

$$\lim_{k\to\infty}W_{\psi_k}(z)=W_{\psi}(z)$$

for every sequence of  $\psi_k \in D(z)$  converging uniformly (as  $k \to \infty$ ) to  $\psi \in D(z)$ . If (2.2) holds then there is a  $\nu_z \in C^*(B)$  such that

$$(2.3) W_{\psi}(z) = \int_{\Omega} \psi(y) \, d\nu_z(y), \qquad \psi \in D(z),$$

$$(2.4) v_{z}(\{z\}) = 0,$$

$$||v_z|| = v_{\infty}^C(z).$$

(2.3) together with any of the two conditions (2.4), (2.5) determine  $v_z$  uniquely.

**Proof.** This follows at once from the equality

$$(2.6) v_{\infty}^{C}(z) = \sup \{W_{\psi}(z) : \psi \in D(z), |\psi| \le 1\}$$

established in 1.6.

2.3. Remark. If (2.2) holds we extend  $W \cdot \cdot \cdot (z)$  defining

$$Wf(z) = \int_{R} f(y) \, d\nu_{z}(y)$$

for any bounded Baire function f on B.

In order to present another integral representation for Wf(z) we introduce the following.

2.4. Notation. Fix  $z \in \mathbb{R}^m$  and  $\theta \in \Gamma$ . We put for t > 0

$$s(t; z, \theta) = \sigma (= \pm 1)$$

if there is a  $\delta > 0$  such that

$$z+(t+\sigma\tau)\theta\in R^m-C, \quad z+(t-\sigma\tau)\theta\in C$$

for a.e.  $\tau \in (0, \delta)$ ; otherwise we set  $s(t; z, \theta) = 0$ .

Clearly,  $s(t; z, \theta) \neq 0$  only if  $z + t\theta$  is a hit of  $\{z + \tau\theta : \tau > 0\}$  on C.

2.5. LEMMA. If  $v_{\infty}^{C}(z) < \infty$  then

(2.7) 
$$Wf(z) = \int_{\Gamma} \left\{ \sum_{t>0} f(z+t\theta)s(t;z,\theta) \right\} dH_{m-1}(\theta)$$

for any bounded Baire function f on B.

**Proof.** Let  $v_{\infty}^{c}(z) < \infty$ . If  $f \in D(z)$  then

$$Wf(z) = \int_{C} \operatorname{grad} f(x) \cdot \frac{x - z}{|x - z|^{m}} dx$$
$$= \int_{C} \left\{ \int_{C_{\bullet}} \partial_{\theta} f(z + t\theta) dt \right\} dH_{m-1}(\theta),$$

where

(2.8) 
$$C_{\theta} = \{t : t > 0, z + t\theta \in C\}, \, \partial_{\theta} f = \theta \cdot \operatorname{grad} f.$$

Noting that  $n_{\infty}^{C}(\theta, z) < \infty$  implies

$$\int_{C_t} \partial_{\theta} f(z+t\theta) dt = \sum_{t>0} f(z+t\theta) s(t; z, \theta)$$

we obtain (2.7).

If  $\{f_k\}$  is a pointwise convergent sequence of functions on B such that, for all k,  $|f_k| \le K$  and (2.7) holds with f replaced by  $f_k$ , then

$$\left|\sum_{t>0} f_k(z+t\theta)s(t;z,\theta)\right| \leq Kn_{\infty}^{C}(\theta,z)$$

a.e.  $\{H_{m-1}\}$  on  $\Gamma$  and, by the Lebesgue convergence theorem, (2.7) holds for  $f=\lim_k f_k$  as well.

We conclude that (2.7) is valid for every bounded Baire function f vanishing at z; in view of (2.4), vanishing at z is irrelevant.

2.6. PROPOSITION. Let  $v_{\infty}^{c}(z) < \infty$ . Denote by  $K_{z}$  and  $L_{z}$  the set of all  $\theta \in \Gamma$  for which there is an  $\varepsilon = \varepsilon(\theta) > 0$  such that

$$H_1(\{z+t\theta:0< t<\varepsilon\}\cap C)=0$$

and

$$H_1(\lbrace z+t\theta: 0 < t < \varepsilon\rbrace - C) = 0,$$

respectively. Then  $K_z$ ,  $L_z$  are measurable  $(H_{m-1})$ ,

(2.9) 
$$H_{m-1}(\Gamma - (K_z \cup L_z)) = 0$$

and  $\nu_z(B) = H_{m-1}(L_z)$  or  $\nu_z(B) = -H_{m-1}(K_z)$  according as C is bounded or not. If  $\psi \in D$ , then

(2.10) 
$$\int_{C} \operatorname{grad} \psi(x) \cdot \frac{x-z}{|x-z|^{m}} dx = W_{\psi}(z) - H_{m-1}(L_{z}) \psi(z).$$

If Q is a convex Borel set, then

$$(2.11) |\nu_z(B \cap Q)| \leq A.$$

**Proof.** It is easily seen that

$$\Gamma \cap \{\theta : n_{\infty}^{C}(\theta, z) < \infty\} \subset L_{\tau} \cup K_{\tau}$$

whence (2.9) follows at once.

Fix now a  $\theta \in \Gamma$  with  $n_{\infty}^{C}(\theta, z) < \infty$ . Let

$$(2.12) t_1 < \cdots < t_a$$

be all the points  $t \in (0, \infty)$  with  $s(t; z, \theta) \neq 0$  (cf. 2.4). Clearly,

$$(2.13) s(t_{j+1}; \cdots) = -s(t_j; \cdots), 1 \le j < q$$

and  $s(t_1; \dots) = 1$  or  $s(t_1; \dots) = -1$  according as  $\theta \in L_z$  or  $\theta \in K_z$ . If C is bounded, then  $s(t_q; \dots) = 1$ , while  $s(t_q; \dots) = -1$  in the opposite case. We conclude that

$$\sum (\theta) = \sum_{t>0} s(t; z, \theta)$$

almost  $(H_{m-1})$  equals the characteristic function of  $L_z$  if C is bounded, while  $-\sum (\theta)$  almost equals the characteristic function of  $K_z$  in the opposite case. Employing (2.7) with  $f \equiv 1$  we get the first part of our proposition.

Let now f be the characteristic function of a convex Borel set Q. Consider again a fixed  $\theta \in \Gamma$ ,  $n_{\infty}^{C}(\theta, z) < \infty$ , and the corresponding sequence (2.12). If  $t_i$  and  $t_k$  are the first and the last members of (2.12) with  $z + t_j \theta \in Q$ , respectively, then (2.13) implies

$$\left|\sum_{j=1}^{q} f(z+t_j\theta)s(t_j;z,\theta)\right| = \left|\sum_{j=1}^{k} s(t_j;z,\theta)\right| \leq 1,$$

whence (2.11) follows by 2.5. If  $\psi \in D$  then we have with the notation from (2.8)

$$\int_{C_{\alpha}} \partial_{\theta} \psi(z+t\theta) dt = \sum_{t>0} \psi(z+t\theta) s(t; z, \theta)$$

for  $\theta \in K_z \cap \{\theta : n_{\infty}^C(\theta, z) < \infty\}$ , while

$$\int_{C} \partial_{\theta} \psi(z+t\theta) dt = \sum_{t>0} \psi(z+t\theta) s(t; z, \theta) - \psi(z)$$

for  $\theta \in L_z \cap \{\theta : n_\infty^c(\theta, z) < \infty\}$ . Hence

$$\int_{C} \operatorname{grad} \psi(x) \cdot \frac{x-z}{|x-z|^{m}} dx = \int_{\Gamma} \left( \int_{C_{\theta}} \partial_{\theta} \psi(z+t\theta) dt \right) dH_{m-1}(\theta)$$
$$= W \psi(z) - H_{m-1}(L_{z}) \psi(z).$$

2.7. Lemma. Let  $v_{\infty}^{c}(z) < \infty$  and define  $L_{z}$  as in 2.6. If  $M \subseteq \Gamma$  is measurable  $(H_{m-1})$ ,  $H_{m-1}(M) > 0$  and

$$\Lambda_M = \{z + t\theta : \theta \in M, t > 0\},\$$

then

(2.14) 
$$\lim_{r\to 0+} \frac{H_m(\Omega_r(z)\cap C\cap \Lambda_M)}{H_m(\Omega_r(z)\cap \Lambda_M)} = \frac{H_{m-1}(L_z\cap M)}{H_{m-1}(M)}.$$

In particular, C has an m-dimensional density

$$d_C(z) = H_{m-1}(L_z)/A$$

at z.

**Proof.** Let  $e(\theta)$  have the meaning described in the definition of  $K_z$ ,  $L_z$  in 2.6 and put

$$K^{r} = M \cap \{\theta : \theta \in K_{z}, \epsilon(\theta) > r\},$$
  
$$L^{r} = M \cap \{\theta : \theta \in L_{z}, \epsilon(\theta) > r\}.$$

We have

$$H_m(\Omega_r(z) \cap C \cap \Lambda_M) \ge m^{-1}r^m \text{ inn } H_{m-1}(L^r),$$
  
$$H_m((\Omega_r(z) - C) \cap \Lambda_M) \ge m^{-1}r^m \text{ inn } H_{m-1}(K^r),$$

where inn  $H_{m-1}$  stands for the inner (m-1)-dimensional Hausdorff measure. Denoting

$$d_r = \frac{H_m(\Omega_r(z) \cap C \cap \Lambda_M)}{H_m(\Omega_r(z) \cap \Lambda_M)}$$

and noting that

$$K^r \uparrow (K_z \cap M), \quad L^r \uparrow (L_z \cap M)$$

as  $r \downarrow 0$ , we obtain

$$\liminf_{r\to 0+} d_r \geq H_{m-1}(L_z\cap M)/H_{m-1}(M),$$

$$\lim_{r\to 0+}\inf(1-d_r) \geq H_{m-1}(K_z \cap M)/H_{m-1}(M),$$

whence (2.14) follows by (2.9).

2.8. Notation. P(C) will denote the perimeter of C defined by

$$P(C) = \sup_{w} \int_{C} \operatorname{div} w(x) \, dx,$$

where  $w = [w_1, ..., w_m]$  ranges over all vector-valued functions with m components  $w_i \in D$  satisfying

$$\left(\sum_{j=1}^m w_j^2\right)^{1/2} = |w| \le 1.$$

(Further information on sets with finite perimeter may be found in [DG], [F3], [FL], [MA].)

For  $M \subseteq R^m$  and  $z \in R^m$  we let

$$\operatorname{dist}(z, M) = \inf\{|z - y| : y \in M\}.$$

2.9. Lemma.  $v_{\infty}^{C}(z)$  is a lower semicontinuous function of z on  $R^{m}$  satisfying the inequality

$$v_{\infty}^{C}(z) \leq P(C)(\operatorname{dist}(z, B))^{1-m}, \quad z \notin B.$$

**Proof.** If  $K < v_{\infty}^{C}(z)$ , then there is a  $\psi \in D(z)$  such that  $|\psi| \le 1$  and  $W_{\psi}(z) > K$  (see (2.6)). Hence

$$\liminf_{y\to z} v_{\infty}^{\mathcal{C}}(y) \ge \lim_{y\to z} W\psi(y) = W\psi(z) > K.$$

Suppose now that  $z \notin B$ , fix an arbitrary  $\psi \in D(z)$  with  $|\psi| \le 1$  and a positive  $\rho < \text{dist } (z, B)$ . Then there is a  $\psi \in D$ ,  $|\psi| \le 1$ , which coincides with  $\psi$  in some neighborhood of B and vanishes on  $\Omega_{\rho}(z)$ . Let us define  $w(z) = O \in \mathbb{R}^m$ ,

$$w(x) = \bar{\psi}(x) \frac{x-z}{|x-z|^m}, \qquad x \neq z,$$

and observe that  $|w| \leq \rho^{1-m}$ ,

grad 
$$\bar{\psi}(x) \cdot \frac{x-z}{|x-z|^m} = \text{div } w(x).$$

Consequently,

$$W\psi(z) = W\bar{\psi}(z) = \int_C \operatorname{div} w(x) \, dx \le \rho^{1-m} P(C).$$

REMARK. We see that  $v_{\infty}^{C}(z)$  is finite on  $R^{m}-B$  provided  $P(C)<\infty$ . The converse is also true as it follows from the following

2.10. Proposition. If

$$\sum_{i=1}^{m+1} v_{\infty}^{C}(z_{i}) < \infty$$

for an (m+1)-tuple of points  $z_1, \ldots, z_{m+1}$  in general position (i.e., not situated on a single hyperplane), then

$$(2.15) P(C) < \infty.$$

**Proof.** To prove (2.15) it is sufficient to show that

$$\sup \left\{ \int_C \partial_\theta \psi(x) \ dx : \psi \in D, |\psi| \le 1 \right\} < \infty$$

for every  $\theta \in \Gamma$ . Fix  $\theta \in \Gamma$ . Let  $\Pi_j$  denote the hyperplane determined by  $\{z_k : k \neq j\}$ . Since

$$\bigcup_{j=1}^{m+1} (R^m - \Pi_j) = R^m,$$

there are  $\alpha_j \in D$  such that

$$\Pi_i \cap \operatorname{spt} \alpha_i = \emptyset$$

and

$$\alpha = \sum_{j=1}^{m+1} \alpha_j = 1$$

in some neighborhood of B.

Noting that

$$\int_C \alpha(x) \partial_\theta \psi(x) \ dx = \int_C \partial_\theta \psi(x) \ dx$$

we see that it is sufficient to prove that

$$\sup \left\{ \int_{C} \alpha_{j}(x) \partial_{\theta} \psi(x) \ dx : \psi \in D, \ |\psi| \leq 1 \right\} < \infty$$

for  $j=1,\ldots,m+1$ . Consider, for instance, j=1. If  $x \in \text{spt } \alpha_1$ , then  $x-z_2,\ldots,x-z_{m+1}$  are linearly independent. Consequently,

$$\theta = \sum_{k=0}^{m+1} a_k(x) \frac{x - z_k}{|x - z_k|^m},$$

where  $a_k$  are infinitely differentiable in some neighborhood of spt  $\alpha_1$ . Extending  $a_k$  arbitrarily to  $R^m$  we get

$$\int_C \alpha_1(x) \partial_\theta \psi(x) \ dx = \sum_{k=2}^{m+1} \int_C \alpha_1(x) a_k(x) \operatorname{grad} \psi(x) \cdot \frac{x - z_k}{|x - z_k|^m} \ dx.$$

Fix  $k \in \langle 2, m+1 \rangle$  and define  $F(x) = \alpha_1(x)a_k(x)$ . Then  $F \in D(z_k)$  and denoting  $K = \max |F|$  we obtain for any  $\psi \in D$  with  $|\psi| \le 1$ 

$$\int_C F(x) \operatorname{grad} \psi(x) \cdot \frac{x - z_k}{|x - z_k|^m} dx = I_1 + I_2,$$

where

$$I_{1} = \int_{C} \operatorname{grad} (F(x)\psi(x)) \cdot \frac{x - z_{k}}{|x - z_{k}|^{m}} dx \leq K v_{\infty}^{C}(z_{k}),$$

$$I_{2} = -\int_{C} \psi(x) \operatorname{grad} F(x) \cdot \frac{x - z_{k}}{|x - z_{k}|^{m}} dx$$

$$\leq \int_{C} |\operatorname{grad} F(x)| \cdot |x - z_{k}|^{1 - m} dx < \infty. (2)$$

2.11. REMARK. It follows from 2.2, 2.9, and 2.10 that (2.12) is a necessary and sufficient condition to secure continuous dependence (with respect to uniform convergence) of  $W\psi(z)$  on  $\psi$  for every  $z \notin B$ . For this reason we agree to impose (2.15) on C throughout the rest of the present paragraph.

Let us recall that  $\theta \in \Gamma$  is called the exterior normal of C at y in the sense of Federer provided the symmetric difference of C and the half-space

$$R^m \cap \{x : (x-y) \cdot \theta < 0\}$$

has m-dimensional density 0 at y (cf. [F1]).

In what follows the term exterior normal is always to be interpreted in this sense. We put  $n^{C}(y) = n(y) = \theta$  if  $\theta$  is the exterior normal of C at y; otherwise n(y) denotes the zero vector. The set of all y with  $n(y) \neq 0$  is called the reduced boundary of C and will be denoted by  $\hat{B}$ . It is known from [DG2] and [F3] that

$$H_{m-1}(\hat{B}) < \infty$$

and

$$\int_C \operatorname{div} w(x) \, dx = \int_{\mathbb{R}} w(y) \cdot n(y) \, dH_{m-1}(y)$$

for every vector-valued function  $w = [w_1, \ldots, w_m]$  with components  $w_i \in D$ .

2.12. LEMMA. For every  $z \in \mathbb{R}^m$ 

(2.16) 
$$v_{\infty}^{C}(z) = \int_{B} \frac{|n(y) \cdot (y-z)|}{|y-z|^{m}} dH_{m-1}(y).$$

If  $v_{\infty}^{c}(z) < \infty$  and  $M \subseteq B$  is a Borel set, then

$$\nu_{z}(M) = \int_{M} \frac{n(y) \cdot (y-z)}{|y-z|^{m}} dH_{m-1}(y).$$

**Proof.** Fix  $z \in \mathbb{R}^m$ . Let  $\psi \in D(z)$  and put  $w(z) = O \in \mathbb{R}^m$ ,

$$w(x) = \psi(x) \frac{x-z}{|x-z|^m}, \qquad x \neq z.$$

<sup>(2)</sup> The author is indebted to Herbert Federer for simplification of this proof.

Then

$$W_{\psi}(z) = \int_{C} \operatorname{div} w(x) \, dx = \int_{B} \psi(y) \, \frac{n(y) \cdot (y-z)}{|y-z|^{m}} \, dH_{m-1}(y)$$

and (2.16) follows from (2.6). Let now  $v_{\infty}^{c}(z) < \infty$ . As we have just seen,

$$\int_{B} f \, d\nu_{z} = \int_{B} f(y) \, \frac{n(y) \cdot (y-z)}{|y-z|^{m}} \, dH_{m-1}(y)$$

provided  $f \in D(z)$ ; it is easily seen that this formula extends to any bounded Baire function f.

The following result will be useful below:

## 2.13. THEOREM. Let

$$V^C = \sup \{v_\infty^C(y) : y \in B\}.$$

Then  $v_{\infty}^{C}(z) \leq A + V^{C}$  for every  $z \in \mathbb{R}^{m}$ .

**Proof.** We may assume  $V^c < \infty$ . Fix  $z \in R^m - B$  and let d be an arbitrary number less than  $v_{\infty}^c(z)$ . Then there exist mutually disjoint closed parallelepipeds  $K_1, \ldots, K_q$  such that

$$\sum_{j=1}^{q} |\nu_z(B \cap K_j)| > d.$$

Put  $\sigma_j = \text{sign } \nu_z(B \cap K_j)$  and consider the function

$$h(x) = \sum_{i=1}^{q} \sigma_i \nu_x(B \cap K_i),$$

which is harmonic on

$$R^m - \bigcup_{i=1}^q B \cap K_i \supset R^m - B.$$

Fix an arbitrary  $y \in B$ . If  $y \notin \bigcup_{i=1}^{q} K_i$ , then

$$\lim_{x\to y}h(x)=h(y)\leq \|\nu_y\|\leq V^C.$$

In the opposite case we may assume that  $y \in K_1$ , so that

$$\lim_{x\to y}\sum_{j=2}^q \sigma_j \nu_x(B\cap K_j) = \sum_{j=2}^q \sigma_j \nu_y(B\cap K_j) \leq \|\nu_y\| \leq V^C$$

and, by Proposition 2.6,

$$\sup |\nu_x(B \cap K_1)| \leq A.$$

We see that

$$\lim_{x \to y; x \notin B} h(x) \le A + V^C.$$

Noting that  $h(x) \to 0$  as  $|x| \to \infty$  we conclude that  $h \le A + V^C$  on  $R^m - B$ . In particular,  $d < h(z) \le A + V^C$ .

2.14. COROLLARY. If r > 0 and  $z \in \mathbb{R}^m$ , then

$$(2.17) H_{m-1}(\Omega_r(z) \cap \hat{B}) \leq m(m+1)^m (A+V^C) r^{m-1}.$$

**Proof.** To prove (2.17) we may clearly assume that z=0. Noting that  $V^C$  is invariant with respect to dilations of C we observe that it is sufficient to establish (2.17) for r=1 only. Let  $e^i$  denote the point in  $R^m$  all of whose coordinates vanish with the exception of the *i*th one which is equal to m+1. We have then for  $\theta \in \Gamma$  and  $y \in \Omega = \Omega_1(0)$ 

$$\sum_{i=1}^{m} |\theta \cdot (y - e^i)| \ge 1,$$

so that

$$H_{m-1}(\hat{B} \cap \Omega) \leq \sum_{i=1}^{m} \int_{B} |n(y) \cdot (y - e^{i})| dH_{m-1}(y)$$

$$\leq (m+1)^{m} \sum_{i=1}^{m} \int_{B} \frac{|n(y) \cdot (y - e^{i})|}{|y - e^{i}|^{m}} dH_{m-1}(y)$$

$$= (m+1)^{m} \sum_{i=1}^{m} v_{\infty}^{C}(e^{i}) \leq m(m+1)^{m}(A + V^{C}).$$

2.15. THEOREM. Let C(B) denote the Banach space of all continuous functions f on B with the norm  $||f|| = \sup |f|$ . If Wf is bounded on  $R^m - B$  for every  $f \in C(B)$  then

$$(2.18) V^{C} < \infty.$$

**If** 

$$C_i = R^m \cap \{z : d_C(z) = i\}$$
  $(i = 0, 1)$ 

and (2.18) holds, then Wf is bounded and uniformly continuous on each of the sets  $C_0$ ,  $C_1$  and

(2.19) 
$$\lim_{z \to y; z \in C_1} Wf(z) = Wf(y) + A(1 - d_C(y))f(y) \quad \text{for } y \in B \cap cl C_1,$$

(2.20) 
$$\lim_{z \to y: z \in C_0} Wf(z) = Wf(y) - Ad_C(y)f(y) \quad \text{for } y \in B \cap \text{cl } C_0$$

whenever  $f \in C(B)$ .

**Proof.** If  $Wf(z) = \langle f, \nu_z \rangle$  is a bounded function of z on  $Q \subseteq R^m$  for every  $f \in C(B)$  then, by the uniform boundedness principle,  $\|\nu_z\| = v_\infty^C(z)$  is bounded on Q. In view of 2.9,  $v_\infty^C(z)$  must be bounded on cl Q as well. For  $Q = R^m - B$  we get the first part of our theorem. Assume (2.18) and fix  $y \in B$ . If  $f \equiv 1$  on B then (2.19),

(2.20) follow from 2.6, 2.7. It is therefore sufficient to prove (2.19), (2.20) assuming  $f \in C(B)$ , f(y) = 0. For every k we have the decomposition  $f = f_k + g_k$ , where  $f_k \in C(B)$  vanishes in some neighborhood of y in B and  $||g_k|| \le 1/k$ . Then  $Wf_k$  is continuous at y and  $||Wg_k|| \le (A + V^c)/k$ . We see that  $Wf = \lim_{k \to \infty} Wf_k$  is continuous at y. The rest is obvious.

## 3. The Fredholm radius of an operator.

3.1. Notation. As in the introduction, G will stand for a fixed open set with a compact boundary B in  $R^m$ . We put  $C = R^m - G$  and write  $v_r(y) = v_r^G(y)$  (=  $v_r^G(y)$ ),  $V = V^G$  (cf. 1.6, 1.7, (1.12), 2.13). We always assume

$$(3.1) V < \infty.$$

In view of 1.13,

$$(3.2) NU: \mu \to NU\mu$$

is a bounded linear operator on  $C^*(B)$ . By 2.7, G has an m-dimensional density  $d_G(y)$  at any  $y \in R^m$ .

3.2. LEMMA. If f is a bounded Baire function on B then

$$\langle f, NU\delta_{\nu} \rangle = Ad_{G}(y)f(y) + W^{C}f(y), \quad y \in B.$$

**Proof.** It is sufficient to prove (3.3) for  $f \in D$  only. Employing 1.3, 2.6, and 2.7 we obtain

$$\langle f, NU\delta_y \rangle = \int_G \operatorname{grad} f(x) \cdot \frac{y - x}{|y - x|^m} dx$$

$$= Af(y) + \int_C \operatorname{grad} f(x) \cdot \frac{x - y}{|x - y|^m} dx$$

$$= Ad_G(y)f(y) + W^C f(y).$$

3.3. DEFINITION. If  $f \in C(B)$  we define

(3.4) 
$$\overline{W}f(y) = \langle f, NU\delta_y \rangle - \frac{1}{2}Af(y), \quad y \in B$$

3.4. Lemma.  $\overline{W}f \in C(B)$  whenever  $f \in C(B)$ . The operator

$$(3.5) \overline{W}: f \to \overline{W}f$$

is bounded on C(B) and the operator (3.2) is adjoint to  $\frac{1}{2}AI + \overline{W}$ , where I is the identity operator on C(B). If  $f \in C(B)$  and  $C_1$  has the meaning described in 2.15, then

$$\overline{W}f(y) = \lim_{z \to y; z \in C_1} W^c f(z) - \frac{1}{2} A f(y), \qquad y \in B \cap \operatorname{cl} C_1,$$

(3.7) 
$$\overline{W}f(y) = W^{c}f(y) + A(d_{G}(y) - \frac{1}{2})f(y) \\ = \lim_{z \to w} W^{c}f(z) + \frac{1}{2}Af(y), \quad y \in B.$$

**Proof.** (3.7), (3.6) follow from (3.4), (3.3), and (2.19), (2.20). By (3.7),  $\overline{W}f \in C(B)$  for  $f \in C(B)$ . If  $\nu_y$  has the meaning described in 2.2 and

(3.8) 
$$\bar{\nu}_{v} = A(d_{G}(y) - \frac{1}{2})\delta_{v} + \nu_{v},$$

then

$$\overline{W}f(y) = \langle f, \bar{\nu}_u \rangle, \quad f \in C(B), \quad y \in B,$$

whence

(3.10) 
$$\|\overline{W}\| = \sup_{y \in B} \|\bar{v}_y\| = \sup_{y \in B} (A|d_G(y) - \frac{1}{2}| + v_{\infty}(y)).$$

By 1.13, the formula (1.2) holds for any  $\psi \in C(B)$ . This together with (3.4) implies

$$(3.11) NU = (\frac{1}{2}AI + \overline{W})^*,$$

where  $(\cdots)^*$  denotes the operator adjoint to  $(\cdots)$ .

3.5. REMARK. In §4 we shall be engaged with the Neumann problem in the following formulation: Given  $\nu \in C^*(B)$  find a  $\mu \in C^*(B)$  with  $NU\mu = \nu$ . By (3.11), this problem reduces to solving the equation

$$(\frac{1}{2}AI + \overline{W})^*\mu = \nu.$$

In connection with this equation it is useful to know the Fredholm radius of  $\overline{W}$ , i.e., the reciprocal of

$$\omega \overline{W} = \inf_{T} \| \overline{W} - T \|,$$

where T ranges over all compact operators on C(B) (cf. [RS]). Our main objective in §3 is to express  $\omega \overline{W}$  in terms of geometric quantities connected with G and investigate relations between  $\omega \overline{W}$  and regularity of B.

3.6. THEOREM. Let  $I_B$  denote the set of all isolated points of B and put  $E=B-I_B$  if  $I_B$  is finite, E=B in the opposite case. Let  $V_r=0$  or

$$V_r = \sup_{y \in E} [A|\frac{1}{2} - d_G(y)| + v_r(y)]$$

according as  $E = \emptyset$  or not and define

$$V_0 = \lim_{r \to 0+} V_r.$$

Then  $\omega \overline{W} = V_0$ .

Proof will be divided into two steps.

Step 1. We first prove that

$$(3.12) \omega \overline{W} \leq V_r$$

for every r > 0 satisfying

(3.13) 
$$H_{m-1}(\hat{B} \cap \{z : |z-y| = r\}) = 0$$
 for all y,

where  $\hat{B}$  is the reduced boundary defined in 2.11. If R is the set of all r > 0 enjoying (3.13) then  $(0, \infty) - R$  is at most countable, because spherical shells with different radii meet each other in a set of  $H_{m-1}$ -measure zero and  $H_{m-1}(\hat{B}) < \infty$ . Hence  $V_0 = \inf\{V_r : r \in R\}$  and

$$(3.14) \omega \overline{W} \leq V_0$$

will follow from (3.12). So let us fix  $r \in R$ . If  $I_B$  is finite we assume, as we may,  $r < \text{dist } (I_B, E) = \inf \{ \text{dist } (z, E) : z \in I_B \}$ . Let  $c_y$  denote the characteristic function of  $B - (\Omega_r(y) \cap E)$  and put

$$W_r f(y) = \int_{\mathbb{R}} c_y f d\bar{v}_y, \quad f \in C(B),$$

where  $\bar{\nu}_{\nu}$  is defined by (3.8). Absolute values of all the functions in

$$\{W_{r}f: f \in C(B), \|f\| \leq 1\}$$

are bounded by  $\sup_{y \in B} \|\bar{v}_y\| \le \frac{1}{2}A + V$ . If  $f \in C(B)$  and x, y are arbitrary points in E with  $|x-y| = d \le \frac{1}{2}r$ , then we obtain from 2.12

$$W_r f(x) - W_r f(y) = J_1(f) + J_2(f),$$

where

$$J_1(f) = \int_B f(z)[c_x(z) - c_y(z)] \frac{n(z) \cdot (z - x)}{|z - x|^m} dH_{m-1}(z),$$

$$J_2(f) = \int_B f(z)c_y(z) \left[ \frac{z - x}{|z - x|^m} - \frac{z - y}{|z - y|^m} \right] \cdot n(z) dH_{m-1}(z).$$

Denoting

$$\alpha(d) = \sup_{x \in \mathcal{A}} H_{m-1}[(\operatorname{cl} \Omega_{r+d}(z) - \Omega_{r-d}(z)) \cap \hat{B}]$$

we get for  $||f|| \le 1$ 

$$|J_1(f)| \le (\frac{1}{2}r)^{1-m}\alpha(d),$$
  
 $|J_2(f)| \le (m+1)d(\frac{1}{2}r)^{-m}.$ 

Since  $r \in R$ , an easy compactness argument yields

$$\lim_{d\to 0+}\alpha(d)=0.$$

We see that all the functions in (3.15) are equicontinuous on E; noting that B-E is finite we conclude that they are equicontinuous on B as well and the operator

$$W_r: f \to W_r f$$

is compact. Hence

$$\omega \overline{W} \leq \|\overline{W} - W_{\star}\|.$$

If  $f \in C(B)$  then

$$W_r f(y) = \overline{W} f(y)$$
 for  $y \in B - E$ 

while (3.9) shows that, for  $y \in E$ ,

$$(\overline{W}-W_r)f(y)=\int f\,d\bar{\nu}_y$$

with the integral extended over  $B \cap \Omega_r(y)$ . Consequently,

$$\|\overline{W} - W_r\| = \sup_{y \in \mathbb{R}} |\bar{\nu}_y| (\Omega_r(y) \cap B) = V_r$$

and (3.12) is established.

Step 2. Now we are going to prove the inequality

$$(3.16) \omega \overline{W} \ge V_0$$

which is trivial if  $E = \emptyset$ . Therefore we assume  $E \neq \emptyset$ , so that E is infinite. A point  $y \in B$  will be termed a discontinuity for a  $\mu \in C^*(B)$  if  $\mu(\{y\}) \neq 0$ . By the Radon theorem, every compact operator on C(B) can be arbitrarily closely approximated by operators of finite rank. If Q is such an operator, sending  $f \in C(B)$  into

$$Qf = \sum_{k=1}^{q} g_k \langle f, m_k \rangle,$$

where  $g_k \in C(B)$  and  $m_k \in C^*(B)$ , then every  $m_k$  can be arbitrarily closely (in the norm of  $C^*(B)$ ) approximated by  $\bar{m}_k \in C^*(B)$  having only a finite number of discontinuities. Defining

$$\bar{Q}\cdots = \sum_{k=1}^{q} g_k \langle \cdots, \bar{m}_k \rangle$$

we see that the deviation  $||Q - \overline{Q}||$  can be made as small as we want. It follows from these observations that, in order to prove (3.16), it is sufficient to show that

for every Q of the type (3.17), where  $m_k \in C^*(B)$  have only a finite number of discontinuities each. Let us fix such a Q and denote by K the (finite) set of all  $y \in B$  which represent a discontinuity for some of the measures  $m_k$   $(k=1,\ldots,q)$ . Every  $m_k$  splits into  $m_k^1$  having no discontinuities and a finite combination of Dirac measures, to be denoted by  $m_k^2$ . Since y is the only possible discontinuity for  $\bar{\nu}_y$ , we have for  $y \in B - K$ 

$$\|\bar{v}_y - \sum_k g_k(y)m_k\| = \|\bar{v}_y - \sum_k g_k(y)m_k^1\| + \|\sum_k g_k(y)m_k^2\|,$$

whence

$$\|\overline{W}-Q\| \ge \sup \left\{ \left\|\bar{v}_y - \sum_k g_k(y)m_k^1\right\| : y \in E-K \right\}.$$

Since the operator

$$f \rightarrow \left\langle f, \bar{v}_y - \sum_k g_k(y) m_k^1 \right\rangle$$

sends each  $f \in C(B)$  into a continuous function of y we conclude that

$$a_{r}(y) = \left| \bar{v}_{y} - \sum_{k} g_{k}(y) m_{k}^{1} \right| (\Omega_{r}(y) \cap B)$$

is a lower semicontinuous function of y for every r > 0. Consequently,

(3.19) 
$$\|\overline{W} - Q\| \ge \sup \{a_r(y) : y \in E - K\}$$
$$= \sup \{a_r(z) : z \in E - (I_B \cap K)\}.$$

Consider now an arbitrary  $y \in E \cap I_B \cap K$  and note that  $E \cap I_B \neq \emptyset$  implies

$$\emptyset \neq E \cap (I_R - K) \subseteq E - (I_R \cap K).$$

If

$$r < \text{dist}(I_R \cap K, E - (I_R \cap K)),$$

then

(3.20) 
$$\left|\sum_{k} g_{k}(y)m_{k}^{1}\right| (\Omega_{r}(y) \cap B) = \left|\sum_{k} g_{k}(y)m_{k}^{1}\right| (\Omega_{r}(y) \cap I_{B}) = 0,$$

$$a_{r}(y) = \left|\bar{\nu}_{y}\right| (\Omega_{r}(y) \cap I_{B}) = \frac{1}{2}A.$$

On the other hand, we have for any  $z \in I_B$ 

$$\frac{1}{2}A \leq |A(\frac{1}{2}-d_G(z)\delta_z)|(\Omega_r(z)\cap B) + \left|\nu_z - \sum_k g_k(z)m_k^1\right|(\Omega_r(z)\cap B) = a_r(z),$$

because  $\nu_z - \sum_k g_k(z) m_k^1$  has no discontinuities. Combining this with (3.20) we get

$$a_r(y) \le \sup \{a_r(z) : z \in E \cap (I_B - K)\} \le \sup \{a_r(z) : z \in E - (I_B \cap K)\}.$$

We have thus for small r > 0

$$(3.21) \sup \{a_r(z) : z \in E - (I_R \cap K)\} = \sup \{a_r(y) : y \in E\}.$$

Note that

$$V_r = \sup_{y \in E} |\bar{v}_y| (\Omega_r(y) \cap B).$$

If  $M = \max\{|g_k(x)| : x \in B, 1 \le k \le q\}$ , then

(3.22) 
$$\sup \{a_r(y) : y \in E\} \ge V_r - M \sum_{k} \sup_{y \in E} |m_k^1| (\Omega_r(y) \cap B).$$

Since  $m_k^1$   $(k=1,\ldots,q)$  have no discontinuities,

$$\lim_{r\to 0+} \sup_{y\in B} |m_k^1|(\Omega_r(y)\cap B) = 0.$$

Making  $r \to 0+$  in (3.22) and using (3.21), (3.19) we arrive at (3.18).

REMARK. The basic idea of the above proof goes back to J. Radon (cf. [RS]).

3.7. Lemma. Let us define  $\hat{B}$  as in 2.11 and put

$$B^* = B \cap \{y : |d_G(y) - \frac{1}{2}| < \frac{1}{2}\}.$$

Then  $\hat{B}$  is dense in  $B^*$  (moreover, every ball of center in  $B^*$  meets  $\hat{B}$  in a set of positive  $H_{m-1}$ -measure) and

$$H_{m-1}(B^*-\hat{B})=0.$$

**Proof.** If  $y \in B^*$  then there is an  $\varepsilon > 0$  such that

$$H_m(\Omega_r(y) \cap G) > \varepsilon H_m(\Omega_r(y)),$$

$$H_m(\Omega_r(y) \cap C) > \varepsilon H_m(\Omega_r(y))$$

for  $0 < r < \varepsilon$ . By the relative isoperimetric inequality for sets with finite perimeter (cf. Theorem (4.3) in [MI]; general isoperimetric inequalities for currents may be found in [FF, §6]) we conclude that

$$H_{m-1}(\Omega_r(y) \cap \hat{B}) \ge \alpha r^{m-1}, \quad 0 < r < \varepsilon,$$

where  $\alpha > 0$  does not depend on r. Hence it follows by [F2, §3] that

$$H_{m-1}(B^*-\hat{B})=0.$$

3.8. Notation. For  $z \in \mathbb{R}^m$ , r > 0 and  $\theta \in \Gamma$  we put

$$\Omega_r(z,\,\theta)\,=\,\Omega_r(z)\,\cap\,\{x:(x-z)\cdot\theta\,>\,0\}.$$

We denote by  $a(\theta, \eta) = \arccos(\theta \cdot \eta)$  the nonoriented angle enclosed by  $\theta, \eta \in \Gamma$ . It is easily seen that

(3.23) 
$$\frac{a(\theta, \eta)}{2\pi} = \frac{H_m(\Omega_r(z, \theta) \cap \Omega_r(z, -\eta))}{H_m(\Omega_r(z))}.$$

The symbol n will always have the meaning described in 2.11. The symmetric difference of P,  $Q \subseteq R^m$  will be denoted by P = Q.

3.9. LEMMA. Let  $z \in \hat{B}$ ,  $\theta = n(z)$ . Then

$$H_m(\Omega_r(z, \theta) \cap \text{int } C) + H_m(\Omega_r(z, -\theta) \cap G) \leq H_m(\Omega_r(z)) \frac{v_r(z)}{4}$$

Proof. Let

$$\gamma_1 < \frac{H_m(\Omega_r(z, \theta) \cap \text{int } C)}{H_m(\Omega_r(z))}, \qquad \gamma_2 < \frac{H_m(\Omega_r(z, -\theta) \cap G)}{H_m(\Omega_r(z))}.$$

Put  $\Gamma_+ = \Gamma \cap \{\eta : \eta \cdot \theta > 0\}$ ,  $\Gamma_- = \Gamma \cap \{\eta : \eta \cdot \theta < 0\}$ ,  $S(\rho) = \{x : |x-z| = \rho\}$  and define  $K_z$ ,  $L_z$  as in 2.6. There are  $\rho_1$ ,  $\rho_2 \in (0, r)$  such that

(3.24) 
$$H_{m-1}(S(\rho_1) \cap \Omega_r(z, \theta) \cap \text{int } C) > \gamma_1 H_{m-1}(S(\rho_1)),$$

$$(3.25) H_{m-1}(S(\rho_2) \cap \Omega_r(z, -\theta) \cap G) > \gamma_2 H_{m-1}(S(\rho_2)).$$

By virtue of 2.7

$$H_{m-1}(L_z \cap \Gamma_+) = \frac{1}{2}A \lim_{\rho \to 0+} \frac{H_m(\Omega_\rho(z,\theta) \cap C)}{H_m(\Omega_\rho(z,\theta))} = 0,$$

$$H_{m-1}(L_z \cap \Gamma_-) = \frac{1}{2}A \lim_{\rho \to 0+} \frac{H_m(\Omega_\rho(z, -\theta) \cap C)}{H_m(\Omega_\rho(z, -\theta))} = \frac{1}{2}A.$$

We see that  $L_z$  is equivalent  $(H_{m-1})$  with  $\Gamma_-$  and  $K_z$  is equivalent  $(H_{m-1})$  with  $\Gamma_+$ . If  $\eta \in L_z$  and  $\{z + \rho \eta : 0 < \rho < r\} \cap G \neq \emptyset$  then, with the notation from 1.6,  $n_r(\eta, z) \ge 1$ . Employing (3.25) we obtain

$$\int_{L_2} n_r(\eta, z) dH_{m-1}(\eta) > \gamma_2 A.$$

Similarly, (3.24) implies

$$\int_{K_{\sigma}} n_{\tau}(\eta, z) dH_{m-1}(\eta) > \gamma_1 A,$$

so that

$$v_r(z) = \int_{\Gamma} n_r(\eta, z) dH_{m-1}(\eta) > (\gamma_1 + \gamma_2)A.$$

3.10. LEMMA. Let  $N \in \Gamma$ ,  $y \in \mathbb{R}^m$ , r > 0 and suppose that

$$\sup_{z \in \mathcal{D}} v_r(z) \leq u_0 A,$$

$$(3.27) H_m(\Omega_r(y, N) \cap C) \leq u_1 H_m(\Omega_r(y)),$$

$$(3.28) H_m(\Omega_r(y, -N) \cap \operatorname{cl} G) \leq u_2 H_m(\Omega_r(y)).$$

If  $s = u_0 + u_1 + u_2 < \frac{1}{2}$ , then for every  $\gamma > s$  there is a  $\delta > 0$  (depending on  $(\gamma - s)r$  only) such that

$$a(n(z), N) \leq \pi \gamma$$
 for  $z \in \hat{B} \cap \Omega_{\delta}(y)$ .

**Proof.** Let  $\gamma = s + 2\varepsilon$ ,  $\varepsilon > 0$ , and consider a  $\theta \in \Gamma$  with  $a(N, \theta) > \gamma \pi$ . We have by (3.23)

$$H_m(\Omega_r(y, -N) \cap \Omega_r(y, \theta)) > \frac{1}{2}\gamma H_m(\Omega_r(y)),$$
  
$$H_m(\Omega_r(y, N) \cap \Omega_r(y, -\theta)) > \frac{1}{2}\gamma H_m(\Omega_r(y)).$$

Let us fix  $\delta > 0$  small enough to secure

$$H_m(\Omega_r(z, \eta) - \Omega_r(y, \eta)) < \varepsilon H_m(\Omega_r(y))$$

for  $|z-y| < \delta$  and any  $\eta \in \Gamma$ . We have then for  $z \in \Omega_{\delta}(y)$ 

$$H_m(\Omega_r(y, -N) \cap \Omega_r(z, \theta)) > \frac{1}{2}sH_m(\Omega_r(z)),$$

$$H_m(\Omega_r(y, N) \cap \Omega_r(z, -\theta)) > \frac{1}{2}sH_m(\Omega_r(z)),$$

whence we obtain on account of (3.27), (3.28)

(3.29) 
$$H_m(\Omega_r(z,\theta) \cap \text{int } C) \ge H_m(\Omega_r(z,\theta) \cap \Omega_r(y,-N)) - H_m(\Omega_r(y,-N) \cap \text{cl } G) \\ > (\frac{1}{2}s - u_2)H_m(\Omega_r(z)),$$

(3.30) 
$$H_m(\Omega_r(z, -\theta) \cap G) \ge H_m(\Omega_r(z, -\theta) \cap \Omega_r(y, N)) - H_m(\Omega_r(y, N) \cap C) > (\frac{1}{2}s - u_1)H_m(\Omega_r(z)).$$

Suppose now that  $z \in \hat{B}$  and  $\theta = n(z)$ . Employing (3.29), (3.30) and Lemma 3.9 we arrive at  $v_r(z) > u_0 A$ , which violates (3.26).

- 3.11. Notation. Let  $P_N$  stand for the orthogonal projection of  $R^m$  onto  $R^m \cap \{x : x \cdot N = 0\}$ . With every  $\alpha \in (0, \frac{1}{2})$  we associate  $B(\alpha) \subseteq B$  as follows. We let  $y \in B(\alpha)$  if for every  $\gamma \in (\alpha, \frac{1}{2})$  there is a neighborhood Q of y in B and an  $N \in \Gamma$  such that  $|P_N(x) P_N(z)| \ge |x z| \cos \pi \gamma$  whenever  $x, z \in Q$ . By Theorem 5.1 in [MI] we get the following corollary of Lemma 3.10:
- 3.12. COROLLARY. If (3.26), (3.27), (3.28) hold and  $s = u_0 + u_1 + u_2 < \frac{1}{2}$ , then  $y \in B(s)$ ; moreover, for every  $\gamma \in (s, \frac{1}{2})$  there is a  $\delta > 0$  (depending on  $r(\gamma s)$  only) such that  $B \cap \Omega_{\delta}(\gamma) \subset B(\gamma)$ .
  - 3.13. THEOREM. If  $V_0 < \frac{1}{2}A$  then  $I_B$  is finite and

$$(3.31) H_{m-1}(B+B(V_0/A)) = 0.$$

If  $V_0 < \frac{1}{4}A$  then  $B = B(2V_0/A)$ .

**Proof.** Let  $V_0 < \frac{1}{2}A$ . Then  $I_B$  must be finite,  $B - I_B = E \subset B^*$  and, by 3.7,  $H_{m-1}(B - \hat{B}) = 0$ . To prove (3.31) it is therefore sufficient to show that

$$\hat{B} \subset B\left(3\varepsilon + \frac{V_0}{A}\right)$$

for every small  $\varepsilon > 0$ . Fix  $y \in \hat{B}$ , N = n(y) and  $\varepsilon > 0$ ,  $3\varepsilon + V_0/A < \frac{1}{2}$ . We have then for sufficiently small r > 0

$$H_{m}(\Omega_{r}(y, N) \cap C) \leq \varepsilon H_{m}(\Omega_{r}(y)),$$

$$H_{m}(\Omega_{r}(y, -N) \cap \operatorname{cl} G) = H_{m}(\Omega_{r}(y, -N) \cap G)$$

$$\leq \varepsilon H_{m}(\Omega_{r}(y)),$$

$$V_{r} < V_{0} + \varepsilon A.$$
(3.32)

Employing 3.12 we get  $y \in B(3\varepsilon + V_0/A)$ . Suppose now that  $\alpha = V_0/A < \frac{1}{4}$  and fix an r > 0 with (3.32). By 3.9 we have for all  $y \in \hat{B}$ 

$$H_m(\Omega_r(y, n(y)) \cap C) + H_m(\Omega_r(y, -n(y)) \cap \operatorname{cl} G) < (\alpha + \varepsilon)H_m(\Omega_r(y)).$$

By 3.12 there is a  $\delta > 0$  independent of y such that  $\Omega_{\delta}(y) \cap B \subseteq B(3\varepsilon + 2\alpha)$  for every  $y \in \hat{B}$ . It remains to note that  $\hat{B}$  is dense in E by 3.7.

3.14. COROLLARY. If  $V_0 < \frac{1}{4}A$  then

$$\lim_{r \to 0+} \sup \{ \rho^{1-m} H_{m-1}(\Omega_{\rho}(y) \cap B) : y \in B, 0 < \rho < r \} \le b_{m-1} \sec (2V_0 \pi/A),$$

where  $b_{m-1}$  denotes the volume of the unit ball in  $R^{m-1}$ .

3.15. THEOREM. Let  $V_0=0$  (which means that  $\overline{W}$  is compact). Then  $I_B$  is finite and  $E=B-I_B$  is a surface of class  $C^1$ .

**Proof.** For every  $\varepsilon > 0$ ,  $\varepsilon < \frac{1}{4}$  there is an r > 0 such that  $V_r < \varepsilon A$ . By 3.9 (note also that  $H_m(B) = 0$ )

$$H_m(\Omega_r(y, n(y)) \cap C) + H_m(\Omega_r(y, -n(y)) \cap \operatorname{cl} G) < \varepsilon H_m(\Omega_r(y))$$

for all  $y \in \hat{B}$ . Employing 3.10 we get a  $\delta > 0$  depending on  $r_{\mathcal{E}}$  only such that, for every couple of points  $y, z \in \hat{B}$ ,  $a(n(z), n(y)) \le 3\varepsilon \pi$  whenever  $|y-z| < \delta$ . We see that n is uniformly continuous on  $\hat{B}$ . By 3.7, n extends to a continuous function N on  $E = \operatorname{cl} \hat{B}$  and, for every  $y \in E$ ,

$$N(y) = \lim_{r \to 0+} \frac{\int N(z) dH_{m-1}(z)}{H_{m-1}(\Omega_r(y) \cap E)}$$

with the integral extended over  $\Omega_r(y) \cap E$ . Hence it follows by [DG3, Theorem III] (see also definition of the reduced boundary presented in [DG3, p. 10]) that E is a surface of class  $C^1$ .

REMARK. The main results of this paper (such as Theorem 1.13 or Theorem 3.6) are expressed in terms of the quantity  $v_r(y)$ . In the definition of  $v_r(y)$  one considers all half-lines issuing at y, i.e., orthogonal trajectories of the level surfaces of the Green function with a fixed pole at y. This suggests the possibility of generalizing these results to the case of a Green space in the sense of [BC].

#### 4. Boundary value problems.

*Notation*. We shall keep the notation and assumptions introduced in §3. Besides that we always assume here that m>2 (see Remark 4.10 below dealing with m=2). We shall start with investigation of solutions of the equations

(4.1) 
$$(\frac{1}{2}AI + \overline{W})f = 0 \quad \text{over } C(B),$$

(4.2) 
$$(\frac{1}{2}AI + \overline{W})^*\mu = 0$$
 over  $C^*(B)$ .

 $C_0(B)$  will denote the class of all  $f \in C(B)$  satisfying (4.1) and  $C^*(B)$  will stand for

the set of all  $\mu \in C^*(B)$  satisfying (4.2). We agree to use M as a generic notation for a Borel set. If  $\mu$  is a signed Borel measure in  $R^m$  and  $R \subseteq R^m$  is a fixed Borel set, we define  $\mu \cap R$  by

$$\mu \cap R(M) = \mu(M \cap R), \qquad M \subseteq R^m.$$

Recalling the definition of  $\bar{\nu}_y$  presented in (3.8) we obtain from (3.9) that, for every  $\mu \in C^*(B)$ ,

$$\overline{W}^*\mu(M) = \int_B \overline{v}_y(M) \ d\mu(y), \qquad M \subseteq B.$$

It follows from (3.10) that

$$||W^*|| \le \frac{1}{2}A + V,$$

where  $V = V^{C}$  has been defined in 2.13.

**4.1.** LEMMA. If  $\mu \in C_0^*(B)$  then  $|\mu|(I_B) = 0$  (see 3.6 for notation).

**Proof.** Let  $\mu \in C_0^*(B)$ ,  $z \in I_B$  and denote by f the characteristic function of  $\{z\}$ . We have by 3.4, 1.13, and (3.3)

$$0 = NU\mu(\{z\}) = \int_{B} (Ad_{G}(y)f(y) + W^{C}f(y)) d\mu(y).$$

It follows from (2.12) that  $W^c f = 0$ , so that  $Ad_G(y)f(y) + W^c f(y) = Af(y)$  for all  $y \in B$ . Hence  $\mu(\{z\}) = 0$ .

REMARK. A refinement of the preceding argument may be used to show that, for every  $\mu \in C_0^*(B)$ ,  $\mu \cap M$  is absolutely continuous with respect to  $H_{m-1} \cap \hat{B}$  provided  $d_G(y) > 0$  for all  $y \in M$ .

As it follows from 4.1,  $C_0^*(B)$  contains only trivial measure in case  $B = I_B$ . In what follows we always exclude the trivial case of a finite B.

4.2. LEMMA. Fix  $z \in B$ ,  $\mu \in C^*(B)$  and put for t > 0

$$(4.5) R_t = B \cap \Omega_t(z),$$

$$\alpha(t) = H_{m-1}(R_t \cap \hat{B}),$$

$$\beta(t) = |\mu|(R_t).$$

Let  $0 < \rho < \delta < \Delta$  and suppose that

$$\mu \cap (R_{\Delta} - R_{\delta}) = \mu.$$

Then

$$(4.8) |\overline{W}^*\mu|(R_\rho) \leq \frac{\alpha(\rho)\beta(\Delta)}{(\Delta-\rho)^{m-1}} + (m-1)\alpha(\rho) \int_{\delta}^{\Delta} \frac{\beta(t) dt}{(t-\rho)^m}.$$

**Proof.** Let g denote the characteristic function of  $\hat{B} \cap R_{\rho}$ . By 2.12 we obtain for  $y \in R_{\Delta} - R_{\delta}$  and  $M \subseteq R_{\rho}$ 

$$|\bar{\nu}_{\nu}(M)| = |\nu_{\nu}(M)| \le \int_{M} g(x)|y-x|^{1-m} dH_{m-1}(x),$$

whence it follows easily by (4.3)

(4.9) 
$$|\overline{W}^*\mu|(R_{\rho}) \leq \iint_{R\times R} g(x)|y-x|^{1-m} dH_{m-1}(x) d|\mu|(y).$$

Since

$$\int_{B} |y-x|^{1-m} d|\mu|(y) \le \int_{\delta}^{\Delta} (t-|x|)^{1-m} d\beta(t)$$

$$\le \frac{\beta(\Delta)}{(\Delta-|x|)^{m-1}} + (m-1) \int_{\delta}^{\Delta} \frac{\beta(t) dt}{(t-|x|)^{m}},$$

(4.9) implies (4.8).

4.3. LEMMA. Fix  $z \in B$ , r > 0 and put, with the notation from 4.2,

$$R = R_r(=\Omega_r(z) \cap B),$$

$$V(R) = \sup \{ |\bar{v}_y|(R) : y \in R \},$$

$$Q(R) = \sup \{ \rho^{1-m}\alpha(\rho) : 0 < \rho < r \},$$

$$K(R) = \inf \left\{ V(R)k^{m-2} + Q(R) \left[ \left( \frac{k}{k-1} \right)^{m-1} - 1 \right] : k > 1 \right\}.$$

Define

$$\overline{W}_{R}^{*}\mu = (\overline{W}^{*}\mu) \cap R, \qquad \mu \in C^{*}(B).$$

Let  $C_R^*$  denote the set of all  $\mu \in C^*(B)$  enjoying

$$J(\mu) = \int_0^r \rho^{1-m} |\mu|(R_\rho) d\rho < \infty$$

and

$$(4.10) |\mu|(B-R) = 0$$

and put

$$\|\mu\|_{R} = \frac{1}{m-2} r^{2-m} \|\mu\| + J(\mu), \qquad \mu \in C_{R}^{*}.$$

Then  $\mu \in C_R^*$  implies  $\overline{W}_R^* \mu \in C_R^*$  and

$$\|\overline{W}_R^*\mu\|_R \leq K(R)\|\mu\|_R.$$

**Proof.** Fix  $\mu \in C_R^*$  and k > 1. We have with the notation from (4.7)

(4.11) 
$$J(\mu) = \int_0^r \rho^{1-m} \beta(\rho) d\rho.$$

Let now  $0 < \rho < r/k$  and define

$$\mu_{\rho} = \mu \cap R_{k\rho}, \qquad \mu^{\rho} = \mu - \mu_{\rho}.$$

In view of (4.3)

Employing 4.2 we obtain

$$(4.13) |\overline{W}_{R}^{*}\mu^{\rho}|(R_{\rho}) \leq \frac{\alpha(\rho)\beta(r)}{(r-\rho)^{m-1}} + (m-1)\alpha(\rho) \int_{k\rho}^{r} \frac{\beta(t) dt}{(t-\rho)^{m}}$$

On account of (4.12), (4.13) we get for  $0 < \rho < r/k$ 

$$\rho^{1-m} | \overline{W}_{R}^{*} \mu | (R_{\rho}) \leq V(R) \rho^{1-m} \beta(k\rho) + Q(R) \frac{\beta(r)}{(r-\rho)^{m-1}} + (m-1)Q(R) \int_{k\rho}^{r} \frac{\beta(t) dt}{(t-\rho)^{m}},$$
 while, by (4.3),

$$\rho^{1-m} |\overline{W}_R^* \mu|(R_\rho) \le V(R) \rho^{1-m} \beta(r) \quad \text{for } r/k \le \rho < r.$$

Using (4.11) we obtain after simple calculation

$$J(\overline{W}_{R}^{*}\mu) = \int_{0}^{r/k} \rho^{1-m} |\overline{W}_{R}^{*}\mu|(R_{\rho}) d\rho + \int_{r/k}^{r} \rho^{1-m} |\overline{W}_{R}^{*}\mu|(R_{\rho}) d\rho$$

$$\leq \frac{\beta(r)}{m-2} r^{2-m} \left( V(R)(k^{m-2}-1) + Q(R) \left[ \left( \frac{k}{k-1} \right)^{m-2} - 1 \right] \right)$$

$$+ J(\mu) \left( V(R)k^{m-2} + Q(R) \left[ \left( \frac{k}{k-1} \right)^{m-1} - 1 \right] \right).$$

Since, by virtue of (4.3),

$$\|\overline{W}_{R}^{*}\mu\| \leq V(R)\beta(r),$$

we get finally

$$\begin{split} \| \, \overline{W}_{R}^{*} \mu \|_{R} &= \frac{1}{m-2} \, r^{2-m} \| \, \overline{W}_{R}^{*} \mu \| + J(\overline{W}_{R}^{*} \mu) \\ &\leq \| \mu \|_{R} \bigg( V(R) k^{m-2} + Q(R) \bigg[ \bigg( \frac{k}{k-1} \bigg)^{m-1} - 1 \bigg] \bigg). \end{split}$$

4.4. Notation. Let

$$Q_r = \sup \{ \rho^{1-m} H_{m-1}(\Omega_{\rho}(z) \cap \hat{B}) : z \in B, 0 < \rho < r \}, \qquad r > 0,$$

$$Q_0 = \lim_{r \to 0+} Q_r.$$

Further define  $V_0$  as in 3.6 and put

(4.14) 
$$K_0 = \inf \left\{ V_0 k^{m-2} + Q_0 \left[ \left( \frac{k}{k-1} \right)^{m-1} - 1 \right] : k > 1 \right\}$$

In what follows we shall always assume that

$$(4.15) K_0 < \frac{1}{2}A.$$

4.5. REMARK. The inequality (4.15) implies

$$(4.16) V_0 < \frac{1}{4}A.$$

Indeed, since B is infinite and  $V_0 < \frac{1}{2}A$ , (3.7) secures  $H_{m-1}(\hat{B}) > 0$ . It is known from [DG2], [F3] that for  $(H_{m-1})$  almost all  $y \in \hat{B}$ 

$$\lim_{\rho \to 0+} \rho^{1-m} H_{m-1}(\Omega_{\rho}(y) \cap \hat{B}) = b_{m-1},$$

where  $b_{m-1}$  denotes the volume of the unit ball in  $R^{m-1}$ . Hence  $Q_0 \ge b_{m-1}$  and k minimizing

$$V_0 k^{m-2} + Q_0 \left[ \left( \frac{k}{k-1} \right)^{m-1} - 1 \right]$$

must satisfy

$$\frac{1}{2}A > Q_0\left[\left(\frac{k}{k-1}\right)^{m-1}-1\right] \ge b_{m-1}\frac{m-1}{k-1},$$

which guarantees  $k^{m-2} > 2$ .

On the other hand, if (4.16) holds, then 3.14 provides an estimate for  $Q_0$  in terms of  $V_0$ . Clearly, (4.15) is fulfilled whenever  $V_0$  is sufficiently small.

In view of (4.16) and 3.6, the Fredholm theory applies to the pair of adjoint equations

$$(\frac{1}{2}AI + \overline{W})f = g,$$

 $(\frac{1}{2}AI + \overline{W})^*\mu = \nu.$ 

4.6. LEMMA. If  $\mu \in C_0^*(B)$  then  $U|\mu|$  (see the introduction for notation) is bounded on B.

**Proof.** Define  $V_r$  and E as in 3.6 and fix r>0 and k>1 such that

$$K = V_{2r}k^{m-2} + Q_r \left[ \left( \frac{k}{k-1} \right)^{m-1} - 1 \right] < \frac{1}{2}A,$$

$$r < \text{dist } (E, B-E).$$

Fix an arbitrary  $z \in E$  and define  $R = \Omega_r(z) \cap B$ . We have then with the notation from 4.3

$$V(R) \leq V_{2r},$$
  $Q(R) \leq Q_r,$   
 $K(R) \leq K < \frac{1}{2}A.$ 

Let  $\mu \in C_0^*(B)$ ,  $\|\mu\| \le 1$  and put

(4.17)

$$\mu_0 = \mu \cap R, \qquad \mu^0 = \mu - \mu_0.$$

In view of (4.2)

$$\frac{1}{2}A\mu_0 + \overline{W}^*\mu_0 = -\frac{1}{2}A\mu^0 - \overline{W}^*\mu^0.$$

Restricting all measures occurring in (4.18) to R we obtain

$$(4.19) (I+2A^{-1}\overline{W}_{R}^{*})\mu_{0} = -2A^{-1}\overline{W}_{R}^{*}\mu^{0}$$

where, of course, I is the identity operator. Employing 4.2 with  $\delta = r$  and  $\Delta = r$  + diam B we obtain easily for  $0 < \rho \le r/2$ 

December

$$\rho^{1-m} |\overline{W}^* \mu^0|(R_\rho) \leq Q_r 2^m r^{1-m} ||\mu^0|| \leq Q_r 2^m r^{1-m}.$$

On the other hand, we have for  $\rho > r/2$ 

$$\rho^{1-m} |\overline{W}^*\mu^0|(R_o) \leq 2^{m-1}r^{1-m} |\overline{W}^*\| \cdot ||\mu^0|| \leq 2^{m-1}r^{1-m}(\frac{1}{2}A+V),$$

so that

$$J(\overline{W}_{R}^{*}\mu^{0}) \leq 2^{m-2}r^{2-m}(2Q_{r}+\frac{1}{2}A+V).$$

Since

$$\|\overline{W}_{R}^{*}\mu^{0}\| \leq \|\overline{W}^{*}\mu^{0}\| \leq \frac{1}{2}A + V$$

we arrive at

$$\|\overline{W}_R^*\mu^0\|_R \leq \gamma_r,$$

where

$$\gamma_r = \frac{1}{m-2} r^{2-m} (\frac{1}{2}A + V) + 2^{m-2} r^{2-m} (2Q_r + \frac{1}{2}A + V).$$

We see that  $\overline{W}_R^*\mu^0 \in C_R^*$ . It is easily seen that  $C_R^*$ , equipped with the norm  $\|\cdot\cdot\cdot\|_R$ , is a Banach space. In view of (4.3) and (4.17)

$$\|\overline{W}_R^*\|_R \leq K < \frac{1}{2}A.$$

Hence we conclude by virtue of (4.19) that  $\mu_0 \in C_R^*$  and

$$\|\mu_0\|_R \leq \left(1 - \frac{2K}{A}\right)^{-1} 2A^{-1}\gamma_\tau = a_\tau.$$

Since  $a_r$  is independent of  $z \in E$ , we have, in particular,

$$\sup_{z\in R}\int_0^r\rho^{1-m}|\mu|(\Omega_\rho(z)\cap B)\,d\rho<\infty,$$

whence it follows easily

$$\sup_{z\in\mathbb{R}}\int_0^\infty \rho^{1-m}|\mu|(\Omega_\rho(z)\cap B)\,d\rho<\infty.$$

Noting that

$$U|\mu|(z) = \frac{1}{m-2} \int_{B} |x-z|^{2-m} d|\mu|(x)$$

$$= \frac{1}{m-2} \int_{0}^{\infty} |\mu|(B \cap \{x : |x-z|^{2-m} > t\}) dt$$

$$= \int_{0}^{\infty} \rho^{1-m} |\mu|(\Omega_{\rho}(z) \cap B) d\rho$$

we see that  $U|\mu|$  is bounded on E. Since, by 4.1, spt  $\mu \subseteq E$  and B - E has a positive distance from E,  $U|\mu|$  is bounded on B as well.

4.7. Notation. It follows easily from (4.16) and 3.13 that G has only a finite number of components; their closures are mutually disjoint. We shall denote by  $q(0 \le q < \infty)$  the number of bounded components of G.  $G_0$  will stand for the unbounded component of G (if any); the bounded components of G will be denoted by  $G_1, \ldots, G_q$ .

Employing 4.6 we obtain by standard reasoning the following.

4.8. Lemma. The dimension of  $C_0^*(B)$  does not exceed q.

**Proof.** Let  $\mu \in C_0^*(B)$ . By 4.6,  $U|\mu|$  is bounded on B. Hence it follows that  $\mu$  has finite energy [B, p. 122] and

$$\int_{\mathbb{R}^m} |\operatorname{grad} U\mu(x)|^2 dx = A \int_{\mathbb{R}} U\mu(y) d\mu(y) < \infty$$

(see [B, pp. 131, 132]). In particular, there are  $\phi_k \in D$  such that

$$\int_{\mathbb{R}^m} |\operatorname{grad} \phi_k(x) - \operatorname{grad} U\mu(x)|^2 dx \to 0 \quad \text{as } k \to \infty.$$

(4.2) means that  $NU\mu = 0$  (see 3.4), so that

$$\int_G \operatorname{grad} \phi_k(x) \cdot \operatorname{grad} U\mu(x) dx = 0$$

for each k; making  $k \to \infty$  we obtain

$$\int_G |\operatorname{grad} U\mu(x)|^2 dx = 0.$$

We see that  $U\mu$  is constant on each  $G_j$  and vanishes on  $G_0$ . Next we prove the following assertion:

(a) If  $U\mu = 0$  on G then  $\mu = 0$ .

Indeed, let  $\mu = \mu_1 - \mu_2$  be the Jordan decomposition of  $\mu$  and assume that  $U\mu_1$  and  $U\mu_2$  coincide on G. Since G has a positive m-dimensional density at any  $z \in B$ , every fine neighborhood of z (in the Cartan topology) meets G (compare

[B, p. 78, paragraph 2, §3 and p. 84, paragraph 6]) and we conclude from the Cartan Theorem [B, p. 86; see also p. 84] that  $U\mu_1(z) = U\mu_2(z)$ . Since  $U\mu_1$  and  $U\mu_2$  coincide on B, they must coincide on  $R^m$ , by the domination principle [B, p. 123]. We have thus  $U\mu = 0$  on  $R^m$ , whence  $\mu = 0$  [B, p. 122].

If q=0 then (a) completes the proof of 4.8. Assume now q>0. With every  $\mu \in C_0^*(B)$  we may associate the q-tuple  $c(\mu) = [c_1(\mu), \ldots, c_q(\mu)]$ , where  $c_j(\mu)$  is the value taken on by  $U\mu$  in  $G_j$ . The map

$$c: \mu \to c(\mu)$$

is an injection of  $C_0^*(B)$  into  $R^q$ . Indeed,  $c(\mu)=0$  means that  $U\mu=0$  on G and (a) implies  $\mu=0$ .

4.9. PROPOSITION. Let  $f_j$  denote the characteristic function of  $\operatorname{fr} G_j$   $(1 \le j \le q)$ . Then  $\{f_1, \ldots, f_q\}$  is a basis in  $C_0(B)$ .

**Proof.** Let us fix  $j \in \langle 1, q \rangle$  and put  $H = R^m - G_j$ . Employing 2.12 and 2.6 we obtain for any  $z \in R^m - \text{cl } G \subset \text{int } H$ 

$$W^C f_i(z) = \nu_z^H (\text{fr } G_i) = 0,$$

whence it follows by (3.6)

$$(\frac{1}{2}AI + \overline{W})f_i = 0,$$

so that  $f_j \in C_0(B)$ . Since the dimension of  $C_0(B)$  coincides with the dimension of  $C_0^*(B)$  which is known to be  $\leq q$  and  $f_1, \ldots, f_q$  are linearly independent, the proof is complete.

4.10. REMARK. Combining the above proposition and Fredholm's theorems one obtains Theorems 4.11–4.13 below.

If m=2 then 4.9 holds under more general assumptions on B. It is sufficient to require that E (see 3.6) consists of mutually disjoint simple closed curves and  $V_0 < \frac{1}{2}A$  (compare [K3], where further references may be found).

4.11. THEOREM. Let  $v \in C^*(B)$ . Then  $v = NU\mu$  for some  $\mu \in C^*(B)$  if and only if

$$\nu(\operatorname{fr} G_i)=0, \qquad j=1,\ldots,q.$$

**Proof.** This follows at once from 4.9 and the Fredholm Theorem.

4.12. THEOREM. Let  $\{f_1, \ldots, f_q\}$  be a basis in  $C_0(B)$ . Given  $g \in C(B)$  there are  $f \in C(B)$  and constants  $\alpha_j$   $(j=1, \ldots, q)$  such that, for every  $y \in B$ , Wf(x) tends to

$$g(y) - \sum_{j=1}^{q} \alpha_j f_j(y)$$

as  $x \to y$ ,  $x \in \text{int } C$ . The constants  $\alpha_j$  are uniquely determined and f is determined modulo  $C_0(B)$ .

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**Proof.** Let  $\{\mu_1, \ldots, \mu_q\}$  and  $\{f_1, \ldots, f_q\}$  be dual bases in  $C_0^*(B)$  and  $C_0(B)$ , respectively. Given  $g \in C(B)$  we can find  $\alpha_k$  so that

$$\left\langle g - \sum_{k=1}^{q} \alpha_k f_k, \mu_j \right\rangle = 0$$

for all j; clearly,  $\alpha_k = \langle g, \mu_k \rangle$ . Then

$$\left\langle g - \sum_{k=1}^{q} \alpha_k f_k, \ C_0^*(B) \right\rangle = 0$$

and the Fredholm Theorem yields an  $f \in C(B)$  such that

$$(\frac{1}{2}AI + \overline{W})f = g - \sum_{k=1}^{q} \alpha_k f_k.$$

The rest follows from (3.6).

Standard reasoning yields also the following.

4.13. THEOREM. Fix  $x_j \in G_j$   $(j=1,\ldots,q)$ . Given  $g \in C(B)$  there are  $f \in C(B)$  (determined modulo  $C_0(B)$ ) and uniquely determined constants  $a_j$  such that, for every  $y \in B$ ,

$$Wf(x) + \sum_{j=1}^{q} a_j |x - x_j|^{2-m}$$

tends to g(y) as  $x \to y$ ,  $x \in \text{int } C$ .

**Proof.** Define  $g_k$  by

$$g_k(x) = \frac{1}{m-2} |x-x_k|^{2-m}.$$

Then  $\langle g_k, \mu \rangle = U\mu(x_k)$  for every  $\mu \in C^*(B)$ . It follows from (3.6) that

$$Wf + \sum_{i=1}^{q} \alpha_i g_i (f \in C(B), \alpha_i \in R^1)$$

represents a solution of the Dirichlet problem for C and the boundary condition g if and only if

$$(4.20) (\frac{1}{2}AI + \overline{W})f = g - \sum_{j=1}^{q} \alpha_j g_j$$

on B. For the existence of an  $f \in C(B)$  satisfying (4.20) it is necessary and sufficient that

$$\left\langle g - \sum_{j=1}^{q} \alpha_j g_j, C_0^*(B) \right\rangle = 0,$$

i.e.,

(4.21) 
$$\sum_{j=1}^{q} \alpha_j U \mu(x_j) = \langle g, \mu \rangle, \qquad \mu \in C_0^*(B).$$

We know from the proof of 4.8 (note also that  $C_0^*(B)$  has dimension q) that

$$\mu \rightarrow [U\mu(x_1), \ldots, U\mu(x_q)]$$

is an isomorphism of  $C_0^*(B)$  onto  $R^q$ . Consequently, (4.21) determines  $\alpha_j$  uniquely. The rest is obvious.

REMARK. Results related to some of those proved in the present paper were announced without proofs in [K1] (for the plane), [BMS] and [MS] (for a domain bounded by a simple closed surface in 3-space), [K2] (for a domain bounded by a hyper-surface in *m*-space) and in Abstract 630-197, (Theorem 1.13), Notices Amer. Math. Soc. 13 (1966).

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