THE BROWNIAN MOTION AND THE CANONICAL STOCHASTIC FLOW ON A SYMMETRIC SPACE

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ABSTRACT. We study the limiting behavior of Brownian motion x_t on a symmetric space $V = G/K$ of noncompact type and the asymptotic stability of the canonical stochastic flow F_t on $O(V)$. We show that almost surely, x_t has a limiting direction as it goes to infinity. The study of the asymptotic stability of F_t is reduced to the study of the limiting behavior of the adjoint action on the Lie algebra $\mathcal{G}$ of G by the horizontal diffusion in G . We determine the Lyapunov exponents and the associated filtration of F_t in terms of root space structure of $\mathcal{G}$.

1. INTRODUCTION

The purpose of this paper is to study the asymptotic behavior of the Brownian motion and the canonical stochastic flow on a Riemannian symmetric space V . If V is of compact type, then the Brownian motion is known to be recurrent and we will show that the canonical stochastic flow has only zero Lyapunov exponent. The case of noncompact type symmetric spaces is more interesting.

It is well known that the Brownian motion on a simply connected Riemannian manifold whose sectional curvatures are bounded from above and below by negative numbers has an asymptotic direction, see [9 and 10]. This is not true if some of the sectional curvatures are allowed to be zero. In fact, the proof of this result cannot be applied to a Riemannian symmetric space of noncompact type, whose sectional curvatures are only nonpositive and some of them may be zero. However, in this case, the Brownian motion has an asymptotic direction. This is a direct consequence of the limiting behavior of the horizontal diffusion process associated with a symmetric space with respect to the Cartan decomposition, see [6]. That paper also discusses the limiting behavior with respect to the Iwasawa decomposition. In fact, the result for the Cartan decomposition is derived from that for the Iwasawa decomposition. See also [11 and 12] for a more accessible treatment of these results. In the present paper, we will present a different and more direct proof for the existence of the asymptotic direction of Brownian motion on a noncompact type symmetric space.

Our main purpose is to determine the Lyapunov exponents and the associated

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filtration for the canonical stochastic flow on the orthonormal frame bundle of a symmetric space of noncompact type.

We will now briefly recall some basic definitions. Let V be a d -dimensional Riemannian manifold and let $O(V)$ be its orthonormal frame bundle. For any orthonormal frame $u = (X_1, X_2, \dots, X_d)$ at $o \in V$, let $u(t)$ be the parallel displacement of u along a curve tangent to X_j at o . $u(t)$ is a curve in $O(V)$. Let $\bar{X}_j(u)$ be the tangent of $u(t)$ at u . Then $\bar{X}_1, \bar{X}_2, \dots, \bar{X}_d$ are n vector fields on $O(V)$. The stochastic flow F_t generated by the Stratonovich stochastic differential equation

$$(1) \quad du_t = \sum_{j=1}^d \bar{X}_j(u_t) \circ dw_t^j$$

is called the canonical stochastic flow on $O(M)$, where $w_t = (w_t^1, w_t^2, \dots, w_t^d)$ is a d -dimensional Wiener process. Let u be an orthonormal frame at o . The image of $F_t(u)$ under the natural projection: $O(V) \rightarrow V$ is a Brownian motion in V , i.e., a diffusion process with one half Laplacian as generator.

Let $\|\cdot\|_c$ be the canonical metric on $O(V)$ defined in [2]. The canonical metric “respects” the Riemannian connection. If $g: V \rightarrow V$ is an isometry, then it induces naturally a map $g: O(V) \rightarrow O(V)$, which is isometric with respect to $\|\cdot\|_c$. The Lyapunov exponents of F_t are defined as the limits of $(1/t) \log \|DF_t(X)\|_c$ as $t \rightarrow \infty$, where DF_t is the differential map of F_t and $X \in TO(V)$.

The Lyapunov exponents describe the asymptotic stability of the canonical stochastic flow and are interesting geometric invariants. A general discussion can be found in [2]. In the case of constant curvature manifolds, the Lyapunov exponents are computed explicitly in [1] and [2]. Note that in the present case, the existence of exponents is not guaranteed by the general theory since the manifold is not compact.

We will take an algebraic approach as in Baxendale [1]. But unlike [1] which relies heavily on explicit computations, we will use the general theory of symmetric spaces. As in the case of constant curvature, the computation of exponents of the canonical stochastic flow can be reduced to computing the exponents of the adjoint action of the horizontal diffusion. One will need the existence of the asymptotic direction of Brownian motion and the asymptotic growth rate of the radial part of Brownian motion. In fact, the filtration associated with the exponents depends on the asymptotic direction of Brownian motion and this dependence can be described in terms of the root space structure of the Lie algebra. At one crucial step, one will have to carefully examine the exponential rate at which the Brownian motion converges to its asymptotic direction and the effect on the adjoint action of the horizontal diffusion. This is now more difficult than in the case of constant curvature because the root system of the Lie algebra is more complicated.

Our paper generalizes the results in the first part of [1] for hyperbolic spaces to general symmetric spaces. In the second part of [1], the stability of the gradient flow on the sphere S^{d-1} is discussed using the fact that the gradient flow can be induced by the horizontal diffusion in $SO(d, 1)$. This second part can also be generalized and the gradient flow on S^{d-1} corresponds to the stochastic flows on the boundaries of a Lie group G induced by the horizontal diffusion in G (see the author’s recent paper [5]).

To make this paper accessible to a more general audience, we will use the space $V = SL(n)/SO(n)$ to explain the theory of symmetric spaces. This method was used in [11 and 12], see also [7]. The reader may choose to limit his attention only to this example, then a solid knowledge in symmetric spaces is not really necessary.

It should be mentioned that our method only yields the exponents for the flow F_t restricted to a subbundle G_u of $O(V)$, the orbit of a frame u under the action of G , which is invariant under F_t . $G_u = O(V)$ if V has constant curvature. It seems that F_t on $O(V)$ should have the same exponents. At least, this is true if all the exponents of F_t on $O(V)$ exist, such is the case if V is compact, see the proof of Theorem 1. But we are unable to prove this in general.

The paper is organized as follows. The next section contains a brief introduction to symmetric spaces. We show that the discussion of the canonical stochastic flow F_t can be reduced to that of the horizontal diffusion g_t in G . Section 3 summarizes some basic facts about symmetric spaces of noncompact type. In §4, we show that, almost surely, Brownian motion in a noncompact type symmetric space has an asymptotic direction and its radial part has a limiting growth rate. Section 5 contains our main result. We determine the limiting behavior of the adjoint action of the horizontal diffusion (Theorem 3) and as a consequence, we obtain the Lyapunov exponents and the associated filtration of the canonical stochastic flow. Section 6 contains the proof of a technical result which is used early.

2. SYMMETRIC SPACES

We will briefly recall some facts about symmetric spaces. The reader is referred to [3] for details.

Let G be a connected Lie group with Lie algebra $\mathcal{G}$. Any $X \in \mathcal{G}$ is identified with a left invariant vector field on G . For $X, Y \in \mathcal{G}$, their Lie bracket $[X, Y]$ is the element of $\mathcal{G}$ which is identified with the left invariant vector field $XY - YX$. We define $\text{ad}(X): \mathcal{G} \rightarrow \mathcal{G}$ by $\text{ad}(X)Y = [X, Y]$. For any $g \in G$, the Lie group automorphism: $G \rightarrow G$ defined by $\psi \mapsto g\psi g^{-1}$ induces a Lie algebra automorphism $\text{Ad}(g): \mathcal{G} \rightarrow \mathcal{G}$. This is called the adjoint action of G on $\mathcal{G}$. We have

$$(2) \quad \forall X \in \mathcal{G}, \quad e^{\text{ad}(X)} = \text{Ad}(e^X).$$

Let K be a compact Lie subgroup of G with Lie subalgebra $\mathcal{K}$ and let θ be an automorphism on G such that θ^2 is the identity map and $I(G_\theta) \subset K \subset G_\theta$, where G_θ is the subgroup of G fixed by θ and $I(G_\theta)$ is the identity component of G_θ . The homogeneous space $V = G/K$ is called a (globally) symmetric space. We will use o to denote the coset K . Note that G acts naturally on V : $g \in G$ maps ψK into $g\psi K$. The subset N of G which fixes every point of V is a normal subgroup of G contained in K . For simplicity, we will assume that $N = \{e\}$, where e is the identity element of G . Then G acts effectively on V in the sense that if $g(x) = x$ for all $x \in V$, then $g = e$. A Riemannian metric on V is said to be G -invariant if it is left invariant by the action of G . All the G -invariant Riemannian metrics have the same Riemannian connection (Corollary 4.3 of [3, Chapter IV]).

Let θ also denote the induced Lie algebra automorphism $\theta: \mathcal{G} \rightarrow \mathcal{G}$. For $X \in \mathcal{K}$, $\theta(X) = X$. Let $\mathcal{P} = \{X \in \mathcal{G}; \theta(X) = -X\}$. Then $\mathcal{G} = \mathcal{K} \oplus \mathcal{P}$ and $\mathcal{P}$ is $\text{Ad}(K)$ -invariant in the sense that $\forall k \in K, \text{Ad}(k)\mathcal{P} \subset \mathcal{P}$. We have

$$[\mathcal{K}, \mathcal{K}] \subset \mathcal{K}, \quad [\mathcal{K}, \mathcal{P}] \subset \mathcal{P}, \quad [\mathcal{P}, \mathcal{P}] \subset \mathcal{K}.$$

Note that $\mathcal{P}$ can be identified with T_oV under the map $Y \mapsto \frac{d}{ds} \exp(sY)|_{s=0}$, for $Y \in \mathcal{P}$. The Killing form of $\mathcal{G}$ is defined $B(X, Y) = \text{Trace}(\text{ad}(X)\text{ad}(Y))$ for $X, Y \in \mathcal{G}$. We have $B(X, Y) = 0$ for $X \in \mathcal{K}$ and $Y \in \mathcal{P}$, and $B(\cdot, \cdot)$ is negative definite on $\mathcal{K} \times \mathcal{K}$. The homogeneous space $V = G/K$ is said to be a symmetric space of compact type if $(\cdot, \cdot)$ is negative definite on $\mathcal{P} \times \mathcal{P}$, it is said to be of noncompact type if $B(\cdot, \cdot)$ is positive definite on $\mathcal{P} \times \mathcal{P}$.

Let $V = G/K$ be a d -dimensional symmetric space of compact or noncompact type. We now introduce an inner product $\langle \cdot, \cdot \rangle$ on $\mathcal{G}$. If G/K is of compact type, we will let $\langle X, Y \rangle = -B(X, Y)$. If G/K is of noncompact type, we will let $\langle X, Y \rangle = -B(X, \theta(Y))$. Since the Killing form B is $\text{Ad}(G)$ -invariant, $\langle \cdot, \cdot \rangle$ is $\text{Ad}(G)$ -invariant when G/K is of compact type. One can also show easily that $\langle \cdot, \cdot \rangle$ is $\text{Ad}(K)$ -invariant when G/K is of noncompact type. We will use $\|X\|$ to denote the square root of $\langle X, X \rangle$. With the identification of $\mathcal{P}$ with T_oV , the norm $\|\cdot\|$ restricted to $\mathcal{P}$ extends to be a G -invariant Riemannian metric on V . This Riemannian metric will be called the standard metric on V .

Let $G = SL(n)$, the group of $n \times n$ real matrices of determinant one. Note that this is usually denoted by $SL(n, R)$. We will use $SL(n)$ instead to simplify our notation. Let $\theta: G \rightarrow G$ be defined by $\theta(A) = (A^*)^{-1}$, where A^* is the transpose of the matrix A . The group G_θ coincides with $SO(n)$, the group of $n \times n$ orthogonal matrices of determinant one. We will let $K = SO(n)$. Now $\mathcal{G} = \mathfrak{sl}(n)$, the space of $n \times n$ matrices of trace zero, $\mathcal{K} = \mathfrak{o}(n)$, the space of skew symmetric matrices, and $\mathcal{P}$ is the space of $n \times n$ symmetric matrices of trace zero. Note that the Lie bracket $[X, Y]$ of X and Y is $XY - YX$ as matrices and the Lie algebra automorphism $\theta: \mathfrak{sl}(n) \rightarrow \mathfrak{sl}(n)$ is given by $\theta(X) = -X^*$. The Killing form on $\mathcal{G} = \mathfrak{sl}(n)$ is given by

$$B(X, Y) = 2n \text{Trace}(XY).$$

It follows that $V = SL(n)/SO(n)$ is a symmetric space of noncompact type. We also note that $\langle X, Y \rangle = 2n \text{Trace}(XY^*)$.

This example will be used throughout to explain our theory. It is much easier to understand the structure theory of symmetric spaces with this example than with a general symmetric space. The reader may choose to work only with this example. Note that V can be identified with the space of positive definite symmetric matrices of determinant one via the map $X \mapsto XX^*$ defined on $SL(n)$. Since such a symmetric matrix represents an n -dimensional ellipsoid of unit volume, V can be regarded as the space of ellipsoids of unit volume.

Any $g \in G$ is an isometry: $V \rightarrow V$. Its differential map Dg induces a map: $O(M) \rightarrow O(M)$, which is isometric with respect to the canonical metric on $O(M)$ and will also be denoted by g . Let u be an orthonormal frame $(X_1, \dots, X_d)$ at o and let

$$(3) \quad G_u = \{g(u); g \in G\}.$$

G_u is a subbundle of $O(V)$. Note that via the map: $G \rightarrow G_u$ defined by $g \mapsto g(u)$, G is naturally identified with G_u and $\mathcal{G}$ is naturally identified with

$T_u G_u$. The canonical metric $\|\cdot\|_c$ restricted to $T_u G_u$ becomes a norm on $\mathcal{G}$, which will still be denoted by $\|\cdot\|_c$.

For $g \in G$, the left and right translations L_g and $R_g: G \rightarrow G$ are defined respectively by $L_g(\psi) = g\psi$ and $R_g(\psi) = \psi g$. Recall that X_j is identified with a left invariant vector field on G . Consider the following stochastic differential equation.

$$(4) \quad dg_t = \sum_{j=1}^d X_j(g_t) \circ dw_t^j.$$

Let g_t be the solution for which $g_0 = e$. The process g_t is called the horizontal diffusion in G . Note that the definition of g_t depends on the choice of an orthonormal frame $u = (X_1, \dots, X_d)$, however, its probability law is independent of u .

Lemma 1. *Let g_t be the horizontal diffusion in G defined with respect to an orthonormal frame u . We have*

$$(5) \quad \forall g \in G, \quad F_t(g(u)) = (gg_t)u.$$

In particular, $F_t(u) = g_t(u)$. Consequently the image x_t of g_t under the natural projection: $G \rightarrow V$ is Brownian motion in V and the canonical stochastic flow F_t leaves the subbundle G_u invariant. Moreover, for any $X \in \mathcal{G} \cong T_u G_u$,

$$(6) \quad \|DF_t(u)X\|_c = \|\text{Ad}(g_t^{-1})X\|_c.$$

Proof. To prove (5), it suffices to show that $u_t = gg_t u$ satisfies (1). Let I be the smooth function: $G \times O(V) \rightarrow O(V)$ defined by $I(g, u) = gu$.

$$d[gg_t u] = D_g I(gg_t, u) L_g \circ dg_t = \sum_j D_g I(gg_t, u) X_j(gg_t) \circ dw_t^j.$$

$$\begin{aligned} D_g I(gg_t, u) X_j(gg_t) &= D_g I(gg_t, u) \frac{d}{ds} gg_t e^{sX_j} \Big|_{s=0} \\ &= \frac{d}{ds} I(gg_t e^{sX_j}, u) \Big|_{s=0} = \bar{X}_j(gg_t u). \end{aligned}$$

The last equality above follows from the fact that for any $X, Y \in \mathcal{G}$, the parallel displacement of Y along the geodesic $t \mapsto e^{tX}o$ is given by $D \exp(tX)(Y)$, see Theorem 3.3 in [3, Chapter IV]. This shows that $u_t = gg_t u$ satisfies (1) and hence proves (5). We have

$$DF_t(u)(X) = \frac{d}{ds} [e^{sX} g_t(u)] \Big|_{s=0} = \frac{d}{ds} [g_t \exp(s \text{Ad}(g_t^{-1})X)(u)] \Big|_{s=0}.$$

Now (6) follows from this and the fact that the canonical metric is invariant under the action of G .

For our example $G = SL(n)$, we may take $\{X_1, \dots, X_d\}$ to be the following symmetric matrices: $E_{jk}/2\sqrt{n}$, $1 \leq j < k \leq n$, and $D_{in}/2\sqrt{n}$ for $1 \leq i < n$, where E_{jk} is the matrix whose (j, k) and (k, j) entries are one and other entries are zero, and D_{jk} is the diagonal matrix whose j th diagonal entry is one, k th diagonal entry is negative one and other entries are zero. Let $g \in SL(n)$ and $X \in \mathfrak{sl}(n)$. The tangent vector to the curve $s \mapsto ge^{sX}$ at $s = 0$ is gX (matrix multiplication). Therefore, when X is considered as a left invariant vector field on $SL(n)$, its value at g is given by gX . The stochastic differential

equation (4) becomes

$$(7) \quad dg_t = \frac{1}{2\sqrt{n}} \sum_{j < k} g_t E_{jk} \circ dw_t^{jk} + \frac{1}{2\sqrt{n}} \sum_{i=1}^{n-1} g_t D_{in} \circ dw_t^i,$$

where $\{w_t^{jk}, w_t^i; 1 \leq j < k \leq n, 1 \leq i < n\}$ is an $[(n-1)(n+2)/2]$ -dimensional Wiener process.

By Lemma 1, to determine the exponents of F_t , it suffices to compute the limiting exponential growth rate of $\|\text{Ad}(g_t^{-1})X\|_c$. Since any two norms on a vector space are equivalent, this is the same as the limiting exponential growth rate of $\|\text{Ad}(g_t^{-1})X\|$. The advantage of using $\|\cdot\|$ instead of $\|\cdot\|_c$ is that the norm $\|\cdot\|$ on $\mathcal{G}$ is $\text{Ad}(G)$ -invariant for compact type G/K and it is $\text{Ad}(K)$ -invariant for noncompact type G/K .

Let $X_t = \text{Ad}(g_t^{-1})X$. We have $X_0 = X$ and X_t satisfies the following stochastic differential equation.

$$(8) \quad dX_t = \sum_{j=1}^d [X_t, X_j] \circ dw_t^j.$$

To prove (8), let J be the smooth function: $G \times \mathcal{G} \rightarrow \mathcal{G}$ defined by $J(g, X) = \text{Ad}(g^{-1})X$.

$$dX_t = D_g J(g_t, X) \circ dg_t = \sum_j D_g J(g_t, X) X_j(g_t) \circ dw_t^j.$$

Since $X_j(g_t)$ is the tangent of the curve

$$s \mapsto g_t \exp(sX_j) \quad \text{at } s = 0,$$

$D_g J(g_t, X) X_j(g_t)$ is the tangent of the curve

$$\begin{aligned} s \mapsto J(g_t e^{sX_j}, X) &= \text{Ad}(e^{-sX_j} g_t^{-1})X = \text{Ad}(e^{-sX_j})X_t \\ &= X_t + s[X_t, X_j] + O(s^2), \end{aligned}$$

so it is $[X_t, X_j]$ as desired. See (4) on p. 128 of [3] for the last equality above. Our claim is proved.

Assume that V is a compact type symmetric space. Since $\langle \cdot, \cdot \rangle$ is an $\text{Ad}(G)$ -invariant inner product on $\mathcal{G}$, $\langle [Z, X], Y \rangle + \langle X, [Z, Y] \rangle = 0$ for $X, Y, Z \in \mathcal{G}$. Hence,

$$d\langle X_t, X_t \rangle = 2 \sum_j \langle X_t, [X_t, X_j] \rangle \circ dw_t^j = -2 \sum_j \langle [X_t, X_t], X_j \rangle \circ dw_t^j = 0.$$

So $t \mapsto \langle X_t, X_t \rangle$ is constant. It follows that F_t restricted to G_u has only zero exponents. In fact, this is also true for the flow F_t on $O(V)$. To see this, note that $F_t(u)$ depends on the Brownian path w . We will write $F_t(u, w)$ for $F_t(u)$ when we wish to indicate this dependence. Any orthogonal matrix a transforms u into a new frame ua . We have $F_t(ua, w) = F_t(u, aw)a$, see [2]. Hence, by the definition of the canonical metric, if $X \in T_u O(V)$ and if X is orthogonal to $T_u G_u$, the length of $DF_t(\cdot, w)X$ is no less than that of X . We see that if F_t has a nonzero exponent on $O(V)$, then it has to be positive. But this is impossible since the mean exponent is zero [2]. Therefore, the flow F_t on $O(V)$ has only zero exponent.

Theorem 1. *The canonical stochastic flow on the orthonormal frame bundle of a Riemannian symmetric space of compact type has only zero Lyapunov exponent.*

3. NONCOMPACT TYPE SYMMETRIC SPACES

Throughout the rest of the paper, we will assume that $V = G/K$ is a d -dimensional Riemannian symmetric space of noncompact type with standard metric and o is the coset K . By the general theory [3], V is diffeomorphic to R^d and has nonpositive sectional curvatures. Recall that $\mathcal{P}$ can be identified with T_oV via the map: $\mathcal{P} \rightarrow T_oV$ defined by $X \mapsto \frac{d}{ds} \exp(sX)|_{s=0}$. Since $T_o pV$ can be identified with V via the exponential map at o , we see that $\mathcal{P}$ and V can also be identified. We will use these identifications without further comments. Note that if $x \in V$ is identified with $X \in \mathcal{P}$, then for any $k \in K$, $k(x)$ is identified with $\text{Ad}(k)X$, therefore, with identification of V and $\mathcal{P}$, we should also identify the action of K on V and the adjoint action of K on $\mathcal{P}$.

Recall that $\langle X, Y \rangle$ defined by $-B(X, \theta(Y))$ is an inner product on $\mathcal{G}$.

Let $\mathcal{A}$ be a maximal abelian subspace of $\mathcal{P}$. Here, the term "abelian" means that $[X, Y] = 0$ for all $X, Y \in \mathcal{A}$. A linear functional α on $\mathcal{A}$ is called a root if the space

$$\mathcal{G}_\alpha = \{X \in \mathcal{G}; \forall H \in \mathcal{A}, \text{ad}(H)X = \alpha(H)X\}$$

is nonzero. $\mathcal{G}_\alpha$ will be called the root space of α . It is clear that 0 is a root and its root space $\mathcal{G}_0 = \mathcal{A} \oplus \mathcal{M}$, where $\mathcal{M}$ is the centralizer of $\mathcal{A}$ in $\mathcal{K}$, i.e., $\mathcal{M} = \{X \in \mathcal{K}; [X, H] = 0 \text{ for } H \in \mathcal{A}\}$. We have

$$(9) \quad \theta(\mathcal{G}_\alpha) \subset \mathcal{G}_{-\alpha} \quad \text{and} \quad [\mathcal{G}_\alpha, \mathcal{G}_\beta] \subset \mathcal{G}_{\alpha+\beta}.$$

The first relation above follows from the fact that θ is a Lie algebra automorphism, $\theta(X) = X$ for $X \in \mathcal{K}$ and $\theta(X) = -X$ for $X \in \mathcal{P}$. The second relation is an easy consequence of the Jacobi identity.

For $H \in \mathcal{A}$, $\text{ad}(H): \mathcal{G} \rightarrow \mathcal{G}$ is symmetric with respect to the inner product $\langle \cdot, \cdot \rangle$. The family of linear maps $\{\text{ad}(H); H \in \mathcal{A}\}$ is commutative, hence, by simultaneous diagonalization, we have the following decomposition of $\mathcal{G}$ which is orthogonal with respect to $\langle \cdot, \cdot \rangle$.

$$(10) \quad \mathcal{G} = \sum_{\alpha \in \Sigma} \mathcal{G}_\alpha \oplus \mathcal{G}_0,$$

where Σ is the set of all nonzero roots. Note that our definition of roots and the above root space decomposition depend on the choice of a maximal abelian subspace $\mathcal{A}$ of $\mathcal{P}$.

Any nonzero root α determines a hyperplane $\alpha = 0$ in $\mathcal{A}$ and $\mathcal{A}$ minus these hyperplanes consists of several open components. These components are called Weyl chambers. Now fix a Weyl chamber $\mathcal{A}^+$ contained in $\mathcal{A}$. A root α is said to be positive if $\alpha > 0$ on $\mathcal{A}^+$. Let Σ^+ be the set of all positive roots. We have $\Sigma = \Sigma^+ \cup \{-\Sigma^+\}$.

For any $\alpha \in \Sigma^+$, there is a unique element $H_\alpha \in \mathcal{A}$ such that $\forall H \in \mathcal{A}$, $\alpha(H) = B(H, H_\alpha)$. We will call H_α the vector representing α . Let $m_\alpha = \dim(\mathcal{G}_\alpha)$, $\rho = \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha \alpha$ and let H_ρ be the vector representing ρ , i.e.,

$$(11) \quad H_\rho = \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha H_\alpha.$$

It can be shown (see [6] or [12]) that

$$(12) \quad H_\rho \in \mathcal{A}^+.$$

Recall that for our example $G = SL(n)$, $\mathcal{G} = sl(n)$, $\mathcal{H} = o(n)$ and $\mathcal{P}$ is the space of symmetric matrices of trace zero. Let $\mathcal{A}$ be the space of diagonal matrices of trace zero. Then $\mathcal{A}$ is a maximal abelian subspace of $\mathcal{P}$. For a diagonal matrix $H = \text{diag}\{\lambda_1, \dots, \lambda_d\}$, let $\alpha_{jk}(H) = \lambda_j - \lambda_k$ for $j \neq k$. The set of nonzero roots is

$$\Sigma = \{\alpha_{jk}; 1 \leq j, k \leq n\}.$$

Let $\mathcal{G}_{jk}$ be the root space of α_{jk} . Then $\mathcal{G}_{jk}$ is 1-dimensional and is generated by the matrix whose (j, k) -entry is one and other entries are zero. Note that for our example, $\mathcal{M} = \{0\}$, so $\mathcal{G}_0 = \mathcal{A}$. A diagonal matrix in $\mathcal{A}$ is contained in one of the hyperplanes $\alpha_{jk} = 0$ if and only if at least two of its diagonal entries are the same.

Let $\mathcal{A}^+$ be the space of diagonal matrices in $\mathcal{A}$ whose diagonal entries are in strictly descending order. Then $\mathcal{A}^+$ is a Weyl chamber. The corresponding set of positive roots is given by

$$\Sigma^+ = \{\alpha_{jk}; 1 \leq j < k \leq n\}.$$

The vector representing α_{jk} is $H_{jk} = \frac{1}{2n}D_{jk}$ (recall that D_{jk} is a diagonal matrix whose j th diagonal entry is one, k th diagonal entry is negative one and other entries are zero) and

$$(13) \quad H_\rho = \frac{1}{2} \sum_{j < k} H_{jk} = \frac{1}{4n} \text{diag}\{n-1, n-3, \dots, -(n-3), -(n-1)\}.$$

Note that (12) holds for our example.

Any element of $\mathcal{P}$ is contained in some maximal abelian subspace of $\mathcal{P}$. In fact, for any $k \in K$, $\text{Ad}(k)\mathcal{A}$ is also a maximal abelian subspace and $\bigcup_{k \in K} \text{Ad}(k)\mathcal{A} = \mathcal{P}$. For our example $G = SL(n)$, this is an easy consequence of the fact that any symmetric matrix can be diagonalized through an orthogonal transformation.

If C and C' are two Weyl chambers, possibly contained in two different maximal abelian subspaces of $\mathcal{P}$, then either $C = C'$ or $C \cap C'$ is empty. Moreover, there exists $k \in K$ such that $\text{Ad}(k)C = C'$. An element of $\mathcal{P}$ is said to be regular if it is contained in some Weyl chamber. Let $\mathcal{P}'$ be the set of regular elements. $\mathcal{P}'$ is an open subset of $\mathcal{P}$ and $\mathcal{P}' = \bigcup_{k \in K} \text{Ad}(k)C$, where C is a Weyl chamber. For our example $G = SL(n)$, $\mathcal{P}'$ consists of symmetric matrices of trace zero having distinct eigenvalues.

Let M be the subgroup of K whose adjoint action fixes $\mathcal{A}$, i.e.,

$$M = \{k \in K; \text{Ad}(k)H = H, H \in \mathcal{A}\}.$$

The Lie algebra of M is $\mathcal{M}$, the centralizer in $\mathcal{H}$ of $\mathcal{A}$. The map $\Phi: (K/M) \times \mathcal{A}^+ \rightarrow \mathcal{P}'$ defined by $\Phi(kM, H) = \text{Ad}(k)H$ is a diffeomorphism (see [3, Chapter IX]). Note that for $G = SL(n)$, the identity component of M is $\{e\}$.

The following lemma will be useful when studying the limiting behavior of Brownian motion in V . It was proved and used in [12].

Lemma 2. *The set $\mathcal{P} - \mathcal{P}'$ of irregular elements is contained in the union of a finitely many submanifolds of $\mathcal{P}$ whose codimensions in $\mathcal{P}$ are at least two.*

Proof. For any nonzero root α , let Γ_α be the hyperplane $\alpha = 0$ in $\mathcal{A}$ and let M_α be the Lie subgroup of K whose adjoint action fixes the elements in Γ_α . The Lie algebra of M_α is

$$\mathcal{M}_\alpha = \{X \in \mathcal{H}; [X, Y] = 0 \text{ for } Y \in \Gamma_\alpha\}.$$

It suffices to prove

$$(14) \quad \forall \alpha \in \Sigma, \quad \dim(\text{Ad}(K)\Gamma_\alpha) \leq d - 2.$$

It is clear that $\mathcal{M} \subset \mathcal{M}_\alpha$. Let $X \in \mathcal{G}_\alpha$. There are $Y \in \mathcal{P}$ and $Z \in \mathcal{H}$ such that $X = Y + Z$. Since $\text{ad}(H)X = 0$ for $H \in \Gamma_\alpha$, we see that $\text{ad}(H)Z = 0$ for $H \in \Gamma_\alpha$. It follows that $\dim(\mathcal{M}) < \dim(\mathcal{M}_\alpha)$, so $\dim(K/M_\alpha) < \dim(K/M)$. Since

$$\dim(K/M) + \dim(\mathcal{A}) = \dim(K/M \times \mathcal{A}^+) = \dim(\mathcal{P}) = d,$$

we see that

$$\dim(\text{Ad}(K)\Gamma_\alpha) = \dim(K/M_\alpha \times \Gamma_\alpha) = \dim(K/M_\alpha) + \dim(\Gamma_\alpha) \leq d - 2.$$

Let S be the unit sphere in $\mathcal{P}$ with respect to the norm $\|\cdot\|$ and let

$$(15) \quad S_\rho = \{\text{Ad}(k)(H_\rho/\|H_\rho\|); k \in K\}.$$

The set S_ρ is an $\text{Ad}(K)$ -invariant subset of S and its definition is independent of the choice of the Weyl chamber $\mathcal{A}^+$. It is also clear that $X \in \mathcal{P}$ is contained in S_ρ if and only if X is $H_\rho/\|H_\rho\|$ with respect to some Weyl chamber.

For our example $SL(n)$, S is the set of symmetric matrices X of trace zero such that $2n \sum_{j,k} X_{jk}^2 = 1$, where X_{jk} is the (j, k) -entry of the matrix X , and S_ρ is the subset of S consisting symmetric matrices having eigenvalues

$$(16) \quad \frac{n-1}{4n}, \frac{n-3}{4n}, \dots, \frac{3-n}{4n}, \frac{3-n}{4n}.$$

We now define a function Ψ on S . For $Y \in S$, choose a maximal abelian subspace $\mathcal{A}$ of $\mathcal{P}$ which contains Y and define

$$(17) \quad \Psi(Y) = \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha |\alpha(Y)|,$$

where the set of positive roots Σ^+ is defined with respect to a Weyl chamber $\mathcal{A}^+$ contained in $\mathcal{A}$. We will see later in (18) that the definition of Ψ is independent of the choice of $\mathcal{A}$ and $\mathcal{A}^+$.

Fix $Y \in S$. Consider the symmetric bilinear form

$$L_Y(X, X') = B(\text{ad}(Y)X, \text{ad}(Y)X')$$

on $\mathcal{P}$. Let $\nu_1, \dots, \nu_r$ be the distinct eigenvalues of L_Y with the corresponding multiplicities $m'_1, \dots, m'_r$. Since $\text{ad}(Y)X \in \mathcal{H}$ for $X \in \mathcal{P}$ and B is negative definite on $\mathcal{H}$, we see that all $\nu_j \leq 0$. We claim

$$(18) \quad \Psi(Y) = \frac{1}{2} \sum_{i=1}^r m'_i \sqrt{-\nu_i}.$$

Choose a maximal abelian subspace $\mathcal{A}$ of $\mathcal{P}$ containing Y and fix a Weyl chamber $\mathcal{A}^+$ contained in $\mathcal{A}$. For $\alpha \in \Sigma^+$, let $\mathcal{P}_\alpha$ be the image of $\mathcal{E}_\alpha$ under the natural projection: $\mathcal{K} \oplus \mathcal{P} \rightarrow \mathcal{P}$. Choose an orthonormal basis $\{Y_1, \dots, Y_d\}$ of $\mathcal{P}$ such that each Y_j is contained either in $\mathcal{A}$ or in some $\mathcal{P}_\alpha$. If $Y_j \in \mathcal{A}$, $\text{ad}(Y)Y_j = 0$. If $Y_j \in \mathcal{P}_\alpha$, then there are $X_j \in \mathcal{E}_\alpha$ and $Z_j \in \mathcal{K}$ such that $X_j = Y_j + Z_j$. Since $\text{ad}(Y)X_j = \alpha(Y)X_j$, $\text{ad}(Y)Y_j \in \mathcal{K}$ and $\text{ad}(Y)Z_j \in \mathcal{P}$, we see that $\text{ad}(Y)Y_j = \alpha(Y)Z_j$, $\text{ad}(Y)Z_j = \alpha(Y)Y_j$ and $\text{ad}(Y)^2 Y_j = \alpha(Y)^2 Y_j$. It follows that

$$L_Y(Y_j, Y_k) = B(\text{ad}(Y)Y_j, \text{ad}(Y)Y_k) = -B(\text{ad}(Y)^2 Y_j, Y_k) = -\alpha(Y)^2 \delta_{jk}.$$

Hence, $\{Y_1, \dots, Y_d\}$ is a complete set of orthonormal eigenvectors of L_Y and the eigenvalue corresponding to Y_j is $-\alpha_j(Y)^2$, where $\alpha_j = 0$ if $Y_j \in \mathcal{A}$ and α_j is the positive root α if $Y_j \in \mathcal{P}_\alpha$. It is now clear that the right-hand sides of (17) and (18) are the same, so (18) is proved. It follows from (18) that Ψ is a continuous function on S .

By (17), $\Psi > 0$ on S . For $Y \in S \cap \mathcal{A}^+$, $\Psi(Y) = B(Y, H_\rho)$, so $\Psi(Y) \leq \|H_\rho\|$ and the equality holds if and only if $Y = H_\rho / \|H_\rho\|$. Since Ψ is $\text{Ad}(K)$ -invariant by its definition, it assumes the same set of values on the closure of any Weyl chamber. This proves the following lemma.

Lemma 3. Ψ defined by (18) is a positive continuous function on S , its maximal value is $\|H_\rho\|$ and $\Psi(Y) = \|H_\rho\|$ if and only if $Y \in S_\rho$.

The function Ψ is naturally associated with the curvature of V . To see this, let $Y_1, \dots, Y_d$ be as above. We may assume $Y_1 = Y$. By Theorem 4.2 in [3, Chapter IV], the curvature tensor is given by $R(X, Y)Z = -[[X, Y], Z]$. Let s_j be the sectional curvature of the section spanned by Y and Y_j . Then

$$s_j = \langle R(Y_j, Y)Y, Y_j \rangle = -B(\text{ad}(Y)^2 Y_j, Y_j) = \alpha_j(Y)^2.$$

It follows that

$$(19) \quad \Psi(Y) = \frac{1}{2} \sum_{j=2}^d \sqrt{-s_j}.$$

4. THE ASYMPTOTIC BEHAVIOR OF BROWNIAN MOTION

Let x_t be a Brownian motion on V with an arbitrary starting point and let $r_t = r(x_t)$, where $r(x) = d(o, x)$ is the Riemannian distance between o and x . As before, we will identify V with $\mathcal{P}$. Fix a maximal abelian subspace $\mathcal{A}$ of $\mathcal{P}$ and a Weyl chamber $\mathcal{A}^+$ contained in $\mathcal{A}$. Recall that the set of regular elements, $\mathcal{P}'$, is an open subset of $\mathcal{P}$ which is diffeomorphic to $(K/M) \times \mathcal{A}^+$ under the map Φ . By Lemma 2 and the well-known fact that Brownian motion will never hit a set of codimension greater than or equal to two, it follows that almost surely,

$$(20) \quad x_t \in \mathcal{P}' \quad \text{for } t > 0.$$

Therefore, we always have the decomposition $x_t = (\bar{k}_t, A_t)$ with $\bar{k}_t \in K/M$ and $A_t \in \mathcal{A}^+$. Assume $m = \dim(\mathcal{A}^+)$ and let $A_1, A_2, \dots, A_m$ be an orthonormal basis of $\mathcal{A}$. Any $A \in \mathcal{A}^+$ can be expressed uniquely as $A = \sum_i a_i A_i$. Note that $\|A\|^2 = \sum_i a_i^2$. We have $r_t = \|A_t\|$.

Our main objective in this section is to prove the following theorem.

Theorem 2. *Almost surely, $\|A_t\| \rightarrow \infty$ and $A_t/t \rightarrow H_\rho$ as $t \rightarrow \infty$, and $\lim_{t \rightarrow \infty} \bar{k}_t$ exists.*

Recall that for $G = SL(n)$ and $K = SO(n)$, $V = G/K$ can be identified with the space of positive definite symmetric matrices of determinant one through the map: $g \mapsto gg^*$ defined on $SL(n)$. Let g_t be the horizontal diffusion in $SL(n)$ defined by (7) with $g_0 = I$, the identity matrix, and let $x_t = g_t g_t^*$. The process x_t in V is called the Brownian motion in the space of ellipsoids by Dynkin. Let X_t be the process in $\mathcal{P}$ such that $x_t = e^{X_t}$. Since almost surely, $X_t \in \mathcal{P}'$, we see that almost surely, x_t has distinct eigenvalues. Let u_t be an orthonormal frame in R^n with respect to which x_t is diagonalized with descending diagonal entries. Such a frame is not unique because the direction of any axis of u_t can be reversed. All such frames form an equivalence class $\bar{u}_t$, called a flag. It is not hard to see that the process $\bar{u}_t$ plays the role of $\bar{k}_t$ in K/M . Note that x_t can be considered as an ellipsoid of unit volume and $\bar{u}_t$ can be considered as the axes of this ellipsoid. Now A_t is a diagonal matrix-valued process whose diagonal entries are the eigenvalues of X_t in descending order. The process A_t describes the behavior of the eigenvalues of x_t . The limit $\lim_{t \rightarrow \infty} A_t/t = H_\rho$ means that for large t , the eigenvalues of x_t behave like

$$\exp \left\{ \frac{1}{4n}(n-1)t \right\}, \exp \left\{ \frac{1}{4n}(n-3)t \right\}, \dots, \\ \exp \left\{ \frac{1}{4n}(3-n)t \right\}, \exp \left\{ \frac{1}{4n}(1-n)t \right\},$$

and the existence of the limit $\lim_{t \rightarrow \infty} \bar{k}_t$ means that when $t \rightarrow \infty$, the frame of the axes of the ellipsoid x_t tends to a limit.

Lemma 4. $r_t \rightarrow \infty$ and $\liminf_{t \rightarrow \infty} r_t/t \geq c$ for some constant $c > 0$.

Proof. With the polar coordinate decomposition $x_t = (r_t, \theta_t)$, where θ_t is a process in S , we have [9],

$$(21) \quad r_t = r_0 + w_t + \int_0^t F(r_s, \theta_s) ds,$$

where w_t is a 1-dimensional Wiener process and F is some function on V . We have a useful expression for F using Jacobi fields. Fix a unit vector Y_1 in $T_0V \cong \mathcal{P}$ and let γ be the geodesic starting from o with $\gamma'(0) = Y_1$. The value of F at $\gamma(r)$ is given by

$$(22) \quad F = \frac{1}{2} \sum_{j=2}^d \langle \tilde{Y}'_j, \tilde{Y}_j \rangle,$$

where $\tilde{Y}_2, \tilde{Y}_3, \dots, \tilde{Y}_d$ are Jacobi fields along γ such that $\tilde{Y}_j(0) = 0$, and $\{\gamma'(r), \tilde{Y}_2(r), \dots, \tilde{Y}_d(r)\}$ form an orthonormal basis in $T_{\gamma(r)}V$.

Let $\bar{Y}_1, \bar{Y}_2, \dots, \bar{Y}_d$ be the parallel displacements of $Y_1, Y_2, \dots, Y_d$ along γ . By solving the Jacobi equation, we see that $\bar{Y}_1 = \gamma'$ and $\bar{Y}_j = f_j \bar{Y}_j$, where

$$f_j(t) = \frac{\sinh(\sqrt{-s_j}t)}{\sinh(\sqrt{s_j}r)}$$

for $0 \leq t \leq r$ and s_j is the sectional curvature of the section spanned by Y_1 and Y_j . By (22), for fixed $\theta = Y_1 \in S$,

$$F(r, \theta) = \frac{1}{2} \sum_{j=2}^d \sqrt{-s_j} \coth(\sqrt{-s_j} r).$$

It follows that $F(r, \theta) \rightarrow \sum_i \sqrt{-s_i} = \Psi(\theta)$ as $t \rightarrow \infty$ uniformly for θ . Recall that Ψ can be defined by (19) and Ψ is a positive continuous function on S , so there is a constant $c > 0$ such that $\Psi \geq c$. As $t \rightarrow \infty$, $w_t = O(\sqrt{t \log \log t})$, it follows from (21) that $\liminf r_t/t \geq c$.

Recall that $\mathcal{P}'$ is identified with an open subset of V and is diffeomorphic to $(K/M) \times \mathcal{A}^+$. Let Δ be the Laplace-Beltrami operator on $\mathcal{P}'$. By Theorem 5.24 in [4, Chapter II], if f is a smooth function on $\mathcal{A}^+$ and if it is considered as a function on $\mathcal{P}' = (K/M) \times \mathcal{A}^+$, then $\Delta f = \Delta_{\mathcal{A}^+} f$, with $\Delta_{\mathcal{A}^+}$ the differential operator on $\mathcal{A}^+$ defined by

$$(23) \quad \Delta_{\mathcal{A}^+} = \Delta_0 + \sum_{\alpha \in \Sigma^+} m_\alpha \coth(\alpha) H_\alpha,$$

where Δ_0 is the Euclidean Laplacian on $\mathcal{A}^+$ and the root vectors H_α are considered as vector fields on $\mathcal{A}^+$.

From this we can conclude that A_t is a diffusion process on $\mathcal{A}^+$ with generator $\Delta_{\mathcal{A}^+}/2$. Hence,

$$(24) \quad A_t = A_0 + W_t + \int_0^t F(A_s) ds,$$

where W_t is an m -dimensional Wiener process and the vector field $F(A)$ on $\mathcal{A}^+$ is given by

$$(25) \quad F(A) = \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha \coth(\alpha(A)) H_\alpha.$$

The limiting property of A_t is stated in the next lemma which is due to Orihara [7]. We present a different proof here.

Lemma 5. *A_t is a diffusion process on $\mathcal{A}^+$ with generator $\Delta_{\mathcal{A}^+}$ defined by (23) and almost surely, $\|A_t\| \rightarrow \infty$ and $A_t/t \rightarrow H_\rho$ as $t \rightarrow \infty$.*

Proof. We have seen that $\|A_t\| = r_t \rightarrow \infty$ as $t \rightarrow \infty$. Since $x_t \in \mathcal{P}'$ for $t > 0$, A_t never hits the boundary of $\mathcal{A}^+$. It remains to prove that $A_t/t \rightarrow H_\rho$ as $t \rightarrow \infty$.

If we can show that $\alpha(A_t) \rightarrow \infty$ as $t \rightarrow \infty$ for any $\alpha \in \Sigma^+$, then by (25),

$$\lim_{t \rightarrow \infty} F(A_t) = \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha H_\alpha = H_\rho.$$

By (24) and the fact that $W_t = O(\sqrt{t \log \log t})$ as $t \rightarrow \infty$,

$$\frac{A_t}{t} = \frac{A_0}{t} + \frac{W_t}{t} + \frac{1}{t} \int_0^t F(A_s) ds \rightarrow H_\rho.$$

Therefore, it suffices to show that $\alpha(A_t) \rightarrow \infty$ as $t \rightarrow \infty$ for any $\alpha \in \Sigma^+$.

For any $A \in \mathcal{A}^+$ with $r = \|A\|$, let $\phi(A)$ be the angle between A and H_ρ , considered as vectors at the origin. Recall that $H_\rho \in \mathcal{A}^+$. We can introduce the

polar coordinates $(r, \phi, \psi_1, \dots, \psi_{m-2})$ on $\mathcal{A}^+$ such that $r = \|A\|$, $\phi = \phi(A)$ and $(\phi, \psi_1, \dots, \psi_{m-2})$ are orthogonal coordinates on the unit sphere S . For any $\alpha \in \Sigma^+$, let $\phi_\alpha(A)$ be the angle between A and the hyperplane $\alpha = 0$. It is clear that for sufficiently small $\varepsilon > 0$, if $\phi(A) \leq \varepsilon$ when $\|A\|$ is sufficiently large, then $\alpha(A) \rightarrow \infty$ for any $\alpha \in \Sigma^+$. Therefore, in order to prove Lemma 5, it suffices to show that $\forall \varepsilon > 0$, $\phi(A_t) \leq 2\varepsilon$ for sufficiently large t .

ϕ can be considered as a function on $\mathcal{A}^+$, and H_ρ , H_α and $F(A)$ as vector fields. A direct computation using polar coordinates shows that $H_\alpha \phi = O(1/r)$ as $r \rightarrow \infty$. Since H_ρ is at the north pole, one can check that $H_\rho \phi = -\|H_\rho\| \sin \phi / r$. On the hyperplane $\alpha = 0$, the vector H_α is in the inward normal direction with respect to $\mathcal{A}^+$, therefore, $H_\alpha \phi \leq 0$ if $\phi_\alpha(A)$ is sufficiently small. By (25),

$$F\phi = H_\rho \phi + \frac{1}{2} \sum_{\alpha \in \Sigma^+} m_\alpha [\coth(\alpha(A)) - 1] H_\alpha \phi.$$

Note that $\coth(\alpha(A)) \approx 1$ when $\alpha(A)$ is large, which is the case if $\|A\|$ is large and $\phi_\alpha(A)$ is not too small. On the other hand, if $\phi_\alpha(A)$ is small, $H_\alpha \phi \leq 0$. Therefore, by the above expression for $F\phi$, we can show that $\forall \varepsilon > 0$, $\exists C, c > 0$ such that

$$(26) \quad F\phi \leq -\frac{c}{r} \text{ if } A \in \mathcal{A}^+ \text{ with } \phi(A) > \varepsilon \text{ and } \|A\| \geq C.$$

We would like to apply Ito's formula to ϕ . However, ϕ is not smooth at $\phi = 0$. Let $f(x)$ be a positive smooth function on $[0, \infty)$ such that $f(x) = x$ for $x > \varepsilon$, $f(x) \leq \varepsilon$ for $x \leq \varepsilon$ and $f'(x) = 0$ for $x \leq \varepsilon/2$. Set $\psi = f(\phi)$. Then ψ is a smooth function on $\mathcal{A}^+$ and $\psi = \phi$ on $\{\phi > \varepsilon\}$. Moreover, $\psi > \varepsilon$ if and only if $\phi > \varepsilon$. It suffices to show $\psi(A_t) \leq 2\varepsilon$ for sufficiently large t .

By Ito's formula,

$$(27) \quad \psi(A_t) = \psi(A_0) + M_t + \frac{1}{2} V_t + \int_0^t (F\psi)(A_s) ds,$$

where $M_t = \int_0^t \nabla \psi(A_s) dW_s$, $V_t = \int_0^t \Delta \psi(A_s) ds$ and the gradient ∇ and the Laplacian Δ are computed with respect to the Euclidean metric.

M_t is a martingale whose bracket $\langle M \rangle_t = \int_0^t |\nabla \psi(A_s)|^2 ds$. Since $\nabla \phi = O(1/r)$, $\nabla \psi = f'(\phi) \nabla \phi$ and $r_t = O(t)$ as $t \rightarrow \infty$, we see that

$$|\nabla \psi(A_s)|^2 = O(r_s^{-2}) = O(s^{-2}).$$

This implies that $\langle M \rangle_\infty < \infty$ and hence, almost surely, M_t has a finite limit as $t \rightarrow \infty$. Recall $m = \dim(\mathcal{A}^+)$. The case when $m = 1$ is trivial. We will assume $m \geq 2$. One can show that $\Delta \phi = 0$ if $m = 2$ and $|\Delta \phi| \leq c/r^{m-1} \sin \phi$ for some constant $c > 0$ if $m > 2$. Since

$$\Delta \psi = f''(\phi) |\nabla \phi|^2 + f'(\phi) \Delta \phi,$$

we see that $\Delta \psi = O(r^{-2})$ if $m > 2$. It follows that $\int_0^\infty |\Delta \psi(A_s)| ds$ is finite and V_t has a finite limit as $t \rightarrow \infty$.

We claim that $\forall T > 0$, $\exists t \geq T$ such that $\psi(A_t) \leq \varepsilon$. Otherwise, for some $T > 0$, we would have $\psi(A_t) > \varepsilon$ for $t \geq T$. Because (26) holds when ϕ is replaced by ψ , $\int_0^t (F\psi)(A_s) ds$ would tend to $-\infty$ as $t \rightarrow \infty$, and by (27),

$\psi(A_t) \rightarrow -\infty$. This is impossible, so our claim is true. Since both M_t and V_t have finite limits as $t \rightarrow \infty$, and $F\psi(A) \leq 0$ when $\psi(A) > \varepsilon$ and $\|A\|$ is large, it follows from (26) and (27) that if $\psi(A_t) \leq \varepsilon$ for some large t , then $\psi(A_t) \leq 2\varepsilon$ as $t \rightarrow \infty$. This concludes our proof of Lemma 5.

Recall Σ^+ is the set of positive roots. For $\alpha \in \Sigma^+$, let $\mathcal{P}_\alpha$ and $\mathcal{K}_\alpha$ be, respectively, the images of $\mathcal{G}_\alpha$ under the natural projections of $\mathcal{P} \oplus \mathcal{K}$ onto $\mathcal{P}$ and $\mathcal{K}$. We have

$$\mathcal{P} = \mathcal{A} \bigoplus \sum_{\alpha \in \Sigma^+} \mathcal{P}_\alpha \quad \text{and} \quad \mathcal{K} = \mathcal{M} \bigoplus \sum_{\alpha \in \Sigma^+} \mathcal{K}_\alpha.$$

Let $Z_1, Z_2, \dots, Z_l$ be a basis of $\sum_{\alpha \in \Sigma^+} \mathcal{K}_\alpha$, which is orthonormal with respect to $\langle \cdot, \cdot \rangle$, such that each Z_i is contained in some $\mathcal{K}_\alpha$. Recall that $A_1, \dots, A_m$ is an orthonormal basis of $\mathcal{A}$. For $(a, b) = (a_1, \dots, a_m, b_1, \dots, b_l) \in R^{m+l}$, define

$$(28) \quad \Phi'(a, b) = \text{Ad} \left(\exp \left(\sum_{i=1}^l b_i Z_i \right) \right) \left(\sum_{j=1}^m a_j A_j \right).$$

For $\delta > 0$, let

$$(29) \quad U'_\delta = \left\{ Y \in \mathcal{P}; Y = \Phi'(a, b), \sum_i a_i A_i \in \mathcal{A}^+ \text{ and } |b| < \delta \right\}.$$

When δ is sufficiently small, U'_δ is an open subset of $\mathcal{P}$ and Φ' is a diffeomorphism from an open subset of R^{m+l} onto U'_δ . Therefore, (a, b) can be used as local coordinates on U'_δ . Note that if we allow $\mathcal{A}^+$ to vary over all Weyl chambers, then $\{U'_\delta\}$ will form an open cover of $\mathcal{P}'$.

We will express the Riemannian metric in the coordinates (a, b) . Let $Z_{l+1}, \dots, Z_h$ be a basis of $\mathcal{M}$. For a small perturbation Δb of b , we have

$$(30) \quad \begin{aligned} & \exp \left(\sum_{j=1}^l (b_j + \Delta b_j) Z_j \right) \\ &= \exp \left(\sum_{j=1}^l b_j Z_j \right) \exp \left(\sum_{i=1}^h \sum_{j=1}^l a_{ij}(b) \Delta b_j Z_i + O(|\Delta b|^2) \right), \end{aligned}$$

where $a_{ij}(b)$ is a smooth function of b and $a_{ij}(0) = \delta_{ij}$.

Lemma 6. For $X \in \mathcal{A}^+$ and $Y \in \mathcal{P}_\alpha$ for some $\alpha \in \Sigma^+$, we have $\exp(X+tY) = \exp(X) \exp(tZ + O(t^2))$, where

$$(31) \quad Z = \alpha(X)^{-1} \sinh(\alpha(X))Y - \alpha(X)^{-2} [\cosh(\alpha(X)) - 1] \text{ad}(X)Y.$$

Proof. By Theorem 1.7 in [3, Chapter II], $\forall X, Y \in \mathcal{G}$, $\exp(X+tY) = \exp(X) \exp(tZ + O(t^2))$, where

$$(32) \quad Z = \sum_{p=0}^{\infty} \frac{(-1)^p}{(p+1)!} \text{ad}(X)^p Y.$$

Now (31) follows from (32) and the identity $\text{ad}(X)^2 Y = \alpha(X)^2 Y$.

For each $Z_i \in \mathcal{K}_\alpha$, we can choose $Y_i \in \mathcal{P}_\alpha$ such that $Y_i + Z_i \in \mathcal{G}_\alpha$. Thus, $Y_1, \dots, Y_l$ form an orthonormal basis of $\sum_{\alpha \in \Sigma^+} \mathcal{P}_\alpha$. We will let α_i be the positive root α if $i \leq l$ and $Z_i \in \mathcal{K}_\alpha$, and let $\alpha_i = 0$ if $i = l+1, \dots, h$. We have

$$(33) \quad \forall H \in \mathcal{A}, \quad \text{ad}(H)Z_i = \alpha_i(H)Y_i \quad \text{and} \quad \text{ad}(H)Y_i = \alpha_i(H)Z_i.$$

Lemma 7. *In the coordinates (a, b) , the Riemannian metric is given by*

$$\begin{aligned} \left\langle \frac{\partial}{\partial a_p}, \frac{\partial}{\partial a_q} \right\rangle &= \delta_{pq}, & \left\langle \frac{\partial}{\partial a_p}, \frac{\partial}{\partial b_q} \right\rangle &= 0, \\ \left\langle \frac{\partial}{\partial b_p}, \frac{\partial}{\partial b_q} \right\rangle &= \sum_{i=1}^l a_{ip}(b)a_{iq}(b) \sinh^2(\alpha_i(A)), \end{aligned}$$

where $A = \sum_{j=1}^m a_j A_j$.

Proof. The first equality follows from the fact that the Riemannian metric is flat on $\mathcal{A}^+$ and $\text{Ad}(k)$ is an isometry for $k \in K$. By (33),

$$\frac{d}{dt} \text{Ad}(\exp(tZ_i))A|_{t=0} = \frac{d}{dt} e^{t \text{ad}(Z_i)} A|_{t=0} = \text{ad}(Z_i)A = -\alpha_i(A)Y_i.$$

Note that Y_i as a vector at o is now considered as a vector at A , the tangent vector of the curve $t \mapsto A + tY_i$ at $t = 0$. Let $\bar{Y}_i$ be the parallel displacement of Y_i at o along the geodesic $\gamma: t \mapsto tA$. Since $e^A: T_0V \rightarrow T_{e^A(o)}V$ gives the parallel displacement along γ and by Lemma 6,

$$\exp(A + tY_i) = e^A \exp(tF + O(t^2)),$$

where $F = \alpha_i(A)^{-1} \sinh(\alpha_i(A))Y_i + Y'$ for some $Y' \in \mathcal{K}$, we see that

$$Y_i = \alpha_i(A)^{-1} \sinh(\alpha_i(A))\bar{Y}_i \quad \text{at } A.$$

Let $Z = \sum_i b_i Z_i$. We have, by (30),

$$\begin{aligned} \text{Ad}(e^{Z+tZ_p})A &= \text{Ad}(e^Z) \text{Ad} \left(\exp \left(t \sum_i a_{ip}(b)Z_i + O(t^2) \right) \right) A \\ &= \text{Ad}(e^Z) e^{t \sum_i a_{ip}(b) \text{ad}(Z_i) + O(t^2)} A \end{aligned}$$

and by (33),

$$\begin{aligned} \text{Ad}(e^{Z+tZ_p})A &= \text{Ad}(e^Z) \left[A - t \sum_i a_{ip}(b) \alpha_i(A) Y_i + O(t^2) \right], \\ \frac{\partial}{\partial b_p} &= \text{Ad}(e^Z) \left[- \sum_i a_{ip}(b) \sinh(\alpha_i(A)) \bar{Y}_i \right]. \end{aligned}$$

Since $\text{Ad}(e^Z)$ is an isometry, we obtain the desired formulae in Lemma 7.

Let γ be a curve contained in U'_δ and let ds be the differential of arclength on γ . By Lemma 7,

$$(34) \quad ds^2 = \sum_i da_i^2 + \sum_{i,p,q} a_{ip}(b)a_{iq}(b) \sinh^2(\alpha_i(A)) db_p db_q.$$

Let

$$(35) \quad U_\delta = \{Y \in \mathcal{P}; Y = \Phi'(a, b), |b| < \delta, \|A\| \geq 1 \text{ and } \phi(A) < \delta\}.$$

Recall that $A = \sum_i a_i A_i$ and $\phi(A)$ is the angle between A and H_ρ . It is clear that U_δ is an open subset of U'_δ . Note that if $Y = \Phi'(a, b)$, then $\|A\| = d(o, Y)$.

Lemma 8. $\forall \varepsilon > 0, \exists \delta > 0$ and $C > 0$ such that along any curve γ contained in U_δ , $|db| \leq C \exp(-(1-\varepsilon)\lambda r/\|H_\rho\|) ds$, where $r = d(o, \gamma)$, the Riemannian distance between o and γ , and $\lambda = \min_{\alpha \in \Sigma^+} \alpha(H_\rho)$.

Proof. For any $\varepsilon > 0$, when $\|A\| \geq 1$ and when $\phi(A)$ is sufficiently small, $A \approx H_\rho \|A\|/\|H_\rho\|$, so

$$\sinh(\alpha(A)) \geq c \exp((1-\varepsilon)\alpha(H_\rho)\|A\|/\|H_\rho\|),$$

for some constant $c > 0$. Since $a_{ip}(b)$ is continuous in b and $a_{ip}(0) = \delta_{ip}$, the smallest eigenvalue of the symmetric matrix $\sum_i a_{ip}(b)a_{iq}(b)$ is bounded from below by a positive constant. Lemma 8 follows from (34).

Lemma 9. Almost surely, $\exists$ an integer $N > 0$ and $0 < \eta < 1$ such that $\forall$ integer $n \geq N$,

$$\sup\{d(x_t, x_n); n \leq t \leq n+1\} \leq n^\eta.$$

The above formula is given in [10] (see line 8 on p. 1541, where p^j should read p^j). In that paper, it was assumed that the sectional curvatures were bounded from above and below by two negative numbers. However, a careful examination of the proof of this formula reveals that the boundedness of sectional curvatures was only used to control the function F in (21), where the boundedness of Ricci curvature suffices. Therefore, this formula holds also for a symmetric space of noncompact type.

Now, we are ready to prove Theorem 2. By Lemma 5, it suffices to show that almost surely, $\exists$ an integer N such that if $x_N \in U_{\delta/2}$ for some Weyl chamber $\mathcal{A}^+$ and $\delta > 0$, then $|b(x_t)| < \delta$ for $t \geq N$ and $\lim_{t \rightarrow \infty} b(x_t)$ exists.

Choose a typical path w . Fix $\varepsilon > 0$ and let N be the integer in Lemma 9. By Lemma 5, $\lim_{t \rightarrow \infty} r_t/t = \|H_\rho\|$, and so we may assume $(1-\varepsilon)\|H_\rho\| \leq r_t/t$ for $t \geq N$. For $n \geq N$, let γ_n be the minimal geodesic joining x_n and x_{n+1} . Since the length of γ_n is at most n^η ,

$$d(o, \gamma_n) \geq d(o, x_n) - n^\eta = r_n - n^\eta \geq (1-\varepsilon)\|H_\rho\|n - n^\eta.$$

N can be chosen to be large enough so that

$$\sum_{n \geq N} C \exp[-(1-\varepsilon)\lambda((1-\varepsilon)\|H_\rho\|n - n^\eta)/\|H_\rho\|] n^\eta < \frac{\delta}{2},$$

where δ is the constant in Lemma 8. Assume $x_N \in U_{\delta/2}$. We have $|b(x_N)| < \delta/2$ and by Lemma 8

$$\sum_{n \geq N} |b(x_{n+1}) - b(x_n)| \leq \sum_{n \geq N} \int_{\gamma_n} |db| < \frac{\delta}{2}.$$

So $\{b(x_n)\}$ is a Cauchy sequence and $|b(x_n)| < \delta$. For $n \leq t \leq n+1$, let γ' be the minimal geodesic joining x_n and x_t . Then

$$|b(x_t) - b(x_n)| \leq \int_{\gamma'} |db| \leq C \exp[-(1-\varepsilon)\lambda((1-\varepsilon)\|H_\rho\|n - n^\eta)/\|H_\rho\|] n^\eta.$$

Hence, $|b(x_t)| < \delta$ for $t \geq N$ and $\lim_{t \rightarrow \infty} b(x_t)$ exists. This concludes the proof of Theorem 2.

As a direct consequence of Theorem 2, we obtain

Corollary 1. *Let $x_t = (r_t, \theta_t)$ be the polar coordinate decomposition of the Brownian motion x_t about o with $\theta_t \in S$. Then, almost surely, $\lim_{t \rightarrow \infty} r_t/t = \|H_\rho\|$, and $\lim_{t \rightarrow \infty} \theta_t$ exists and is contained in S_ρ .*

Note that if $x_0 = o$, then $\theta_\infty = \lim_{t \rightarrow \infty} \theta_t$ is uniformly distributed on S_ρ in the sense that its distribution is $\text{Ad}(K)$ -invariant.

5. THE ASYMPTOTIC STABILITY OF THE CANONICAL STOCHASTIC FLOW

We will continue to use the notations introduced earlier. Fix an orthonormal frame $u = (X_1, \dots, X_d)$ at o . In §2, we have seen that to determine the Lyapunov exponents of the canonical stochastic flow F_t on G_u , it suffices to determine the exponential growth rate of $\|\text{Ad}(g_t^{-1})X\|$ for any $X \in \mathcal{G}$, where g_t is the horizontal diffusion in G defined with respect to the frame u . Recall that the norm $\|\cdot\|$ is $\text{Ad}(K)$ -invariant on $\mathcal{G}$.

By Lemma 1, the image x_t of g_t under the natural projection: $G \rightarrow V$ is Brownian motion in V . By Theorem 1.1 in [3, Chapter VI], the map: $\mathcal{P} \times K \rightarrow G$ defined by $(X, k) \mapsto e^X k$ is a diffeomorphism, so with the identification of V with $\mathcal{P}$, $g_t = \exp(x_t)k_t$ for some process k_t on K . With polar decomposition, $x_t = r_t \theta_t$, we may write $g_t = \exp(r_t \theta_t)k_t$ and

$$\|\text{Ad}(g_t^{-1})W\| = \|\text{Ad}(k_t^{-1})\text{Ad}(e^{-r_t \theta_t})W\| = \|e^{-r_t \text{ad}(\theta_t)}W\|.$$

Note that almost surely, $\theta_\infty = \lim_{t \rightarrow \infty} \theta_t$ exists and is contained in S_ρ . Therefore, there is a Weyl chamber $\mathcal{A}^+$ such that $\theta_\infty \in \mathcal{A}^+$ and $\theta_\infty = H_\rho/\|H_\rho\|$.

Theorem 3. *Assume that θ_∞ is contained in $\mathcal{A}^+$. If $W \in \mathcal{G}_\beta$ with $W \neq 0$, where β is a root, then*

$$(36) \quad \lim_{t \rightarrow \infty} \|\text{Ad}(g_t^{-1})W\|^{1/t} = e^{-\beta(H_\rho)}.$$

Proof. Since $\theta_t \approx \theta_\infty$ for large t and $\text{ad}(\theta_\infty)W = \beta(\theta_\infty)W$, it may seem that (36) can be derived as follows.

$$\|e^{-r_t \text{ad}(\theta_t)}W\|^{1/t} \approx \|e^{-r_t \text{ad}(\theta_\infty)}W\|^{1/t} = e^{-\beta(\theta_\infty)r_t/t} \|W\|^{1/t},$$

which tends to $\exp(-\beta(\theta_\infty)\|H_\rho\|)$ as $t \rightarrow \infty$. However, the above $\approx$ cannot be easily justified. This forces us to use a more careful argument.

We may assume that $x_t \in U_\delta$ for sufficiently large t , $x_t = \text{Ad}(h_t)A_t$, where $h_t = \exp(\sum_{p=1}^l b_p(x_t)Z_p)$ and $A_t \in \mathcal{A}^+$, and $A_t/t \rightarrow H_\rho$ and $b_p(x_t) \rightarrow 0$ as $t \rightarrow \infty$. Recall that $Z_1, \dots, Z_l$ is a basis of $\sum_{\alpha \in \Sigma^+} \mathcal{K}_\alpha$ such that each Z_i is contained in some $\mathcal{K}_\alpha$. We have

$$\begin{aligned} \|\text{Ad}(g_t^{-1})W\| &= \|\text{Ad}(e^{-x_t})W\| = \|e^{-\text{ad}[\text{Ad}(h_t)A_t]}W\| \\ &= \|\text{Ad}(h_t)e^{-\text{ad}(A_t)}\text{Ad}(h_t^{-1})W\| = \|e^{-\text{ad}(A_t)}\text{Ad}(h_t^{-1})W\|. \end{aligned}$$

Let $W_1, \dots, W_n$ be a basis of $\mathcal{G}$ such that each W_i is contained in $\mathcal{G}_\beta$ for some root β . We will use β_i to denote the root β if $W_i \in \mathcal{G}_\beta$. We may assume $W = W_j$ for some j . We have

$$(37) \quad \text{Ad}(e^{-\sum_{p=1}^l b_p Z_p})W_j = \sum_{k=1}^n f_{jk}(b)W_k.$$

It is clear that the $f_{jk}(b)$ are bounded smooth functions and $f_{jk}(0) = \delta_{jk}$. We have

$$(38) \quad \begin{aligned} e^{-\text{ad}(A_t)} \text{Ad}(h_t^{-1}) W_j &= e^{-\text{ad}(A_t)} \text{Ad}(e^{-\sum_p b_p(x_t) Z_p}) W_j \\ &= \sum_{k=1}^n f_{jk}(b(x_t)) e^{-\beta_k(A_t)} W_k. \end{aligned}$$

Note that $f_{jk}(b(x_t)) \rightarrow \delta_{jk}$ and $\beta_k(A_t) = t\beta_k(A_t/t) \approx t\beta_k(H_\rho)$ as $t \rightarrow \infty$, so the j th term of the right-hand side of (38) has the correct exponential growth rate for (36) with $W = W_j$. To prove (36), we need to show that the exponential growth rates of the other terms are not greater.

The following lemma will be proved in the next section.

Lemma 10. *If $\beta_j \neq \beta_k$, then $\forall \varepsilon > 0$,*

$$(39) \quad |f_{jk}(b(x_t))| \leq e^{-(1-\varepsilon)|\beta_j(H_\rho) - \beta_k(H_\rho)|t},$$

for sufficiently large $t > 0$.

We now show that Theorem 3 follows from the above lemma. Note that the sum on the right-hand side of (38) is orthogonal, we have

$$\begin{aligned} \|\text{Ad}(g_t^{-1}) W_j\|^2 &= \|e^{-\text{ad}(A_t)} \text{Ad}(h_t^{-1}) W_j\|^2 = \sum_k |f_{jk}(b(x_t))|^2 e^{-2\beta_k(A_t)}. \\ \liminf_{t \rightarrow \infty} \|\text{Ad}(g_t^{-1}) W_j\|^{1/t} &\geq \liminf_{t \rightarrow \infty} |f_{jj}(b(x_t))|^{1/t} e^{-\beta_j(A_t)/t} = e^{-\beta_j(H_\rho)}. \end{aligned}$$

Since $A_t = H_\rho t + o(t)$, by Lemma 10,

$$|f_{jk}(b(x_t))| e^{-\beta_k(A_t)} \leq e^{-\beta_j(H_\rho)t + \varepsilon|\beta_j - \beta_k|(H_\rho)t + o(t)}.$$

It follows that

$$\limsup_{t \rightarrow \infty} \|\text{Ad}(g_t^{-1}) W_j\|^{1/t} \leq e^{-\beta_j(H_\rho)} \max_k e^{\varepsilon|\beta_j - \beta_k|(H_\rho)}.$$

Since $\varepsilon > 0$ can be made arbitrarily small, Theorem 3 is proved.

Let $\mu_1 > \mu_2 > \dots > \mu_s$ be the distinct values contained in the set $\{\alpha(H_\rho); \alpha \in \Sigma^+\}$. Since any nonzero root is either α or $-\alpha$ for some $\alpha \in \Sigma^+$, the eigenvalues of the linear map $\text{ad}(H_\rho): \mathcal{G} \rightarrow \mathcal{G}$ are given by $\{\mu_i; i = 0, \pm 1, \pm 2, \dots, \pm s\}$, where $\mu_0 = 0$ and $\mu_{-i} = -\mu_i$.

Let $\mathcal{G}_i$ be the eigenspace of the map $\text{ad}(H_\rho)$ corresponding to μ_i , for $i = 0, \pm 1, \dots, \pm s$. Note that when $i = 0$, $\mathcal{G}_i$ is $\mathcal{G}_0$ as defined earlier. Each $\mathcal{G}_i$ is a direct sum of $\mathcal{G}_\beta$'s, where β is a root satisfying $\beta(H_\rho) = \mu_i$. We have the following orthogonal decomposition of $\mathcal{G}$.

$$\mathcal{G} = \sum_{i=-s}^s \mathcal{G}_i.$$

Now fix a typical path w . We may assume $\theta_\infty = H_\rho / \|H_\rho\|$. Fix $u \in O(V)$ and recall that G_u is defined to be the orbit of u under the action of G on V and it is an F_t -invariant subbundle of $O(V)$. With the natural identification of G_u with G , we may identify $T_u G_u$ with $\mathcal{G}$. The following corollary is a direct consequence of Theorem 3 and (6).

Corollary 2. Consider the canonical stochastic flow F_t restricted to G_u for some orthonormal frame u based at $o \in V = G/K$. Let $\theta_\infty \in T_o V$ be the limiting direction of the Brownian motion which is the image of $F_t(u)$ under the natural projection: $O(V) \rightarrow V$. With the identification of $T_o V$ and $\mathcal{P}$, we may think of θ_∞ as an element of $\mathcal{G} \equiv T_u G_u$. The linear map $\text{ad}(\theta_\infty): \mathcal{G} \rightarrow \mathcal{G}$ has the following eigenvalues

$$-\mu_1 < -\mu_2 < \cdots < -\mu_s < 0 < \mu_s < \cdots < \mu_2 < \mu_1.$$

Let $\mathcal{G}'_i$ be the eigenspace corresponding to μ_i , for $i = 0, \pm 1, \dots, \pm s$, where $\mu_0 = 0$ and $\mu_{-i} = -\mu_i$. Then if $W \in \mathcal{G}'_i$ with $W \neq 0$,

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log \|DF_t(W)\| = -\mu_i.$$

Note that $\mathcal{G}'_i = \mathcal{G}_i$ if $\theta_\infty \in \mathcal{A}^+$. The following theorem establishes the existence of the so-called stable manifold for the flow F_t restricted to G_u .

Theorem 4. Let $G_u^- = \{e^X u; X \in \sum_{i=1}^s \mathcal{G}'_i\}$ and let d be the distance on G_u induced by the canonical metric. Then for any $v_1, v_2 \in G_u^-$, $d(F_t(v_1), F_t(v_2))$ tends to zero exponentially fast as $t \rightarrow \infty$ in the sense that

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log d(F_t(v_1), F_t(v_2)) \leq -\mu_s.$$

Proof. We may assume $\theta_\infty \in \mathcal{A}^+$ and $\mathcal{G}'_i = \mathcal{G}_i$. It suffices to prove the above for $v_1 = u$ and $v_2 = e^X u$, $X \in \mathcal{G}_i$, $i = 1, 2, \dots, s$. The distance d on G_u is G -invariant and it is easy to see that when X is contained in a neighborhood of 0 in $\mathcal{G}$, $d(u, e^X u) \leq c\|X\|$ for some constant $c > 0$. We have

$$\begin{aligned} d(F_t(u), F_t(e^X u)) &= d(g_t u, e^X g_t u) = d(u, g_t^{-1} e^X g_t u) \\ &= d(u, e^{\text{Ad}(g_t^{-1})X} u) \leq c\|\text{Ad}(g_t^{-1})X\|. \end{aligned}$$

It now follows from (36) that if X is a nonzero vector contained in $\mathcal{G}_i$ for $i = 1, 2, \dots, s$, then

$$(40) \quad \lim_{t \rightarrow \infty} \frac{1}{t} \log d(F_t(u), F_t(e^X u)) \leq -\mu_i.$$

Theorem 4 is proved.

For $G = SL(n)$ and $K = SO(n)$, by the root space structure and (13), $s = n - 1$ and

$$\mu_1 = \frac{n-1}{2n}, \quad \mu_2 = \frac{n-2}{2n}, \quad \dots, \quad \mu_{n-1} = \frac{1}{2n}.$$

Let g_t be the horizontal diffusion in $SL(n)$ defined by (7). We have seen that the process $x_t = g_t g_t^*$ is the projection of g_t into V . Let $x_t = e^{r_t \theta_t}$ be the polar decomposition of x_t , where r_t is a positive real-valued process such that r_t/t tends to

$$\|H_\rho\| = \sqrt{(n^2 - 1)/24},$$

the process θ_t is S -valued and the limit $\theta_\infty = \lim_{t \rightarrow \infty} \theta_t$ is a symmetric matrix having eigenvalues (16). The eigenvalues of the linear map $\text{ad}(\theta_\infty): sl(n) \rightarrow sl(n)$ are given by μ_i , $i = 0, \pm 1, \dots, \pm(n-1)$, where $\mu_0 = 0$ and $\mu_{-i} =$

$-\mu_i$. By Theorem 3, if W in $sl(n)$ is contained in the eigenspace of μ_i , then $\|g_t^{-1}Wg_t\|^{1/t}$ tends to $e^{-\mu_i}$ as $t \rightarrow \infty$, where $\|\cdot\|$ can be any norm on $sl(n)$.

6. PROOF OF LEMMA 10

As before, let $W_1, \dots, W_n$ be an orthonormal basis of $\mathcal{G}$ such that each W_j is contained in some root space $\mathcal{G}_\beta$, let $Z_1, \dots, Z_h$ be an orthonormal basis of $\mathcal{H}$ such that each Z_i is contained in some $\mathcal{H}_\alpha$ for $1 \leq i \leq l$ and $Z_i \in \mathcal{M}$ for $i > l$, and let $Y_1, \dots, Y_l$ be a basis of $\sum_{\alpha \in \Sigma^+} \mathcal{P}_\alpha$ such that each Y_i is contained in some $\mathcal{P}_\alpha$ and $Y_i + Z_i \in \mathcal{G}_\alpha$. Recall that β_j is the root β such that $X_j \in \mathcal{G}_\beta$. Let α_i be the positive root α such that $Y_i \in \mathcal{P}_\alpha$ and $Z_i \in \mathcal{H}_\alpha$. We have $-Y_i + Z_i \in \mathcal{G}_{-\alpha}$,

$$[Z_i, X_j] = \frac{1}{2}[Y_i + Z_i, X_j] + \frac{1}{2}[-Y_i + Z_i, X_j] \in \mathcal{G}_{\beta_j + \alpha} + \mathcal{G}_{\beta_j - \alpha}$$

and

$$(41) \quad \text{ad}(Z_i)W_r = \sum_{k=1}^n C_{irk} W_k,$$

where $C_{irk} = 0$ if $\beta_k \neq \beta_r \pm \alpha_i$.

Fix $\varepsilon > 0$. Recall that we have assumed that

$$x_t = \text{Ad}(h_t)A_t = \exp \left(\sum_{p=1}^l b_p(x_t) \text{ad}(Z_p) \right) A_t,$$

where $b_p(x_t)$ tends to zero and A_t/t tends to H_ρ as $t \rightarrow \infty$. Let N be the integer in Lemma 9. For $n \geq N$, let γ_n be the minimal geodesic joining x_n and x_{n+1} . Since $A_n = H_\rho n + o(n)$ and the length of γ_n is at most n^η , where $0 < \eta < 1$, it follows that the $\mathcal{A}^+$ -component of γ_n is also equal to $H_\rho n + o(n)$. By (34), we see that along γ_n , when N is sufficiently large,

$$\left| \sum_{p=1}^l a_{ip}(b) db_p \right| \leq C e^{-(1-\varepsilon)\alpha_i(H_\rho)n} ds, \quad \text{for } i = 1, 2, \dots, l.$$

Similarly, by Lemma 8, we obtain, along γ_n ,

$$|db| \leq C e^{-(1-\varepsilon)\lambda n} ds.$$

Recall $\lambda = \min_{\alpha \in \Sigma^+} \alpha(H_\rho)$. We can introduce a new parameter u_n and γ_n such that $du_n = e^{-(1-\varepsilon)\lambda(n-N)} ds$. We then have

$$\left| \sum_{p=1}^l a_{ip}(b) db_p \right| \leq C e^{-(1-\varepsilon)\alpha_i(H_\rho)N} du_n, \quad \text{for } i = 1, 2, \dots, h,$$

where α_i is defined to be zero if $i = l+1, \dots, h$, and

$$\sum_{n \geq N} \int_{\gamma_n} |du_n| \leq \sum_{n \geq N} e^{-(1-\varepsilon)\lambda(n-N)} n^\eta \leq N^\eta \sum_{k=0}^{\infty} e^{-(1-\varepsilon)k} (k+1)^\eta \leq L N^\eta,$$

where L is a positive constant independent of small $\varepsilon > 0$. By piecing these parameters u_n together we can define a piecewise smooth map $\psi: (0, U] \rightarrow R^l$

such that $U \leq LN^\eta$, $\psi(U) = b(x_N)$, $\psi(u) \rightarrow 0$ as $u \rightarrow 0$ and

$$(42) \quad \left| \sum_{p=1}^l a_{ip}(\psi) \frac{d}{du} b_p \right| \leq C e^{-(1-\varepsilon)\alpha_i(H_\rho)N}, \quad \text{for } i = 1, 2, \dots, h,$$

where α_i is $\alpha \in \Sigma^+$ if $Y_i \in \mathcal{P}_\alpha$ for $i = 1, 2, \dots, l$ and $\alpha_i = 0$ for $i = l+1, \dots, h$.

By (30),

$$\begin{aligned} \exp \left(- \sum_j (b_j + \Delta b_j) Z_j \right) &= \exp \left(- \sum_{i,j} a_{ij} \Delta b_j Z_i + O(|\Delta b|^2) \right) \exp \left(- \sum_j b_j Z_j \right), \\ \text{Ad}(e^{-\sum_j (b_j + \Delta b_j) Z_j}) &= \left[I - \sum_{i,j} a_{ij} \Delta b_j \text{ad}(Z_i) + O(|\Delta b|^2) \right] \text{Ad}(e^{-\sum_j b_j Z_j}). \end{aligned}$$

Recall f_{jk} are defined by (37). We have

$$\begin{aligned} \sum_{k=1}^n df_{jk} W_k &= d[\text{Ad}(e^{-\sum_p b_p Z_p}) W_j] \\ &= - \sum_{i=1}^h \sum_{p=1}^l a_{ip} db_p \text{ad}(Z_i) [\text{Ad}(e^{-\sum_p b_p Z_p}) W_j] \\ &= - \sum_{i=1}^h \sum_{p=1}^l \sum_{r=1}^n a_{ip} dp_p f_{jr} \text{ad}(Z_i) W_r \\ &= - \sum_{k=1}^n \sum_{i=1}^h \sum_{r=1}^n C_{irk} f_{jr} \left(\sum_{p=1}^l a_{ip} db_p \right) W_k. \end{aligned}$$

Hence,

$$df_{jk} = - \sum_{i=1}^h \sum_{r=1}^n C_{irk} f_{jr} \left(\sum_{p=1}^l a_{ip} db_p \right).$$

Let

$$g_{jk} = f_{jk} e^{(1-\varepsilon)|\beta_j - \beta_k|(H_\rho)N}$$

and

$$dv_i = e^{(1-\varepsilon)\alpha_i(H_\rho)N} \sum_{p=1}^l a_{ip} db_p.$$

Since $C_{irk} = 0$ if $\beta_k \neq \beta_r \pm \alpha_i$ and $(|\beta_j - \beta_r| + \alpha_i)(H_\rho) \geq |\beta_j - \beta_k|(H_\rho)$ if $\beta_k = \beta_r \pm \alpha_i$, it follows that

$$dg_{jk} \sum_{i=1}^h \sum_{r=1}^n \tilde{C}_{irk} g_{jr} dv_i,$$

where $|\tilde{C}_{irk}| \leq |C_{irk}|$. With the map ψ defined above, we can regard b_i , $f_{jk} \circ \psi$ and $g_{jk} \circ \psi$ as piecewise smooth functions of u and by (42), we have $|dv_i/du| \leq C$. It follows that $g_{jk} \circ \psi$ satisfy a system of linear homogeneous differential

equations

$$\frac{d}{du} g_{jk} \circ \psi = \sum_r C_{rk}(u) g_{jr} \circ \psi,$$

with bounded coefficients $C_{rk}(u)$.

Now fix j . Let $|g_j|$ be the square root of $\sum_k |g_{jk} \circ \psi|^2$. Then there exists a constant $\Lambda > 0$ such that $|g_j|(U) \leq |g_j|(0)e^{\Lambda U} \leq |g_j|(0)e^{\Lambda LN^n}$. Since $f_{jk}(0) = \delta_{jk}$, we see that $|g_j|(0) = |f_{jj}(0)| = 1$. Hence,

$$|f_{jk} \circ \psi(U)| = |g_{jk} \circ \psi(U)| e^{-(1-\varepsilon)|\beta_j - \beta_k|(H_\rho)N} \leq e^{\Lambda LN^n} e^{-(1-\varepsilon)|\beta_j - \beta_k|(H_\rho)N}.$$

If $\beta_j \neq \beta_k$, $|\beta_j - \beta_k|(H_\rho) > 0$. Since $0 < \eta < 1$, $\Lambda LN^n \leq \varepsilon |\beta_j - \beta_k|(H_\rho)N$ when N is sufficiently large. It follows that

$$|f_{jk}(b(x_N))| = |f_{jk} \circ \psi(U)| \leq e^{-(1-2\varepsilon)|\beta_j - \beta_k|(H_\rho)N}.$$

It is easy to see that in the previous discussion the integer N can be replaced by any large real number t . We obtain (39) by replacing 2ε by ε . Lemma 10 is proved.

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