TRANSACTIONS OF THE AMERICAN MATHEMATICAL SOCIETY Volume 353, Number 12, Pages 4687–4727 S 0002-9947(01)02807-0 Article electronically published on June 27, 2001

ORTHOGONAL, SYMPLECTIC AND UNITARY REPRESENTATIONS OF FINITE GROUPS

CARL R. RIEHM

ABSTRACT. Let K be a field, G a finite group, and $\rho: G \to \mathbf{GL}(V)$ a linear representation on the finite dimensional K-space V. The principal problems considered are:

- **I.** Determine (up to equivalence) the nonsingular symmetric, skew symmetric and Hermitian forms $h: V \times V \to K$ which are G-invariant.
- II. If h is such a form, enumerate the equivalence classes of representations of G into the corresponding group (orthogonal, symplectic or unitary group).
- III. Determine conditions on G or K under which two orthogonal, symplectic or unitary representations of G are equivalent if and only if they are equivalent as linear representations and their underlying forms are "isotypically" equivalent.

This last condition means that the restrictions of the forms to each pair of corresponding isotypic (homogeneous) KG-module components of their spaces are equivalent.

We assume throughout that the characteristic of K does not divide 2|G|. Solutions to \mathbf{I} and \mathbf{II} are given when K is a finite or local field, or when K is a global field and the representation is "split". The results for \mathbf{III} are strongest when the degrees of the absolutely irreducible representations of G are odd – for example if G has odd order or is an Abelian group, or more generally has a normal Abelian subgroup of odd index – and, in the case that K is a local or global field, when the representations are split.

Let G be a finite group of order g, K a field of characteristic relatively prime to 2g with an involution (possibly the identity) $a \mapsto \bar{a}$, and $\rho : G \to \mathbf{GL}(V)$ a linear representation of G on the finite dimensional K-vector space V.

The group algebra KG has an involution $\bar{}$ extending that on K and inverting the group elements. Since KG is a semisimple algebra, the involution algebra $(KG, \bar{})$ is a direct sum of simple involution algebras:

$$(KG, \bar{\ }) = (A_1, \bar{\ }) \oplus (A_2, \bar{\ }) \oplus \cdots \oplus (A_r, \bar{\ }),$$

where each A_i either is a simple algebra stabilized by the involution or is a "simple hyperbolic algebra" – a direct sum of two simple algebras interchanged by the involution. Now let

$$h: V \times V \to K$$

Received by the editors April 5, 2000 and, in revised form, October 30, 2000. 2000 Mathematics Subject Classification. Primary 20C99, 11E08, 11E12; Secondary 20G05, 51F25.

be a symmetric, skew symmetric or Hermitian form on V (we assume throughout that all forms are nonsingular) which is G-invariant. The decomposition

$$V = A_1 V \oplus A_2 V \oplus \cdots \oplus A_r V$$

of the KG-module V into "isotypic" components is an orthogonal direct sum. (A_iV) is the direct sum of two isotypic components in the usual sense if A_i is hyperbolic.) The restrictions of h to these isotypic components are called the isotypic components of h, and two forms are called isotypically equivalent if their corresponding isotypic components are equivalent.

To say that h is G-invariant is the same as saying that ρ is an orthogonal representation $G \to \mathbf{O}(V, h)$, a symplectic representation $G \to \mathbf{Sp}(V, h)$ or a unitary representation $G \to \mathbf{U}(V, h)$, according to the type of h. We refer to such representations as equivariant representations.

Two equivariant representations ρ and ρ' are (equivariantly) equivalent if there is an isometry between their forms which is also KG-linear. There are therefore two obvious necessary conditions for ρ and ρ' to be equivalent, namely

- (i) ρ and ρ' are equivalent as linear representations, and
- (ii) their underlying forms are isotypically equivalent.

This allows us to restrict our attention by and large to the isotypic case, that is to say, when $V = A_i V$ for some i. (In this case we say that V, or the associated representation of G, is A_i -isotypic or isotypic of type A_i .) Furthermore if the involution algebra $(A_i, \bar{\ })$ is hyperbolic, linear equivalence implies equivariant equivalence, and so we can assume in addition that A_i is a simple algebra.

Problems I, II and III were solved earlier for K algebraically closed or real closed.

In the algebraically closed case, Frobenius showed that two orthogonal or two symplectic representations are equivalent if and only if they are equivalent as linear representations ([13], pp. 184-186); furthermore, Frobenius and Schur characterized linear representations which are equivalent to an orthogonal or symplectic representation (cf. [22], $\S13.2$), that is to say, for which there is a G-invariant symmetric or skew symmetric form.

In the case of a real closed field K, Fröhlich and McEvett showed ([9], Prop. 4.9) that two unitary (over $K(\sqrt{-1})$) or orthogonal representations are equivalent if and only if they are linearly equivalent and their underlying forms are isotypically equivalent. They also showed that an invariant symmetric or Hermitian form on an irreducible KG-module is definite. Of course the existence of an invariant positive definite symmetric or Hermitian form on an arbitrary KG-module V is well known when K is formally real – one such form is $\sum_{s \in G} f(sx, sy)$, where f is any positive definite symmetric or Hermitian form on V.

Recently, G. Nebe has given a method in [16] for calculating, under certain circumstances, the determinant or the Hasse invariant of an invariant symmetric form of a representation of a perfect group over a totally real number field, and in [17] she gives a recursion formula for the invariant symmetric form of certain irreducible representations of a symmetric group. This form is also determined, using different methods, in [10] – we give an example in §6.

Another result relevant here is the following (cf. §1.3): If $\rho: G \to \mathbf{GL}(V)$ is a given linear representation, there is at least one G-invariant form h of a given type (symmetric, skew symmetric or Hermitian) on V if and only if the following hold:

- 1. In the symmetric case, len_AAV is even if $(A, \bar{\ })$ is a simple symplectic component of $(KG, \bar{\ })$ of index 1.
- 2. In the skew symmetric case, len_AAV is even if $(A, \bar{\ })$ is a simple orthogonal component of $(KG, \bar{\ })$ of index 1.
 - 3. $\dim_K AV = \dim_K \bar{A}V$ for all simple algebra components A of KG.

This is an easy consequence of results of McEvett [14].

Before summarizing our results, it is necessary to introduce some additional notions and notation. Unexplained terms can be found in §1.

Let A be a simple K-algebra, say $A \cong M(n, D)$ for the division algebra D with center L. If $\bar{}$ is an involution on A stabilizing K, K_0 denotes the subfield of elements of K fixed by the involution, and L_0 that of L.

An arbitrary linear representation is called *split* if it is the sum of absolutely irreducible representations. It is said to be *of odd type* if AV=0 for each simple summand A of KG which has even degree and which is stable under the canonical involution. We shall say that G has odd representation type (with respect to K and its involution) if all nonhyperbolic simple involution components of KG are quasisplit and of odd degree. This is the case, for example, if G has odd order.

In general, we ignore the case of a unitary representation with respect to a skew Hermitian form, since any such form is a scalar multiple of an Hermitian form.

Since skew symmetric forms are equivalent if and only if they have the same rank, symplectic representations are particularly easy to deal with. In particular since a space V has at most one equivalence class of skew symmetric forms, invariant or not, problem \mathbf{I} is trivial.

Symplectic representations (cf. §2).

- II Let A be a simple algebra component of KG, stable under $\bar{\ }$, and let m be a positive integer.
 - $(A, \bar{\ })$ orthogonal. Suppose that A has index 1 or that K is finite, real closed, local or global. Then there is exactly one equivalence class of A-isotypic symplectic representations $G \to \mathbf{Sp}(V)$ of length m (assuming that there is at least one such symplectic representation i.e. that m is even if the index of A is 1).
 - $(A, \bar{\ })$ symplectic. The equivalence classes of A-isotypic symplectic representations $G \to \mathbf{Sp}(V)$ of length m are in bijective correspondence with the equivalence classes of symmetric bilinear forms over L (respectively skew Hermitian forms over D) of rank m, if A has index 1 (respectively > 1).

It follows that the number of equivalence classes of such symplectic representations $G \to \mathbf{Sp}(V)$ is

```
\begin{array}{ll} 2 & \text{if $K$ is finite,} \\ (L^*:L^{*2}) \text{ resp. } 2(L^*:L^{*2}) & \text{if $K$ is local, $A$ has index $1$, and} \\ & m=1 \text{ respectively $m>1$,} \\ (L^*:L^{*2})-\delta_{1m} & \text{if $K$ is local and $A$ has index $>1$,} \\ 1 & \text{if $K$ is real closed,} \\ \infty & \text{if $K$ is global.} \end{array}
```

 $(A, \bar{\ })$ unitary. The equivalence classes of A-isotypic symplectic representations $G \to \mathbf{Sp}(V)$ of length m are in bijective correspondence with the skew Hermitian forms of rank m over D.

Thus the number of equivalence classes of such symplectic representations $G \to \mathbf{Sp}(V)$ is

 $\begin{array}{ll} 1 & \text{if } K \text{ is finite,} \\ 2 & \text{if } K \text{ is local,} \\ m+1 & \text{if } K \text{ is real closed,} \\ \infty & \text{if } K \text{ is global.} \end{array}$

- III Let ρ and ρ' be symplectic representations of G. Suppose that at least one of the following conditions holds:
 - 1. G is a symmetric group.
 - 2. K is finite.
 - 3. ρ is split.
 - 4. If $(A, \bar{\ })$ is a unitary simple involution component of KG such that $AV \neq 0$ under the action provided by ρ , then $(A, \bar{\ })$ is hyperbolic.

Assume in addition that ρ is of odd type in cases 2, 3 and 4; then ρ and ρ' are equivalent if and only if they are linearly equivalent.

From this we get a conjugacy result:

Let G and G' two subgroups of $\mathbf{Sp}(V,h)$ of order relatively prime to char K such that either

- 1. G is a symmetric group, or
- 2. G and G' are of odd representation type, and K is either finite or a splitting field for G.

Then G and G' are conjugate in $\mathbf{Sp}(V,h)$ if and only if they are conjugate in $\mathbf{GL}(V)$.

For the determinant det(⁻) of an involution, see §1.2.

Unitary representations (cf. Theorem 3.1, Theorem 4.1, Corollary 4.4, Theorem 5.2).

K finite.

I, II and III. There is only one equivalence class of Hermitian forms of a given rank, invariant or not, and two arbitrary (not necessarily isotypic) unitary representations of G are equivalent if and only if they are linearly equivalent.

K local.

- **I** and **II**. Let A be a simple algebra component of KG, stable under $\bar{\ }$, V an A-module of length m, and h an Hermitian form on V. There is a G-invariant Hermitian form on V equivalent to h if and only if n is odd or det $h = N_{L/K}(\det(\bar{\ }))^m$. If h' is an invariant form, there is exactly one class of unitary representations $G \to U(V, h')$ if n is odd; if n is even, there are two.
- **III.** Two unitary representations of G of odd type are equivalent if and only if they are equivalent as linear representations and their underlying forms are isotypically equivalent.
- **K** global. Assume that A is a simple component of KG which is split and is stable under $\bar{}$. Let V be an A-module of length m and h an Hermitian form on V. Let \wp be the set of real primes of K_0 which do not split in K.
 - **I.** There is an invariant form on V equivalent to h if and only if the positive and negative indices of h are divisible by n at each $\mathfrak{p} \in \wp$ and, when n is even, $\det h = (\det(^-))^m$.

- II. Let h' be an invariant form on V.
 - (i) If n is odd, there is exactly one equivalence class of unitary representations $G \to \mathbf{U}(V, h')$ for which V is A-isotypic.
 - (ii) If n is even, the equivalence classes of unitary representations $G \to \mathbf{U}(V,h')$ for which V is A-isotypic are in bijective correspondence with those norm classes in $K_0^*/N_{K/K_0}K^*$ which are positive at each $\mathfrak{p} \in \wp$.
- **III.** Two split unitary representations of G of odd type are equivalent if and only if they are equivalent as linear representations and their forms are isotypically equivalent.

Witt equivalence between symmetric forms is denoted by $h \sim_W g$.

Orthogonal representations (cf. Theorem 3.1, Theorem 4.1, Corollary 4.4, Theorem 4.9, Theorem 5.3). Let A be a simple algebra component of KG, stable under $\bar{\ }$, and let m be a positive integer.

K finite.

- **I, II.** Let V be an A-isotypic module of length m.
 - $(A, \bar{\ })$ symplectic. V supports an invariant symmetric form if and only if m is even. If V does have an invariant symmetric form, every invariant form is hyperbolic and there is exactly one equivalence class $G \to \mathbf{O}(V)$ of A-isotypic orthogonal representations.
 - $(A, \bar{\ })$ orthogonal. When n is odd, there are invariant forms of both determinants on V and there is exactly one equivalence class of orthogonal representations for each of these forms.

When n is even, an invariant form h on V has determinant

$$N_{L/K}(\det(^{-}))^m$$
,

and there are two equivalence classes of orthogonal representations $G \to \mathbf{O}(V,h)$.

 $(A, \overline{\ })$ unitary. An invariant form on V has determinant

$$(-\operatorname{disc}(L/L_0))^{mn|L_0^*|/|K^*|}$$

and supports exactly one equivalence class of orthogonal representations. **III.** Let $\rho: G \to \mathbf{O}(V,h)$ be an orthogonal representation such that BV=0 for every component $(B,\bar{\ })$ of $(KG,\bar{\ })$ which is orthogonal and of even degree. If ρ' is another orthogonal representation on V, then ρ and ρ' are equivalent if and only if they are linearly equivalent and their forms are isotypically equivalent. In particular, if G has odd representation type, two orthogonal representations are equivalent if and only if they are linearly equivalent and their forms are isotypically equivalent.

K local. I, II. See Theorems 4.1 and 4.9.

III. Let ρ and ρ' be orthogonal representations of G of odd type, and assume that either ρ is split or G is Abelian. Then ρ and ρ' are equivalent if and only if they are linearly equivalent and their forms are isotypically equivalent.

K global. Assume that A is split.

- $(A, \bar{\ })$ symplectic.
 - I, II. If h is an invariant symmetric form on the A-isotypic module V, it is hyperbolic and the orthogonal representation it affords is unique up to equivalence.

 $(A, \bar{\ })$ orthogonal.

I. See Theorem 5.3.

II. If h is an invariant symmetric form on the A-isotypic module V, there is (up to equivalence) only one orthogonal representation $G \to \mathbf{O}(V,h)$ if n is odd, and there are an infinite number of equivalence classes of orthogonal representations $G \to \mathbf{O}(V,h)$ if n is even.

III. Two split orthogonal representations of odd type are equivalent if and only if they are equivalent as linear representations and their underlying forms are isotypically equivalent.

The case K local, $(A, \bar{\ })$ orthogonal, $D = L \neq K$, n odd, and m = 1 is not completely resolved; its solution depends on the calculation of "trace forms" in the extension L/K. This is carried out in Theorem 4.9 when K is nondyadic (which means, given our assumptions on K, that K is not a finite extension of the 2-adic numbers \mathbb{Q}_2). The dyadic case is unresolved, but a partial solution (for the trace form problem) can be found in [6].

The proofs, when V = AV with A simple, are based on the determination of h in terms of the matrix h_0 (cf. §1.2) and the discriminant matrix $\underline{\check{h}}$ of the form \check{h} over D which corresponds to ρ under Hermitian Morita equivalence (cf. §1.4). This computation appears in its simplest form when A is split: then the discriminant matrix of h is simply $\frac{n}{a}(\epsilon_0\underline{\check{h}}\otimes h_0^t)$, where $h_0^*=\epsilon_0h_0$.

There is an extensive theory calculating the Witt group of equivariant representations, even in the integral case – cf. [23], [4]. But this work does not concern itself with the questions dealt with in this paper.

If K is a global field, we give a proof of the Hasse Principle (Theorem 5.6) for equivariant representations of finite groups over K. It describes the precise conditions under which the equivalence of two equivariant representations over a global field K is implied by their equivalence over all completions of K.

This theorem is well-known in the sense that anyone familiar with the Fröhlich-McEvett theory [9] and the Hasse Principle for ϵ -Hermitian forms over division algebras over global fields (cf. [21], p. 347) is aware that such a result exists. But to my knowledge, it is not documented in the literature.

The Hasse Principle *always* holds for unitary representations, but its validity in the orthogonal and symplectic cases depends on the nature of the representations as linear representations – see Corollary 5.10.

1. Preliminaries

1.1. Sesquilinear forms over fields and division algebras. If $h: V \times V \to D$ is a form over D, we denote by $\det h \in L^*/\mathrm{N}_{L/L_0}L^*$ the "norm class" of the reduced norm $\mathrm{nrd}_{B/L}\underline{h}$, where $\underline{h} \in B = \mathrm{M}(k,D)$ is the matrix of h with respect to some basis of V over D and $k = \dim_D V$. We interpret $\mathrm{N}_{L/L_0}L^*$ to be $= L^{*2}$ if the involution is the identity on L, i.e. if the involution on D is of the first kind. We note that $\det h \in L_0^*/\mathrm{N}_{L/L_0}L^*$ if h is Hermitian.

We also define the discriminant of a symmetric bilinear form h (when D=L) to be disc $h=(-1)^{k(k-1)/2}\det h$, and that of a skew Hermitian form over L to be disc $h=\det\sqrt{\lambda_0}h\in L_0^*/N_{L/L_0}L^*$, where $L=L_0(\sqrt{\lambda_0})$. Of course $\sqrt{\lambda_0}h$ is an Hermitian form. We put disc $h=\det h$ if h is Hermitian.

Lemma 1.1. Let L/K be a finite separable extension such that if the involution on L is \neq the identity, then it is also \neq the identity on K. Suppose that $h: V \times V \to L$

is either a nonsingular symmetric bilinear form or a nonsingular Hermitian or skew Hermitian form of rank k. Then the transfer $\operatorname{Tr}_{L/K} h: V \times V \to K$ has determinant

$$\det \operatorname{Tr}_{L/K} h = (\operatorname{disc}(L/K))^k \operatorname{N}_{L/K} (\det h),$$

where $\operatorname{disc}(L/K)$ is the field discriminant. Similarly,

$$\operatorname{disc}\operatorname{Tr}_{L/K}h = ((-1)^{l(l-1)/2}\operatorname{disc}(L/K))^k\operatorname{N}_{L/K}(\operatorname{disc}h),$$

where l = (L : K). If h is Hermitian, we also have

$$\det \operatorname{Tr}_{L/K} h = (\operatorname{disc}(L_0/K_0))^k \operatorname{N}_{L_0/K_0}(\det h).$$

A proof for the bilinear case can be found, e.g., in [15], Lemma 2.2, and a similar proof applies to the Hermitian and skew Hermitian cases if one carries out the calculation using a basis of L_0 over K_0 .

The following result of Milnor ([15], pp. 89 and 91) is critical in the study of equivariant representations over local fields:

Lemma 1.2. If L/K is a finite separable extension of local fields, the transfers from L to K of two inequivalent nonsingular symmetric forms with the same determinant are inequivalent over K. Similarly, if L has a nonidentity involution which is the identity on K, the transfers of two inequivalent Hermitian forms from L to K remain inequivalent, in fact have the same determinant but different Hasse symbols.

Let $b = \langle a_1, \ldots, a_m \rangle$ be a diagonalization of the symmetric bilinear form b. We use the definition $S_K(b) = S(b) = \prod_{i < j} (a_i, a_j)_K$ of the Hasse-Witt invariant, where $(a_i, a_j)_K$ stands for the Brauer class of the quaternion algebra – which we also denote by $(a_i, a_j)_K$.

Lemma 1.3. (i) If $\eta \in K^*$,

$$S(\eta b) = S(b)(\eta, -1)_K^{m(m-1)/2}(\eta, \det b)_K^{m-1}.$$

(ii) If b_1, \ldots, b_r are symmetric forms over K,

$$S(b_1 \perp \ldots \perp b_r) = \prod_i S(b_i) \prod_{i < j} (\det b_i, \det b_j)_K.$$

(iii) If $\eta_1, \ldots, \eta_n \in K^*$,

$$S(\langle \det \eta_1 b, \dots, \det \eta_n b \rangle)$$

$$= \mathbf{S}(\langle \eta_1^m, \dots, \eta_n^m \rangle) (\det b, -1)_K^{n(n-1)/2} (\det b, \eta_1 \cdots \eta_n)_K^{m(n-1)}.$$

(iv) Let h_0 be another symmetric form, say of rank n. Then

$$S(b \otimes h_0) = S(b)^n S(h_0)^m (\det b, -1)_K^{n(n-1)/2} (\det b, \det h_0)_K^{mn-1} (\det h_0, -1)_K^{m(m-1)/2}.$$

(v) If b is hyperbolic of dimension m = 2k, then

$$S(b) = (-1, -1)_K^{k(k-1)/2}.$$

These are either well known or easily checked.

The equivalence theory of forms over finite, real closed, local (non-Archimedean) and global fields is summarized in the following table. It is derived from [21], p. 347. In it, "1st k." refers to the involution being of the first kind (cf. §1.2), and "Hasse" means that the Hasse principle holds.

Type of form	finite	real	local	global		
symmetric	dim, det	dim, sgn	dim, det, S	Hasse		
skew-symmetric	dim	dim	dim	dim		
Herm/quat.(1 st k.)	∄	dim, sgn	dim	Hasse		
skew-Herm/quat.	∄	dim	dim, det			
Herm/field	\dim	dim, sgn	dim, det	$\dim, \det, \operatorname{sgn}_{\mathfrak{p}}$		
Herm/quat.(2 nd k.)	∄	∄	∄	$\dim, \det, \operatorname{sgn}_{\mathfrak{p}}$		

Table 1.

1.2. Simple involution algebras and representations of finite groups.

Lemma 1.4. The center L of any simple direct summand A of KG is Abelian over K. And if A is stable under the canonical involution $\bar{}$ of KG, L/K_0 is also Abelian.

Proof. If K is a finite field, L/K is of course Abelian, and the same is true for an arbitrary field K of characteristic $\neq 0$ by extension of scalars from the finite case. If the characteristic of K is 0, it is well known that L is a subfield of a cyclotomic extension of K (cf. [3], §70) – in fact it is generated by the character values of any absolutely irreducible representation ρ arising from A – and so is Abelian.

Suppose then that A is stable under the involution of KG and that $K \neq K_0$. Let A_1 be the simple direct summand of K_0G from which A arises by extension of scalars. If L_1 is the center of A_1 , $K \otimes_{K_0} L_1$ is the center of $K \otimes_{K_0} A_1 \subset KG$. By [1], Prop. 3, $K \otimes_{K_0} L_1$ is the direct sum of the composites of K and L_1 over K_0 , and therefore either $K \otimes_{K_0} L_1$ is a field, namely L, or $K \otimes_{K_0} L_1 \cong L_1 \oplus L_1$. In the first case, the group generated by the automorphisms $K_0 = K_0 \otimes_{K_0} L_1 \otimes_{K_0$

By Brauer's Theorem ([22], p. 24), every representation of G over K is split (i.e. K is a splitting field of G) if the exponent of G divides the order $|\mu(K)|$ of the group of roots of unity of K, or if it divides the order of the multiplicative group of the residue class field when K is local.

We note that G has odd representation type if it has odd order or is Abelian, or more generally if it has a normal Abelian subgroup of odd index. See [22], Corollary, p. 61, for the case of characteristic 0. The case of prime characteristic p follows from the fact that any absolutely irreducible representation over a field of characteristic p which contains a primitive $g^{\rm th}$ root of unity is the reduction "mod p" of an absolutely irreducible representation in characteristic 0.

The algebra $A \cong M(n, D)$ is called *split* if D = K, *quasisplit* or of (Schur) index 1 if D = L. Otherwise A is "not quasisplit" or it is "of index > 1". The index of A is d and the degree of A is nd, where $\dim_L D = d^2$.

An involution on the simple algebra A is of the first kind if the involution is the identity on the center of A; otherwise it is of the second kind, or unitary. An involution of the first kind is orthogonal if its 1-eigenspace has dimension $\frac{1}{2}nd(nd+1)$ (where nd is the degree of A) over the center of A; otherwise it is symplectic – in which case the 1-eigenspace has dimension $\frac{1}{2}nd(nd-1)$.

A hyperbolic involution component of KG is also considered to be of the second kind.

If the simple algebra $A \cong M(n, D)$ has an involution, then the division algebra D has one of the same kind. If D is not a field, it can be chosen to be a symplectic involution; in this case we denote it by *.

If D is a quaternion algebra over K, * will be assumed to be the standard conjugation on D. In this case D_0 denotes the skew conjugate elements, the "pure" quaternions. If $\bar{}$ is an orthogonal involution on D, $\bar{d} = j^{-1}d^*j$ for $j \in D_0$ uniquely determined up to a nonzero element of K.

Note that if K is a local field, a quaternion division algebra D does not admit an involution of the second kind ([21], Theorem 2.2 (ii), p. 353).

The symbol a^* will also denote the "transpose conjugate" of a matrix $a \in M(n, D)$, or more generally of a rectangular matrix with entries in D. If A is identified with M(n, D), there is a matrix $h_0 \in A$ such that $\bar{a} = h_0^{-1} a^* h_0$, satisfying $h_0^* = \epsilon_0 h_0$ for $\epsilon_0 = \pm 1$; we can and shall suppose that $\epsilon_0 = 1$ if the involution on A is unitary.

Suppose that the involution $\bar{\ }$ on A is of the first kind. If D=L, the transpose on A is an orthogonal involution, and $\bar{\ }$ is an orthogonal respectively symplectic involution if h_0 is a symmetric respectively skew symmetric matrix. If D is a quaternion algebra, then transpose conjugate is a symplectic involution, and the involution $\bar{\ }$ on A is a symplectic respectively orthogonal involution if h_0 is an Hermitian respectively skew Hermitian matrix (with respect to *).

If the involution $\bar{}$ on A is orthogonal and A has even degree nd, its determinant $\det(\bar{}) \in L^*/L^{*2}$ and discriminant $\operatorname{disc}(\bar{}) = (-1)^{nd/2} \det(\bar{})$ are defined. If D = L, then $\det(\bar{}) = \det h_0$, and if D is a quaternion algebra, then $\operatorname{disc}(\bar{}) = \operatorname{nrd}_{A/L} h_0$. See [11], Prop. 7.3(2),(3), p. 81.

It is useful to define as well the determinant of an involution of the second kind on a central simple algebra A of even degree. In this case, with the assumption $\epsilon_0 = 1$, we define $\det(\bar{\ }) = \operatorname{nrd}_{A/K} h_0 \in L_0^*/\operatorname{N}_{L/L_0} L^*$. It is not difficult to check that it is well-defined, since A has even degree.

We note that it follows from [14], 2.5, that a simple module V over A supports a nonsingular Hermitian form respectively skew Hermitian form $h:V\times V\to A$ if the simple involution algebra $(A, \bar{\ })$ is orthogonal respectively symplectic – and if A is has index > 1 or if $(A, \bar{\ })$ is unitary, it supports both. In the exceptional case when A has index 1 and the involution is of the first kind, it supports only an Hermitian form if the involution is orthogonal, and only a skew Hermitian form if the involution is symplectic.

Every orthogonally indecomposable nonsingular Hermitian or skew Hermitian space (V, h) over a simple hyperbolic involution algebra is hyperbolic (of length 2), and is uniquely determined up to equivalence.

Now let K be a real closed field, and denote by \mathbf{H} the unique quaternion division algebra $(-1,-1)_K$ over K. It is known that all simple components of KG are stable under the canonical involution (which is the identity on K), and that for each of the three possibilities $A \cong \mathbf{M}(n,D), D=K, K(\sqrt{-1}), \mathbf{H}$, the induced involution is conjugate transpose; it is orthogonal, unitary or symplectic respectively. See for example [9] or [21], 8.13.3, p. 323.

1.3. Reformulation of the equivalence of equivariant representations. The canonical trace $\operatorname{Tr}_{KG/K}=\operatorname{Tr}:KG\to K$ is the K-linear functional

$$\operatorname{Tr}(\sum_{s \in G} \alpha_s s) = \alpha_1.$$

It is clear that this is the same thing as $\frac{1}{g}\text{Tr}_{\text{reg}}$, where Tr_{reg} is the "algebra trace" arising from the regular representation.

If A_1 is a separable K-algebra, recall that $\operatorname{trd} = \operatorname{trd}_{A_1/K}: A_1 \to K$ denotes the reduced trace.

Theorem 1.5. If $A \cong M(n, D)$ is an arbitrary simple component of KG, then for all $a \in A$

(1.1)
$$\operatorname{Tr}_{KG/K}a = \frac{nd}{g}\operatorname{trd}_{A/K}a.$$

Proof. The regular trace of A is the restriction of the regular trace of KG, and is also $nd \operatorname{trd}_{A/K}$.

Let $h: V \times V \to K$ be a (nonsingular, as always) ϵ -Hermitian form with $\epsilon = \pm 1$ – if the involution on K is the identity, we interpret this to mean that h is symmetric or skew symmetric – and $\rho: G \to \mathbf{I}(V,h)$ an equivariant representation, $\mathbf{I} = \mathbf{O}, \mathbf{Sp}$, or \mathbf{U} . The equivalence class of ρ is determined by the equivalence class of the nonsingular ϵ -Hermitian form

(1.2)
$$\hat{h}: V \times V \to KG, \quad \hat{h}(u,v) = \sum_{s} h(\rho(s^{-1})u, v)s$$

over the group algebra KG with the canonical involution (cf. [8], §7). Note that

(1.3)
$$\operatorname{Tr}_{KG/K} \circ \hat{h} = h,$$

and that \hat{h} is the unique ϵ -Hermitian form on V satisfying (1.3).

Let $(KG, \bar{}) = \bigoplus_{i=1}^r (A_i, \bar{})$ be the decomposition of $(KG, \bar{})$ into simple involution components. The associated orthogonal decomposition

$$V = A_1 V \perp A_2 V \perp \cdots \perp A_r V$$

with respect to h is also an orthogonal decomposition with respect to the form \hat{h} . The restriction \hat{h}_i of \hat{h} to the isotypic component A_iV takes its values in A_i and so can be considered as an ϵ -Hermitian form $\hat{h}_i: A_iV \times A_iV \to A_i$. Since any isomorphism of KG-modules is an isomorphism on corresponding isotypic components, the equivalence class of the equivariant representation ρ is therefore determined by the equivalence classes of the \hat{h}_i . If A_i is a simple hyperbolic involution algebra, the equivalence class of \hat{h}_i is completely determined by the length of the A_i -module A_iV (see [14], §2, especially 2.3), and hence by the equivalence class of ρ as a linear representation.

This means that ρ is determined up to equivalence by its linear equivalence class and its isotypic subrepresentations $G \to \mathbf{I}(A_iV)$, where A_i runs over the simple algebras fixed by the involution of KG. Suppose that these simple algebras are A_1, \ldots, A_k .

We can now apply the Hermitian Morita theory ([8], §8, or §1.4 of this paper) to $\hat{h}_1, \ldots, \hat{h}_k$. This yields forms $\check{h}_1, \ldots, \check{h}_k$, where \check{h}_i is a symmetric, skew symmetric, Hermitian or skew Hermitian form over the division algebra which is Brauer equivalent to A_i . Once again the equivalence classes of the \check{h}_i characterize the equivalence class of ρ . Moreover, if ρ is orthogonal respectively symplectic and A_i has index 1

with \bar{h}_i symplectic respectively orthogonal, then \check{h}_i is a skew symmetric form and so is completely determined by $\dim_K A_i V$. Thus we can ignore such A_i as well.

Therefore let A_1, \ldots, A_l be the simple summands of KG such that $A_i = A_i$ and such that if ρ is orthogonal respectively symplectic and A_i has index 1, then the involution $\bar{}$ on A_i is orthogonal respectively symplectic. Then the equivalence class of ρ is determined by its equivalence class as a linear representation and by the equivalence classes of $\check{h}_1, \ldots, \check{h}_l$.

Another simple consequence of this procedure is that if $\rho: G \to \mathbf{GL}(V)$ is a given linear representation, there is always a G-invariant form h of a prescribed type on V if and only if the following holds for each simple component A of KG:

- 1. If A is stable under the involution of KG and has index 1, then len_AAV is even if either
 - (i) $(A, \bar{})$ is symplectic and h is to be symmetric, or
 - (ii) $(A, \bar{})$ is orthogonal and h is to be skew symmetric.
 - 2. $\dim_K AV = \dim_K \bar{A}V$.

Condition 1 arises from the fact that if D is a division algebra with an involution, there is a nonsingular form \check{h} of any type (symmetric, skew symmetric,...) and any given rank $m \geq 1$ over D unless D is a field with trivial involution, \check{h} is skew symmetric, and m is odd. Condition 2 results from the fact that any nonsingular ϵ -Hermitian form over a hyperbolic algebra is hyperbolic (§2, [14]).

1.4. Explicit Hermitian Morita theory and transfer theory. Suppose that D is a division algebra over K, with an involution * which is compatible with the involution on K. Let $A = \mathrm{M}(n,D)$, and denote the conjugate transpose of $a \in A$ by a^* . Let $h_0 \in \mathrm{GL}(n,D)$ be ϵ_0 -Hermitian, $h_0^* = \epsilon_0 h_0$ with $\epsilon_0 = \pm 1$. Suppose that A is given the involution $\bar{a} = h_0^{-1} a^* h_0$.

Denote by $D^{k \times l}$ the $k \times l$ matrices over D, and let * again stand for conjugate transpose $D^{k \times l} \to D^{l \times k}$. $D^{n \times k}$ is a semisimple left module over A of length k, and every (finitely generated) left module over A is of this form, up to isomorphism.

Lemma 1.6. (a) The map

$$D^{m \times k} \to \operatorname{Hom}_A(D^{n \times m}, D^{n \times k})$$

given by right multiplication is an isomorphism of M(k, D)-modules.

(b) Multiplication

$$D^{m \times n} \otimes_A D^{n \times k} \to D^{m \times k}$$

is an isomorphism of (M(m, D), M(k, D))-bimodules.

- *Proof.* (a) follows at once by looking at the homomorphisms $D^{n\times m}\to D^{n\times k}$ as matrices with respect to the direct sum decompositions of $D^{n\times m}$ and $D^{n\times k}$ into their "columns".
- (b) Every element of $D^{1\times n}\otimes_A D^{n\times 1}$ is of the form $e_{11}\otimes e'_{11}d$, where $d\in D$ and e_{11} and e'_{11} are matrix units. It follows that $D^{1\times n}\otimes_A D^{n\times 1}$ is a 1-dimensional vector space over D, and then (b) follows easily.

Now suppose that $V=D^{n\times k}$. By the foregoing lemma, $V^*=\operatorname{Hom}_A(V,A)=D^{k\times n}$. Let $f:V\times V\to (A,\bar{\ })$ be a sesquilinear form, and consider $f_r:V\to V^*$, $f_r(v)=f_r(\cdot,v)$. If we compose this map with the map $V^*\to V$ given by $x\mapsto h_0^{-1}x^*$, the result is an A-linear homomorphism $V\to V$, and so is given by

right multiplication by a matrix $b \in D^{k \times k}$. It follows that $f(\cdot, v) = \epsilon_0 b^* v^* h_0$, and so if we set $\epsilon_0 b^* = f \in M(k, D)$, we get the formula

$$(1.4) f(u,v) = ufv^*h_0.$$

Thus \underline{f} is the generalization of the notion of "discriminant matrix" (sometimes also called the "Gram matrix") of a sesquilinear form over a division ring. It is of fundamental importance in this paper.

We note that f is nonsingular if and only \underline{f} is an invertible matrix, and f is ϵ -Hermitian if and only if $\underline{f}^* = \epsilon_0 \epsilon \underline{f}$.

We give next a matrix version of Hermitian Morita theory for A = M(n, D). We refer to Chapter 4 of [20] for the "ordinary" Morita theory (between categories of modules) and to §8 of [8] for the Hermitian Morita theory.

Let B = M(m, D). We have perfect pairings

$$V \times V^* \to A, \quad V^* \times V \to B,$$

given respectively by

$$\langle v, x \rangle = vx, \quad [x, v] = xv,$$

satisfying the "associative laws"

$$\langle v, x \rangle w = v[x, w], \quad x \langle v, y \rangle = [x, v]y.$$

These data constitute a Morita context which provides a Morita equivalence between the categories ${}_A\mathcal{M}$ of left A-modules and ${}_B\mathcal{M}$ of left B-modules. The equivalence functors are $U \rightsquigarrow V^* \otimes_A U$ of ${}_A\mathcal{M}$ into ${}_B\mathcal{M}$ and $X \rightsquigarrow V \otimes_B X$ in the opposite direction.

If we restrict the Morita equivalence to the "skeletal" subcategory of ${}_{A}\mathcal{M}$ of modules of the form $D^{n\times k}$, it follows from Lemma 1.6, (b), that the resulting functor is isomorphic to $D^{n\times k}\leadsto D^{m\times k}$, with the morphism $D^{n\times k}\to D^{n\times l}$ in ${}_{A}\mathcal{M}$ given by right multiplication by a matrix in $D^{k\times l}$, being transformed into the morphism $D^{m\times k}\to D^{m\times l}$ in ${}_{B}\mathcal{M}$ given by right multiplication by the same matrix.

Suppose that h_1 is an ϵ_1 -Hermitian form over A on a simple A-module, where $\epsilon_1 = \pm 1$ – for example, one can always find such an h_1 if $\epsilon_1 = 1$ unless D = L and the involution $\bar{}$ on A is symplectic, i.e. h_0 is skew symmetric, in which case h_1 exists for $\epsilon_1 = -1$ (cf. §1.2 – this also follows easily by use of the discriminant matrix). Then an ϵ -Hermitian form \hat{h} over A is Hermitian Morita equivalent to an $\epsilon_1\epsilon$ -Hermitian form \check{h} over D, where D has the adjoint involution of h_1 . See [8], §8. The Hermitian Morita theory tells us that $\hat{h} \cong \hat{g}$ if and only if $\check{h} \cong \check{g}$.

Hermitian Morita equivalence in the case at hand is very easily described in terms of the discriminant matrix; we give it here only in the case of interest to us, when h_1 is defined on the simple module $V_1 = D^{n \times 1}$.

Lemma 1.7. A sesquilinear form f over $(A, \bar{\ })$ on $D^{n \times k}$ with discriminant matrix $\underline{f} \in M(k, D)$ corresponds, via the Hermitian Morita equivalence effected by h_1 , to the sesquilinear form over $(D, \bar{\ })$ with the discriminant matrix $\epsilon_1 \underline{f}$. The involution $\bar{\ }$ on D is the adjoint with respect to h_1 .

Proof. The discriminant matrix \underline{h}_1 of h_1 is an $\epsilon_0 \epsilon_1$ -Hermitian element of $(D,^*)$, i.e. $\underline{h}_1^* = \epsilon_0 \epsilon_1 \underline{h}_1$. The adjoint involution on D with respect to h_1 is $\bar{d} = \underline{h}_1 d^* \underline{h}_1^{-1}$.

Let \bar{V}_1 be the (A, D)-bimodule V_1 twisted into a (D, A)-bimodule by the involution \bar{V}_1 on both A and D. The ϵ_1 -Hermitian form $H: \bar{V} \times \bar{V} \to (D, \bar{V}_1)$ which effects

the Morita equivalence between the categories of sesquilinear forms over $(A, \bar{\ })$ and $(D, \bar{\ })$ respectively is defined by

$$h_1(v_1, v_2)v_3 = v_1H(\bar{v}_2, \bar{v}_3)$$
 for all $v_1, v_2, v_3 \in V$

(cf. (8.3), [8]), where \bar{v}_i stands for the vector $v_i \in V$ considered as a vector of \bar{V}_1 . Since $h_1(v_1, v_2) = v_1 \underline{h}_1 v_2^* h_0$, this implies that

(1.5)
$$H(\bar{v}_2, \bar{v}_3) = \underline{h}_1 v_2^* h_0 v_3.$$

This is the analogue of (1.4) for a form on a right module instead of a left module. Thus the discriminant matrix of H is h_0 .

We identify the twisted bimodule \bar{V}_1 with the A-dual $V_1^* = D^{1 \times n}$ via the (A, D)-bimodule isomorphism h_{1r} which takes \bar{v} to $h_1(\cdot, v) = \underline{h}_1 v^* h_0$.

Now let (U, f) be a sesquilinear form over $(A, \bar{\ })$, where $U = D^{n \times k}$, and suppose that the discriminant matrix of f is \underline{f} . We wish to find the discriminant matrix of the sesquilinear form $(\bar{V}_1 \otimes_A U, Hf)$ over D which corresponds to (U, f) under the Hermitian Morita equivalence effected by h_1 and H. Both of the mappings

$$\bar{V}_1 \otimes_A U \stackrel{h_1_r \otimes \mathrm{id}_U}{\longrightarrow} V_1^* \otimes_A U \stackrel{\mathrm{mult.}}{\longrightarrow} D^{1 \times k}$$

are isomorphisms of left *D*-spaces, and their composition takes $\bar{v} \otimes u$ to $\underline{h}_1 v^* h_0 u \in D^{1 \times k}$. We identify $\bar{V} \otimes_A U$ and $D^{1 \times k}$ by this isomorphism.

Now by definition of the product form Hf,

$$(1.6) Hf(\bar{v}_1 \otimes u_1, \bar{v}_2 \otimes u_2) = H(\bar{v}_1 f(u_1, u_2), \bar{v}_2) = H(\overline{f(u_1, u_2)} v_1, \bar{v}_2).$$

A straightforward computation shows that

$$Hf(\bar{v}_1 \otimes u_1, \bar{v}_2 \otimes u_2) = \epsilon_1(\bar{v}_1 \otimes u_1)\underline{f}(\bar{v}_2 \otimes u_2)^*h_1^{-1},$$

which implies that the discriminant matrix of Hf is $\epsilon_1 f$.

This explicit version of the Hermitian Morita theory underlies our computation of the equivalence classes of equivariant representations in the rest of the paper, and we now describe the version of it which will be used.

If the involution on A = M(n, D) is of the first kind and D is a quaternion algebra, we choose it to be conjugation * .

Now choose $h_1: V_1 \times V_1 \to A$ to be the form $h_1(u_1, v_1) = u_1 v_1^* h_0$. Then h_1 is ϵ_0 -Hermitian with respect to $\bar{}$ and its adjoint involution on D is the involution $\bar{}$ chosen above; in particular it is conjugation if it is of the first kind and D is a quaternion algebra.

We now apply Lemma 1.7 to get:

Lemma 1.8. With the foregoing notation, the ϵ -Hermitian form

$$\hat{h}: D^{n \times m} \times D^{n \times m} \to A$$

with discriminant matrix $\hat{h} \in D^{m \times m}$ (which is $\epsilon_0 \epsilon$ -Hermitian),

$$\hat{h}(u,v) = u\hat{h}v^*h_0,$$

corresponds via the Hermitian Morita theory arising from h_1 to the $\epsilon_0\epsilon$ -Hermitian form

$$\check{h}: D^{1\times m} \times D^{1\times m} \to D$$

which has discriminant matrix $\epsilon_0 \hat{\underline{h}}$,

$$\check{h}(u,v) = u\epsilon_0 \hat{\underline{h}}v^*.$$

And if D is a quaternion algebra and the involution on A is of the first kind, the involution on D is conjugation.

Remark 1.9. In the exceptional case when $(A, \bar{\ })$ is symplectic of index 1, the correspondence between forms over A and over $L=\operatorname{cen} A$ under which the form over A with matrix f corresponds to the form over L with matrix f is a category equivalence, since for example the functor $(W,g) \leadsto (W,-g)$ is certainly an automorphism of the category of bilinear forms over L. But this correspondence does *not* arise from a Morita equivalence.

We now use the discriminant matrix to compute the transfer $\operatorname{trd}_{A/L}\hat{h}$ of the ϵ -Hermitian form \hat{h} over A; the transfer is an ϵ -Hermitian form over L (symmetric or skew symmetric if \bar{h} is the identity on K).

We note that if $a = (a_{ij}) \in A$, then

$$\operatorname{trd}_{A/K} a = \sum_{i} \operatorname{trd}_{D/K} a_{ii} = \operatorname{trd}_{D/K} \sum_{i} a_{ii}.$$

Define $\operatorname{trd}_{A/D} a = \sum_i a_{ii}$. This depends on the identification $A = \operatorname{M}(n, D)$, but is nevertheless useful. The above formula becomes

$$\operatorname{trd}_{A/K} = \operatorname{trd}_{D/K} \circ \operatorname{trd}_{A/D}.$$

A straightforward matrix computation proves:

Lemma 1.10. Suppose that D = L. The discriminant matrix of $\operatorname{trd}_{A/L}\hat{h}$ (in a suitable basis) is

$$(1.7) \qquad \qquad \underline{\hat{h}} \otimes h_0^t,$$

and its determinant is

$$(1.8) \qquad (\det \underline{\hat{h}})^n (\det h_0)^m.$$

Now consider the case where A has index > 1, i.e. D is not commutative. We can suppose that h_0 and $\underline{\hat{h}}$ are diagonal matrices, say $h_0 = \langle \eta_{01}, \dots, \eta_{0n} \rangle$ and $\underline{\hat{h}} = \langle \eta_1, \dots, \eta_m \rangle$. Note that for all i and j, $\eta_{0i}^* = \epsilon_0 \eta_{0i}$ and $\eta_j^* = \epsilon_0 \epsilon \eta_j$. The one dimensional form

(1.9)
$$H_{ij}: D \times D \to D, \quad H_{ij}(u,v) = u\eta_j v^* \eta_{0i}, \quad 1 \le i \le n, 1 \le j \le m,$$

is an ϵ -Hermitian form with respect to the involution

$$(1.10) d \mapsto \eta_{0i}^{-1} d^* \eta_{0i}$$

of D. Another matrix computation proves:

Lemma 1.11. (a) The transfer $\operatorname{trd}_{A/L}\hat{h}: D^{n\times m} \times D^{n\times m} \to L$ is an ϵ -Hermitian form and is the orthogonal direct sum of the transfers from D to L of the nm forms H_{ij} in (1.9), where H_{ij} is a one dimensional ϵ -Hermitian form with respect to the involution (1.10).

(b) Suppose that $h_0 = \eta_0 I_n$ (for example, $h_0 = I_n$). Then the transfer

$$H = \operatorname{trd}_{A/D} \hat{h} : D^{n \times m} \times D^{n \times m} \to D$$

is a nonsingular ϵ -Hermitian form with respect to the involution

$$\bar{d} = \eta_0^{-1} d^* \eta_0,$$

and its transfer to L is the transfer of \hat{h} to L,

$$\operatorname{trd}_{D/L} H = \operatorname{trd}_{A/L} \hat{h}.$$

Its discriminant matrix $\underline{H} \in D^{nm \times nm}$, defined by $H(u,v) = u\underline{H}v^*\eta_0$, $u,v \in D^{1 \times nm}$, is given by

$$\underline{H} = \underline{\hat{h}} \otimes h_0.$$

If K is a non-Archimedean local field and D is the unique quaternion algebra over K, with conjugation * as its involution, it is always possible to achieve $h_0 = \eta \mathbf{I}_n$ except in the case n even and $h_0^* = -h_0$. See Table 1 in §1.

The next lemma is useful in calculating the transfers of the H_{ii} .

Let D be a central quaternion division algebra over K with an orthogonal involution $\bar{}$. There is a pure quaternion j such that $\bar{d} = j^{-1}d^*j$ for all $d \in D$, where * denotes conjugation in D (cf. §1.2).

Thus if $h:D\times D\to (D,\bar{}\,)$ is a rank 1 Hermitian form, there is another pure quaternion η such that

$$h(d_1, d_2) = d_1 \eta d_2^* j = d_1 \eta j \bar{d}_2.$$

With this notation, we have:

Lemma 1.12. The quaternary quadratic form $\operatorname{trd}_{D/K}h$ over K has determinant 1, and is isotropic (hence hyperbolic) if and only if $(\eta^2, j^2)_K \cong D$.

Proof. Conjugation by j of the space D_0 of pure quaternions is an involutory linear transformation, and it follows, by consideration of the eigenspaces, that we can find another pure quaternion $i \neq 0$ satisfying $\eta = \theta j + \delta i$ with $\theta \in K$, ij = -ji, and $\delta = 0$ or 1.

Let
$$i^2 = \alpha, j^2 = \beta$$
, so $D = (\alpha, \beta)_K$. And

$$\eta^2 = \theta^2 \beta + \delta^2 \alpha.$$

The discriminant matrix of $\operatorname{trd}_{D/L}h$ in the basis 1, k = ij, i, j of D is

$$2\beta \left(\begin{array}{cccc} \theta & -\alpha\delta & 0 & 0 \\ -\alpha\delta & -\theta\alpha\beta & 0 & 0 \\ 0 & 0 & \theta\alpha & -\alpha\delta \\ 0 & 0 & -\alpha\delta & -\theta\beta \end{array} \right).$$

Its determinant is $4\beta^2(-\theta^2\alpha\beta - \alpha^2\delta^2)^2 = 1$ in K^*/K^{*2} .

If $\theta = 0$, a glance at the above matrix shows that $\operatorname{trd}_{D/K}h$ is isotropic; furthermore $\eta = i$, so $(\eta^2, j^2)_K = D$.

Suppose $\theta \neq 0$. The forms b_1 and b_2 with matrices

$$\begin{pmatrix} \theta & -\alpha\delta \\ -\alpha\delta & -\theta\alpha\beta \end{pmatrix} \text{ and } \begin{pmatrix} \theta\alpha & -\alpha\delta \\ -\alpha\delta & -\theta\beta \end{pmatrix}$$

have the same determinant, and so their sum $b_1 \perp b_2$ is isotropic if and only if $b_2 \cong -b_1$. This is equivalent to the form $\langle \theta, -\theta^3 \alpha \beta - \theta \alpha^2 \delta^2 \rangle$ representing $\theta \beta$, hence to $\langle 1, -\theta^2 \alpha \beta - \alpha^2 \delta^2 \rangle$ representing β . Since binary forms are classified by their determinant and Hasse symbol, this in turn is equivalent to

$$(\beta, -\theta^2 \alpha \beta^2 - \alpha^2 \delta^2 \beta)_K = (1, -\theta^2 \alpha \beta - \alpha^2 \delta^2)_K = 1$$

i.e. to $(\beta, \theta^2 \alpha \beta + \alpha^2 \delta^2)_K = 1$. Thus the condition is

$$1 = (\beta, \alpha)_K (\beta, \theta^2 \beta + \alpha \delta^2)_K = (\beta, \alpha)_K (j^2, \eta^2)_K,$$

i.e.
$$D = (\alpha, \beta)_K \cong (\eta^2, j^2)_K$$
.

2. Symplectic Representations

Because of the fact that two nonsingular skew symmetric forms are equivalent if and only if they have the same rank, symplectic representations are considerably easier to deal with than are orthogonal or unitary representations, and so we treat them separately here.

We now prove the statements on symplectic representations given earlier.

We identify A = M(n, D) and $V = D^{n \times m}$. The involution on A is of the form $\bar{a} = h_0^{-1} a^* h_0$ – see §1.2.

If $\underline{\hat{h}}$ is an $m \times m$ matrix, the form $h(u,v) = \text{Tr}_{A/K}(u\underline{\hat{h}}v^*h_0)$ on $D^{n\times m}$ will be skew symmetric if and only if $\hat{h}(u,v) = u\underline{\hat{h}}v^*h_0$ is skew Hermitian.

Suppose that $(A, \bar{})$ is orthogonal and of index 1. Then $\underline{\hat{h}}$ must be skew symmetric (in order for h to be skew symmetric). This verifies **II** (in the orthogonal case) for any field K if $(A, \bar{})$ has index 1. This is always the case if K is finite or real closed – see §1.2 – which proves **I** for these fields (by Table 1).

Suppose next that $(A, \bar{\ })$ is orthogonal but has index > 1. Recall that we assume that the involution * on D is symplectic when $D \neq L$. Since h_0 is then skew Hermitian, $\underline{\hat{h}}$ must be an Hermitian matrix, so the equivalence classes of symplectic representations on V are in bijective correspondence with the equivalence classes of Hermitian forms of rank m over D by Hermitian Morita theory. There is only 1 when K is local, by Table 1.

Now suppose that K is global. We must count the number of Hermitian forms \check{h} of rank m over D, a quaternion division algebra with the canonical involution. If D splits at the prime \mathfrak{p} of its center L, $\check{h}_{\mathfrak{p}}$ is an Hermitian form over $\mathrm{M}(2, L_{\mathfrak{p}})$ with a symplectic involution. Thus we can assume that $\check{h}_{\mathfrak{p}}(u,v)=u\underline{\hat{h}}v^th_1$, where h_1 is a skew symmetric matrix of degree 2. Therefore, as a $2m\times 2m$ matrix over $L_{\mathfrak{p}}$, $\underline{\hat{h}}$ is skew symmetric and so is uniquely determined up to equivalence.

We note that D does split at every real prime \mathfrak{p} of the center, since $(A, \bar{\ })$ is orthogonal – cf. §1.2.

If D is not split at the finite prime \mathfrak{p} , $\check{h}_{\mathfrak{p}}$ is an Hermitian form over the local division algebra $D_{\mathfrak{p}}$ and so is again uniquely determined up to equivalence by its rank (cf. Table 1). By the Hasse Principle for Hermitian forms over D (cf. Table 1), this finishes the proof for $(A, \bar{})$ orthogonal.

Suppose now that $(A, \bar{\ })$ is symplectic. This means that h_0 is skew symmetric if A has index 1 and is Hermitian otherwise. Then $h(u,v)=\operatorname{trd}_{A/K}(u\hat{\underline{h}}v^*h_0)$ is an invariant skew symmetric form on $D^{n\times m}$ if and only if $\hat{\underline{h}}$ is nonsingular and symmetric in the first case and skew Hermitian in the second. The cases of K finite, or K global, or K local and A of index 1 follow easily. If K is real closed, A is necessarily of index > 1 (§1.2); by Table 1, skew Hermitian forms over D are classified by their rank and so there is only 1 equivalence class of symplectic representations in this case. Finally, the case of K local and $(A, \bar{\ })$ of index > 1 follows from [21], Theorem 10.3.6.

The case (A^-) unitary is proved in a similar manner. Note that (noncommutative) division algebras over local or real closed fields do not admit involutions of the second kind – in the real closed case, A admits a unitary involution if and only if A is a full matrix algebra over the algebraic closure of K, again by §1.2.

Now III. If G is a symmetric group, it is well known that all of the simple components of KG are split and stable under the canonical involution, and that the induced involution in each case is orthogonal (cf. §6). This proves III in this case (by II). Now consider 2, 3 and 4. The assumption of odd representation type rules out both a symplectic involution and an orthogonal involution on an algebra of Schur index > 1. So III is clear if K is finite. Otherwise conditions 3 and 4 both rule out a unitary involution which is not hyperbolic. Thus each simple component A of KG, stable under the canonical involution and for which $AV \neq 0$, is orthogonal of index 1.

Finally, consider the statement on conjugacy of subgroups of $\mathbf{Sp}(V,h)$. Since G and G' are conjugate in $\mathbf{GL}(V)$, there is a $\phi \in \mathbf{GL}(V)$ such that $s \mapsto \phi^{-1}s\phi$ is an isomorphism $G \to G'$. This map and the identity are symplectic representations which are linearly equivalent, so by \mathbf{III} we can find $\psi \in \mathbf{Sp}(V,h)$ such that $s \to \psi^{-1}s\psi$ is an isomorphism $G \to G'$.

3. Unitary and orthogonal representations over finite fields

If K is a finite field, the simple algebra A is a matrix algebra $\mathcal{M}(n,L)$ over the field L.

Theorem 3.1. Let K be a finite field, A a simple K-algebra and V an A-module of length $len_AV = m$.

Let $h: V \times V \to K$ be a symmetric, Hermitian or skew Hermitian form.

I, II.

Unitary representations. There is exactly 1 equivalence class of A-isotypic unitary representations $G \to \mathbf{U}(V,h)$, in both the Hermitian and skew Hermitian cases.

Orthogonal representations. If h is symmetric, then the number of equivalence classes of A-isotypic orthogonal representations $G \to \mathbf{O}(V, h)$ is

- (a) 1 if $(A, \bar{})$ is symplectic, m is even and h is hyperbolic,
- (b) 1 if $(A, \bar{})$ is orthogonal and n is odd,
- (c) 2 if $(A, \bar{})$ is orthogonal, n is even and $\det h = N_{L/K}(\det(\bar{}))^m$,
- (d) 1 if $(A, \bar{})$ is unitary and det $h = (-\operatorname{disc}(L/L_0))^{mn|L_0^*|/|K^*|}$,

and is 0 otherwise.

III.

Unitary representations. Two unitary representations of G over K are equivalent if and only if they are linearly equivalent.

Orthogonal representations. Two orthogonal representations of G over K are equivalent if and only if they are linearly equivalent and their forms are isotypically equivalent, unless KG has a simple orthogonal component $(A, \bar{\ })$ of even degree for which $AV \neq 0$.

If $\rho: G \to \mathbf{O}(V,h)$ is an orthogonal representation and r is the number of orthogonal components (A^-) of even degree for which $AV \neq 0$, the number of

equivalence classes of orthogonal representations $G \to \mathbf{O}(V,h)$ which are linearly equivalent to ρ is 2^r .

In particular, two orthogonal representations of G of odd type are equivalent if and only if they are equivalent as linear representations and have isotypically equivalent forms.

Corollary 3.2. If K is a finite field, two subgroups of $\mathbf{U}(V,h)$ which have order relatively prime to char K are conjugate in $\mathbf{U}(V,h)$ if and only if they are conjugate in $\mathbf{GL}(V)$.

Proof of the theorem. We view the succession of equivalences $\rho \leadsto \hat{h} \leadsto \check{h}$ (cf. §1.3) in the reverse direction. Thus we consider all possibilities for \check{h} (up to equivalence) and $(A, \bar{\ })$, and for each such pair $\check{h}, (A, \bar{\ })$ we determine the form h by first determining \hat{h} by Hermitian Morita theory using Lemma 1.8, and then $h = \frac{n}{g} \mathrm{trd}_{A/K} \hat{h}$ via the transfer theory using Lemma 1.10. The equivalence classes of h's so obtained are those whose forms which admit an equivariant representation linearly equivalence class of h is the number of equivalence classes of h's which lead to the equivalence class of h is the number of nonequivalent orthogonal representations $G \to \mathbf{O}(V,h)$ or unitary representations $G \to \mathbf{U}(V,h)$.

We use the notation of Lemma 1.8. The form \check{h} is a symmetric, skew symmetric, Hermitian or skew Hermitian form over L on L^m with matrix $\epsilon_0 \hat{\underline{h}}$.

Suppose first that \check{h} is skew symmetric – in particular, m is even and the involution on K is the identity. If the involution on A is orthogonal, the form \hat{h} is skew Hermitian and the form h must be skew symmetric. This case is already handled in $\S 2$.

If \check{h} is skew symmetric and the involution on A is symplectic, \hat{h} is an Hermitian form over A on $L^{n\times m}$, and its transfer $h'=\operatorname{trd}_{A/L}\hat{h}$ is a symmetric form over L on $L^{n\times m}$ with matrix $\underline{\hat{h}}\otimes h_0^t$ (cf. §1.4) which, since h_0 and $\underline{\hat{h}}$ are both skew symmetric, is hyperbolic. Thus $\operatorname{Tr}_{L/K}(h')=\operatorname{trd}_{A/K}\hat{h}$ is also hyperbolic, and so also $h=\operatorname{Tr}\hat{h}=\frac{n}{a}\operatorname{trd}_{A/K}\hat{h}$. This is (a).

Now suppose that \check{h} is symmetric. If the involution on A is symplectic, \check{h} is skew Hermitian, so $\operatorname{Tr} \hat{h} = \frac{n}{q} \operatorname{trd}_{A/K} \hat{h}$ is skew symmetric and can be disregarded.

If \check{h} is symmetric and the involution is orthogonal, \hat{h} is Hermitian, and $\operatorname{trd}_{A/L}\hat{h}$ is symmetric; moreover by the determinant formula $\det(\operatorname{trd}_{A/L}\hat{h}) = (\det \hat{\underline{h}})^n (\det h_0)^m$ (cf. (1.8)), the two possibilities for \check{h} (up to equivalence) give rise to two nonequivalent transfers $\operatorname{trd}_{A/L}\hat{h}$ if n is odd, while if n is even there is only one possibility for $\operatorname{trd}_{A/L}\hat{h}$, up to equivalence. Moreover in the latter case, $\operatorname{trd}_{A/L}\hat{h}$ has determinant $(\det h_0)^m = (\det(\bar{}))^m$. Since the norm $N_{L/K}$ preserves nonsquares, by Lemma 1.1 the same thing is true for $\operatorname{trd}_{A/K}\hat{h} = \operatorname{Tr}_{L/K}\operatorname{trd}_{A/L}\hat{h} = \frac{g}{n}\operatorname{Tr}_{KG/K}\hat{h} = \frac{g}{n}h$ (namely two nonequivalent forms when n is odd, and one when n is even), so also for h, where h has determinant $(\frac{n}{g})^{lmn}N_{L/K}(\det h_0)^m = N_{L/K}(\det(\bar{}))^m$ in K^*/K^{*2} when n is even. This gives (b) and (c).

Now suppose that the involution on A is of the second kind, so we can take $h_0 = \mathbf{I}_n$ since Hermitian forms over a finite field are characterized by their dimension (cf. Table 1). Consider first the case where the involution on K is the identity. If \check{h} is skew Hermitian, h is skew symmetric. If \check{h} is Hermitian, we get one class of orthogonal representations for the form h since there is only one equivalence class of

Hermitian forms of a given rank. Furthermore if $L = L_0(\sqrt{\lambda_0})$, h has discriminant

$$N_{L_0/K}(-\lambda_0)^{mn} = (-\lambda_0)^{|L_0^*|/|K^*|}$$

by Lemma 1.1, since $\operatorname{trd}_{A/L}\hat{h}$ has matrix $I_m \otimes I_n$ and the discriminant of the binary symmetric form $\operatorname{Tr}_{L/L_0}(x\bar{y})$ on L is $-\lambda_0$. This is (d).

Now suppose the involution on K is also not the identity. There is only one equivalence class of skew Hermitian forms on L^m , and it gives rise to a single equivalence class of unitary representations (with respect to a skew Hermitian form). Similarly we get a single equivalence class of unitary representations with respect to an Hermitian form from the unique equivalence class of Hermitian forms on L^m .

III is clear from I and II. \Box

4. Unitary and orthogonal representations over local fields

If \mathcal{A} is an Abelian group, $\sigma_2(\mathcal{A})$ denotes the number of square classes $(\mathcal{A}:\mathcal{A}^2)$. In this section K is a local (non-Archimedean) field. It is "dyadic" if 2 is not a unit, "nondyadic" otherwise, and

$$\sigma_2(L^*) = (L^* : L^{*2}) = \begin{cases} 4 & \text{if } L \text{ is nondyadic,} \\ 2^{2+(L:\mathbb{Q}_2)} & \text{if } L \text{ is dyadic,} \end{cases}$$

([21], p. 217). Let g_K denote the unique quaternary anisotropic form over K, and \mathcal{G} the (Abelian) Galois group $\operatorname{Gal}(L/K)$.

The integer m' in part (k) of the next theorem is

$$m' = \begin{cases} 2 & \text{if } m = 1 \text{ and either } n \text{ is odd and } h \sim_W 0, \\ & \text{or } n \text{ is even and } h \sim_W g_K, \\ m & \text{otherwise.} \end{cases}$$

Theorem 4.1. Let K be a local field, $A \cong M(n, D)$ a simple algebra component of KG stable under $\bar{}$, and V an A-module of length len $_AV = m$.

Let $h: V \times V \to K$ be a symmetric or Hermitian form.

Unitary representations. The number of equivalence classes of A-isotypic unitary representations $G \to \mathbf{U}(V,h)$ is

and 0 otherwise.

Orthogonal representations. The number of equivalence classes of A-isotypic orthogonal representations $G \to \mathbf{O}(V,h)$ is

and 0 otherwise.

Remark 4.2. 1. In (f) and (g), $\sigma_2(L^*) = \sigma_2(K^*)$ if K is nondyadic, $\sigma_2(\mathcal{G}) = 1$ and $(N_{L/K}L^*)K^{*2} = K^*$ if (L:K) is odd.

2. In (g), $\langle \alpha h_0 \rangle$ is the symmetric form of rank n and matrix αh_0 . The determinant of its trace $\text{Tr}_{L/K} \langle \alpha h_0 \rangle$ is $\text{disc}(L/K) \text{N}_{L/K} (\alpha \det h_0)$. Its Hasse symbol can be calculated using [6], Lemma 1, 3, but the result unfortunately involves the unknown factor $\text{S}_K(\langle \alpha \operatorname{disc} h_0 \rangle)$, the Hasse symbol of a "scaled trace form" of the extension L/K. It is possible, however, to give complete results when K is a nondyadic field; this is carried out in Theorem 4.9.

We note that the discriminants of the h in this case are

$$(\frac{n}{g})^l(\operatorname{disc}(L/K))(\operatorname{N}_{L/K}L^*)K^{*2}$$

and, by Remark 1, the number of equivalence classes is 1 if l is odd and K is nondyadic, or if A is split.

3. In (i), $S(h_0)$ is well-defined. In fact, by Lemma 1.3 (i), if $\eta \in L^*$ then

$$S(\eta h_0) = S(h_0)(\eta, -1)_L^{n(n-1)/2}(\eta, (-1)^{n(n-1)/2})_L = S(h_0),$$

since disc $h_0 = 1$ implies that det $h_0 = (-1)^{n(n-1)/2}$.

4. The integer m can be calculated easily from a knowledge of h and $(A, ^-)$. Namely, the rank of h is mnd^2l .

Proof. The proof proceeds in the same way as that of Theorem 3.1, starting with the form

$$\check{h}:D^m\times D^m\to D$$

and then "descending" first to

$$\hat{h}: D^{n \times m} \times D^{n \times m} \to M(n, D) = A$$

via Morita theory using Lemma 1.8, then to

$$\operatorname{trd}_{A/D}\hat{h}: D^{nm} \times D^{nm} \to D$$

via a transfer from A to D, then to

$$\operatorname{trd}_{D/L}\operatorname{trd}_{A/D}\hat{h} = \operatorname{trd}_{A/L}\hat{h} : L^{d^2nm} \times L^{d^2nm} \to L$$

(where $d^2 = \dim_L D = 1$ or 4) via a transfer from D to L, and then finally to

$$\frac{nd}{g}\mathrm{trd}_{L/K}\mathrm{trd}_{A/L}\hat{h} = \frac{nd}{g}\mathrm{trd}_{A/K}\hat{h} = \mathrm{Tr}_{KG/K}\hat{h} = h: K^{ld^2nm} \times K^{ld^2nm} \to K$$

via the transfer from L to K. The "reduced trace" $\mathrm{trd}_{A/D}$ is defined just before Lemma 1.10.

 $\check{h}:L^m\times L^m\to L$ skew symmetric. This means that $\underline{\hat{h}}$ is a skew symmetric matrix (Lemma 1.7), m is even, and A has index 1. If the involution on A is orthogonal, i.e. $h_0^*=h_0$ so $\epsilon_0=1$, then \hat{h} is skew Hermitian (cf. p. 4698), and so $\mathrm{trd}_{L/K}\hat{h}=\frac{g}{n}h$ and h are skew symmetric. Since the skew symmetric case is handled in §2, we ignore it here.

If the involution on A is symplectic, h_0 is skew symmetric and \hat{h} is Hermitian. The transfer $\operatorname{trd}_{A/L}\hat{h}$ is symmetric on L^{nm} with discriminant matrix $-\hat{\underline{h}}\otimes h_0$ by (1.7). This implies readily that $\operatorname{trd}_{A/L}\hat{h}$ is hyperbolic, and so $\operatorname{trd}_{A/K}\hat{h}$ and h are also hyperbolic. Thus we get exactly one orthogonal representation, up to equivalence, and it is on a hyperbolic space. This is the index 1 case of (e).

 $\check{h}:L^m\times L^m\to L$ symmetric. Thus $\hat{\underline{h}}$ is a symmetric matrix. If the involution on A is symplectic, \hat{h} is skew Hermitian and h is skew symmetric, and this is already handled elsewhere.

Now suppose the involution on A is orthogonal. Then \hat{h} is Hermitian and the transfer $\operatorname{trd}_{A/L}\hat{h}$ is a symmetric form on L^{nm} with discriminant matrix $\underline{\hat{h}} \otimes h_0$ and determinant $(\det \underline{\hat{h}})^n (\det h_0)^m$ (cf. Lemma 1.10), and h is symmetric as well.

Consider first the case n odd. Then the determinant of $b = \operatorname{trd}_{A/L} \hat{h}$ is

$$(\det \hat{\underline{h}})(\det h_0)^m$$

and so is arbitrary since $\det(\underline{\hat{h}}) = \det \check{h}$ is arbitrary. Assume also that m > 1. Then by Lemma 1.3 (iv), the Hasse symbol of b is also arbitrary; in other words, b runs over all equivalence classes of symmetric forms on L^{nm} as \check{h} runs over all equivalence classes of symmetric forms on L^m – thus the correspondence is bijective. Now consider the transfer $b_K = \operatorname{trd}_{L/K} b$. Since L/K is Abelian,

$$l = [L : K] = [K^* : N_{L/K}L^*]$$

by local class field theory, and it follows that, when l is odd, the map

$$\bar{N}: L^*/L^{*2} \to K^*/K^{*2}$$

induced by the norm is onto; thus it is an isomorphism when K is nondyadic, and in general has kernel of order $\sigma_2(L^*)/\sigma_2(K^*)$. This means there are exactly

 $\sigma_2(L^*)/\sigma_2(K^*)$ equivalence classes of orthogonal representations for each symmetric form on K^{lnm} by Lemmas 1.1 and 1.2. This gives (f) when l is odd.

Suppose that l is even. The image of \bar{N} is $(N_{L/K}L^*)K^{*2}/K^{*2}$, and by local class field theory, $(N_{L/K}L^*)K^{*2}$ consists of the norms from the compositum of the quadratic extensions of K contained in L; the degree of this compositum over K is $\sigma_2(\mathcal{G}) = (\mathrm{Gal}(L/K) : \mathrm{Gal}(L/K)^2)$. Thus since $(L^* : L^{*2}) = |\mathrm{im}\bar{N}| \cdot |\ker \bar{N}|$, each b_K is, up to equivalence, the image of $|\ker \bar{N}|$ of the b, where

$$|\ker \bar{\mathbf{N}}| = \sigma_2(L^*)\sigma_2(\mathcal{G})/\sigma_2(K^*).$$

Thus in this case the symmetric forms on K^{lmn} which support an orthogonal representation of G which is linearly equivalent to ρ are those with determinant in $(\operatorname{disc}(L/K))^{mn}(N_{L/K}L)^*K^{*2}$ (since $(g/n)^{lmn}$ is a square), and each of them supports $|\ker \bar{\mathbf{N}}|$ different orthogonal equivalence classes of orthogonal representations. This completes the proof of (f).

Now suppose that n is odd and m=1. If $\underline{\hat{h}}=(\alpha)$, $b=\operatorname{trd}_{A/L}\hat{h}=\langle\alpha\,h_0\rangle$, which has determinant $\alpha^n \det h_0$. Since n is odd, we get one form b over L for each possible discriminant $\alpha \in L^*/L^{*2}$. By the same analysis as in the case m>1, the discriminants which occur among the transfers b_K down to K are $(\operatorname{disc}(L/K))(N_{L/K}L^*)K^{*2}$ and each discriminant receives $\frac{\sigma_2(\mathbf{G})\sigma_2(L^*)}{\sigma_2(K^*)}$ of the b. This proves (g). We note also that this shows that the possible discriminants of h are $(\frac{n}{a})^l(\operatorname{disc}(L/K))(N_{L/K}L^*)K^{*2}$, as mentioned in Remark 2 after the theorem.

Now consider the case when n is even (and the involution of A is orthogonal). The determinant of the transfer $b = \operatorname{trd}_{A/L} \hat{h}$ down to L is the same for all \check{h} , namely $(\det h_0)^m$, and

(4.3)
$$S(b) = S(\hat{\underline{h}} \otimes h_0) = S(h_0)^m (\det \hat{\underline{h}}, \operatorname{disc} h_0)_L (\det h_0, -1)_L^{m(m-1)/2}$$

by Lemma 1.3 (iv). If disc $h_0 \notin L^{*2}$, this implies that we get both forms of determinant $(\det h_0)^m$ over L, and so, by Lemmas 1.1 and 1.2, both forms of determinant $(\operatorname{disc}(L/K))^{mn} \mathcal{N}_{L/K} (\det h_0)^m = \mathcal{N}_{L/K} (\det h_0)^m$ over K via the transfer from L to K. Furthermore, by (4.3) one of the forms arises from those \check{h} whose determinants are in the kernel of canonical homomorphism

$$L^*/L^{*2} \to L^*/N_{L(\sqrt{\operatorname{disc} h_0})/L}L(\sqrt{\operatorname{disc} h_0})^* \cong \mathbb{Z}/2,$$

so the number of equivalence classes of orthogonal representations for each of the two forms is $\sigma_2(L^*)$ if m > 1, $\frac{1}{2}\sigma_2(L^*)$ if m = 1. This is (h).

On the other hand, disc $h_0 \in L^{*2}$ means that det $h_0 = (-1)^{n(n-1)/2} = (-1)^{n/2}$ and det $b = (-1)^{mn/2}$; in this case we get only *one* form over L as a transfer – that with determinant $(-1)^{mn/2}$ and Hasse symbol

$$S(b) = S(h_0)^m (-1, -1)_L^{mn(m-1)/4}.$$

Therefore there we get only one G-invariant symmetric form b_K over K. Its determinant is $(\operatorname{disc}(L/K))^{mn} N_{L/K}(-1)^{mn/2} = (-1)^{lmn/2}$, and we now determine its equivalence class.

Suppose first that mn/2 is even. Then det b=1 and dim $b=mn\equiv 0 \mod 4$, so $b\sim_W 0$ or $b\sim_W g_L$. Moreover, by Lemma 1.3(v),

$$b \sim_W 0 \Leftrightarrow S(b) = (-1, -1)_L^{mn/4}$$

$$\Leftrightarrow S(h_0)^m (-1, -1)_L^{mn(m-1)/4} = (-1, -1)_L^{mn/4}$$

$$\Leftrightarrow S(h_0)^m = (-1, -1)_L^{m^2n/4}.$$

On the other hand, if mn/2 is odd, then $\det b = -1$ and $\dim b \equiv 2 \mod 4$, so if c is a hyperbolic plane, $\det(b \perp c) = 1$ and $\dim(b \perp c) \equiv 0 \mod 4$, and so since $b \sim_W b \perp c$, we see again that $b \sim_W 0$ or $b \sim_W g_L$. Now $S(b \perp c) = S(b)(-1, -1)_L$ by Lemma 1.3 (ii), and by applying the same kind of argument to $b \perp c$ as we did above to b, we get (i).

 $\check{h}:L^m\times L^m\to L$ skew Hermitian. The involution on A is unitary, so we are assuming that h_0 is an Hermitian matrix, $h_0^*=h_0$. The form \hat{h} and its discriminant matrix $\underline{\hat{h}}$ are skew Hermitian. If the involution is the identity on K, h is skew symmetric and we can ignore it.

Suppose therefore that the involution is not the identity on K, say $K = K_0(\sqrt{\lambda_0})$; then also $L = L_0(\sqrt{\lambda_0})$. The transfer $\operatorname{trd}_{A/L}\hat{h}$ is a skew Hermitian form over L of rank mn and determinant $(\det \hat{\underline{h}})^n (\det h_0)^m$. Write $\hat{\underline{h}} = \sqrt{\lambda_0} \hat{\underline{h}}_1$, where $\hat{\underline{h}}_1$ is an Hermitian matrix. Then the determinant of $\operatorname{trd}_{A/L}\hat{h}$ is $\sqrt{\lambda_0}^{mn} (\det \hat{\underline{h}}_1)^n (\det h_0)^m$, and $\det \hat{\underline{h}}_1$ and $\det h_0$ are both in L_0^* .

If n is even, we get but one form (up to equivalence) as a transfer over L — it has determinant $(\lambda_0^{\frac{n}{2}} \det h_0)^m$ — and so only one transfer down to K, of determinant $N_{L/K}(\lambda_0^{\frac{n}{2}} \det h_0)^m$ by Lemma 1.1. This form gives rise, then, to two inequivalent unitary representations with respect to this unique skew Hermitian form. This is the skew Hermitian version of (b) (cf. the definition of disc h in §1.1).

Suppose now that n is odd. Then there are two transfers (up to equivalence) down to L, with their determinants representing the two possible classes in $L^*/\mathcal{N}_{L/L_0}L^*$. Since the restriction of $\mathcal{N}_{L/K}$ to L_0 is \mathcal{N}_{L_0/K_0} , the following lemma and Lemma 1.1 imply that their transfers down to K are also distinct, and so we have 2 distinct skew Hermitian forms over K each with a single unitary representation. This is the skew Hermitian version of (a).

Lemma 4.3. The homomorphism $\bar{N}: L_0^*/N_{L/L_0}L^* \to K_0^*/N_{K/K_0}K^*$ induced by N_{L_0/K_0} is onto.

Proof. Let $\operatorname{Gal}_{L_0}^{ab}$ be the Galois group of the Abelian closure L_0^{ab} of L_0 in some separable closure. Define $\operatorname{Gal}_{K_0}^{ab}$ similarly, using the same separable closure. Let Gal_{L_0} and Gal_{K_0} be the absolute Galois groups of L_0 and K_0 . We may assume $\operatorname{Gal}_{L_0} \subset \operatorname{Gal}_{K_0}$, and this inclusion induces a homomorphism

$$\operatorname{Gal}_{L_0}^{ab} = \operatorname{Gal}_{L_0}/\operatorname{Gal}_{L_0}' \xrightarrow{i} \operatorname{Gal}_{K_0}^{ab} = \operatorname{Gal}_{K_0}/\operatorname{Gal}_{K_0}', \sigma \operatorname{Gal}_{L_0}' \mapsto \sigma \operatorname{Gal}_{K_0}'.$$

This fits into the commutative diagram

$$L_0^* \longrightarrow \operatorname{Gal}_{L_0}^{ab}$$

$$\downarrow_i$$

$$K_0^* \longrightarrow \operatorname{Gal}_{K_0}^{ab}$$

where the horizontal maps are given by the norm residue symbol – cf. [2], p. 141. This implies a commutative diagram

where the right vertical map is restriction – and is an isomorphism. Since the horizontal maps are isomorphisms by local class field theory, \bar{N} is an isomorphism as well

 $\check{h}:L^m\times L^m\to L$ Hermitian. Again h_0 is Hermitian and the involution is unitary. The transfer $\mathrm{trd}_{A/L}\hat{h}$ of \hat{h} down to L is Hermitian with determinant $(\det \underline{\hat{h}})^n(\det h_0)^m$. Thus if n is even we get only one form over L (up to equivalence), while if n is odd we get two.

We consider first the case when the involution is the identity on K (so h is symmetric) and n is even. Thus $\operatorname{trd}_{A/L}\hat{h}$ has determinant $(\det h_0)^m$. The transfer of a rank 1 Hermitian form with matrix (η) over $L = L_0(\sqrt{\lambda_0})$ down to L_0 is the symmetric form $\langle 2\eta, -2\eta\lambda_0 \rangle$, so the transfer of \hat{h} down to L_0 is the symmetric form of rank 2mn with matrix $\operatorname{trd}_{A/L}(\hat{h} \otimes \langle 2, -2\lambda_0 \rangle)$, under the assumption that $\operatorname{trd}_{A/L}\hat{h}$ is diagonal – in fact we can assume that $\operatorname{trd}_{A/L}\hat{h} = \langle 1, \ldots, 1, (\det h_0)^m \rangle$. The determinant of this form over L_0 is

$$(\det \operatorname{trd}_{A/L}\hat{h})^2(-\lambda_0)^{mn} = 1,$$

and by Lemma 1.3 (iv) its Hasse invariant is

$$(-1,-1)_{L_0}^{mn/2}((-1)^{n/2}\det h_0,\lambda_0)_{L_0}^m.$$

Since its rank is divisible by 4, it is $\sim_W 0$ or g_{L_0} , and is $\sim_W 0$ if and only if $(-1,-1)_{L_0}^{mn/2}((-1)^{n/2}\det h_0,\lambda_0)_{L_0}^m=(-1,-1)_{L_0}^{mn/2}$ by Lemma 1.3; this condition is equivalent to $(-1)^{mn/2}(\det h_0)^m\in \mathrm{N}_{L/L_0}L^*$. By Lemma 1.2, the same situation obtains when we take the transfer down to K, and in either case we get a single symmetric form h supporting 2 nonequivalent orthogonal representations. This is (d).

Now suppose that the involution is the identity on K and n is odd. As in the case n even, the two transfers to L_0 have matrix $(\operatorname{trd}_{A/L}\hat{h}) \otimes \langle 2, -2\lambda_0 \rangle$. Their determinants are both $(-\lambda_0)^{mn} = (-\operatorname{disc}(L/L_0))^m$, and their Hasse invariants are given by

$$\left((-1)^{m(mn-1)/2} (2 \det h_0)^m \det \underline{\hat{h}}, \ \lambda_0 \right)_{L_0} (-1, -1)_{L_0}^{m(mn-1)/2}.$$

These Hasse invariants are distinct since $\det \underline{\hat{h}}$ represents both norm residue classes in $L_0^*/N_{L/L_0}L^*$, and so the transfers to L_0 remain distinct. Both transfers to K have determinant $N_{L_0/K}(-\operatorname{disc}(L/L_0))^m$, and they remain inequivalent by Lemma 1.2. This is (c).

Now suppose the involution is *not* the identity on K. As before, the transfer $\operatorname{trd}_{A/L}\hat{h}$ is an Hermitian form over L with determinant $(\det \hat{h})^n(\det h_0)^m$. If n is even, we get but one form (up to equivalence) as a transfer over L — it has determinant $(\det h_0)^m$ and rank mn — and so also only one transfer down to K, of determinant $N_{L_0/K_0}(\det h_0)^m$ by Lemma 1.1 and rank lmn. Thus this form

supports two inequivalent unitary representations. This is (b) in the Hermitian case.

If n is odd, there are two distinct transfers (up to equivalence) down to L, with determinants $\det \hat{h}(\det h_0)^m$ representing the two norm classes in $L_0^*/N_{L/L_0}L^*$. By Lemmas 1.1 and 4.3, their transfers down to K are also inequivalent, and so we have two inequivalent Hermitian forms over K, each with a single unitary representation. This is (a) in the Hermitian case.

The remaining cases involve A of index > 1. Thus A = M(n, D), where D is a quaternion division algebra over K with conjugation * as its involution. Since an Hermitian or skew Hermitian form over D has an orthogonal basis, we can suppose that h_0 is diagonal, say $h_0 = \langle \eta_{01}, \ldots, \eta_{0n} \rangle$, where $\eta_{0j}^* = \epsilon_0 \eta_{0j}$ for all j. If $\epsilon_0 = 1$, we can assume that $h_0 = I_n$ (cf. Table 1).

Similarly h is either Hermitian or skew Hermitian, and we can assume that its matrix $\epsilon_0 \underline{\hat{h}}$ is diagonalized, say $\underline{\hat{h}} = \langle \eta_1, \dots, \eta_m \rangle$, and that $\underline{\hat{h}} = I_m$ if \check{h} is Hermitian.

 $\check{h}: D^m \times D^m \to D$ Hermitian. Suppose first that h_0 is Hermitian (i.e. $(A, \bar{\ })$ is symplectic of index > 1 – cf. §1.2), so $h_0 = I_n$, $\hat{\underline{h}} = I_m$, and $\hat{h}(u,v) = uv^*$. By Lemma 1.11, (b), if we define the "trace" $\operatorname{trd}_{A/D}(a_{ij}) = \sum_i a_{ii}$, then $\operatorname{trd}_{A/D}\hat{h}$ is the nonsingular Hermitian form on D^{nm} with respect to conjugation, with discriminant matrix I_{nm} . Furthermore $\operatorname{trd}_{A/L}\hat{h} = \operatorname{trd}_{D/L}\operatorname{trd}_{A/D}\hat{h}$, and so it follows that $\operatorname{trd}_{A/L}\hat{h}$ is the orthogonal direct sum of nm copies of the norm form g_L of D. Since $g_L \perp g_L$ is hyperbolic, $\operatorname{trd}_{A/L}\hat{h}$ is hyperbolic of rank 4nm if n or m is even – in which case $\operatorname{trd}_{A/K}\hat{h}$ is also hyperbolic, of rank 4lnm. Otherwise $\operatorname{trd}_{A/L}\hat{h} \sim_W g_L$, and by Lemma 1.2, $\operatorname{trd}_{A/K}\hat{h} \sim_W g_K$.

In each of these two cases, nm even or odd, we get a unique orthogonal representation linearly equivalent to ρ . This is (e) in the nonsplit case.

If h_0 is skew Hermitian $((A, \bar{\ })$ is orthogonal with index > 1), then \hat{h} is also skew Hermitian. It follows that $\operatorname{trd}_{A/K}\hat{h}$ is skew symmetric, so we can ignore it.

 $\check{h}: D^m \times D^m \to D$ skew Hermitian. If h_0 is Hermitian $((A, \bar{\ })$ symplectic with index > 1), then \hat{h} is skew Hermitian and the transfer $\operatorname{trd}_{A/K}\hat{h}$ is a skew symmetric form (on K^{4lnm}).

Suppose then that $(A, \bar{})$ is orthogonal, so h_0 is skew Hermitian, \hat{h} is Hermitian and $\hat{\underline{h}}$ is a skew Hermitian matrix. By Lemma 1.11(a), $\operatorname{trd}_{A/L}\hat{h}$ is the orthogonal direct sum of the mn transfers

$$h_{ij}(u,v) = \operatorname{trd}_{D/L}(u\eta_i v^* \eta_{0j}) \quad (1 \le i \le m, 1 \le j \le n)$$

of one dimensional forms over D. By Lemma 1.12, h_{ij} is a quaternary symmetric form of determinant 1, and is hyperbolic if and only if $(\eta_i^2, \eta_{0j}^2)_L = -1$. It follows that $\operatorname{trd}_{A/L} \hat{h} \sim_W 0$ if and only if

$$\prod_{i,j} (\eta_i^2, \eta_{0j}^2)_L = (-1)^{mn},$$

and otherwise it is $\sim_W g_L$. Now

$$\prod_{i} \eta_{i}^{2} = \prod_{i} (-\eta_{i} \eta_{i}^{*}) = \prod_{i} (-\operatorname{nrd}_{D/L} \eta_{i}) = (-1)^{m} \operatorname{nrd}_{B/L} \underline{\hat{h}}$$

(B = M(m, D)), so $\operatorname{trd}_{A/L} \hat{h} \sim_W 0$ if and only if

$$((-1)^m \operatorname{nrd}_{B/L} \hat{\underline{h}}, (-1)^n \operatorname{nrd}_{A/L} h_0)_L = (-1)^{mn}.$$

Parts (j) and (k) now follow if one takes into account the following facts, along with Lemma 1.2:

- (i) Two nonsingular skew Hermitian forms of the same rank over D are equivalent if and only if their determinants are equal (in L^*/L^{*2}).
- (ii) For any fixed rank r and square class $\lambda \in L^*/L^{*2}$, there is a skew Hermitian form of rank r and determinant λ unless r=1 and $\lambda=-1$. See [21], Theorem 3.6, p. 363.

This finishes the proof of Theorem 4.1.

Corollary 4.4. We use the same notation and assumptions as in Theorem 4.1; in particular K is a local non-Archimedean field and ρ is isotypic. Assume in addition that ρ has odd type.

Unitary representations. There is exactly 1 equivalence class of unitary representations $G \to \mathbf{U}(V,h)$ linearly equivalent to ρ .

Thus two unitary representations of odd type are equivalent if and only if they are linearly equivalent and their underlying forms are isotypically equivalent.

Orthogonal representations. The number of equivalence classes of orthogonal representations $G \to \mathbf{O}(V, h)$ which are linearly equivalent to ρ is as follows:

```
\begin{array}{lll} & \text{kind of} & \# \text{ of equiv.} & \text{conditions} \\ & (A, \bar{\ }) & \text{classes} & \\ & \textit{first} & \frac{\sigma_2(\mathcal{G})\sigma_2(L^*)}{\sigma_2(K^*)} & m>1 \ \textit{and} \ \det h \in (\mathrm{disc}(L/K))^m(\mathrm{N}_{L/K}L^*)K^{*2}, \\ & \textit{first} & 1 \leq \# & m=1 \ \textit{and} \ h \cong \mathrm{Tr}_{L/K}\langle \alpha h_0 \rangle, \alpha \in L^*, \\ & \leq \frac{\sigma_2(\mathcal{G})\sigma_2(L^*)}{\sigma_2(K^*)} & \\ & \textit{second} & 1 & \det h = \mathrm{N}_{L_0/K}(-\mathrm{disc}(L/L_0))^m, \end{array}
```

and 0 otherwise.

When G is Abelian, we get

```
kind of (A, \bar{\ }) # of equiv. classes conditions first 1 second 1 \det h = N_{L_0/K}(-\operatorname{disc}(L/L_0))^m,
```

and 0 otherwise.

Two not necessarily isotypic orthogonal representations of odd type, which we assume to be split if G is not Abelian, are equivalent if and only if they are linearly equivalent and their underlying forms are isotypically equivalent.

Remark 4.5. When G is Abelian and the involution on K is the identity, the restriction of the involution of KG to any direct summand L must be nontrivial if $L \neq K$ (i.e the involution is unitary), since L is generated over K by the images of G under the projection $KG \to L$.

Proof. The assumption that ρ has odd type means that A has index 1, and that n is odd. The statements about the number of equivalence classes in each case follow by Theorem 4.1 – and by Remark 4.5 in the case of an orthogonal representation of an Abelian group.

The statements about the equivalence of two not necessarily isotypic representations follow since the conditions stated for orthogonal representations rule out the cases where the number of equivalence classes of isotypic representations is > 1. \square

We now treat in detail the nondyadic case in Theorem 4.1, (g), for orthogonal representations, and we begin with two auxiliary lemmas. We assume that K_{nr} is

the unramified closure of K in L, with $(K_{nr}:K)=f$, and that K_{tm} is the largest tamely ramified subextension of L/K, with $(K_{tm}:K_{nr})=e$. Let $(L:K_{tm})=q$, which is a power of the residue class field characteristic p and so is odd.

Recall that $\mathcal{G} = \operatorname{Gal}(L/K)$. Note that in the case when K is nondyadic, $\sigma_2(\mathcal{G}) = (\mathcal{G}:\mathcal{G}^2) = 1, 2$, or 4 (since, for example, it is the order of the kernel of the map $L^*/L^{*2} \to K^*/K^{*2}$ induced by the norm, according to the proof of (f) of Theorem 4.1).

Lemma 4.6. (a) The Galois group $Gal(K_{tm}/K)$ is isomorphic to the direct product of $Gal(K_{nr}/K)$ and $Gal(K_{tm}/K_{nr})$.

(b) If K is nondyadic or L/K is tamely ramified, then

$$\sigma_2(\mathcal{G}) = \begin{cases} 1 & \text{if and only if e and f are odd,} \\ 2 & \text{if and only if e and f have different parity,} \\ 4 & \text{if and only if e and f are both even.} \end{cases}$$

Proof. (a) is a special case of [18], aufgabe 1, p. 185¹, according to which

$$Gal(L/K) \cong Gal(L/K_{nr}) \rtimes Gal(K_{nr}/K)$$

for any tamely ramified Galois extension L/K of a Henselian field K. (b) follows at once from (a), since the wild ramification index $(L:K_{\rm tm})$ is odd.

Let $c_K(h)$ denote the Witt invariant of the symmetric form h. The following lemma is easily checked.

Lemma 4.7. (a) If the rank of h is odd, then $c_K(\alpha h) = c_K(h)$ for any $\alpha \in K^*$. (b) If the rank of h is even and K is nondyadic, then $c_K(\alpha h) = c_K(h)$ for any unit $\alpha \in K^*$.

If M/K is any finite separable extension, $\langle M \rangle$ stands for the symmetric form $\text{Tr}_{M/K}(xy)$ $(x,y\in M)$; in other, words, $\langle M \rangle$ is the transfer of the symmetric bilinear form over M with matrix (1). We also denote by $\text{ord}_K\alpha$ the order of $\alpha \in K^*$ with respect to a prime element of the K.

Let h be a symmetric form of rank n over L. Define

$$r = \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(\operatorname{Tr}_{L/K_{\operatorname{tm}}} h)$$

$$= \operatorname{ord}_{K_{\operatorname{tm}}} \left((\operatorname{disc} L/K_{\operatorname{tm}})^n \operatorname{N}_{L/K_{\operatorname{tm}}} (\operatorname{disc} h) \right)$$

$$= n \operatorname{ord}_{K_{\operatorname{tm}}} (\operatorname{disc} L/K_{\operatorname{tm}}) + \operatorname{ord}_{L} (\operatorname{disc} h).$$

Lemma 4.8. Suppose that K is a nondyadic field and that the rank n of h is odd. (a) If (L:K) is odd,

$$c_K(\operatorname{Tr}_{L/K}h) = c_L h.$$

(b) If (L:K) is even,

 $c_K(\operatorname{Tr}_{L/K}h) = c_K \langle K_{\operatorname{tm}} \rangle^{r+1} (\pi, \operatorname{disc}(\operatorname{Tr}_{L/K}h))_K^{er} (\Pi, \operatorname{disc}(\operatorname{Tr}_{L/K_{\operatorname{tm}}}h))_{K_{\operatorname{tm}}}^{(e+1)(r+1)} c_L h,$ and

$$c_K \langle K_{tm} \rangle = \begin{cases} 1 & \text{if e is odd,} \\ (\pi, \ (-1)^{(f-1)/2} e)_K & \text{if e is even and f is odd,} \\ -(\pi, \ (-1)^{f/2} \mathrm{disc} L/K)_K & \text{if e and f are both even.} \end{cases}$$

¹I am grateful to M. Kolster for providing this reference.

Here π and Π are prime elements of K and $K_{\rm tm}$ respectively, arbitrary unless f is odd, in which case they are chosen to satisfy $\Pi^e \equiv -\pi \mod K_{\rm nr}^{*2}$.

Proof. The first formula (4.4) follows from [5], Theorem 4.4, 3. The second formula follows from [5], Theorem 5.6, after a straightforward computation. It uses the facts that if $\alpha \in L$, then $(\pi, \alpha)_L = (\pi, N_{L/K}\alpha)_K$ (cf. [12], Theorem 2.14, 8.), and that $c_{K_{\text{tm}}}(\text{Tr}_{L/K_{\text{tm}}}h) = c_L h$ (which is the special case of (4.4) with $K = K_{\text{tm}}$). The formula for $c_K \langle K_{\text{tm}} \rangle$ follows from [5], Theorems 4.2, 5.3, 5.4, and 5.5.

Theorem 4.9. Let K be a nondyadic local field, and suppose that $(A, \bar{\ })$ is orthogonal of odd degree n with center L and index 1. We denote by f, e, and q respectively the index of inertia, the tame ramification index, and the wild ramification index of L/K.

Suppose that ρ is a linear representation of type A on the vector space V of length 1, and that h is a symmetric form on V.

- 1. e and f odd. Then there is an invariant form equivalent to h if and only if $c_K(h) = c_L(h_0)$, and each invariant form admits exactly one orthogonal representation (up to equivalence, of course).
- 2. e odd and f even. An invariant form has determinant disc L/K or ϵ disc L/K, where ϵ is any nonsquare unit of K. Assume that h has one of these as its determinant.

If $(\pi, \operatorname{disc} h)_K = 1$, there is a form equivalent to h which supports two nonequivalent orthogonal representations if $c_K(h) = c_L(h_0)$; otherwise there is no invariant form equivalent to h.

- If $(\pi, \operatorname{disc} h)_K = -1$, there is an invariant form equivalent to h and it supports one orthogonal representation.
- 3. e even and f odd. There is an invariant form equivalent to h if and only if $\det h \in (\operatorname{disc}(L/K))(\operatorname{N}_{L/K}L^*)K^{*2}$ and, if $\operatorname{ord}_K(\det h)$ is even, $\operatorname{c}_K(h) = \operatorname{c}_L(h_0)$. In the latter case, an invariant form supports two inequivalent orthogonal representations. Each of the two inequivalent invariant forms with determinant of odd order supports a single orthogonal representation.
- 4. e and f both even. There is an invariant form equivalent to h if and only if $\det h = \operatorname{disc}(L/K)$, and it admits three inequivalent orthogonal representations if $c_K(h) = c_L(h_0)$, and one otherwise.

Proof. We know that the invariant forms on V are those of the form $\operatorname{Tr}_{L/K}\alpha h_0$ for $\alpha \in L^*$. Since n is odd, we can assume that $\det h_0 = 1$. Then $\det \operatorname{Tr}_{L/K}\alpha h_0 = \operatorname{disc}(L/K) \operatorname{N}_{L/K}\alpha$ by Lemma 1.1.

Suppose e and f are both odd. Then (L:K) is also odd, and by (4.4) and Lemma 4.7 (a), $c_K \operatorname{Tr}_{L/K} \alpha h_0 = c_L h_0$. Since the map $L^*/L^{*2} \to K^*/K^{*2}$ is an isomorphism when (L:K) is odd, the theorem follows in this case.

Suppose e is odd and f is even. We first prove that the image of $\bar{N}: L^*/L^{*2} \to K^*/K^{*2}$ consists of the square classes K^{*2} and ϵK^{*2} , where ϵ is any nonsquare unit of K. (Note that $(U_K:U_K^2)=2$ since K is nondyadic.) The image certainly is of order 2, since its kernel has order $\sigma_2(\mathcal{G})=2$ by (4.2) and Lemma 4.6. The norm-induced map $L^*/L^{*2} \to K_{\rm nr}^*/K_{\rm nr}^{*2}$ is bijective since the degree of $L/K_{\rm nr}$ is odd. The norm of a nonsquare unit of $K_{\rm nr}$ in K is a nonsquare since

$$\mathfrak{o}_{K_{\mathrm{nr}}} \longrightarrow k_{\mathrm{nr}}$$
 $\downarrow \qquad \qquad \downarrow$
 $\mathfrak{o}_{K} \longrightarrow k$

is commutative, and the norm in a finite extension of finite fields is onto. (Here \mathfrak{o} is a ring of integers, k its residue class field, and the vertical maps are norms.) Thus the image of \bar{N} is as stated. It also follows that each of these images is the image of a square class of L containing a unit and of one containing a prime.

Thus $\det(\operatorname{Tr}_{L/K}\alpha h_0) = \operatorname{disc}(L/K)\operatorname{N}_{L/K}\alpha = \operatorname{disc}(L/K)$ or $\epsilon \operatorname{disc}(L/K)$, so an invariant form must have one of these determinants. By Lemma 4.8, (b),

$$c_K(\operatorname{Tr}_{L/K}\alpha h_0) = (\pi, \operatorname{disc}(\operatorname{Tr}_{L/K}\alpha h_0))_K^r c_L(h_0),$$

where $r = \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) + \operatorname{ord}_{L}\alpha$. (We can drop the *n* from this expression, since *n* is odd and *r* only appears in the exponents of powers of -1.) Thus

$$\begin{array}{lcl} \mathbf{c}_K(\mathrm{Tr}_{L/K}\alpha h_0) & = & \mathbf{c}_L(h_0) & \mathrm{if} & \mathrm{ord}_L\alpha \equiv \mathrm{ord}_{K_{\mathrm{tm}}}\mathrm{disc}(L/K_{\mathrm{tm}}) & \mathrm{mod}\,2, \\ & = & (\pi,\mathrm{disc}(\mathrm{Tr}_{L/K}\alpha h_0))_K\,\mathbf{c}_L(h_0) & \mathrm{otherwise}. \end{array}$$

By local class field theory, $N_{K(\sqrt{\pi})/K}K(\sqrt{\pi})^*$ consists of two of the four square classes in K^*/K^{*2} , and it is clear they must be K^{*2} and $-\pi K^{*2}$. It follows that ϵ is not a norm from $K(\sqrt{\pi})$, and so $(\pi, \epsilon)_K = -1$. Since an invariant form h satisfies $c_K(h) = c_L(h_0)$ if it arises from an α satisfying $\operatorname{ord}_L \alpha \equiv \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) \operatorname{mod} 2$, and otherwise satisfies $c_K(h) = (\pi, \operatorname{disc}(h))_K c_L(h_0)$, the statement in the theorem for e odd and f even follows readily.

Suppose next that e is even and f is odd. The norm from L to $K_{\rm tm}$ (on nonzero elements) is bijective mod squares since the degree is odd. It follows from Lemma 4.6, (b), that the norm from $K_{\rm tm}$ to $K_{\rm nr}$ takes units to square units, and all primes to a single square class containing primes, and so the same thing is true for the norm from L to K since $(K_{\rm nr}:K)=f$ is odd.

By Lemma 4.8,

$$(4.5) c_K(\operatorname{Tr}_{L/K}\alpha h_0) = c_K \langle K_{\operatorname{tm}} \rangle^{r+1} (\Pi, \operatorname{disc}(\operatorname{Tr}_{L/K_{\operatorname{tm}}}\alpha h_0))_{K_{\operatorname{tm}}}^{r+1} c_L h_0.$$

Thus if $\operatorname{ord}_L \alpha \not\equiv \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) \mod 2$, then $\operatorname{c}_K(\operatorname{Tr}_{L/K} \alpha h_0) = \operatorname{c}_L(h_0)$; since $\operatorname{ord}_L \alpha \equiv \operatorname{ord}_L \alpha' \mod 2$ implies that the norms of α and α' down to K are equal mod squares, we get one invariant form supporting two inequivalent orthogonal representations.

We now show that the condition $\operatorname{ord}_L \alpha \not\equiv \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) \mod 2$ is equivalent to $\operatorname{ord}_K(\det \operatorname{Tr}_{L/K} \alpha h_0)$ being even. Note that

$$\operatorname{ord}_L \alpha$$
 and $\operatorname{ord}_K N_{L/K} \alpha$

have the same parity, and the same is true of

$$\operatorname{ord}_{K_{\operatorname{tm}}}\operatorname{disc}(L/K_{\operatorname{tm}})$$
 and $\operatorname{ord}_{K}\operatorname{N}_{K_{\operatorname{tm}}/K}\operatorname{disc}(L/K_{\operatorname{tm}})$.

Thus the condition is equivalent to

$$\begin{array}{cccc} \operatorname{ord}_K(\operatorname{disc}(L/K)\mathrm{N}_{L/K}\alpha) & \not\equiv & \operatorname{ord}_K(\operatorname{disc}(L/K)\mathrm{N}_{K_{\operatorname{tm}}/K}\operatorname{disc}(L/K_{\operatorname{tm}})) \\ & & \equiv & \operatorname{ord}_K(\operatorname{disc}(K_{\operatorname{tm}}/K)^q(\mathrm{N}_{K_{\operatorname{tm}}/K}\operatorname{disc}(L/K_{\operatorname{tm}}))^2) \\ & & \equiv & \operatorname{ord}_K(\operatorname{disc}(K_{\operatorname{tm}}/K) \\ & = & f(e-1) & \text{by Dedekind's discriminant theorem} \\ & \equiv & 1 \mod 2, \end{array}$$

as desired.

Now suppose that $\operatorname{ord}_L \alpha \equiv \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) \mod 2$. By a now familiar argument, $(\Pi, \mathcal{N}_{L/K_{\operatorname{tm}}} \alpha)_{K_{\operatorname{tm}}}$ takes on both ± 1 for the two possible square classes that α represents, and so we get two invariant forms, each supporting one orthogonal representation. This finishes the proof of the case e even and f odd.

Now suppose both e and f are even. Then $\det \operatorname{Tr}_{L/K} \alpha h_0 = \operatorname{disc}(L/K)$ by Lemma 4.6 (b). Also (4.5) again holds, and so, if $\operatorname{ord}_L \alpha \not\equiv \operatorname{ord}_{K_{\operatorname{tm}}} \operatorname{disc}(L/K_{\operatorname{tm}}) \mod 2$, we get one invariant form of determinant $\operatorname{disc}(L/K)$ and Witt invariant $\operatorname{c}_L(h_0)$ with two inequivalent orthogonal representations. In the other case, we get two inequivalent invariant forms, again with determinant $\operatorname{disc}(L/K)$, with one orthogonal representation for each. This finishes the proof of the case e and f both even, and of the theorem as well.

5. Global fields and the Hasse Principle

In this section, K is a global field with an involution $\bar{}$. Our principal goals are to consider problems **I**, **II** and **III** for split representations over K, and to prove the Hasse Principle for equivariant representations.

In the case of split representations, it is particularly easy to determine the equivariant representations of G: if A is simple with involution $\bar{a} = h_0^{-1} a^* h_0$, the association $\underline{\hat{h}} \leadsto \underline{\hat{h}} \otimes h_0$ yields a bijective correspondence between the equivalence classes of ϵ -Hermitian forms of a given rank m and the equivalence classes of all equivariant representations of G of rank mn and type A with respect to $\epsilon_0 \epsilon$ -Hermitian forms. (It is understood that if the involution on K is the identity, then Hermitian means symmetric.) As we already have seen, it is easy to calculate such things as the determinant, Hasse symbol and signatures from this formula.

The case of split symplectic representations has already been covered in §2, so we deal only with unitary and orthogonal representations.

If K_0 is formally real and h_0 is symmetric or Hermitian, we can assume that h_0 is a positive definite matrix at each ordering of K_0 .

If h is a symmetric bilinear form over \mathbf{R} or an Hermitian form over \mathbf{C} , the number of -1's in any diagonalization $\langle 1, \ldots, 1, -1, \ldots, -1 \rangle$ is the negative index of h. Similarly the number of 1's is the positive index. If h is a symmetric or Hermitian form over the number field K and \mathfrak{p} is a real prime of K_0 which does not split in K, the indices of $h_{\mathfrak{p}}$ are denoted by $r_{\mathfrak{p}}^-(h)$ and $r_{\mathfrak{p}}^+(h)$ respectively.

Lemma 5.1. Let $\delta \in K_0^*$. Let \wp be the set of all real primes of K_0 which do not split in K. Suppose that m is a positive integer and, for each $\mathfrak{p} \in \wp$, that $r_{\mathfrak{p}}$ is an integer such that $0 \le r_{\mathfrak{p}} \le m$ and $\delta(-1)^{r_{\mathfrak{p}}} >_{\mathfrak{p}} 0$. Then there is an $m \times m$ Hermitian matrix $\underline{\hat{h}}$ whose determinant is δ and whose negative index at each $\mathfrak{p} \in \wp$ is $r_{\mathfrak{p}}$.

Proof. If m=1, take $\underline{\hat{h}}=(\delta)$. Suppose m>1. By the weak approximation theorem, there is an $\alpha_m \in K_0^*$ such that $\alpha_m>_{\mathfrak{p}} 0$ if $r_{\mathfrak{p}}< m$, $\alpha_m<_{\mathfrak{p}} 0$ if $r_{\mathfrak{p}}=m$. Put $\delta'=\delta\alpha_m$, $r'_{\mathfrak{p}}=r_{\mathfrak{p}}$ if $\alpha_m>_{\mathfrak{p}} 0$, $=r_{\mathfrak{p}}-1$ if $\alpha_m<_{\mathfrak{p}} 0$. Then $\delta'(-1)^{r'_{\mathfrak{p}}}>0$, and so by induction there is an Hermitian matrix $\underline{\hat{h}}'$ of rank m-1 with $\det \underline{\hat{h}}'=\delta'$ and with negative indices $r'_{\mathfrak{p}}$. Then $\underline{\hat{h}}=\underline{\hat{h}}'\perp(\alpha_m)$ has the required properties. \square

Theorem 5.2 (Split unitary representations). Suppose that the simple involution algebra component A of KG is $\cong M(n,K)$, and that K is a global field with a nontrivial involution. Let \wp be the set of real primes of K_0 which do not split in K. Let V be an A-module of length m and h an Hermitian form on V.

- **I.** There is an invariant form on V equivalent to h if and only if the positive and negative indices of h are divisible by n for each real prime $\mathfrak{p} \in \wp$ and, when n is even, $\det h = (\det h_0)^m$.
- **II.** Suppose h is invariant.
 - (i) If n is odd, h supports exactly one unitary representation of type A (up to equivalence).
 - (ii) If n is even, the equivalence classes of unitary representations supported by h are in bijective correspondence with the norm classes in $K_0^*/N_{K/K_0}K^*$ which are positive at each $\mathfrak{p} \in \wp$. (Note that the elements of $N_{K/K_0}K^*$ are positive at each $\mathfrak{p} \in \wp$.)
- III. Two split unitary representations of odd type are equivalent if and only if they are equivalent as linear representations and their forms are isotypically equivalent.

Proof. Most of this follows easily from the fact that there is a bijection between Hermitian forms over K and isotypic unitary representations, arising from $\underline{\hat{h}} \leadsto \underline{\hat{h}} \otimes h_0^t$. The necessity of the condition in \mathbf{I} that the indices be divisible by n is a consequence of the fact that the $n \times n$ matrix h_0 is definite. Conversely, suppose that the indices of h are $nr_{\mathfrak{p}}^-$ and $nr_{\mathfrak{p}}^+$. If n is odd, put

$$\delta = (\frac{n}{q})^m (\det h_0)^m \det h.$$

Since det h_0 is totally positive and $(\det h)(-1)^{nr_{\bar{\mathfrak{p}}}}=1$ for all $\mathfrak{p}\in\wp$, we can apply the above lemma to find an Hermitian matrix $\underline{\hat{h}}$ with determinant δ and negative indices $r_{\mathfrak{p}}$. Since $\frac{n}{g}(\underline{\hat{h}}\otimes h_0)$ has the same determinant and indices as h, it is equivalent to h. Furthermore since the determinant and indices of $\underline{\hat{h}}$ are uniquely determined by those of h (and h_0), we get \mathbf{H} in the case of n odd as well.

Suppose n is even. The necessity of \mathbf{I} is clear. Conversely, it is easy to see by Lemma 5.1 that there are Hermitian matrices $\underline{\hat{h}}$ with indices equal to those of h divided by n, and then, for any such matrix, $\frac{n}{g}(\underline{\hat{h}}\otimes h_0)$ is equivalent to h. This proves \mathbf{I} in the case of even n. Furthermore, any two such matrices $\underline{\hat{h}}$ have determinants differing by an element of K_0 which is positive at each $\mathfrak{p} \in \wp$. Conversely, if $\alpha_0 \in K_0$ is positive at each $\mathfrak{p} \in \wp$ and $\underline{\hat{h}}$ is such an Hermitian matrix, then by the same lemma, there is another such matrix with determinant $\alpha_0 \det \underline{\hat{h}}$. This proves \mathbf{II} in the case of even n.

Theorem 5.3 (Split orthogonal representations). Suppose that K is a global field and that the simple involution algebra component A of KG is $\cong M(n, K)$. Let V be an A-module of length m.

- $(A, \bar{\ })$ symplectic.
 - I, II. Any invariant form on V is hyperbolic, and the orthogonal representation it affords is unique up to equivalence.
- (A, -) orthogonal.
 - **I.** Suppose that h is a symmetric form on V.

If n is odd, there is an invariant form \cong h on V if and only if (i) $h \cong \langle \alpha h_0 \rangle$ for some $\alpha \in K^*$ when m=1, and (ii) $n \mid \operatorname{sgn}_{\mathfrak{p}} h$ for all real primes \mathfrak{p} of K when m>1. If n is even, there is an invariant form $\cong h$ on V if and only if

(iii) det
$$h = (\det h_0)^m$$
, and
(iv) for all real primes \mathfrak{p} of K , $n|r_{\mathfrak{p}}^-(h)$, and
(v) $S_{\mathfrak{p}}(h) = S_{\mathfrak{p}}(h_0)^m(-1,-1)_{\mathfrak{p}}^{\frac{nm(m-1)}{4}}$ for all \mathfrak{p} at which disc $h_0 = 1$.

II. If h is invariant, there is (up to equivalence) only one orthogonal representation $G \to \mathbf{O}(V,h)$ if n is odd, and there are an infinite number if n is even.

III. Two split orthogonal representations of odd type are equivalent if and only if they are equivalent as linear representations and their underlying forms are isotypically equivalent.

Remark 5.4. 1. In (v), $S_{\mathfrak{p}}(h_0)$ is well-defined, since for any $\alpha \in K^*$, $S_{\mathfrak{p}}(\alpha h_0) = S_{\mathfrak{p}}(h_0)$ when n is even and disc $h_0 = 1$ at \mathfrak{p} .

2. In III, "odd type" can be weakened to "AV=0 for all simple orthogonal involution components $(A, \bar{\ })$ of even degree."

Proof. If $(A, \bar{})$ is symplectic, \hat{h} must be skew symmetric and this case follows.

Suppose that $(A, \bar{})$ is orthogonal. If n is odd, the necessity of (i) follows since $\underline{\hat{h}} = \langle \alpha \rangle$ implies $\underline{\hat{h}} \otimes h_0 = \alpha h_0$. The necessity of (ii) is clear since $h \cong \langle \underline{n}(\underline{\hat{h}} \otimes h_0) \rangle$ for some $\underline{\hat{h}}$ (and h_0 is positive definite).

The sufficiency of (i) is also clear. Suppose that n is odd and m > 1. By Lemmas 1.1 and 1.3 (iv), and the fact that $\operatorname{sgn}_{\mathfrak{p}}(\underline{\hat{h}} \otimes h_0) = n(\operatorname{sgn}_{\mathfrak{p}}\underline{\hat{h}})$, the association $\underline{\hat{h}} \leadsto \underline{\hat{h}} \otimes h_0$ is injective (on equivalence classes of symmetric forms) since n is odd. We now show that its image consists of all equivalence classes of symmetric forms on V with signature at each real prime \mathfrak{p} divisible by n. Suppose that h is such a form, with signatures $nr_{\mathfrak{p}}$. We show the existence of a symmetric form $\underline{\hat{h}}$ such that $h \cong \langle \underline{\hat{h}} \otimes h_0 \rangle$. Its determinant satisfies $\det h = (\det \underline{\hat{h}})^n (\det h_0)^m$, so $\det \underline{\hat{h}} = (\det h)(\det h_0)^m$. Similarly its Hasse-Witt invariant is determined by Lemma 1.3 (iv):

(5.1)

$$S(\underline{\hat{h}}) = S(h)S(h_0)^m (\det \underline{\hat{h}}, -1)_K^{n(n-1)/2} (\det \underline{\hat{h}}, \det h_0)_K^{mn-1} (\det h_0, -1)_K^{m(m-1)/2},$$

and its real signatures are $r_{\mathfrak{p}}$. We must check that the desired signatures are compatible with the determinant and Hasse-Witt invariant.

Let $r_{\mathfrak{p}}^- = (m - r_{\mathfrak{p}})/2$ be the negative index at \mathfrak{p} . At any real prime \mathfrak{p} , det $h_0 = 1$, so

$$\det \underline{\hat{h}} = \det h = (-1)^{nr_{\mathfrak{p}}^-} = (-1)^{r_{\mathfrak{p}}^-},$$

as desired.

By (5.1) the Hasse invariant at \mathfrak{p} is

$$\begin{array}{lcl} \mathbf{S}_{\mathfrak{p}}(\underline{\hat{h}}) & = & \mathbf{S}_{\mathfrak{p}}(h)(\det\underline{\hat{h}},-1)_{\mathfrak{p}}^{(n-1)/2} \\ & = & (-1)^{nr_{\mathfrak{p}}^{-}(nr_{\mathfrak{p}}^{-}-1)/2}(-1)^{(n-1)r_{\mathfrak{p}}^{-}/2}. \end{array}$$

It is easy to check that this is $=(-1)^{r_{\mathfrak{p}}^-(r_{\mathfrak{p}}^--1)/2}$, as desired.

The "local-global existence theorem" for quadratic forms ([19], Theorem 72:1) shows that \hat{h} exists. The upshot is that every form h satisfying (i) or (ii) is equivalent to the trace $\operatorname{trd}_{A/K}\hat{h}$ of an Hermitian form \hat{h} over $(A, \bar{\ })$ and so is equivalent to an

invariant form. The bijectivity implies **II** as well when n is odd and m > 1. And in the case m = 1, **II** follows from the fact that $\langle \alpha h_0 \rangle \cong \langle \beta h_0 \rangle$ implies $\langle \alpha \rangle \cong \langle \beta \rangle$.

Now assume n even. Suppose that h is invariant. Since $h \cong \langle \frac{n}{g}(\underline{\hat{h}} \otimes h_0) \rangle$ for some $m \times m$ nonsingular symmetric matrix $\underline{\hat{h}}$, (iii) and (iv) follow at once. From Lemma 1.3 (i) and (iv),

$$S(h) = S(\frac{n}{g}(\underline{\hat{h}} \otimes h_0))$$

$$= S(h_0)^m (\det \underline{\hat{h}}, \operatorname{disc} h_0) (\det h_0, -1)^{m(m-1)/2} (\frac{n}{g}, \operatorname{disc} h_0)^m.$$

If disc $h_0 = 1$ at \mathfrak{p} , then det $h_0 = (-1)^{n/2}$, and (v) follows at once.

Conversely, suppose that (iii), (iv) and (v) prevail. First we show there is $\delta \in K^*$ satisfying

(a)
$$(\delta, \operatorname{disc} h_0) = S(h)S(h_0)^m (\det h_0, -1)^{m(m-1)/2} (\frac{n}{a}, \operatorname{disc} h_0)^m$$
, and

(b) the sign of δ at any real prime \mathfrak{p} at which disc $h_0 = 1$ is $(-1)^{r_{\mathfrak{p}}}$,

where $r_{\mathfrak{p}}^-(h) = nr_{\mathfrak{p}}^-$ is the negative index of h. By Lemma 5.5 it is enough to find δ satisfying (a). If disc h_0 is a square at \mathfrak{p} , the right side of (a) is 1 at \mathfrak{p} by assumption (iv). By the Hilbert reciprocity law, and [19], 71:19 and 71:19a, there is a δ satisfying (a).

Now suppose \mathfrak{p} is a real prime of K. Since h_0 is positive definite at all real primes,

$$S(h_0) = 1$$
, $\det h_0 = 1$, $\operatorname{disc} h_0 = (-1)^{n/2}$ at \mathfrak{p} .

It follows from (a) that, also at \mathfrak{p} ,

$$(\delta, \operatorname{disc} h_0) = (\delta, -1)^{\frac{n}{2}}$$
$$= S(h) = (-1)^{\frac{nr_{\mathfrak{p}}^-}{2}} = (-1)^{r_{\mathfrak{p}}^-(\frac{n}{2})}.$$

Let $\hat{h}_{\mathfrak{p}}$ be a symmetric bilinear form of rank m over $K_{\mathfrak{p}}$ with negative index $r_{\mathfrak{p}}^-$. If $\operatorname{disc} h_0 \neq 1$ at \mathfrak{p} , then n/2 must be odd, and it follows that $(\delta, -1)_{\mathfrak{p}} = (-1)^{r_{\mathfrak{p}}^-} = \det \hat{h}_{\mathfrak{p}}$. Since each of δ and $\det \hat{h}_{\mathfrak{p}}$ can be considered to be ± 1 at \mathfrak{p} , it follows that $\delta = \det \hat{h}_{\mathfrak{p}}$. On the other hand, if $\operatorname{disc} h_0$ is a square at \mathfrak{p} , we get $\delta = \det \hat{h}_{\mathfrak{p}}$ at \mathfrak{p} by (b).

It follows once more from the local-global existence theorem that there is a nonsingular symmetric matrix $\underline{\hat{h}}$ of rank m over K of determinant δ whose localizations at each real prime \mathfrak{p} are the $\hat{h}_{\mathfrak{p}}$ just constructed. From (a), the expression for $S(\frac{n}{g}(\underline{\hat{h}}\otimes h_0))$ in (5.2), the fact that $\det \frac{n}{g}(\underline{\hat{h}}\otimes h_0) = (\det h_0)^m$, and $r_{\mathfrak{p}}^-(\underline{\hat{h}}\otimes h_0) = nr_{\mathfrak{p}}^-(\underline{\hat{h}}) = nr_{\mathfrak{p}}^- = r_{\mathfrak{p}}^-(h)$, it follows that $\mathrm{Tr}_{KG/K}\hat{h}\cong h$, where \hat{h} is the Hermitian form over $(A, \bar{})$ on $K^{n\times m}$ with discriminant matrix $\underline{\hat{h}}$. Thus $\mathrm{Tr}_{KG/K}\hat{h}$ is an invariant form $\cong h$.

In fact there are an infinite number of such $\underline{\hat{h}}$ which are inequivalent, since we can choose the $S_{\mathfrak{p}}(\underline{\hat{h}})$ for \mathfrak{p} finite arbitrarily (up to the Hilbert reciprocity law). Thus we get \mathbf{H} for n even: each invariant form h supports an infinite number of inequivalent orthogonal representations.

III is a consequence of II, of course.

Lemma 5.5. Let $\gamma \in K^*$ and let (δ, γ) be a fixed quaternion Brauer class over the algebraic number field K. Then the signs of δ at the real primes $\mathfrak p$ at which γ is a square (i.e. for which $\gamma >_{\mathfrak p} 0$) can be arbitrarily prescribed.

Proof. Let "signs" $\epsilon_{\mathfrak{p}} = \pm 1$ be given for each real prime at which γ is a square. For each such prime, choose $\alpha_{\mathfrak{p}}$ and $\beta_{\mathfrak{p}}$ in $K_{\mathfrak{p}}$ so that $(\alpha_{\mathfrak{p}}^2 - \beta_{\mathfrak{p}}^2 \gamma) \delta \epsilon_{\mathfrak{p}} >_{\mathfrak{p}} 0$. Apply the weak approximation theorem to find α and β in K such that $(\alpha^2 - \beta^2 \gamma) \delta \epsilon_{\mathfrak{p}} >_{\mathfrak{p}} 0$ for each \mathfrak{p} , and set $\delta' = (\alpha^2 - \beta^2 \gamma) \delta$. Then

$$(\delta', \gamma) = (\alpha^2 - \beta^2 \gamma, \gamma)(\delta, \gamma) = (\delta, \gamma),$$

since, if γ is not a square in K, $\alpha^2 - \beta^2 \gamma$ is a norm in $K(\sqrt{\gamma})/K$. Furthermore,

$$\delta' \epsilon_{\mathfrak{p}} = (\alpha^2 - \beta^2 \gamma) \delta \epsilon_{\mathfrak{p}} >_{\mathfrak{p}} 0$$

for any real \mathfrak{p} at which γ is a square.

The Hasse Principle. We now prove the Hasse Principle for equivariant representations.

The completion of the fixed field K_0 of the involution at any discrete or Archimedean prime \mathfrak{p} is denoted by $K_{0\mathfrak{p}}$. Similarly $V_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes_{K_0} V$, $A_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes_{K_0} A$, ...

- these are all modules over $K_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes_{K_0} K$. The latter ring has a K-involution given by $\overline{\alpha \otimes \beta} = \alpha \otimes \overline{\beta}$. If \mathfrak{p} splits in K – which implies that the involution on K is not the identity – $K_{\mathfrak{p}}$ is the hyperbolic involution algebra $K_{0\mathfrak{p}} \oplus K_{0\mathfrak{p}}$. Otherwise it is the completion of K with respect to the unique extension of K to K. Similarly,

$$(KG)_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes_{K_0} KG = K_{\mathfrak{p}} \otimes_K KG = K_{\mathfrak{p}}G$$

is also a hyperbolic involution algebra if \mathfrak{p} splits in K. In this case any Hermitian form over $K_{\mathfrak{p}}G$ is hyperbolic, and so is determined by the isomorphism class of the $K_{\mathfrak{p}}G$ -module $V_{\mathfrak{p}}$ ([14], 2.3), and so by the isomorphism class of the KG-module V itself

Of course if the involution on K is the identity, then $K_0 = K$ and $K_{0\mathfrak{p}} = K_{\mathfrak{p}}$. Note that any sesquilinear form $f: V \times V \to A$ over the K-involution algebra A has a unique extension to a sesquilinear form

$$f_{\mathfrak{p}}:V_{\mathfrak{p}}\times V_{\mathfrak{p}}\to A_{\mathfrak{p}}$$

determined by

$$f_{\mathfrak{p}}(\alpha \otimes v, \beta \otimes u) = \alpha \beta \otimes f(v, u),$$

where $\alpha, \beta \in K_{0\mathfrak{p}}$.

We can also extend an equivariant representation $\rho: G \to \mathbf{I}(V, h)$ ($\mathbf{I} = \mathbf{O}, \mathbf{Sp}$, or \mathbf{U}) to an equivariant representation $\rho_{\mathfrak{p}}: G \to \mathbf{I}(V_{\mathfrak{p}}, h_{\mathfrak{p}})$ in the obvious way,

$$\rho_{\mathfrak{p}}(s)(\alpha \otimes v) = \alpha \otimes \rho(s)v.$$

It is clear that $\rho_{\mathfrak{p}}(s) \in \mathbf{I}(V_{\mathfrak{p}}, h_{\mathfrak{p}})$ and that $\rho_{\mathfrak{p}}$ is a homomorphism.

Theorem 5.6 (Hasse Principle for equivariant representations). Let G be an arbitrary finite group and K a global field. Let $\rho: G \to \mathbf{I}(V,h)$ be an equivariant representation, and P the set of all equivariant representations on V which are linearly equivalent to ρ . Then the "Hasse Principle"

for all
$$\rho' \in P$$
, $\rho \cong \rho' \Leftrightarrow \rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}}$ for all primes \mathfrak{p} of K_0

holds if and only if AV=0 for every simple direct summand A of KG which satisfies the following:

(*) A is a matrix algebra over a quaternion algebra which is nonsplit at more than 2 primes (of its center), and the restriction of the canonical involution on KG to A is an involution of orthogonal type if ρ is orthogonal, and of symplectic type if ρ is symplectic.

Remark 5.7. In particular, this means that the Hasse Principle always holds for unitary representations.

Proof. Suppose that

$$\rho: G \to \mathbf{I}(V, h), \quad \rho': G \to \mathbf{I}(V', h')$$

are two equivariant representations which are "of the same type" (h and h' both symmetric, or both Hermitian, ...) and that they are linearly equivalent. In fact we assume that they are equal (as linear representations). Let $\epsilon=1$ if h and h' are symmetric or Hermitian, -1 if they are skew symmetric or skew Hermitian. We shall refer to h and h' as ϵ -Hermitian in both cases.

According to §1.3 there are simple summands A_1, \ldots, A_k of KG stable under and forms $\check{h}_1, \ldots, \check{h}_k$ over the division algebras D_1, \ldots, D_k , with D_i Brauer equivalent to A_i , whose (ordinary) equivalence classes characterize the equivariant equivalence classes of ρ . We now look more closely at the last step in this association, the Hermitian Morita equivalence of \hat{h}_i and \check{h}_i , using the "Hermitian Morita context" of Lemma 1.8.

There is an ϵ_i -Hermitian matrix $\underline{h}_{0i} \in A_i = \mathrm{M}(n_i, D_i)$ such that $\bar{a} = \underline{h}_{0i}^{-1} a^* \underline{h}_{0i}$ for all $a \in A_i$. Let V_{0i} be the simple A_i -module $D_i^{n_i \times 1}$. It is an (A_i, D_i) -bimodule. By Lemma 1.8, the nonsingular ϵ_i -Hermitian form $h_{0i} : V_{0i} \times V_{0i} \to A_i$ defined by $h_{0i}(u,v) = uv^*\underline{h}_{0i}$ is ϵ_i -Hermitian and, if D_i is a quaternion algebra and the involution on A_i is of the first kind, the adjoint involution \bar{a} on D_i is conjugation; in this latter case we note that $\epsilon_i = 1$ respectively -1 if (A, \bar{a}) is symplectic respectively orthogonal. Twist the action of A_i and D_i on V_{0i} using their involutions, and let \bar{V}_{0i} denote the resulting (D_i, A_i) -bimodule.

By the Hermitian Morita theory, there is a nonsingular ϵ_i -Hermitian form H_{0i} : $\bar{V}_{0i} \times \bar{V}_{0i} \to D_i$ whose adjoint involution on A_i is $\bar{}$ and which satisfies the Hermitian Morita associative relationship

(5.3)
$$h_{0i}(u,v)w = uH_{0i}(\bar{v},\bar{w}) \text{ for all } u,v,w \in V_{0i}.$$

It effects an equivalence between the category $A_i \mathcal{H}_{\epsilon}$ of ϵ -Hermitian forms over A_i and the category $D_i \mathcal{H}_{\epsilon \epsilon_i}$ of $\epsilon \epsilon_i$ -Hermitian forms over D_i , via the map $\hat{g} \rightsquigarrow H_{0i}\hat{g}$ (product of forms–cf. [8], §2). This is the equivalence described in Lemma 1.8.

By Table 1 in §1.1 and 10.4.6, [21], the Hasse Principle applies to the forms $H_{0i}\hat{g}$ unless they are skew Hermitian ($\epsilon\epsilon_i = -1$) and D_i is a quaternion division algebra which is nonsplit at more than 2 primes. These exceptional cases are precisely those arising from (*), and so, in order to prove the sufficiency of the condition in the theorem, we assume that $A_iV = 0$ for any such exceptional $i, 1 \leq i \leq k$. Of course this means also that $\hat{h}_i = 0$.

It follows that $\rho \cong \rho'$ if and only if $(H_{0i}\hat{h}_i)_{\mathfrak{P}} \cong (H_{0i}\hat{h}'_i)_{\mathfrak{P}}$ for $1 \leq i \leq k$ and all primes \mathfrak{P} of L_{i0} , where L_i is the center of D_i and L_{i0} is the subfield of elements fixed by the involution of L_i . We now wish to show that this is equivalent with

(5.4)
$$\rho \cong \rho' \Leftrightarrow (H_{0i}\hat{h}_i)_{\mathfrak{p}} \cong (H_{0i}\hat{h}'_i)_{\mathfrak{p}} \text{ for } 1 \leq i \leq k \text{ and all primes } \mathfrak{p} \text{ of } K_0.$$

In doing this we shall drop the index i from L_i, L_{i0}, D_i , etc., in order to simplify the notation.

By [2], p. 57, there is an isomorphism $K_{0\mathfrak{p}} \otimes_{K_0} L_0 \cong \bigoplus_{\mathfrak{P}|\mathfrak{p}} L_{0\mathfrak{P}}$, which implies an isomorphism

$$L_{\mathfrak{p}} \cong \bigoplus_{\mathfrak{P} \mid \mathfrak{p}} L_{\mathfrak{P}} \qquad (L_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes_{K_0} L, \quad L_{\mathfrak{P}} = L_{0\mathfrak{P}} \otimes_{L_0} L)$$

given by

$$\alpha_{\mathfrak{p}} \otimes \beta \mapsto (\iota_1 \alpha_{\mathfrak{p}} \otimes \beta, \dots, \iota_q \alpha_{\mathfrak{p}} \otimes \beta),$$

where $\iota_j: K_{0\mathfrak{p}} \to L_{0\mathfrak{P}_j}$ is the inclusion. We identify $L_{\mathfrak{p}}$ and $\bigoplus_{\mathfrak{P}|\mathfrak{p}} L_{\mathfrak{P}}$ via this isomorphism. Similarly we identify

$$D_{\mathfrak{p}} = \bigoplus_{\mathfrak{P}|\mathfrak{p}} D_{\mathfrak{P}} \quad \text{and} \quad W_{\mathfrak{p}} = \bigoplus_{\mathfrak{P}|\mathfrak{p}} W_{\mathfrak{P}},$$

where W is a vector space over D, via the isomorphisms

$$\alpha_{\mathfrak{p}} \otimes d \mapsto (\iota_1 \alpha_{\mathfrak{p}} \otimes d, \dots, \iota_q \alpha_{\mathfrak{p}} \otimes d)$$
 and $\alpha_{\mathfrak{p}} \otimes w \mapsto (\iota_1 \alpha_{\mathfrak{p}} \otimes w, \dots, \iota_q \alpha_{\mathfrak{p}} \otimes w).$

These identifications are compatible with the inclusion of D respectively W on both sides, as well as with the action of $D_{\mathfrak{p}}$ on $W_{\mathfrak{p}}$ and $\bigoplus_{\mathfrak{P}|\mathfrak{p}} D_{\mathfrak{P}}$ on $\bigoplus_{\mathfrak{P}|\mathfrak{p}} W_{\mathfrak{P}}$.

Let $f: W \times W \to D$ be a sesquilinear form.

Lemma 5.8. (a) The sesquilinear module $(W_{\mathfrak{p}}, f_{\mathfrak{p}})$ is the orthogonal direct sum of the sesquilinear modules $(W_{\mathfrak{p}}, f_{\mathfrak{p}})$. Briefly, $f_{\mathfrak{p}} = \perp_{\mathfrak{p}|\mathfrak{p}} f_{\mathfrak{p}}$.

(b) Let $g: U \times U \to D$ be another sesquilinear form. Then $f_{\mathfrak{p}} \cong g_{\mathfrak{p}}$ if and only if $f_{\mathfrak{P}} \cong g_{\mathfrak{P}}$ for all primes $\mathfrak{P}|\mathfrak{p}$ of L_0 .

Proof. First of all, $f_{\mathfrak{P}}: W_{\mathfrak{P}} \times W_{\mathfrak{P}} \to D_{\mathfrak{P}} \subset D_{\mathfrak{p}}$ and so can be considered as a sesquilinear form over $D_{\mathfrak{p}}$. Then

$$(\perp_{\mathfrak{P}|\mathfrak{p}} f_{\mathfrak{P}})(\alpha \otimes w, \alpha' \otimes w')$$

$$= (f_{\mathfrak{P}_{1}}(\iota_{1}\alpha \otimes w, \iota_{1}\alpha' \otimes w'), \dots, f_{\mathfrak{P}_{q}}(\iota_{q}\alpha \otimes w, \iota_{q}\alpha' \otimes w'))$$

$$= (\iota_{1}\alpha\alpha' \otimes f(w, w'), \dots, \iota_{q}\alpha\alpha' \otimes f(w, w'))$$

$$= \alpha\alpha' \otimes f(w, w') = f_{\mathfrak{p}}(\alpha \otimes w, \alpha' \otimes w'),$$

which proves (a). And (b) follows, since $W_{\mathfrak{P}} = D_{\mathfrak{P}}W_{\mathfrak{p}}$ and $U_{\mathfrak{P}} = D_{\mathfrak{P}}U_{\mathfrak{p}}$.

It follows then that (5.4) holds.

Lemma 5.9. Suppose that A and B are K-involution algebras, that $f: U \times U \to B$ is a sesquilinear form admitting A, and that $g: V \times V \to A$ is a sesquilinear form. If \mathfrak{p} is a prime of K_0 , the forms $(fg)_{\mathfrak{p}}$ and $f_{\mathfrak{p}}g_{\mathfrak{p}}$ over $B_{\mathfrak{p}}$ are canonically equivalent.

Proof. There is a standard $K_{0\mathfrak{p}}$ -isomorphism $\phi: (U \otimes_A V)_{\mathfrak{p}} \to U_{\mathfrak{p}} \otimes_{A_{\mathfrak{p}}} V_{\mathfrak{p}}$ taking $\alpha \otimes (u \otimes v)$ to $(\alpha \otimes u) \otimes (1 \otimes v)$ $(\alpha \in K_{0\mathfrak{p}}, u \in U, v \in V)$. It is easy to check that ϕ is an isomorphism of $B_{\mathfrak{p}}$ -modules, and that it is also an equivalence between the forms $(fg)_{\mathfrak{p}}$ and $f_{\mathfrak{p}}g_{\mathfrak{p}}$. (Recall that the definition of the product $fg: (U \otimes_A V) \times (U \otimes_A V) \to B$ is $(fg)(u \otimes v, u' \otimes v') = f(ug(v, v'), u')$).

We now prove that the Hasse Principle holds, under the assumption that AV = 0 for every simple direct summand A of KG which satisfies (*). Any such summand is certainly one of the A_i , $1 \le i \le k$, defined in §1.3; let A_i , $1 \le i \le m$, be the remaining A_i . From (5.4) and Lemma 5.9, we get

$$(5.5) \rho \cong \rho' \Leftrightarrow H_{0i\mathfrak{p}}\hat{h}_{i\mathfrak{p}} \cong H_{0i\mathfrak{p}}\hat{h}'_{i\mathfrak{p}} \text{ for all } \mathfrak{p} \text{ and } 1 \leq i \leq m.$$

Now consider $\rho_{\mathfrak{p}}: G \to \mathbf{I}(V_{\mathfrak{p}}, h_{\mathfrak{p}}), \ h_{\mathfrak{p}}: V_{\mathfrak{p}} \times V_{\mathfrak{p}} \to K_{\mathfrak{p}}$. Then $\widehat{h_{\mathfrak{p}}}: V_{\mathfrak{p}} \times V_{\mathfrak{p}} \to K_{\mathfrak{p}}$. $K_{\mathfrak{p}}G = \bigoplus_{i=1}^t A_{i\mathfrak{p}}$ and $(\widehat{h_{\mathfrak{p}}})_i: A_{i\mathfrak{p}}V_{\mathfrak{p}} \times A_{i\mathfrak{p}}V_{\mathfrak{p}} \to A_{i\mathfrak{p}}$. Furthermore, it is easy to check that $\rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}}$ if and only if $(\widehat{h_{\mathfrak{p}}})_i \cong (\widehat{h'_{\mathfrak{p}}})_i$ for all $i, 1 \leq i \leq t$.

Now suppose that i > k (cf. §1.3). If A_i is a hyperbolic involution algebra, so is $A_{i\mathfrak{p}}$. Otherwise A_i is of index 1 with a symplectic respectively orthogonal involution (which implies that the involution on K is the identity), and so $A_{i\mathfrak{p}}$ is likewise of index 1 with a symplectic respectively orthogonal involution, or is a direct sum of such involution algebras. Thus if ρ is orthogonal respectively symplectic, the forms $(\widehat{h_{\mathfrak{p}}})_i$ and $(\widehat{h_{\mathfrak{p}}'})_i$ arising from these algebras are determined by the $K_{\mathfrak{p}}G$ -module structure of the spaces on which they are defined (cf. §1.3).

Thus
$$\rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}}$$
 if and only if $(\widehat{h_{\mathfrak{p}}})_i \cong (\widehat{h'_{\mathfrak{p}}})_i$ for all $i, 1 \leq i \leq k$.

The next step is to show that $(\widehat{h_{\mathfrak{p}}})_i = \widehat{h}_{i\mathfrak{p}}$. Now $\widehat{h}_{i\mathfrak{p}}$ is defined on $(A_iV)_{\mathfrak{p}} = K_{0\mathfrak{p}} \otimes A_iV$, which we identify with a submodule of $K_{0\mathfrak{p}} \otimes V = V_{\mathfrak{p}}$ in the usual way. Note that $A_{i\mathfrak{p}}V_{\mathfrak{p}}$ is spanned, as an Abelian group, by elements of the form $(\alpha \otimes a_i)(\beta \otimes v) = \alpha\beta \otimes a_iv \in (A_iV)_{\mathfrak{p}}$. It follows that $A_{i\mathfrak{p}}V_{\mathfrak{p}} = (A_iV)_{\mathfrak{p}}$. We can now show that $(\widehat{h_{\mathfrak{p}}})_i = \widehat{h}_{i\mathfrak{p}}$. Let $\alpha, \beta \in K_{0\mathfrak{p}}$ and $u, v \in A_iV$. Then (cf. (1.2))

$$\widehat{h_{\mathfrak{p}}}(\alpha \otimes u, \beta \otimes v)$$

$$= \sum_{s} h_{\mathfrak{p}}(\rho_{\mathfrak{p}}(s^{-1})(\alpha \otimes u), \beta \otimes v)s$$

$$= \sum_{s} h_{\mathfrak{p}}(\alpha \otimes \rho(s^{-1})u, \beta \otimes v)s$$

$$= \sum_{s} \alpha \beta \otimes h(\rho(s^{-1})u, v)s = \alpha \beta \otimes \sum_{s} h(\rho(s^{-1})u, v)s$$

$$= \alpha \beta \otimes \hat{h}(u, v) = \hat{h}_{i\mathfrak{p}}(\alpha \otimes u, \beta \otimes v).$$

Thus

$$\rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}} \quad \Leftrightarrow \quad \hat{h}_{i\mathfrak{p}} \cong \hat{h}'_{i\mathfrak{p}} \text{ for all } i, 1 \leq i \leq k.$$

The forms $h_{0i}: V_{0i} \times V_{0i} \to A_i$ and $H_{0i}: \bar{V}_{0i} \times \bar{V}_{0i} \to D_i$ are nonsingular ϵ_i -Hermitian forms which satisfy the associativity relationship (5.3). The forms $h_{0i\mathfrak{p}}$ and $H_{0i\mathfrak{p}}$ also satisfy the associativity relationship:

$$h_{0i\mathfrak{p}}(\alpha \otimes u, \beta \otimes v)(\gamma \otimes w) = (\alpha\beta \otimes h_{0i}(u, v))(\gamma \otimes w) = \alpha\beta\gamma \otimes h_{0i}(u, v)w$$

$$= \alpha\beta\gamma \otimes (uH_{0i}(\bar{v}, \bar{w})) = (\alpha \otimes u)(\beta\gamma \otimes H_{0i}(\bar{v}, \bar{w}))$$

$$= (\alpha \otimes u)H_{0i\mathfrak{p}}(\beta \otimes \bar{v}, \gamma \otimes \bar{w}).$$

It follows from the Hermitian Morita theory that $h_{0i\mathfrak{p}}$ and $H_{0i\mathfrak{p}}$ induce a category equivalence between the category of ϵ -Hermitian forms over $A_{i\mathfrak{p}}$ and the category of $\epsilon_i\epsilon$ -Hermitian forms over $D_{i\mathfrak{p}}$. This implies that

$$\rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}} \Leftrightarrow H_{0i\mathfrak{p}} \hat{h}_{i\mathfrak{p}} \cong H_{0i\mathfrak{p}} \hat{h}'_{i\mathfrak{p}} \text{ for all } i, 1 \leq i \leq k.$$

This together with (5.5) shows that $\rho \cong \rho'$ if and only if $\rho_{\mathfrak{p}} \cong \rho'_{\mathfrak{p}}$ for all \mathfrak{p} (since $\hat{h}_i = 0$ for $m < i \le k$).

Conversely, suppose that $A_iV \neq 0$ for some A_i satisfying (*). In particular, ρ is orthogonal ($\epsilon = 1, \epsilon_i = -1$) or symplectic ($\epsilon = -1, \epsilon_i = 1$). Then $H_{0i}\hat{h}_i$ is a skew Hermitian form over D_i on $\bar{V}_{0i} \otimes A_iV$, and there is another nonsingular skew Hermitian form over D_i on the same space, which is locally equivalent to $H_{0i}\hat{h}_i$

at all primes \mathfrak{P} but not globally equivalent to it (cf. [21], 10.4.6). By Morita equivalence there is an ϵ -Hermitian form \hat{h}_i'' over A_i on A_iV which is locally but not globally equivalent to \hat{h}_i . This gives rise in an obvious way to an orthogonal or symplectic representation $\rho'': G \to \mathbf{U}(V, h'')$ which is locally equivalent to ρ at all \mathfrak{p} but not globally equivalent. Namely, one defines $\hat{h}'' = \bot_j \hat{h}_j''$, where $\hat{h}_j'' = \hat{h}_j$ for all $j \neq i$, and then $h'' = \mathrm{Tr}_{KG/K} \circ \hat{h}'$ (cf. (1.3)). This finishes the proof of Theorem 5.6.

Corollary 5.10. The Hasse Principle always holds in the following cases:

- (a) The representations are unitary.
- (b) The characteristic of K is $\neq 0$.
- (c) The representations are of odd type.
- (d) G is nilpotent and K contains either a cubic or quartic root of unity.

Proof. If the representation is unitary, (*) does not apply. If the characteristic is $\neq 0$, the A_i all have index 1 and so again (*) does not apply. Suppose that the characteristic is 0. If the degree of every absolutely irreducible character is odd, no A_i is similar to a quaternion algebra. In (d) the A_i also have index 1 – see [7], 14.5, p. 77.

6. Equivariant representations of the symmetric group.

As with linear and projective representations, the equivariant representation theory of S_r is especially explicit – the essential points are that all representations are split and that one can calculate the invariant symmetric form h_0 explicitly for an irreducible representation $\rho: S_r \to \mathbf{GL}(V)$. This is of course the same matrix involved in the involution $\bar{a} = h_0^{-1} a^* h_0$ on the direct summand of KG corresponding to ρ , induced by the canonical involution of KG. The procedure for the calculation of h_0 is described in [10]; we illustrate it by an example. This method applies if char K = 0 or p > r.

We note that when $G = \mathbf{S}_r$, every simple involution algebra component A of KG is orthogonal. In characteristic 0, this follows from the existence of a nonsingular invariant symmetric form on a simple A-module – in fact it can be assumed to be a positive definite form defined over \mathbb{Q} – and from the fact that such a form is unique up to scalar multiples since A is split. In characteristic p, there is also a nonsingular invariant symmetric form on any simple module, which is described explicitly later in this section via the example.

If K has a nontrivial involution and $K\mathbf{S}_r$ has the corresponding canonical involution, then every simple involution component A of $K\mathbf{S}_r$ is again a simple algebra. This follows from the fact that $K\mathbf{S}_r$ is split over the prime subfield, so $A = K \otimes_{K_0} A_0$, where A_0 is a simple involution component of $K_0\mathbf{S}_r$, and the involution on A is the tensor product of the involutions on K and A_0 . This implies that the Hermitian matrix h_0 for the unitary involution on A is identical with the symmetric matrix for the involution of the first kind on A_0 .

All of the facts cited in the following about representations of S_r can be found in [10].

We recall that each irreducible representation of S_r arises from a partition $\alpha = [\alpha_1, \alpha_2, \dots, \alpha_k]$ of r; thus the α_i are positive integers satisfying $\alpha_1 \geq \alpha_2 \geq \cdots \geq \alpha_k$ and $\sum_i \alpha_i = r$ (cf. [10], pp. 350 and 376). We shall describe the calculation of h_0

through an example, namely the partition

$$\alpha = [3, 2, 2]$$

of 7, which gives rise to an irreducible representation of S_7 . The standard α -tableaus are the arrays

1 4 6	2 5 7	3	1 4 5		3	1 3 6	2 5 7	4	1 3 5	2 6 7	4	1 3 6	2 4 7	5	1 3 4	2 6 7	5
1 3 5	2 4 7	6	1 3 4		6	1 3 5	2 4 6	7	1 3 4		7	1 2 6	3 5 7	4	1 2 5	3 6 7	4
1 2 6	3 4 7	5	1 2 4	6	5	1 2 5	3 4 7	6	$1\\2\\4$	3 5 7	6	1 2 5	3 4 6	7	$\begin{array}{c} 1 \\ 2 \\ 4 \end{array}$	3 5 6	7
				1 2 3		5	1 2 3	4 5 7	6	1 2 3	4 5 6	7					

They are characterized by the fact that the row lengths constitute the given partition of 7, and the integers in each row and in each column are increasing. The number of standard α -tableaus, 21, is the degree of the corresponding representation ([10], 3.1.13, p. 107).

There is an orthogonal basis u_1, \dots, u_{21} (with respect to h_0) of the representation space for which one can calculate $h_0(u_i, u_i)$. One starts with the i^{th} standard tableau; then

$$h_0(u_i, u_i) = \prod_{x=1}^7 \prod_k \frac{h(x, k)}{h(x, k) - 1},$$

where h(x, k) is a "hook length" defined as follows. k = 1, 2, 3 is the number of a row. h(x, k) is not defined (and hence does not appear in the above product) unless the integer x is in a row lower than row k; thus h(1, k) and h(x, 3) are not defined for any k and x.

Suppose x is in a row lower than row k. Then h(x,k) is the number of integers in the "hook" consisting of

- (i) the integer x,
- (ii) the integers above x up to row k (but not in rows $1,\ldots,k-1$) in the same column as x, and
- (iii) the integers $\leq x$ in row k to the right of the column of x.

For example, in the 8th standard tableau in the above display

$$\begin{array}{ccc} 1 & 2 & 6 \\ 3 & 5 \\ 4 & 7 \end{array}$$

we have h(4,1) = 4, h(4,2) = 2 (and of course h(4,3) is not defined). It is easy to check that

$$h_0(u_8, u_8) = \prod_{x=2}^7 \prod_{k=1}^2 \frac{h(x, k)}{h(x, k) - 1} = (\frac{3}{2})(\frac{4}{3} \cdot \frac{2}{1})(\frac{2}{1})(\frac{4}{3} \cdot \frac{2}{1}) = \frac{2^6}{3},$$

where the parenthesized factors correspond respectively to x = 3, 4, 5, 7. In this way one gets for $h_0(u_i, u_i), 1 \le i \le 21$,

24, 32, 36.

After adjusting by squares,

$$h_0 = \langle 10, 30, 5, 15, 15, 1, 1, 3, 2, 6, 15, 5, 5, 3, 3, 1, 6, 2, 6, 2, 1 \rangle$$

Thus one can compute the determinant and Hasse symbol of h_0 ; they are 1 and $(3,3)_K$ respectively. This means that, over a local or global field

$$h_0 \cong \langle 1, 1, \dots, 1, 3, 3 \rangle.$$

References

- [1] N. Bourbaki, Algèbre (modules et anneaux semi-simples), Actualités Scientifiques et Industrielles, no. 1261, Hermann, 1958. MR 20:4576
- [2] J. W. S. Cassels and A. Fröhlich, Algebraic number theory, Conference Proceedings, Academic Press Inc., London, 1967. MR 35:6500
- [3] Charles W. Curtis and Irving Reiner, Representation theory of finite groups and associative algebras, Pure and Applied Mathematics, vol. XI, Interscience Publishers, John Wiley and Sons, New York, 1962. MR 26:2519
- [4] Andreas W. M. Dress, Induction and structure theorems for orthogonal representations of finite groups, Annals of Mathematics 102 (1975), 291–325. MR 52:8235
- [5] Martin Epkenhans, Spurformen über Lokalen Körpern, Schriftenreihe der Mathematischen Instituts der Universität Münster, vol. 44, Math. Inst. Univ. Münster, 1987. MR 88j:11017
- [6] _____, Trace forms of normal extensions over local fields, Linear and Multilinear Algebra 24 (1989), 103–116. MR 90m:11188
- [7] Walter Feit, Characters of Finite Groups, Mathematics Lecture Notes, W.A.Benjamin Inc., New York, 1967. MR 36:2715
- [8] A. Fröhlich and A. M. McEvett, Forms over rings with involution, Journal of Algebra 12 (1969), 79–104. MR 43:243
- [9] _____, The representations of groups by automorphisms of forms, Journal of Algebra 12 (1969), 114–133. MR 39:1569
- [10] Gordon James and Adalbert Kerber, The representation theory of the symmetric group, Encyclopedia of Mathematics and Its Applications, vol. 16, Addison-Wesley, Reading, MA, 1981. MR 83k:20003
- [11] Max-Albert Knus, Alexander Merkurjev, Markus Rost, and Jean-Pierre Tignol, The book of involutions, Colloquium Publications, vol. 44, American Mathematical Society, Providence, R.I., 1998. MR 2000a:16031
- [12] H. Koch, Number theory II, Encyclopaedia of Mathematical Sciences, vol. 62, Springer-Verlag, 1992. MR 98g:11118 (reprint)
- [13] A. I. Malcev, On semisimple subgroups of Lie groups, Amer. Math. Soc. Transl. No. 33 (1950); reprint, Amer. Math. Soc. Transl. (1) 9 (1962), 172–213. MR 12:317c
- [14] A. M. McEvett, Forms over semisimple algebras with involution, Journal of Algebra 12 (1969), 105–113. MR 43:244

- [15] John Milnor, On isometries of inner product spaces, Invent. Math. 8 (1969), 83–97. MR 40:2764
- [16] Gabriele Nebe, Invariants of orthogonal G-modules from the character table, Experimental Mathematics 9 (2000), 623–629. CMP 2001:06
- [17] ______, Orthogonal Frobenius reciprocity, Journal of Algebra 225 (2000), 250–260. MR 2000m:20003
- [18] Jürgen Neukirch, Algebraische Zahlentheorie, Springer-Verlag, Berlin, Heidelberg, 1992. MR 2000m:11104 (English transl.)
- [19] O. T. O'Meara, Introduction to Quadratic Forms, Grund. d. math. Wiss., vol. 117, Springer-Verlag, New York, Heidelberg, Berlin, 1963. MR 27:2485
- [20] I. Reiner, Maximal orders, L.M.S. Monographs, Academic Press, Inc., London, New York, San Francisco, 1975. MR 52:13910
- [21] W. Scharlau, Quadratic and hermitian forms, Grund. Math. Wiss., vol. 270, Springer-Verlag, New York, Heidelberg, Berlin, 1985. MR 86k:11022
- [22] J.-P. Serre, Linear representations of finite groups, Graduate Texts in Mathematics, vol. 42, Springer-Verlag, New York, Heidelberg, Berlin, 1977. MR 56:8675
- [23] C. T. C. Wall, Classification of Hermitian Forms. VI. Group rings, Ann. of Math. (2) 103 (1976), 1–80. MR 55:5720

Deptartment of Mathematics and Statistics, McMaster University, Hamilton, Ontario, Canada, L8S $4\mathrm{K}1$

 $E ext{-}mail\ address: riehm@mcmaster.ca}$